Distributed Systems

Spring Semester 2020

Lecture 22: Big Data Systems (Naiad)

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Why Naiad?

- Batch and stream processing
- Cyclic dataflows (even nested iterations)
- Efficient incremental computations (Differential Dataflow)
- Impressive performance results (low latency high throughput)

PageRank

```
val links = spark.textFile(...).map(...).persist()
var ranks = // RDD of (URL, rank) pairs
for (i <- 1 to ITERATIONS) {
  // Build an RDD of (targetURL, float) pairs
  // with the contributions sent by each page
  val contribs = links.join(ranks).flatMap {
    (url, (links, rank)) =>
      links.map(dest => (dest, rank/links.size))
  // Sum contributions by URL and get new ranks
  ranks = contribs.reduceByKey((x,y) => x+y)
             mapValues(sum => a/N + (1-a)*sum)
```

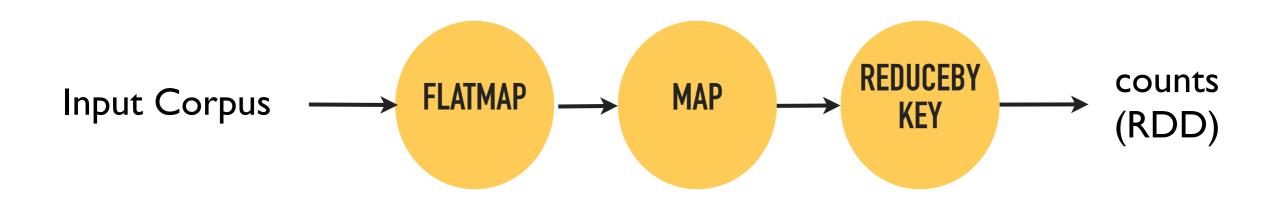
PageRank

```
val links = spark.textFile(...).map(...).persist()
var ranks = // RDD of (URL, rank) pairs
for (i <- 1 to ITERATIONS) {
  // Build an RDD of (
                           What if new pages
  // with the contribu
                       are added to the input file?
  val contribs = links
    (url, (links, rank)) =>
      links.map(dest => (dest, rank/links.size))
  // Sum contributions by URL and get new ranks
  ranks = contribs.reduceByKey((x,y) => x+y)
             .mapValues(sum => a/N + (1-a)*sum)
```

PageRank

```
val links = spark.textFile(...).map(...).persist()
var ranks = // RDD of (URL, rank) pairs
for (i <- 1 to ITERATIONS) {
  // Build an RDD of (targetURL, float) pairs
  // with the contributions sent by each page
  val contri
                                     latMap {
    (url, (l
               Start all over again!
      links.
                                     links.size))
  // Sum contributions by URL and get new ranks
  ranks = contribs.reduceByKey((x,y) => x+y)
             .mapValues(sum => a/N + (1-a)*sum)
```

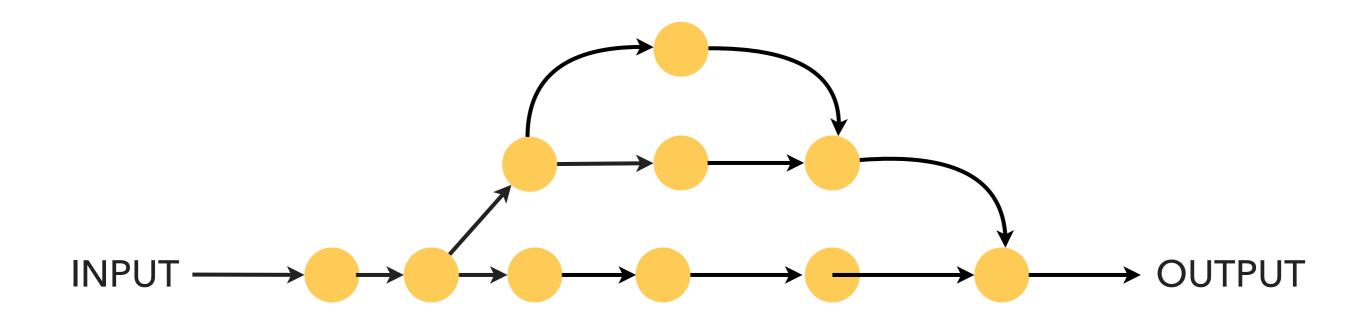
Dataflow Graphs



```
Data Operator
```

→ Flow of data

Dataflow Graphs



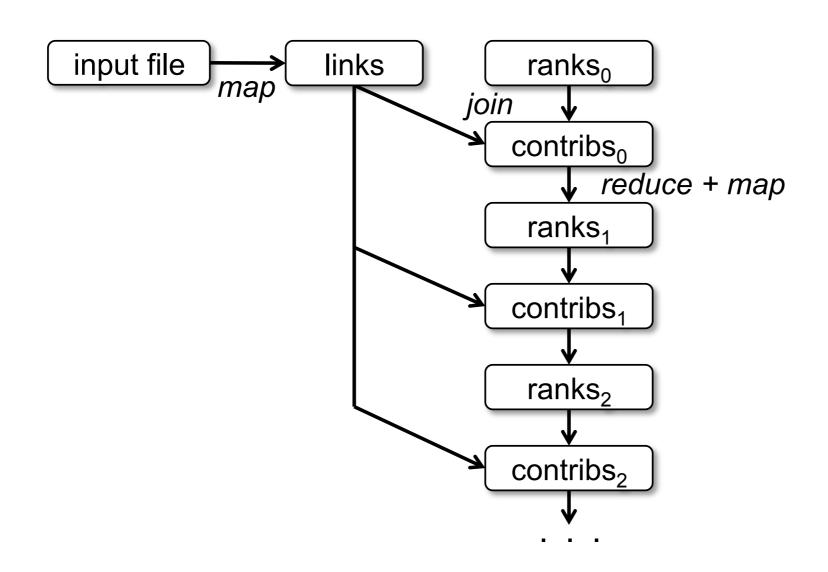


 \rightarrow Flow of data

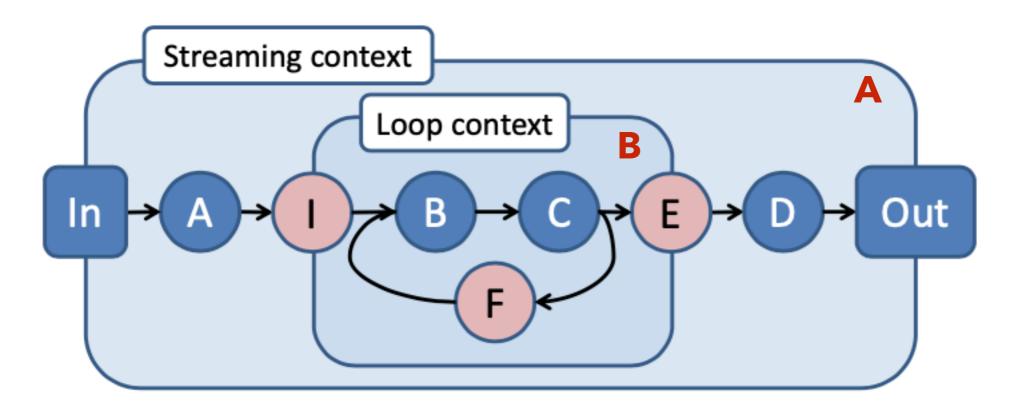
Spark supports DAGs

(Directed Acyclic Graphs)

Spark "unfolds" loops



Dataflow Graphs in Naiad

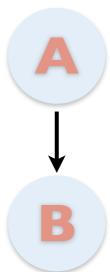


Contexts form a hierarchy

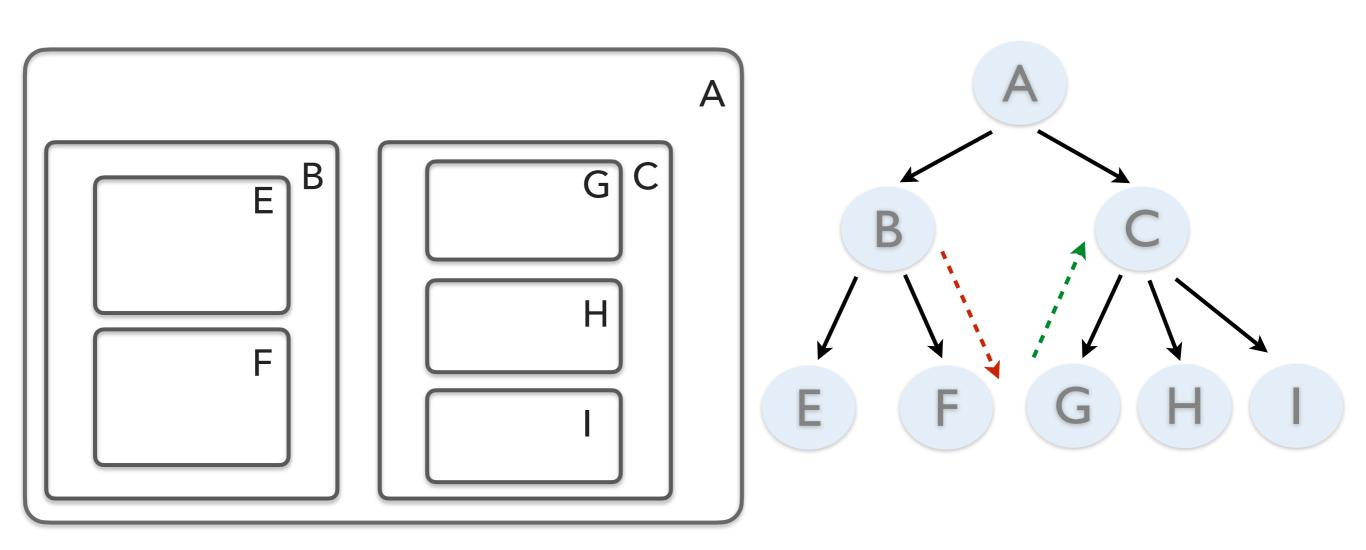
I: Ingress (enter a context)

E: Egress (exit a context)

F: Feedback (feedback loop)



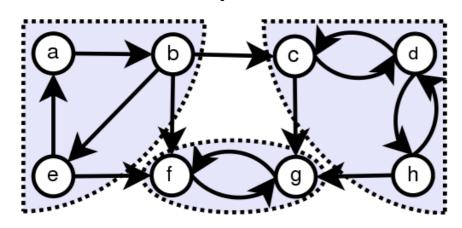
Context Hierarchy

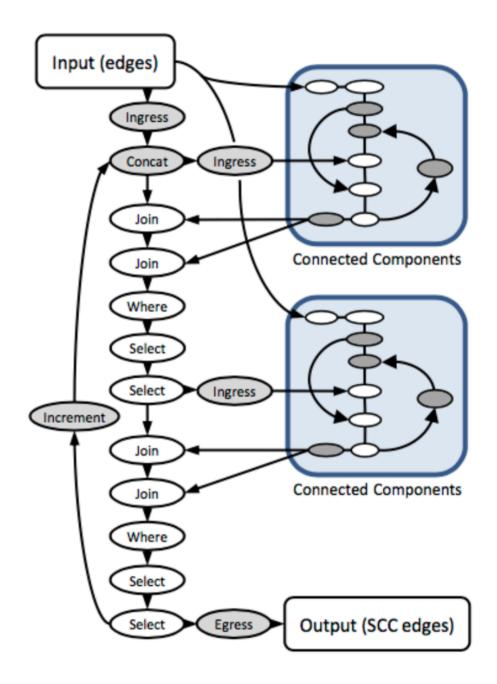


A record going through an ingress (resp. egress) node in the data flow graph is going "down" (resp. "up") in the context tree

Graph Processing in Naiad

Strongly Connected Components





Credits: Frank McSherry

Logical Timestamps

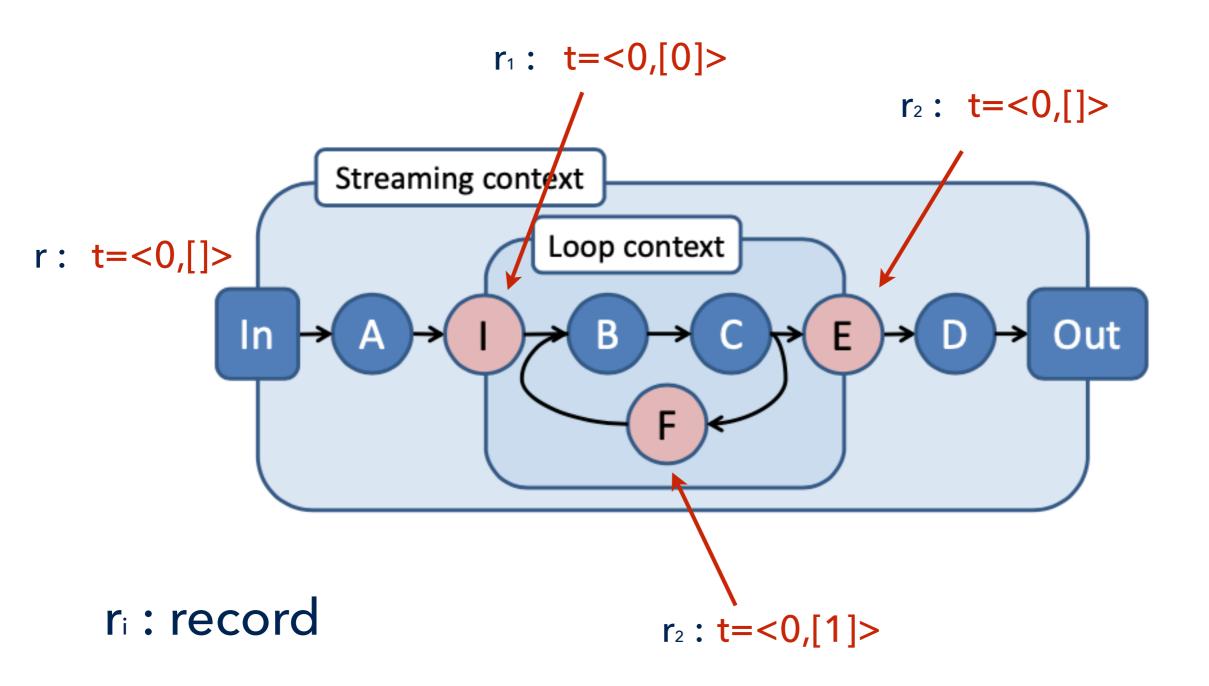
Timestamp:
$$(e \in \mathbb{N}, \langle c_1, \dots, c_k \rangle \in \mathbb{N}^k)$$

- Used to track progress of the computation
- Epoch generated by the source ("round of data")
- Each loop counter counts the number of times a record has gone through a specific loop
- Maximum number of loop counters depends on the depth of context tree — in practice I or 2

Actions on Timestamps

```
Vertex Input timestamp Output timestamp Ingress (e \in \mathbb{N}, \langle c_1, \dots, c_k \rangle \in \mathbb{N}^k) (e, \langle c_1, \dots, c_k \rangle) (e, \langle c_1, \dots, c_k \rangle) (e, \langle c_1, \dots, c_k \rangle)
```

Actions on Timestamps



- Protocol to know when to deliver notifications to vertices
- Notification for a timestamp t: vertex won't see any more records with this timestamp in its input(s)
- Intuition: deliver notification for t when it is impossible for predecessors to generate a timestamp earlier than t
- Distributed protocol requires broadcasts

```
this. SENDBY (e : Edge, m : Message, t : Timestamp)
this. NOTIFYAT(t : Timestamp).
```

- SENDBY: vertex sends data message to another vertex
- NOTIFYAT: vertex requires notification at timestamp t

```
this. SENDBY (e: Edge, m: Message, t: Timestamp) this. NOTIFYAT(t: Timestamp).

the actual data vertex u
```

- SENDBY: vertex sends data message to a vertex
- NOTIFYAT: vertex requires notification for timestamp t

```
v.ONRECV(e: Edge, m: Message, t: Timestamp) v.ONNOTIFY(t: Timestamp).
```

- ONRECEIVE: vertex v receives data message from a vertex
- ONNOTIFY: vertex v receives a notification for timestamp t

```
v.ONRECV(e: Edge, m: Message, t: Timestamp)v.ONNOTIFY(t: Timestamp).Edge: (u,v)
```

- ONRECEIVE: vertex v receives data message from a vertex
- ONNOTIFY: vertex v receives a notification for timestamp t

Pointstamp : $(t \in \text{Timestamp}, \ \widetilde{l} \in \text{Edge} \cup \text{Vertex})$

- Each event (notification or data message) has a timestamp t and a location ℓ "pointstamp"
- Each time an event happens its pointstamp becomes "active"
- For an active pointstamp p, the system maintains:
 - An occurrence count (OC): how many active events of the same type (message or notification) have the same pointstamp p
 - A precursors count (PC): how many active events "could result in" an event with this pointstamp p

```
this.SENDBY(e: Edge, m: Message, t: Timestamp)this.NOTIFYAT(t: Timestamp).v.ONRECV(e: Edge, m: Message, t: Timestamp)v.ONNOTIFY(t: Timestamp).
```

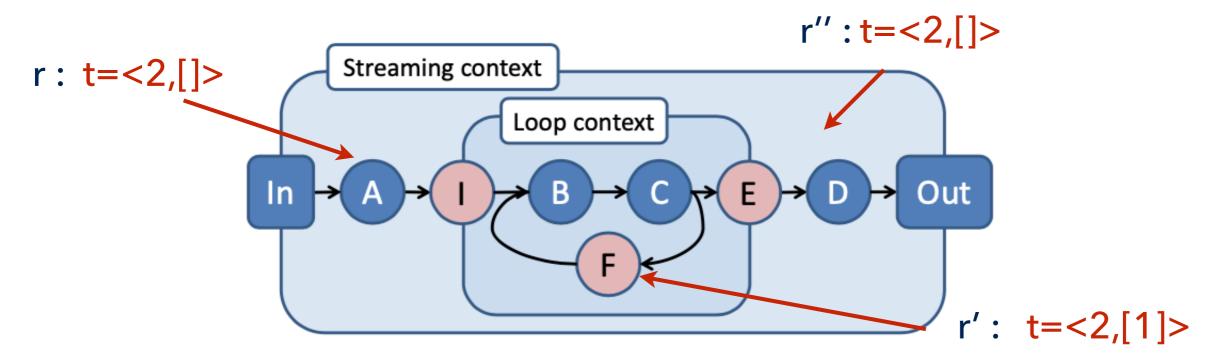
- SENDBY and NOTIFYAT generate "active" events increase counters
- ONRECEIVE and ONNOTIFY consume "active" events decrease counters

- A pointstamp p leaves the set of "active" pointstamps when its occurrence count becomes zero
- When a pointstamp p leaves the active set, the system decreases the precursor count for all active pointsamps p could result in
- Frontier: the set of active pointstamps with precursor counters equal to zero
- How do check if a pointstamp "could result in" another pointstamp?

Path Summaries

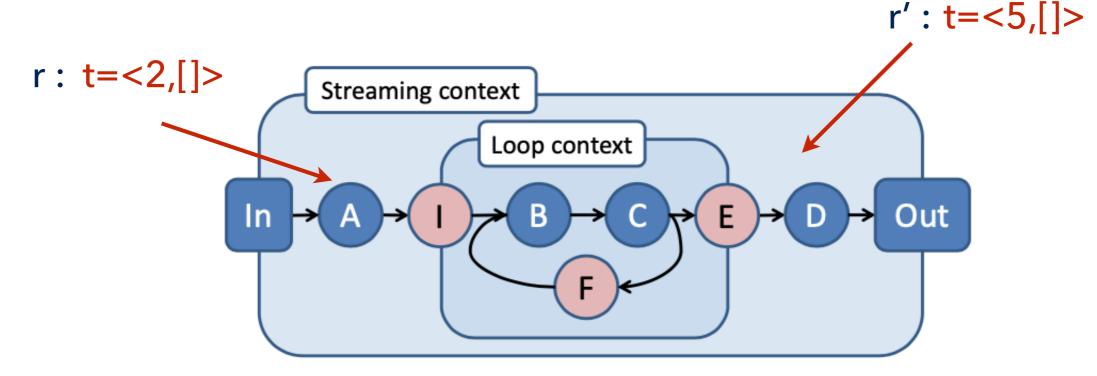
- Functions that describe what should happen to an active event if it goes through a path in the dataflow graph
- Path summary for the path $A \rightarrow B \rightarrow C \rightarrow B \rightarrow C \rightarrow D$: IFE
- For two pointsamps $p=(t,\ell)$ and $p'=(t',\ell')$:

p "could result in" p' iff $PS[\ell,\ell'](t) \le t$



Path Summaries

- PS for the path A \rightarrow B \rightarrow C \rightarrow B \rightarrow C \rightarrow D: IFE
 - Record r generated by A $\rightarrow p = (<2,[]>,A)$
 - Record r' generated by D $\rightarrow p' = (<5,[]>,D)$
 - PS[A,D](2) = 2 < 5 (p "can result in" p')



Fault-tolerance

- Synchronous checkpoints: Stop execution → take checkpoint → resume
 - User observes latency spikes at steady state
 - If failure happens, system "rolls back" to the last checkpoint
- Alternative approach would be to log all events to disk before sending them - Write-ahead logging
 - Much higher latency per-record expensive I/Os
- Lineage-based fault-tolerance (Spark) difficult to implement in Naiad
 - Need to keep track of lineage information per record too many dependencies to maintain

References

- Lineage Stash: https://cs-people.bu.edu/liagos/material/sosp19.pdf
 - Lineage-based fault-tolerance for record-at-a-time execution
- Timely Dataflow: https://github.com/TimelyDataflow/timely-dataflow
 - Rust prototype of Naiad
- Differentias | Dataflow: https://github.com/TimelyDataflow/differential-dataflow
 - Incremental computation on Timely Dataflow
- Materialize Inc: https://materialize.io
 - Streaming Data Warehouse on Timely/Differential Dataflow