

# Errors

- Basic idea popped out some meetings ago
- We want to do “statistics” for each prediction
- `errors(features)` or, even better, `error-distribution(features)`
- Assumption (for the moment at least):  
    `error1-distribution(feature1),`  
    `error2-distribution(feature2),`  
    ...
- **Disclaimer: maybe what I am doing makes no sense :)** (in any case doing this I realized that there are some further issues)

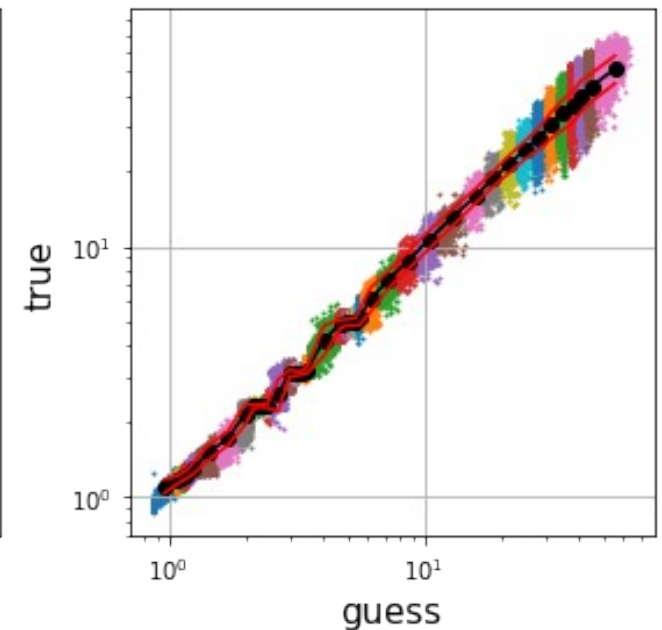
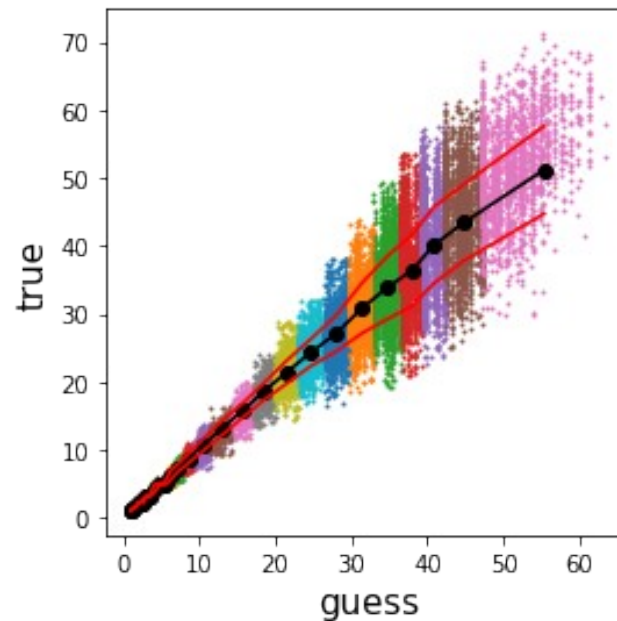
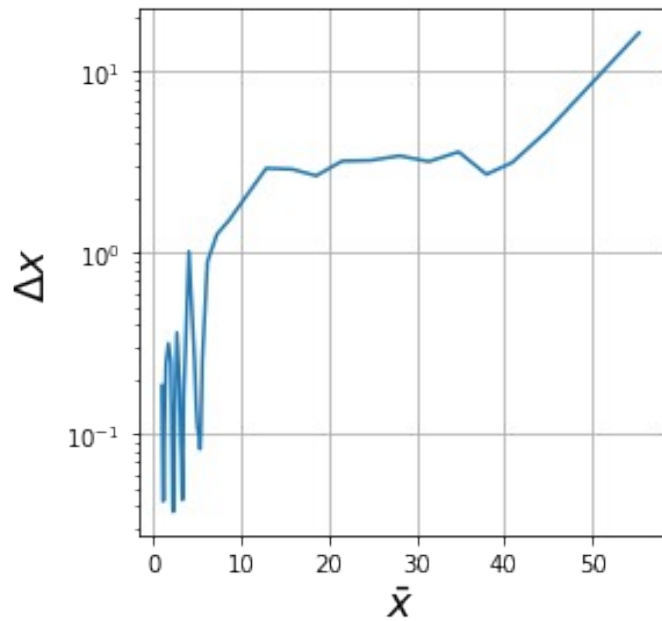
# Finding error-distr(feature)

- We consider predicted/recovered (x-axis) vs injected (y-axis)
- In an ideal world,  $y=x$ . In practice for each x-value we have many y-values.  
More y-values  $\rightarrow$  less reliable prediction, i.e. bigger error
- Let's quantify: for each x-value, we want a probability distribution for the true value y.
- We need to create bins with a small  $dx$ , then we consider all the y-values in these bins and we hope that they follow a reasonable distribution (possibly not multimodal)

# Choosing the bins

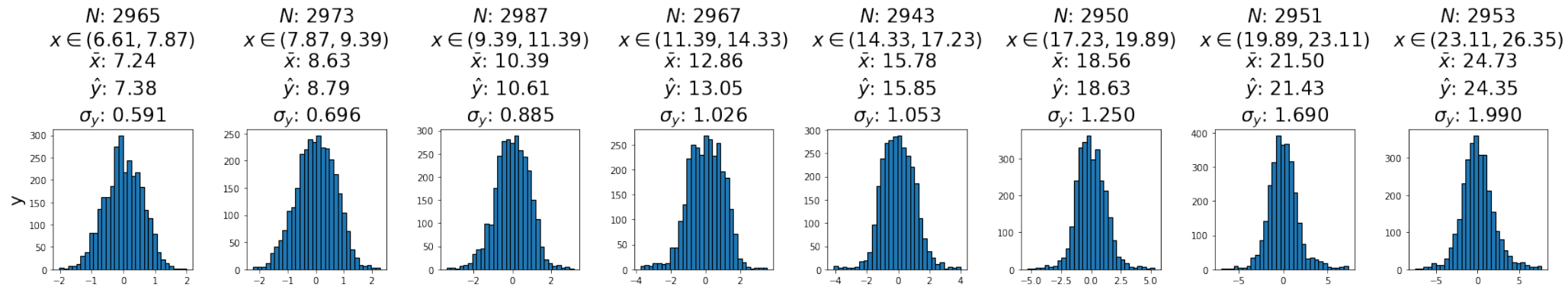
- Issues:
  - 1) If  $dx$  is too small, we do not have enough points:  $\rightarrow$  statistics make no sense
  - 2) If  $dx$  too big, we are mixing  $x$ -values:  $\rightarrow$  statistics make no sense
  - 3) Not uniformly distributed data  $\rightarrow$  constant  $dx$  is not good
- For the moment I am fixing the number of points in each bin  $\rightarrow$  issue (2) is quite relevant, let's ignore it just for a moment

# Example: chirp mass



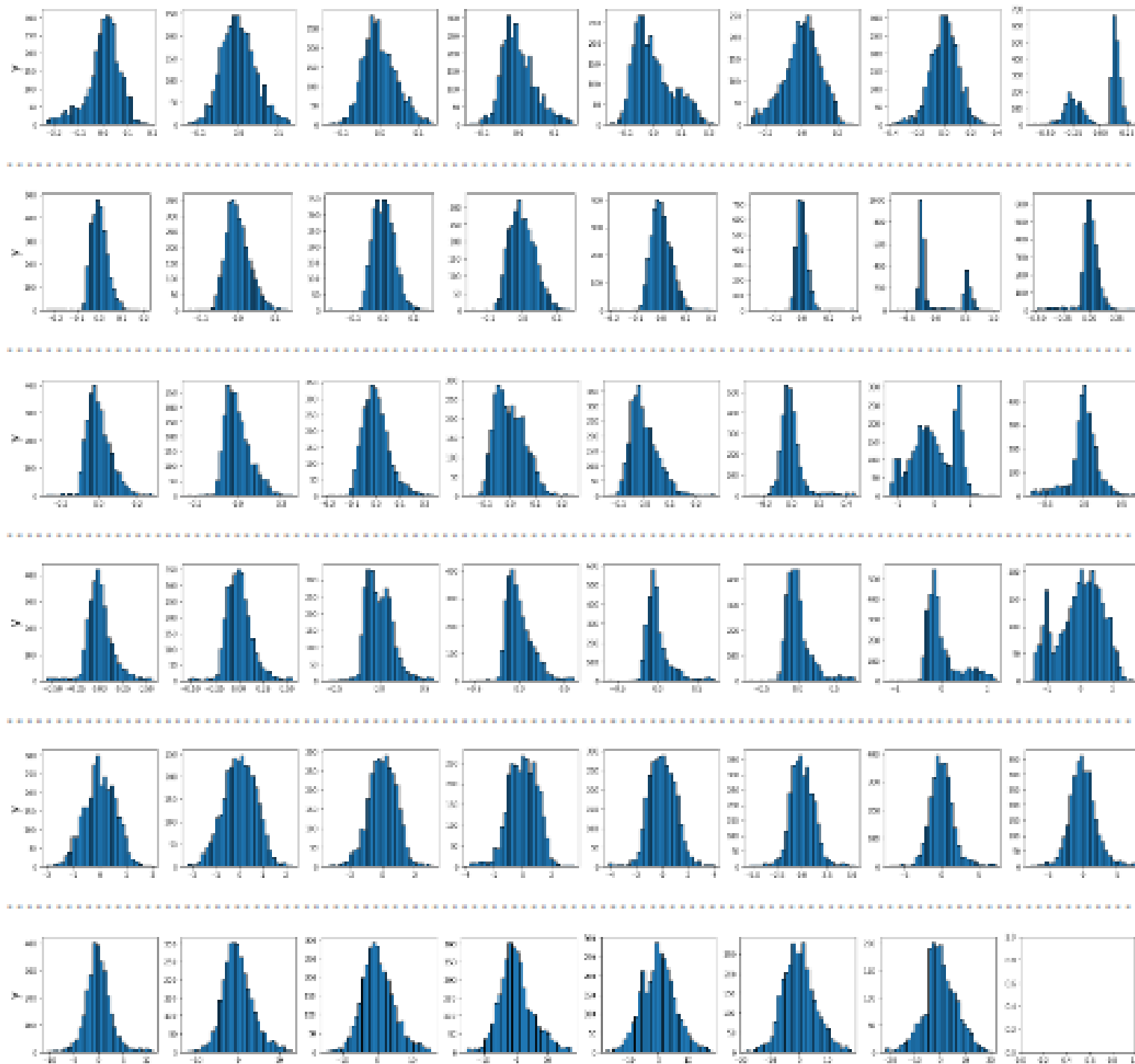
- guess is prediction
- 3k points for bins
- black dots: mean(y) for each bin
- red line: std(y) for each bin

# Example: chirp mass



Some distributions:

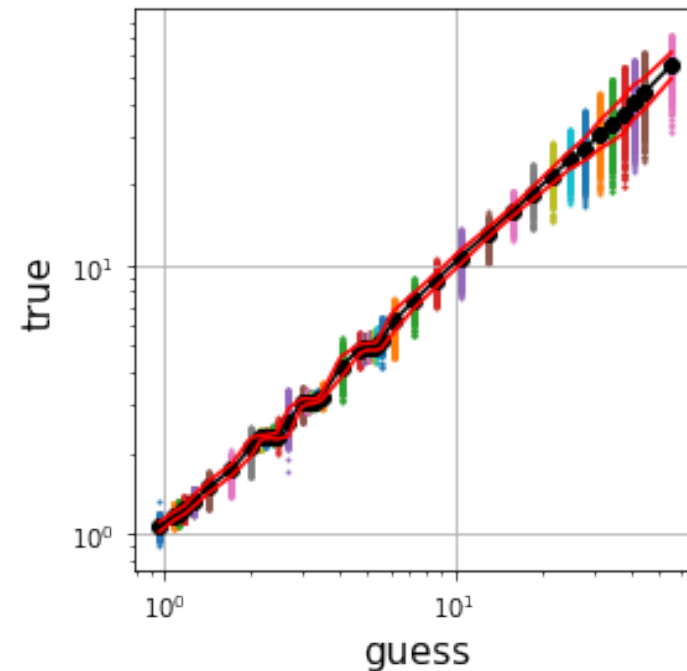
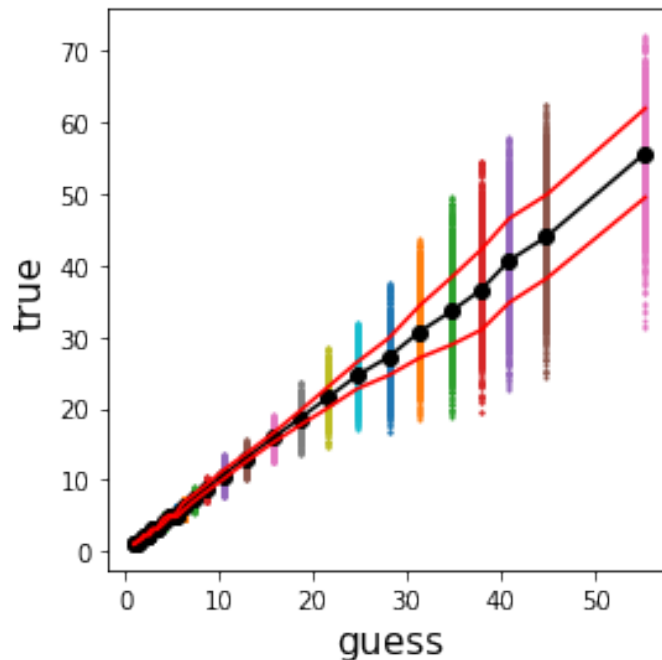
- $N \sim 3k$ , but slightly smaller  $\rightarrow$  I am removing some outliers
- if  $x$ -middle is close to  $y$ -mean with a low  $y$ -std, we are happy
- Skewness  $\neq 0$  is not a big issue (we will see why later)
- these distributions seem good, but it's cherry picking

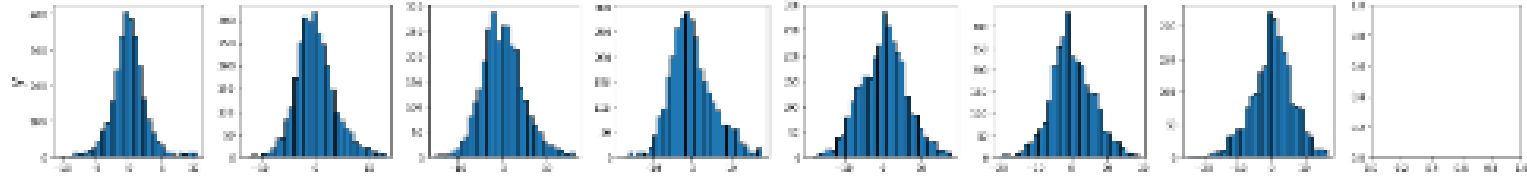
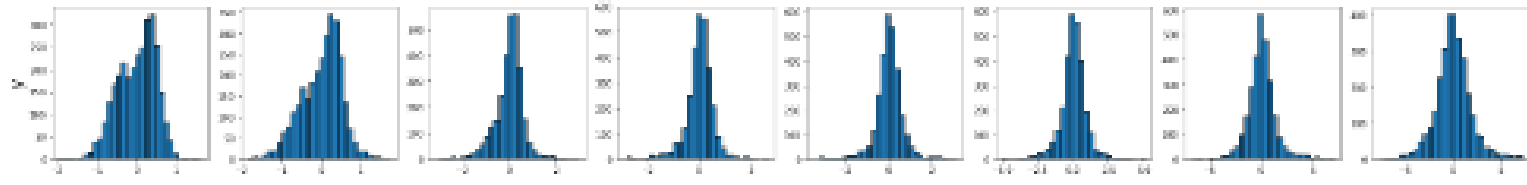
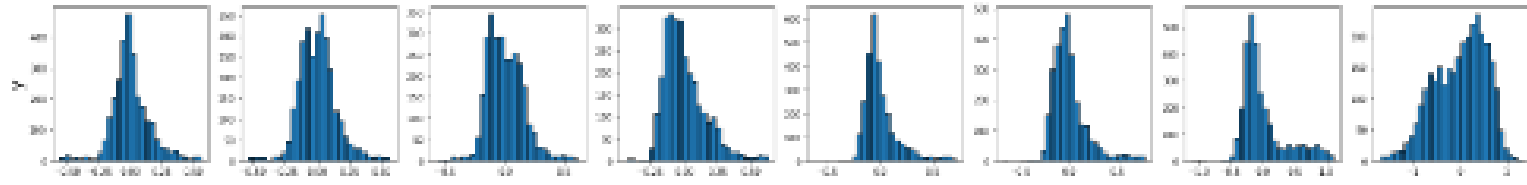
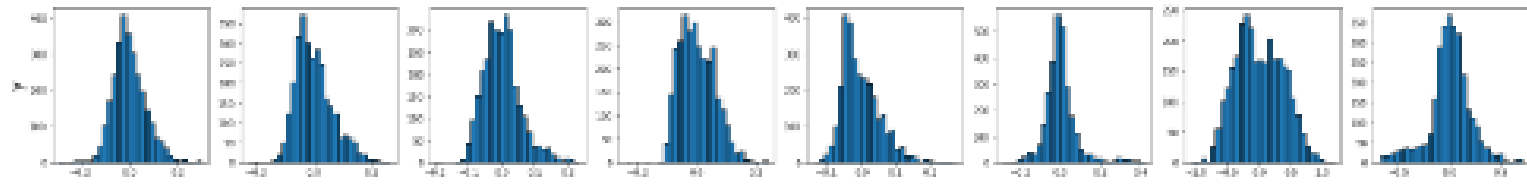
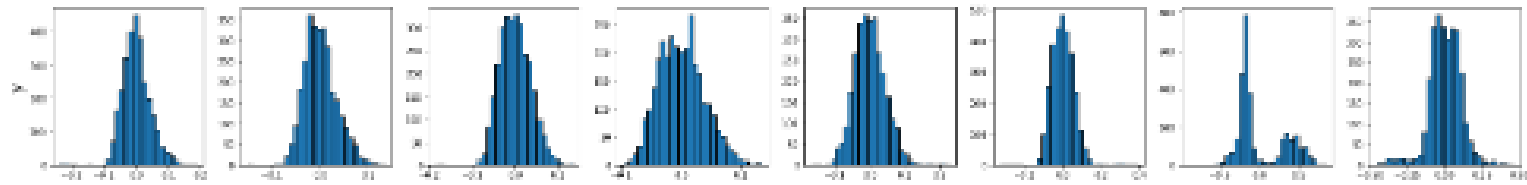
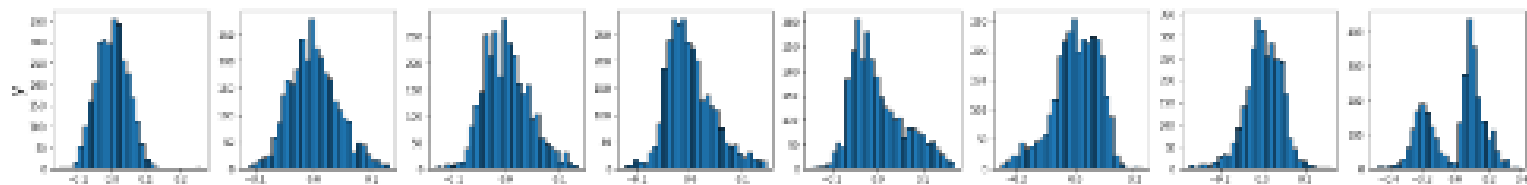


Low-quality image that shows all the distributions

# Improve the bins-procedure

- Since  $dx$  can be quite big, the  $y$ -values do not refer to the same  $x$  (i.e.,  $x_{\text{mid}}$  is not very representative)
- → project the  $y$  values on the  $x=x_{\text{mid}}$  using the  $y=x$  line (in practice  $x'=x_{\text{mid}}$ ,  $y'=y+x_{\text{mid}}-x$ )







# Skew normal distribution

Fancy ref: <https://doi.org/10.1093/biomet/83.4.715>

Ref that I actually used : [https://en.wikipedia.org/wiki/Skew\\_normal\\_distribution](https://en.wikipedia.org/wiki/Skew_normal_distribution)

- In a few cases the histo are bimodal. This is really bad.
- In most cases we have distr with non-zero skewness, so they are not Gaussians. This is not dramatic, let's consider a 1-parameter family of deformed gaussians:

## Definition [\[edit\]](#)

Let  $\phi(x)$  denote the [standard normal probability density function](#)

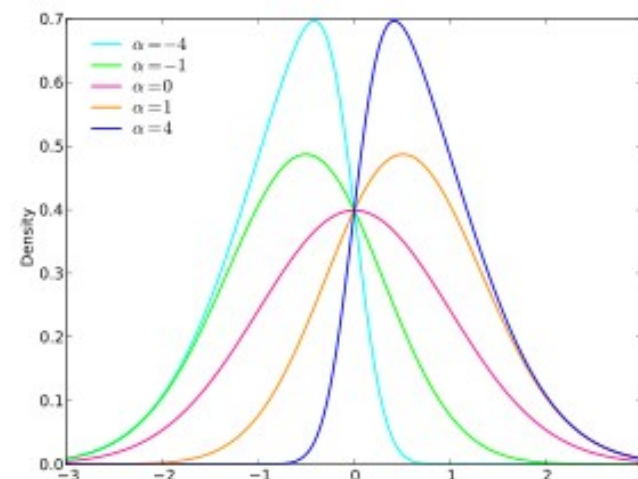
$$\phi(x) = \frac{1}{\sqrt{2\pi}} e^{-\frac{x^2}{2}}$$

with the [cumulative distribution function](#) given by

$$\Phi(x) = \int_{-\infty}^x \phi(t) dt = \frac{1}{2} \left[ 1 + \operatorname{erf}\left(\frac{x}{\sqrt{2}}\right) \right],$$

where "erf" is the [error function](#). Then the probability density function (pdf) of the skew-normal distribution with parameter  $\alpha$  is given by

$$f(x) = 2\phi(x)\Phi(\alpha x).$$



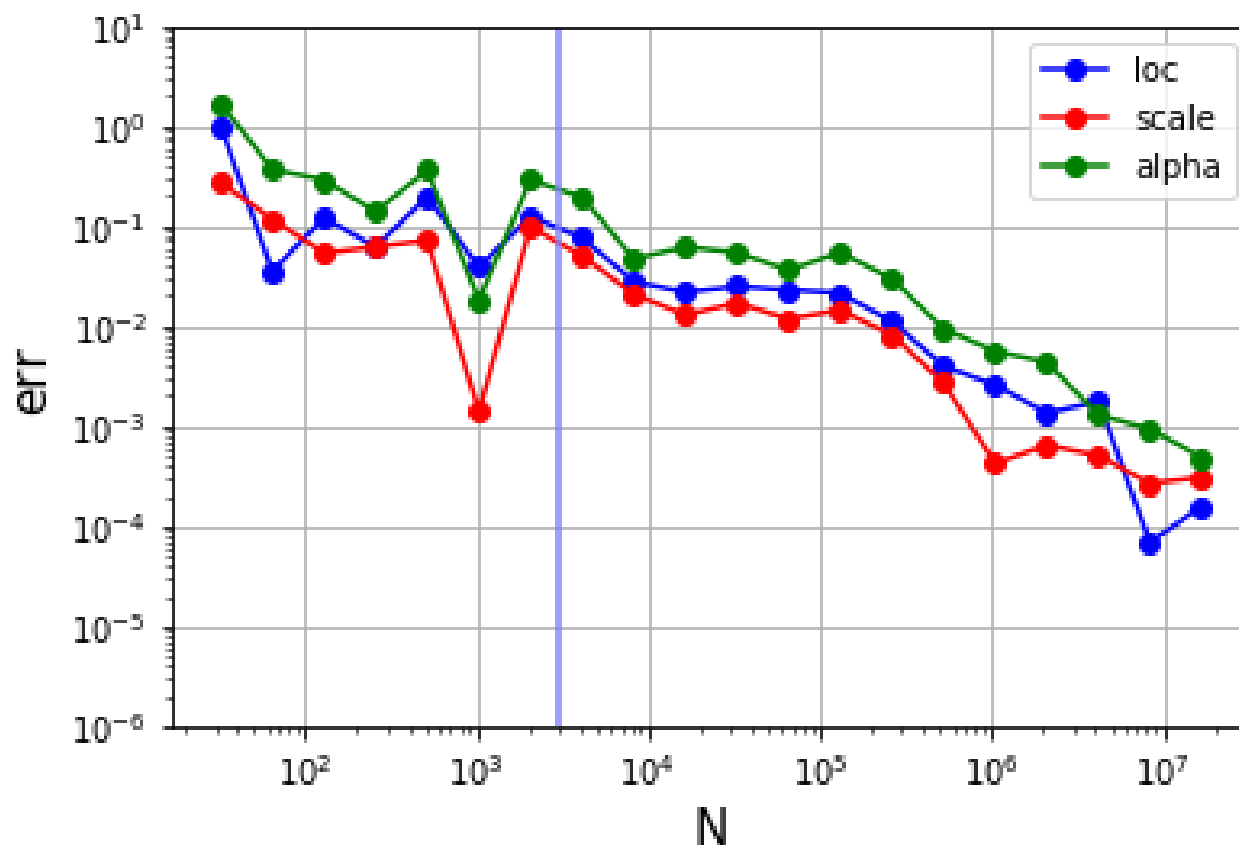
# Skew normal distribution

- If alpha is zero we go back to Gaussian
- Given our data, how we find the corresponding distribution?  
Measure mean, variance, skewness and compute loc, scale and shape
- Caveat: skew normal distribution can reproduce only skewness in (-1,1)

<b>Parameters</b>	$\xi$ location (real) $\omega$ scale (positive, real) $\alpha$ shape (real)
<b>Support</b>	$x \in (-\infty; +\infty)$
<b>PDF</b>	$\frac{2}{\omega\sqrt{2\pi}} e^{-\frac{(x-\xi)^2}{2\omega^2}} \int_{-\infty}^{\alpha\left(\frac{x-\xi}{\omega}\right)} \frac{1}{\sqrt{2\pi}} e^{-\frac{t^2}{2}} dt$
<b>CDF</b>	$\Phi\left(\frac{x-\xi}{\omega}\right) - 2T\left(\frac{x-\xi}{\omega}, \alpha\right)$ $T(h, a)$ is Owen's T function
<b>Mean</b>	$\xi + \omega\delta\sqrt{\frac{2}{\pi}}$ where $\delta = \frac{\alpha}{\sqrt{1+\alpha^2}}$
<b>Mode</b>	$\xi + \omega m_o(\alpha)$
<b>Variance</b>	$\omega^2 \left(1 - \frac{2\delta^2}{\pi}\right)$
<b>Skewness</b>	$\gamma_1 = \frac{4-\pi}{2} \frac{(\delta\sqrt{2/\pi})^3}{(1-2\delta^2/\pi)^{3/2}}$

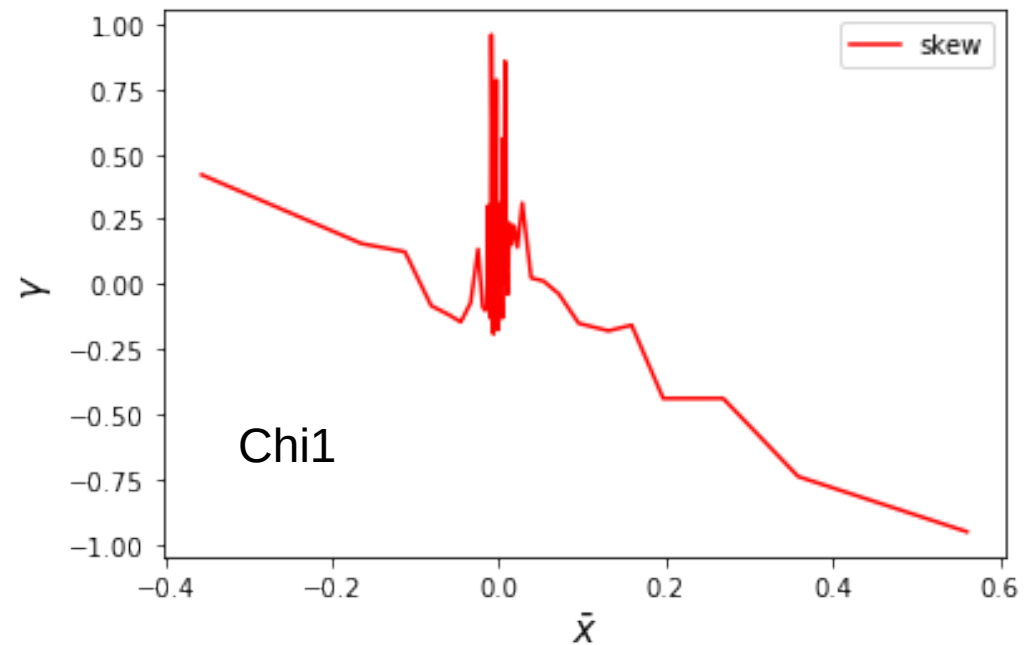
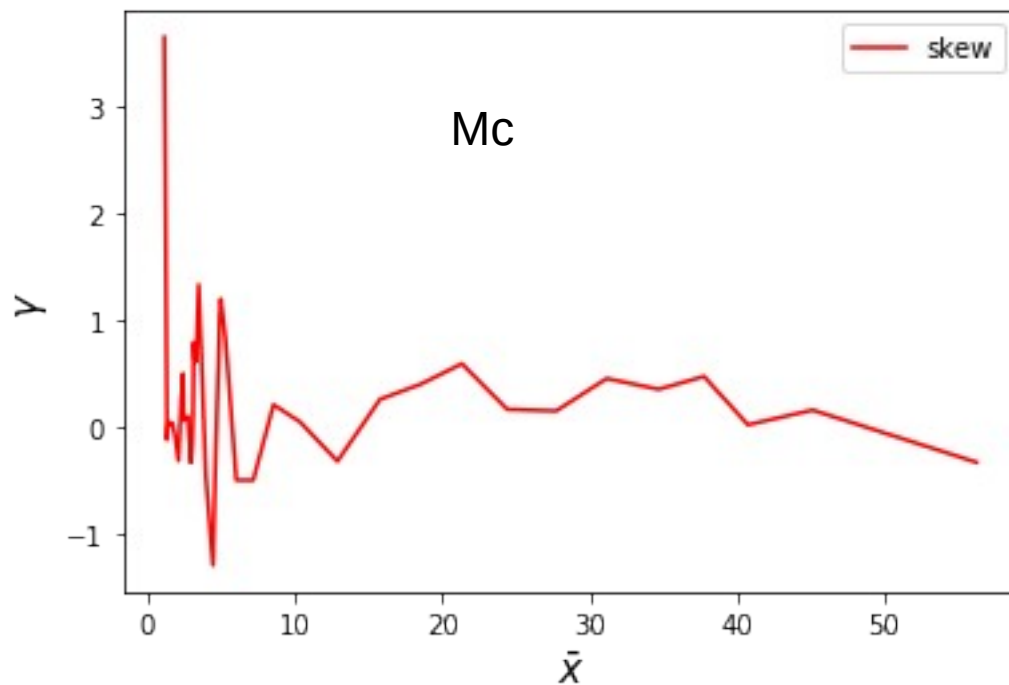
# Skew normal distribution

- How good is the loc/scale/shape recovery from mean/var/skewness for  $N \sim 3k$ ?

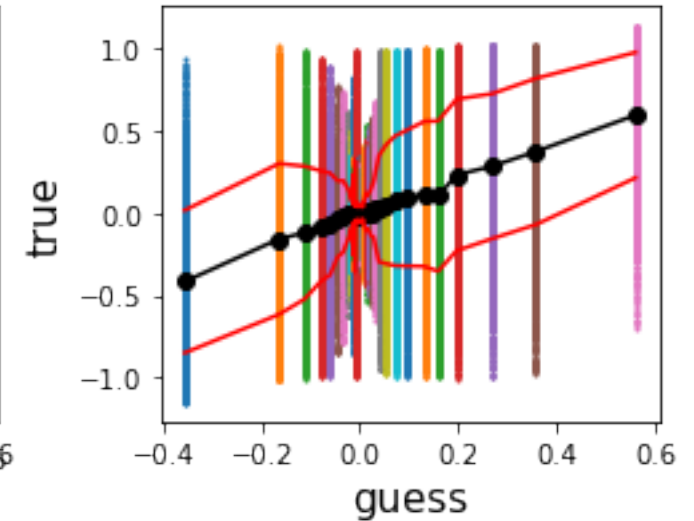
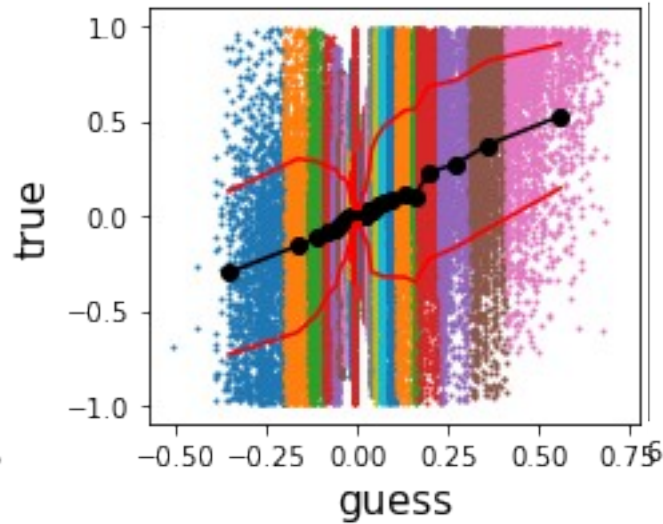
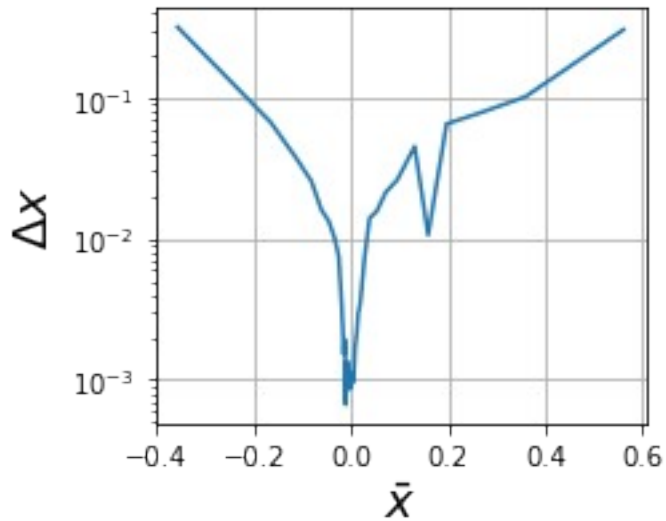


# Skew normal distribution

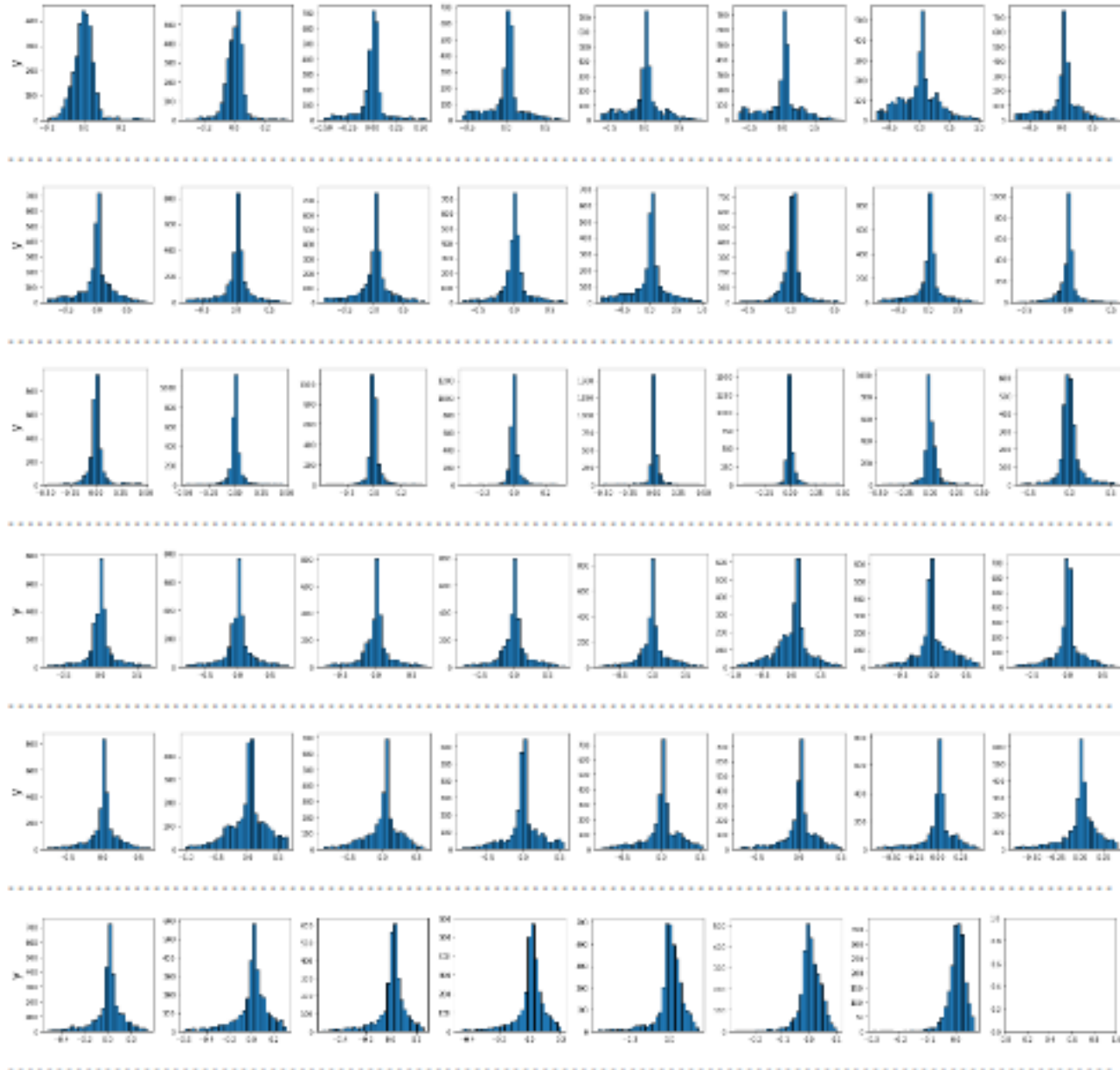
- Skewness in our case:



# And btw, these are the plots for chi1



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# Summary (of the idea)

- Create bins
- Find mean, var, skewness
- If these three values change smoothly we can interpolate and for each feature we have these three values as function of the feature
- From mean, var, skew we can compute the distribution and compute errors/probability/stuff