

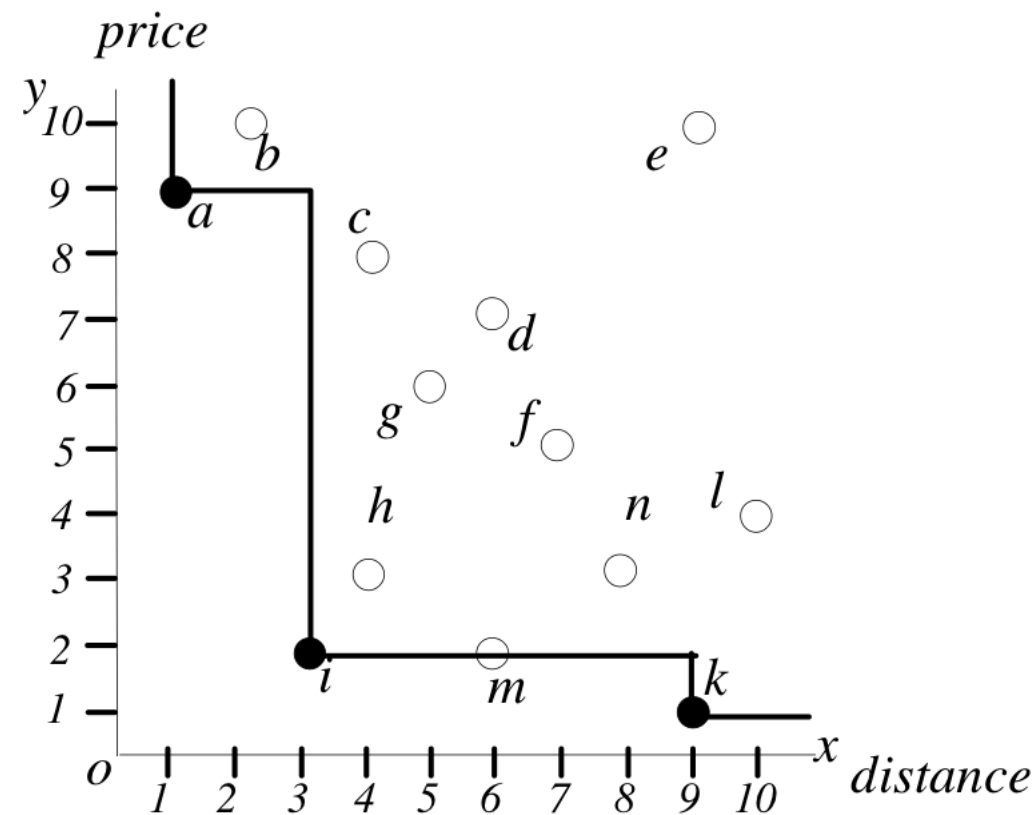
Lab 3

1st Programming assignment introduction

Skyline

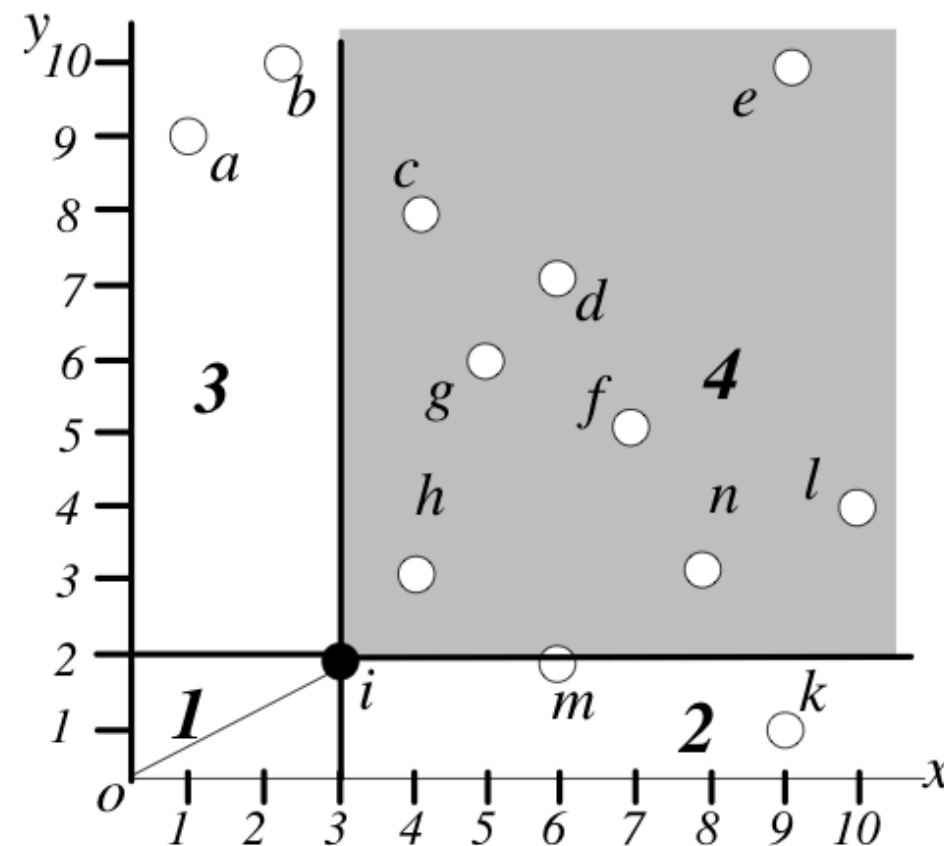
Assuming that we have a set of hotels and for each hotel we store its distance from the beach (x axis) and its price (y axis)

What is a good choice?



Dominance region of point i

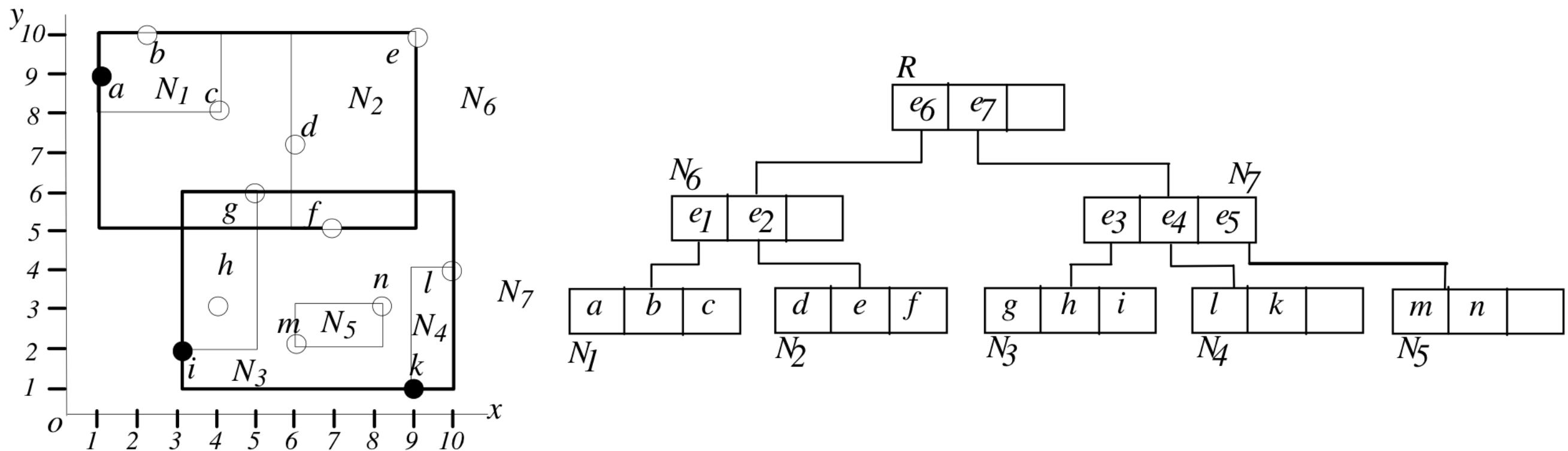
The region in which all of the points contained have a lower value than point i in all dimensions.



Point *i* dominates all other points except *a*, *b* and *k*.

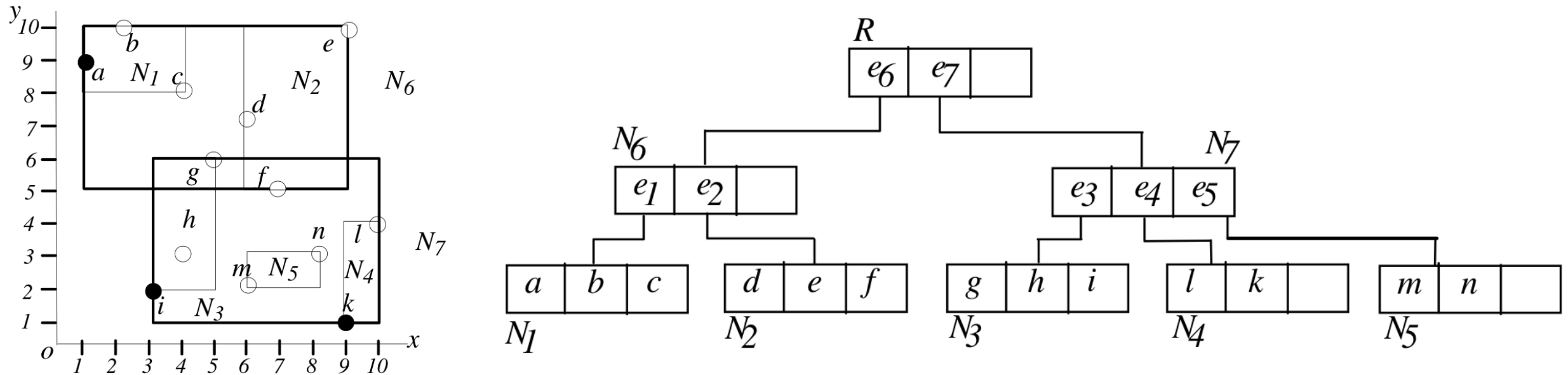
(1) Branch and Bound Skyline Algorithm (BBS)

Algorithm based on nearest neighbor search. Can be used with any data partitioning method. In the assignment, you will use an R-tree.



Points in the 2D space are stored in an R-tree as shown in previous labs.

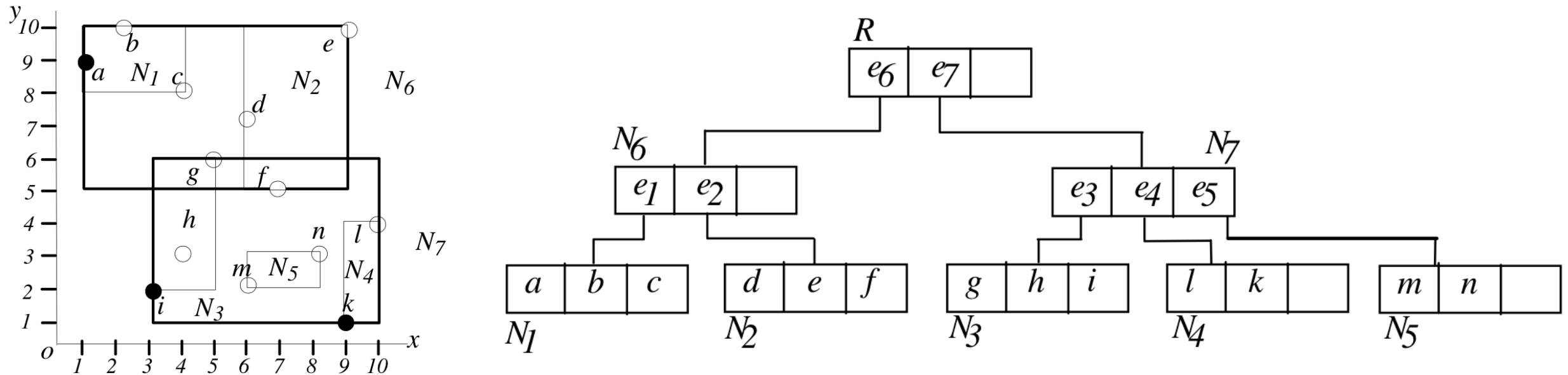
(2) Branch and Bound Skyline Algorithm (BBS)



- Starts from the root node of the R-tree and inserts all its entries (e6, e7) in a heap sorted according to their mindist.

Action	heap contents	S
access root	$\langle e_7, 4 \rangle \langle e_6, 6 \rangle$	\emptyset

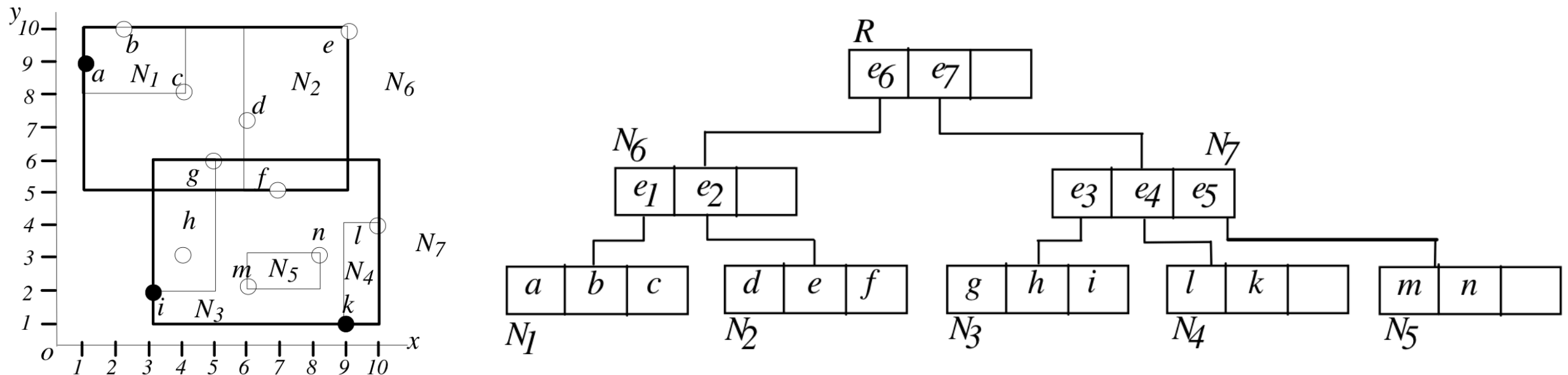
(3) Branch and Bound Skyline Algorithm (BBS)



- Then, the entry with the minimum mindist (e_7) is expanded. This expansion removes the entry (e_7) from the heap and inserts its children (e_3 , e_4 , e_5)

Action	heap contents	S
access root	$\langle e_7, 4 \rangle \langle e_6, 6 \rangle$	\emptyset
expand e_7	$\langle e_3, 5 \rangle \langle e_6, 6 \rangle \langle e_5, 8 \rangle \langle e_4, 10 \rangle$	\emptyset

(4) Branch and Bound Skyline Algorithm (BBS)



- The next expanded entry is again the one with the minimum mindist (e_3), in which the first nearest neighbor (i) is found

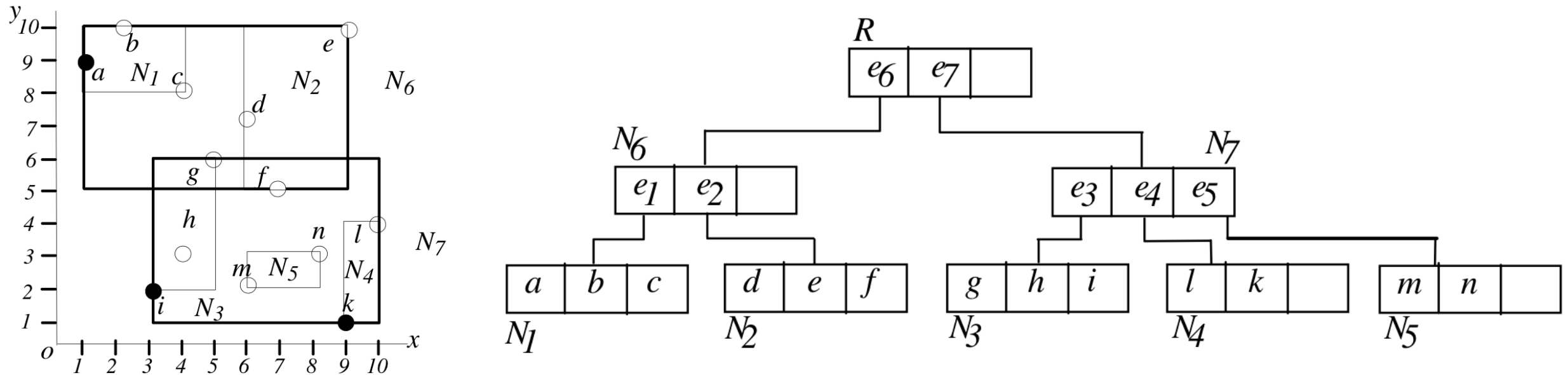
Action	heap contents	S
access root	$\langle e_7, 4 \rangle \langle e_6, 6 \rangle$	\emptyset
expand e_7	$\langle e_3, 5 \rangle \langle e_6, 6 \rangle \langle e_5, 8 \rangle \langle e_4, 10 \rangle$	\emptyset
expand e_3	$\langle i, 5 \rangle \langle e_6, 6 \rangle \langle h, 7 \rangle \langle e_5, 8 \rangle \langle e_4, 10 \rangle \langle g, 11 \rangle$	$\{i\}$

- This point (i) belongs to the skyline, and is inserted to the list S of skyline points.

!

Notice that up to this step BBS behaves like the best-first (BF) nearest neighbor algorithm. Although, BF would now terminate. Why?

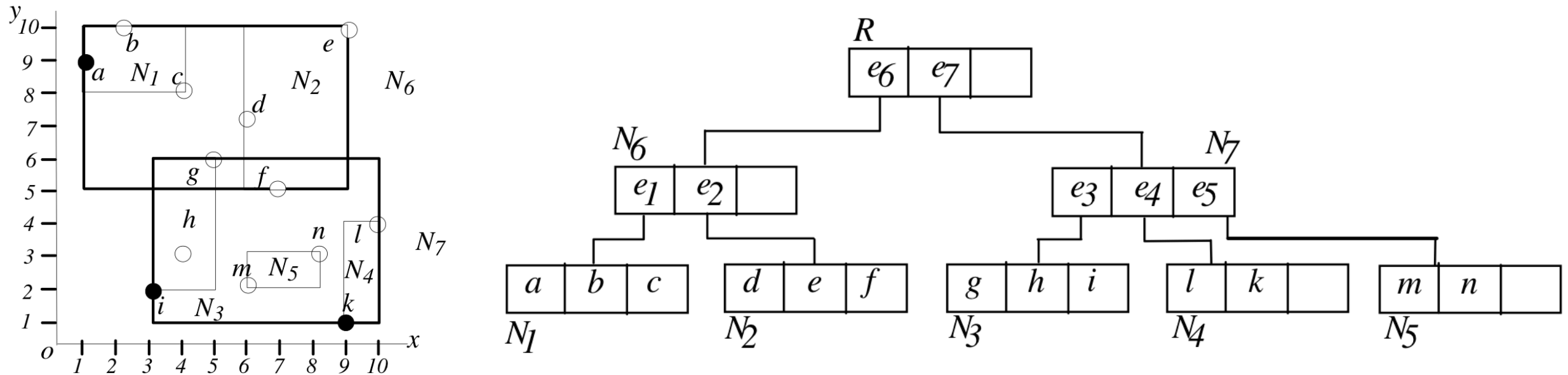
(4) Branch and Bound Skyline Algorithm (BBS)



- What is the next step?

Action	heap contents	S
access root	$\langle e_7, 4 \rangle \langle e_6, 6 \rangle$	\emptyset
expand e_7	$\langle e_3, 5 \rangle \langle e_6, 6 \rangle \langle e_5, 8 \rangle \langle e_4, 10 \rangle$	\emptyset
expand e_3	$\langle i, 5 \rangle \langle e_6, 6 \rangle \langle h, 7 \rangle \langle e_5, 8 \rangle \langle e_4, 10 \rangle \langle g, 11 \rangle$	$\{i\}$

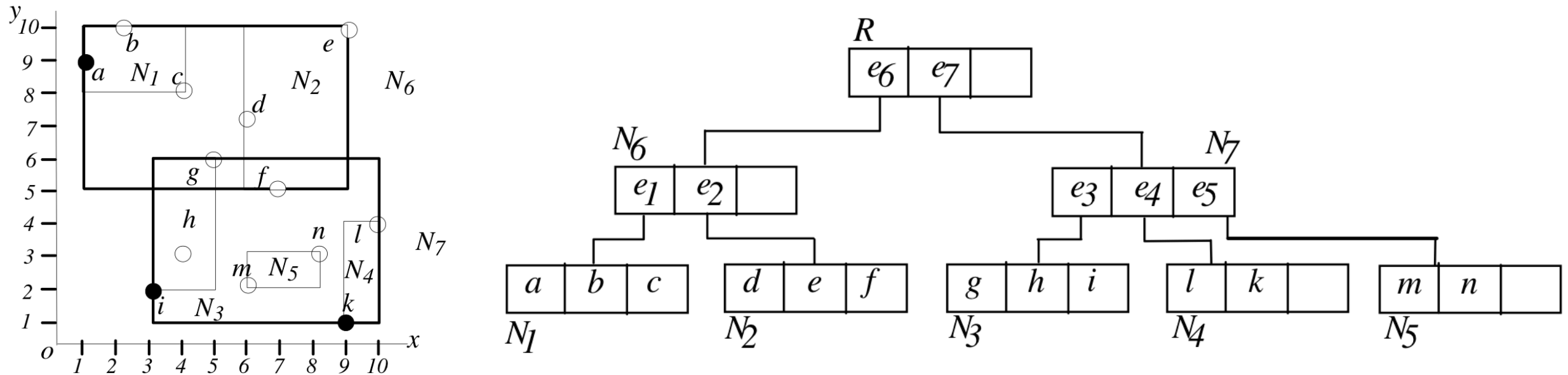
(5) Branch and Bound Skyline Algorithm (BBS)



- BBS will proceed because node N6 may contain skyline points (e.g., a). Among the children of e6, however, only the ones that are not dominated by some point in S are inserted into the heap. In this case, e2 is pruned because it is dominated by point i. Entries h, e5 and g are also pruned as they are also dominated by point i.

Action	heap contents	S
access root	$\langle e_7, 4 \rangle \langle e_6, 6 \rangle$	\emptyset
expand e_7	$\langle e_3, 5 \rangle \langle e_6, 6 \rangle \langle e_5, 8 \rangle \langle e_4, 10 \rangle$	\emptyset
expand e_3	$\langle i, 5 \rangle \langle e_6, 6 \rangle \langle h, 7 \rangle \langle e_5, 8 \rangle \langle e_4, 10 \rangle \langle g, 11 \rangle$	$\{i\}$
expand e_6	$\langle h, 7 \rangle \langle e_5, 8 \rangle \langle e_1, 9 \rangle \langle e_4, 10 \rangle \langle g, 11 \rangle$	$\{i\}$

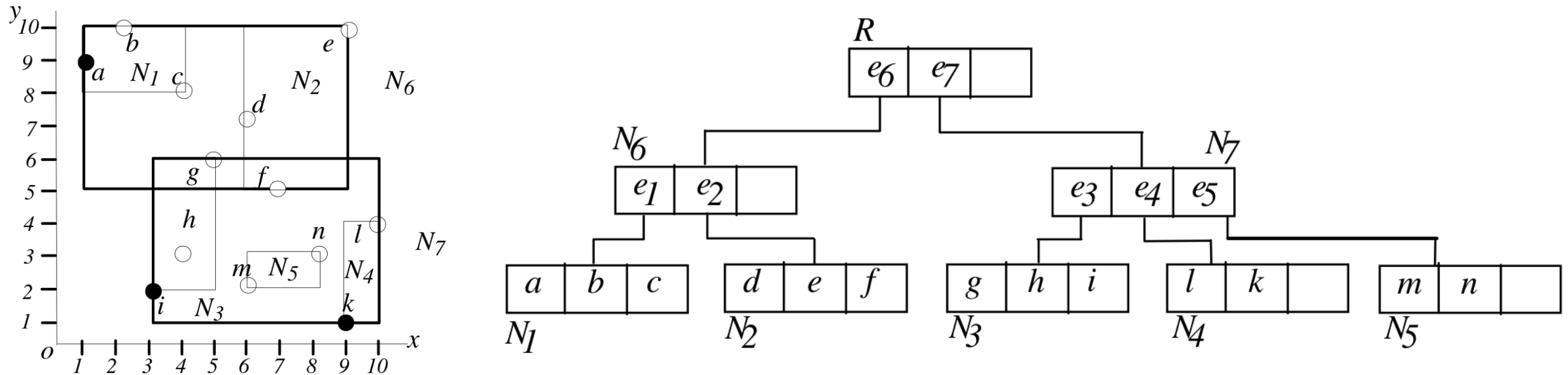
(6) Branch and Bound Skyline Algorithm (BBS)



- We expand e_1 and prune the points that are dominated by i .

Action	heap contents	S
access root	$\langle e_7, 4 \rangle \langle e_6, 6 \rangle$	\emptyset
expand e_7	$\langle e_3, 5 \rangle \langle e_6, 6 \rangle \langle e_5, 8 \rangle \langle e_4, 10 \rangle$	\emptyset
expand e_3	$\langle i, 5 \rangle \langle e_6, 6 \rangle \langle h, 7 \rangle \langle e_5, 8 \rangle \langle e_4, 10 \rangle \langle g, 11 \rangle$	$\{i\}$
expand e_6	$\langle h, 7 \rangle \langle e_5, 8 \rangle \langle e_1, 9 \rangle \langle e_4, 10 \rangle \langle g, 11 \rangle$	$\{i\}$
expand e_1	$\langle a, 10 \rangle \langle e_4, 10 \rangle \langle b, 12 \rangle$	$\{i, a\}$

(7) Branch and Bound Skyline Algorithm (BBS)

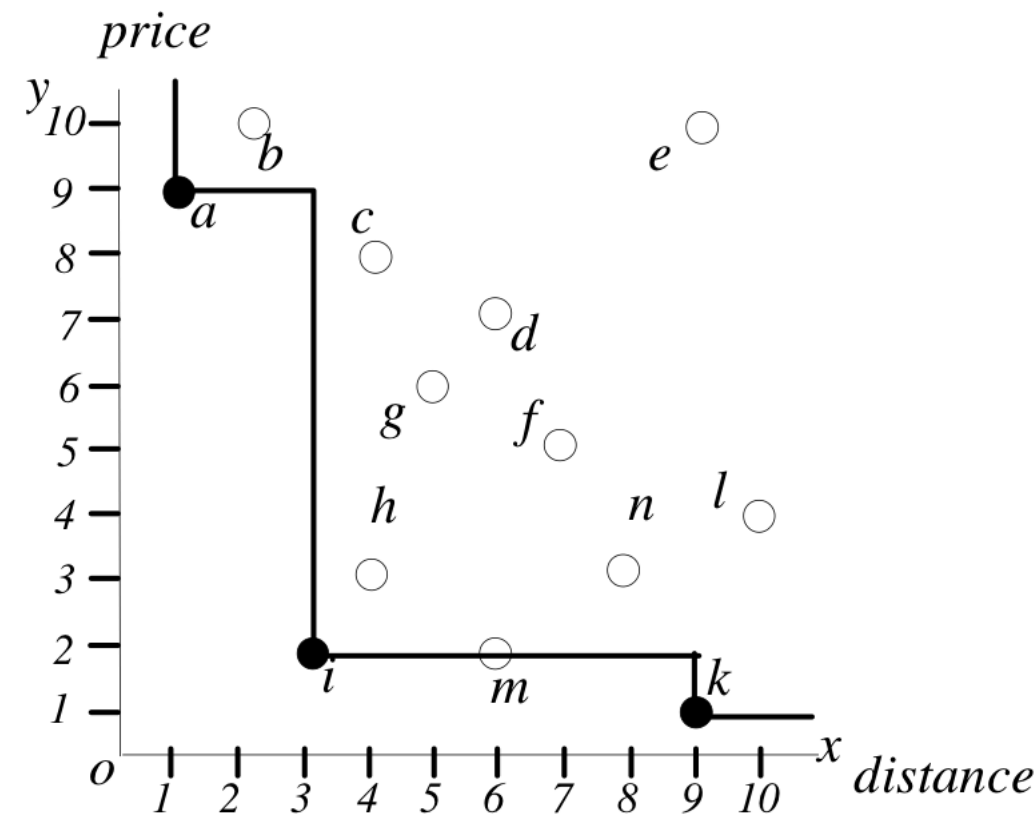


- We continue and we expand e4. We stop when all points are dominated

Action	heap contents	S
access root	$\langle e_7, 4 \rangle \langle e_6, 6 \rangle$	\emptyset
expand e_7	$\langle e_3, 5 \rangle \langle e_6, 6 \rangle \langle e_5, 8 \rangle \langle e_4, 10 \rangle$	\emptyset
expand e_3	$\langle i, 5 \rangle \langle e_6, 6 \rangle \langle h, 7 \rangle \langle e_5, 8 \rangle \langle e_4, 10 \rangle \langle g, 11 \rangle$	$\{i\}$
expand e_6	$\langle h, 7 \rangle \langle e_5, 8 \rangle \langle e_1, 9 \rangle \langle e_4, 10 \rangle \langle g, 11 \rangle$	$\{i\}$
expand e_1	$\langle a, 10 \rangle \langle e_4, 10 \rangle \langle b, 12 \rangle$	$\{i, a\}$
expand e_4	$\langle k, 10 \rangle \langle b, 12 \rangle \langle l, 14 \rangle$	$\{i, a, k\}$

(8) Branch and Bound Skyline Algorithm (BBS)

Points a, i, k build the skyline

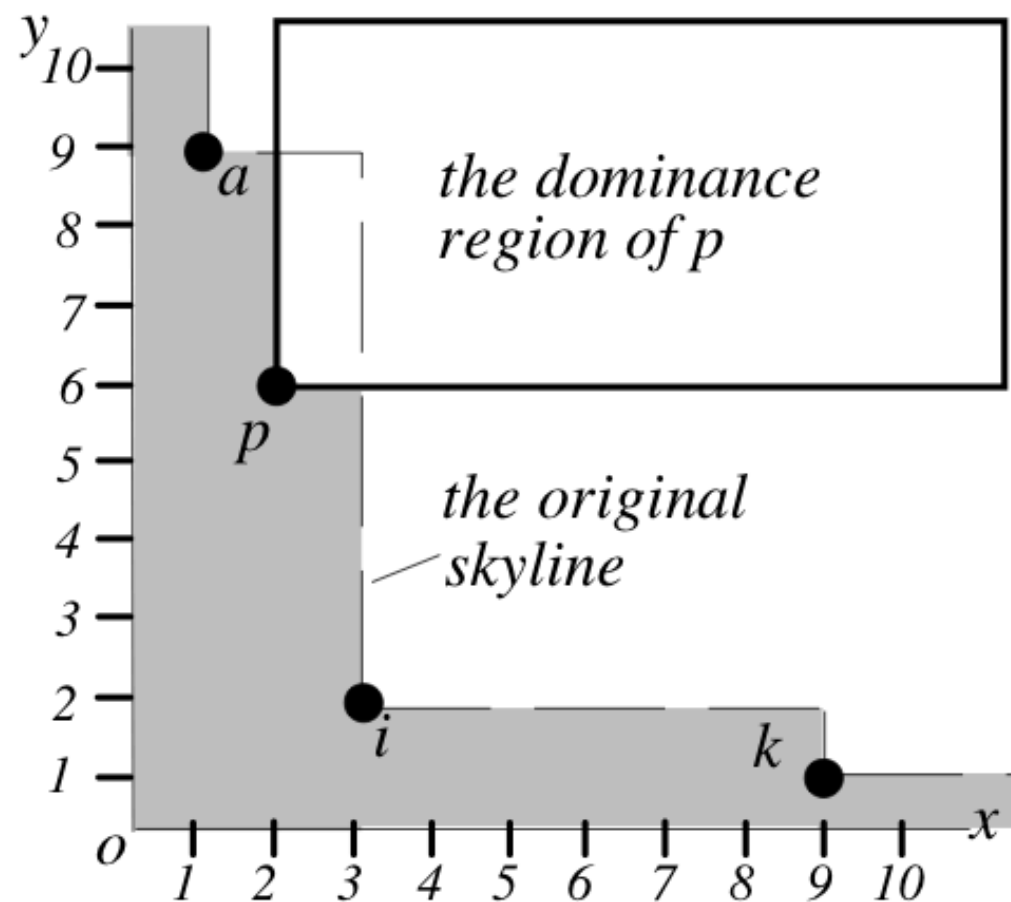


Maintaining the Skyline

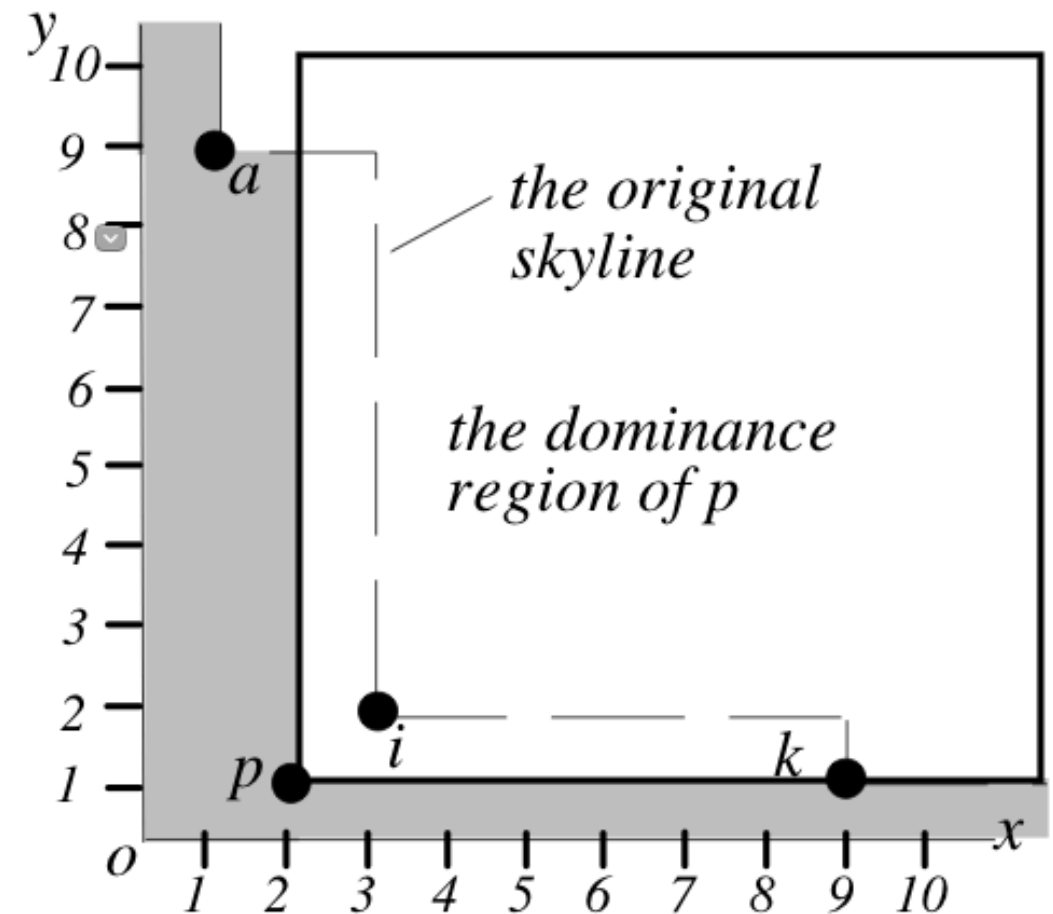
- The skyline may change due to subsequent updates (i.e., insertions and deletions) to the database
- We want to avoid re-computation

Maintaining the Skyline

Insertions



Case 1, No overlapping



Case 2, With overlapping

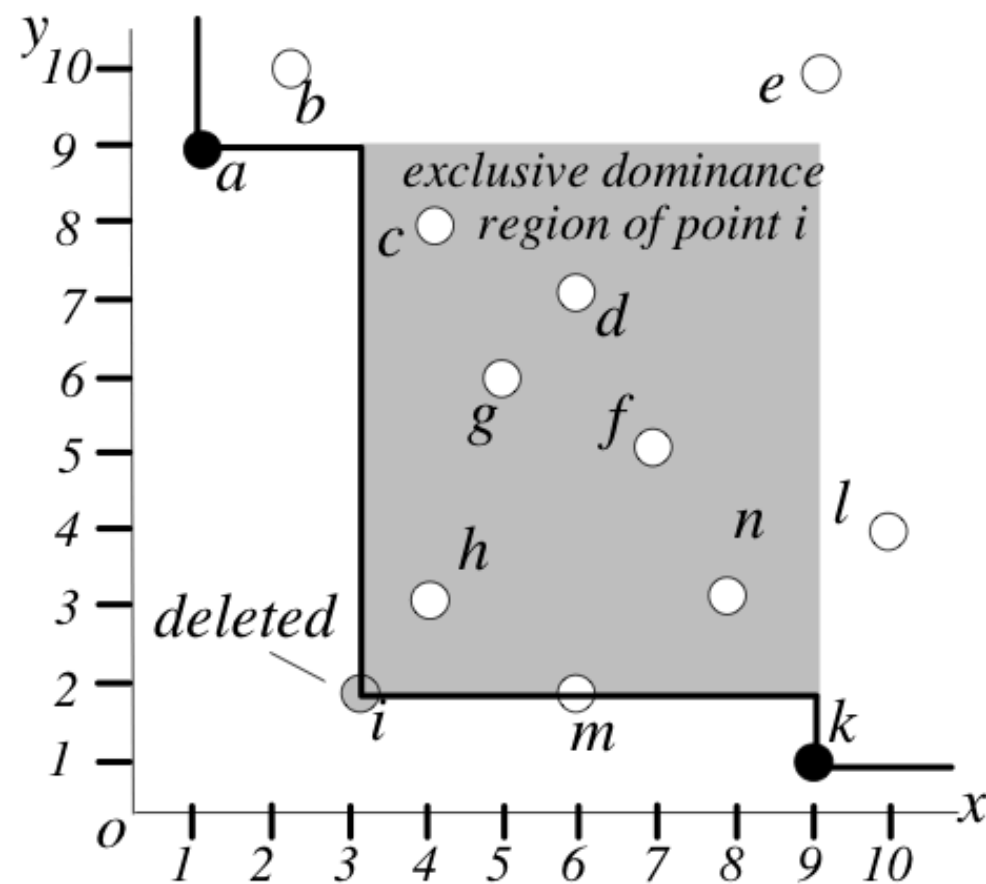
Maintaining the Skyline

Deletions

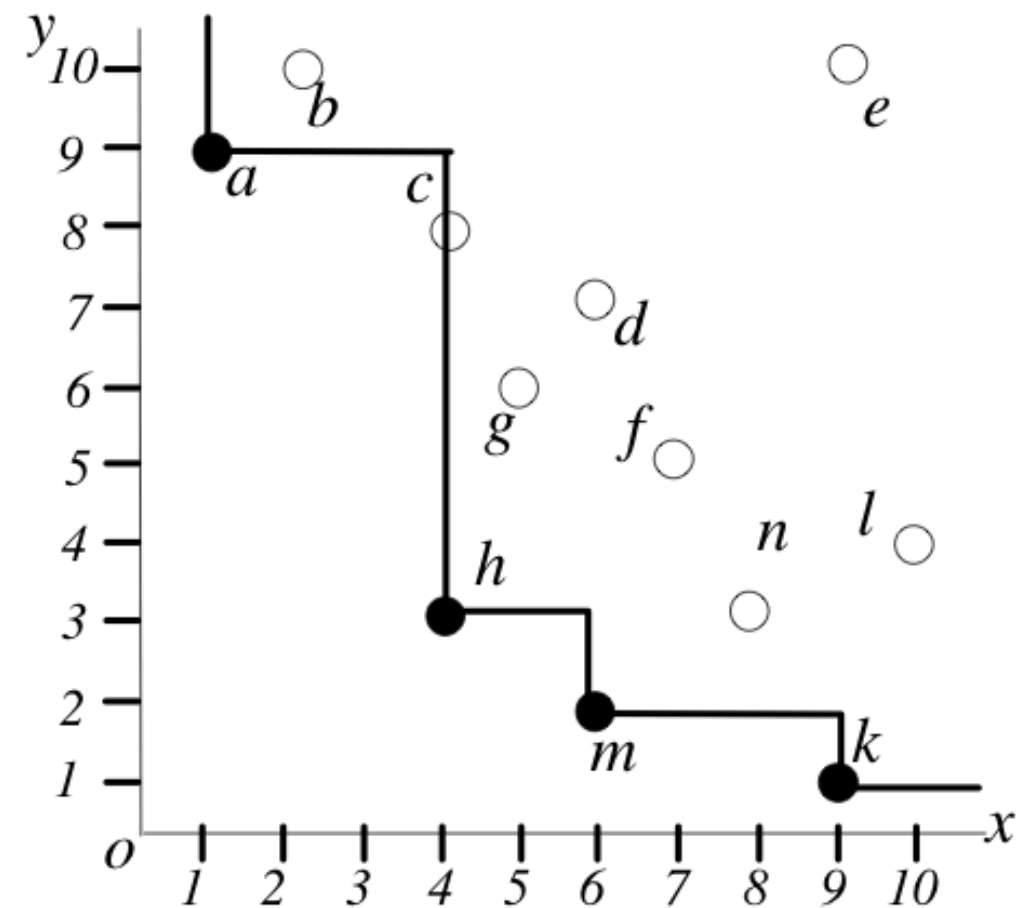
- If the point removed is not in the skyline (which can be easily checked by the main-memory R-tree using the point's coordinates), no further processing is necessary.
- Otherwise...

Maintaining the Skyline

Deletions



Step 1, find the dominance area of the point that needs to be deleted.



Step 2, find the skyline for that area and merge.