# Pregel and Spark

## Plan for today

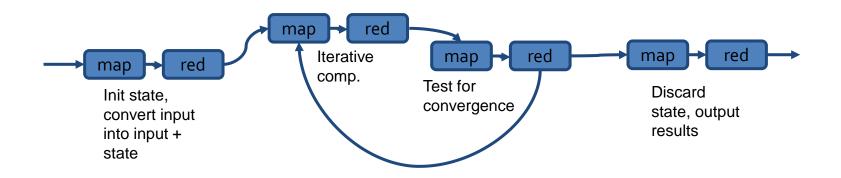
Generalizing the computation model » Bulk synchronous parallelism (BSP)



Pregel

Spark

#### Recall: Iterative computation in MapReduce



#### MapReduce is functional

- » map() and reduce() 'forget' all state between iterations
- » Hence, we have no choice but to put the state into the intermediate results
- » This is a bit cumbersome

#### What if we could remember?

#### Suppose we were to change things entirely:

- » Graph is partitioned across a set of machines
- » State is kept entirely in memory
- » Computation consists of message passing, i.e., sending updates from one portion to another

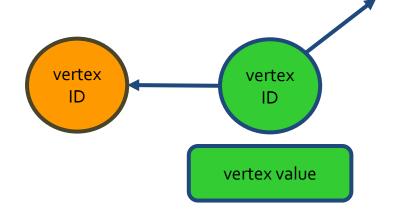
#### Let's look at two versions of this:

- » Pregel (Malewicz et al., SIGMOD'10 Google's version)
- » Spark (Zaharia et al., NSDI'12 UC Berkeley's version)

#### Let's think about the MapReduce model

How does MapReduce process graphs?

- » "Think like a vertex"
- » What do the vertices do?
- » What are the edges, really?



How good a fit is MapReduce's keys -> values model for this?

» ... and what are the consequences?

#### The BSP model

This is similar to the bulk-synchronous parallelism (BSP) model

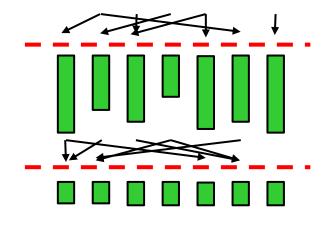
» Developed by Leslie Valiant at Harvard during the 1980s

#### BSP computations consist of:

- » Lots of components that process data
- » A network for communication, and a way to synchronize

#### Three distinct phases:

- » Concurrent computation
- » Communication
- » Barrier synchronization
- » Repeat



## Properties of the BSP model

Can BSP computations have:

- » Deadlocks?
- » Race conditions?
- » If so, when? If not, why note?

How well do BSP computations scale? Why?

#### Generalizing the computation model 🔏 » Bulk synchronous parallelism (BSP)

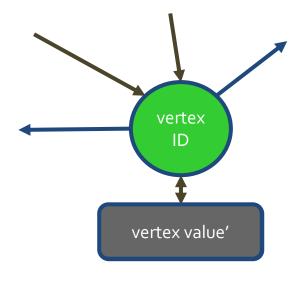


Pregel



Spark

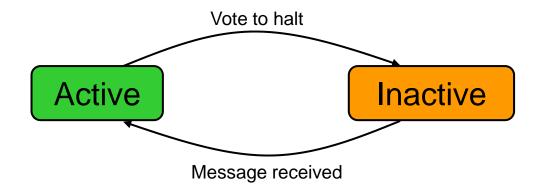
### The basic Pregel execution model



A sequence of supersteps, for each vertex:

- Receive incoming messages
- Compute()
  - Update value / state
- Send outgoing messages
- Optionally change toplogy

## **Pregel: Termination test**



How do we know when the computation is done?

- » Vertexes can be active or inactive
- » Each vertex can independently vote to halt, transition to inactive
- » Incoming messages reactivate the vertex
- » Algorithm terminates when all vertexes are inactive
- » Examples of when a vertex might vote to halt?

# Pregel: A simple example (max value)

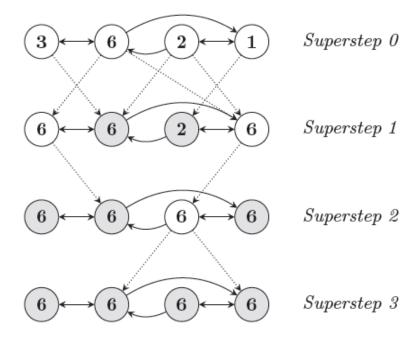


Figure 2: Maximum Value Example. Dotted lines are messages. Shaded vertices have voted to halt.

## Pregel: Producing output

# Output is the set of values explicitly output by the vertices

- » Often a directed graph isomorphic to the input...
- » ... but it doesn't have to be (edges can be added or removed)
- » Example: Clustering algorithm

#### What if we need some global statistic instead?

- » Example: Number of edges in the graph, average value
- » Each vertex can output a value to an aggregator in superstep S
- » System combines these values using a form of 'reducer', and result is available to all vertexes in superstep S+1
- » Aggregators need to be commutative and associative (why?)

## The Pregel API in C++

A Pregel program is written by sub-classing the Vertex class:

```
To define the types for vertices,
template <typename VertexValue,
                                                          edges and messages
typename EdgeValue,
typename MessageValue>
class Vertex {
                                                                          Override the
public:
                                                                       compute function to
     virtual void Compute(MessageIterator* msgs) = 0;
                                                                           define the
                                                                       computation at each
     const string& vertex id() const;
                                                                           superstep
     int64 superstep() const;
                                                   To get the value of the
     const VertexValue @ GetValue();
                                                     current vertex
     VertexValue* MutableValue(); •
                                                        To modify the value of
     OutEdgeIterator GetOutEdgeIterator();
                                                           the vertex
     void SendMessageTo(const string& dest vertex,
     const MessageValue& message);
                                                                    To pass messages to
     void VoteToHalt();
                                                                       other vertices
};
```

#### Pregel Code for Finding the Max Value

```
Class MaxFindVertex
        : public Vertex<double, void, double> {
 public:
        virtual void Compute(MessageIterator* msgs) {
                int currMax = GetValue();
                SendMessageToAllNeighbors(currMax);
                for ( ; !msgs->Done(); msgs->Next()) {
                         if (msgs->Value() > currMax)
                                 currMax = msgs->Value();
                if (currMax > GetValue())
                         *MutableValue() = currMax;
                else VoteToHalt();
};
```

## Example: PageRank in Pregel

```
class PageRankVertex : public Vertex<double, void, double> {
public:
  virtual void Compute(MessageIterator* msgs) {
    if (superstep() >= 1) {
      double sum = 0;
      for (; !msqs->Done(); msqs->Next())
        sum += msqs->Value();
      *MutableValue() = 0.15 / NumVertices() + 0.85 * sum;
    if (superstep() < 30) {</pre>
      const int64 n = GetOutEdgeIterator().size();
      SendMessageToAllNeighbors(GetValue() / n);
    } else {
      VoteToHalt();
};
```

## **Pregel: Additional complications**

How to coordinate?

» Basic Master/worker design (just like MapReduce)

How to achieve fault tolerance?

- » Crucial!! Why?
- » Failures detected via heartbeats (just like in MapReduce)
- » Uses checkpointing and recovery
- » Basic checkpointing vs. confined recovery

How to partition the graph among the workers?

- » Very tricky problem!
- » Addressed in much more detail in later work

## **Summary: Pregel**

Bulk Syncronous Parallelism – sequence of synchronized supersteps

Consider the nodes to have state (memory) that carries from superstep to superstep

Connections to MapReduce model?

## Plan for today

Generalizing the computation model 🔏



» Bulk synchronous parallelism (BSP) 💜





#### **Another Abstraction: Spark**

Let's think of just having a big block of RAM, partitioned across machines...

» And a series of operators that can be executed in parallel across the different partitions

#### That's basically Spark's resilient distributed datasets (RDDs)

- » Spark programs are written by defining functions to be called over items within collections
- » (similar model to LINQ, FlumeJava, Apache Crunch, and several other environments)

# Outline

Spark programming model

Implementation

User applications

# Programming Model

#### Resilient distributed datasets (RDDs)

- » Immutable, partitioned collections of objects
- » Created through parallel *transformations* (map, filter, groupBy, join, ...) on data in stable storage
- » Can be cached for efficient reuse

#### Actions on RDDs

» Count, reduce, collect, save, ...

# **Example: Log Mining**

Load error messages from a log into memory, then interactively search for various patterns

Block a

Cache 1

Cache 2

```
Transformed RDD
lines = spark.textFile("hdfs://...")
                                                                  Worker
                                                       results
errors = lines.filter(_.startsWith("ERROR"))
                                                            tasks
messages = errors.map(_.split('\t')(2))
                                                                  Block 1
                                                   Driver
cachedMsgs = messages.cache()
                                                   Action
cachedMsgs.filter(_.contains("foo")).count
cachedMsgs.filter(_.contains("bar")).count
                                                                 Worker
                                                     Cache 3
                                                                 Block 2
                                                Worker
  Result: scaled to 1 TB data in 5-7 sec
      (vs 170 sec for on-disk data)
```

# RDD Fault Tolerance

RDDs maintain *lineage* information that can be used to reconstruct lost partitions

```
EX: messages = textFile(...).filter(_.startsWith("ERROR"))
.map(_.split('\t')(2))

HDFS File

Filtered RDD

Mapped RDD

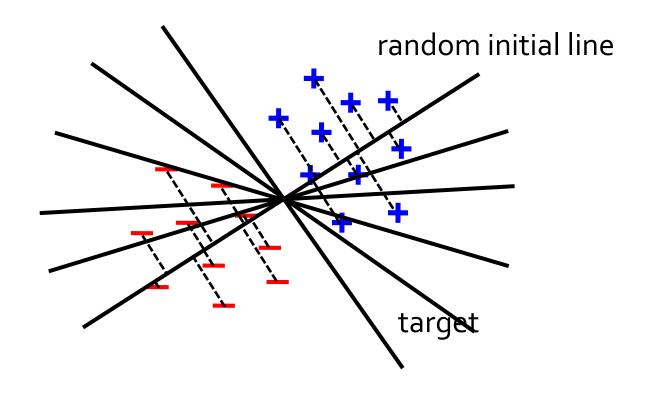
filter

(func = _.contains(...))

(func = _.split(...))
```

# **Example: Logistic Regression**

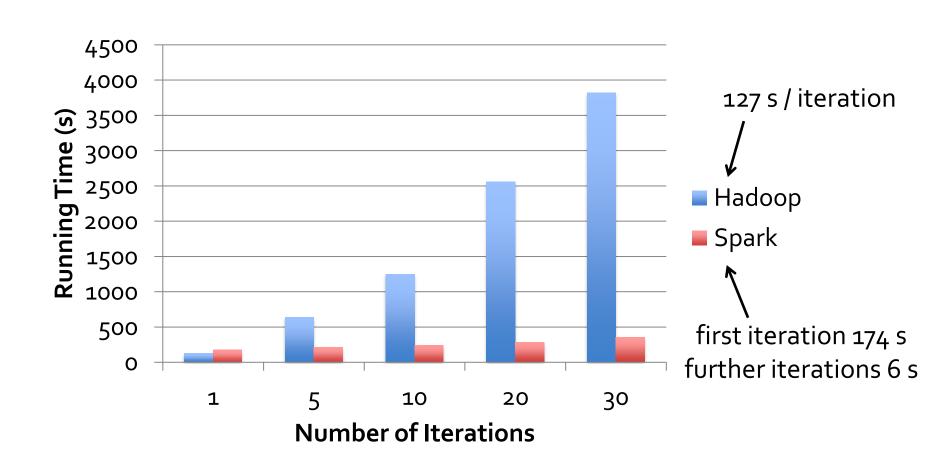
Goal: find best line separating two sets of points



# **Example: Logistic Regression**

```
val data = spark.textFile(...).map(readPoint).cache()
var w = Vector.random(D)
for (i <- 1 to ITERATIONS) {
  val gradient = data.map(p =>
    (1 / (1 + \exp(-p.y*(w \text{ dot } p.x))) - 1) * p.y * p.x
  ) reduce(_ + _)
 w -= gradient
println("Final w: " + w)
```

## Logistic Regression Performance



## Fault-Tolerance Through Lineage

Represent RDD with 5 pieces of information

- A set of partitions
- A set off dependencies on parent partitions
  - Distinguishes between **narrow** (one-to-one)
  - And wide dependencies (one-to-many)
- Function to compute dataset based on parent
- Metadata about partitioning scheme and data placement

RDD = Distributed relation + lineage

#### **Query Execution Details**

- Lazy evaluation
  - RDDs are not evaluated until an action is called

- In memory caching
  - Spark workers are long-lived processes
  - RDDs can be materialized in memory in workers
  - Base data is not cached in memory

# **Spark Operations**

map flatMap
filter union

Transformations sample join
(define a new RDD) groupByKey cogroup
reduceByKey cross
sortByKey mapValues

collect

**Actions** 

(return a result to driver program)

collect reduce count save lookupKey

# **Spark Applications**

In-memory data mining on Hive data (Conviva)

Predictive analytics (Quantifind)

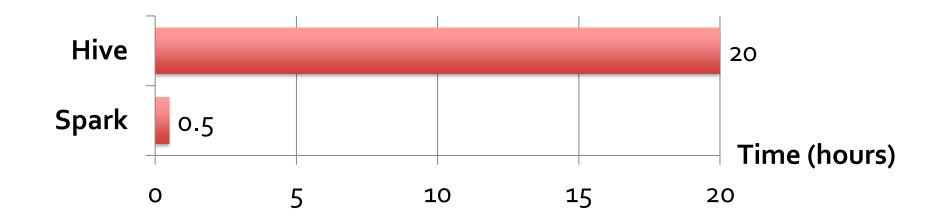
City traffic prediction (Mobile Millennium)

Twitter spam classification (Monarch)

Collaborative filtering via matrix factorization

. . .

# Conviva GeoReport



Aggregations on many keys w/ same WHERE clause

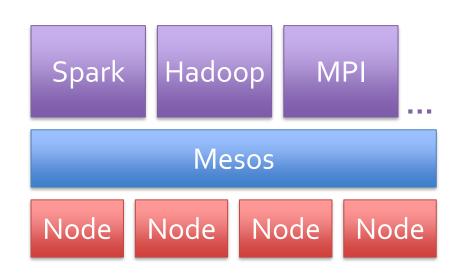
#### 40 × gain comes from:

- » Not re-reading unused columns or filtered records
- » Avoiding repeated decompression
- » In-memory storage of deserialized objects

# Implementation

Runs on Apache Mesos to share resources with Hadoop & other apps

Can read from any Hadoop input source (e.g. HDFS)



No changes to Scala compiler

# Spark Scheduler

Dataflow as DAGs

Pipelines functions within a stage

Cache-aware work reuse & locality

Partitioning-aware to avoid shuffles

