

```
import spidev

import time

import threading

import RPi.GPIO as GPIO

import paho.mqtt.client as mqtt

import logging


# ---Logging Setup---#

logging.basicConfig(level=logging.DEBUG, format='%(asctime)s - %(levelname)s - %(message)s')


# ---MQTT Setup---#

MQTT_BROKER = "iot.kmitlnext.com"

MQTT_PORT = 9001

MQTT_TOPIC_R2 = "phon/log"

MQTT_TOPIC_LDR = "phon/ldr"

MQTT_TOPIC_DIM = "phon/dim"

MQTT_TOPIC_CONTROL = "led/control"

MQTT_USERNAME = "kmitliot"

MQTT_PASSWORD = "KMITL@iot1234"


client = mqtt.Client(transport="websockets")

client.username_pw_set(MQTT_USERNAME, MQTT_PASSWORD)


# ---SPI Setup---#

spi = spidev.SpiDev()

spi.open(0, 0)
```

```
spi.max_speed_hz = 1000000
```

```
# ---GPIO Setup---#
```

```
GPIO.setmode(GPIO.BCM)
```

```
GREEN_LED = 17
```

```
RED_LED = 18
```

```
GPIO.setup(GREEN_LED, GPIO.OUT)
```

```
GPIO.setup(RED_LED, GPIO.OUT)
```

```
# Initialize PWM for Red LED
```

```
pwm = GPIO.PWM(RED_LED, 1000)
```

```
pwm.start(0)
```

```
# ---Global Variables---#
```

```
previous_r2 = None
```

```
previous_green_led = None
```

```
previous_duty_cycle = None
```

```
# ---Helper Functions---#
```

```
def read_spi(channel):
```

```
    raw = spi.xfer2([1, (channel << 4) | 0x80, 0])
```

```
    return ((raw[1] & 3) << 8) | raw[2]
```

```
def calculate_voltage(adc_value, v_ref=3.3, resolution=1024):
```

```
    return (adc_value / resolution) * v_ref
```

```
# ---MQTT Handlers---#
```

```
def on_connect(client, userdata, flags, rc):
```

```
    logging.debug(f"Connected to MQTT broker with result code {rc}")
```

```
    client.subscribe(MQTT_TOPIC_CONTROL)
```

```
def on_message(client, userdata, msg):
```

```
    try:
```

```
        message = msg.payload.decode()
```

```
        logging.debug(f"Received message on {msg.topic}: {message}")
```

```
        if msg.topic == MQTT_TOPIC_CONTROL:
```

```
            if message.lower() == "green_on":
```

```
                GPIO.output(GREEN_LED, 1)
```

```
                logging.debug("Green LED turned ON via MQTT")
```

```
            elif message.lower() == "green_off":
```

```
                GPIO.output(GREEN_LED, 0)
```

```
                logging.debug("Green LED turned OFF via MQTT")
```

```
            elif message.startswith("dim:"):

```

```
                try:
```

```
                    brightness = float(message.split(":")[1])
```

```
                    pwm.ChangeDutyCycle(brightness)
```

```
                    logging.debug(f"Red LED brightness set to {brightness}% via MQTT")
```

```
            except ValueError:
```

```
                logging.error("Invalid brightness value received in MQTT message")
```

```
except Exception as e:
```

```
    logging.error(f"Error processing MQTT message: {e}")
```

```

def mqtt_loop():

    client.on_connect = on_connect

    client.on_message = on_message

    client.connect(MQTT_BROKER, MQTT_PORT)

    client.loop_forever()


# ---Thread Functions---#


# In the lab_1_r2 function

def lab_1_r2():

    global previous_r2

    ch = 0

    while True:

        adc_value = read_spi(ch)

        voltage = calculate_voltage(adc_value)

        resistance = ((voltage * 1000) / (3.3 - voltage)) * 10 # R2 = (Vout * R1) / (Vin - Vout)

        current = voltage / resistance


        # Log the details

        logging.debug(f"Voltage: {voltage:.2f} V | Resistance: {resistance:.2f} Ohm | Current: {current}
mA")


        client.publish(MQTT_TOPIC_R2, f"Resistance: {resistance:.2f} Ohm")


        previous_r2 = resistance

```

```
# Check if the resistance has changed by more than 1k $\Omega$  or if it is the first reading
```

```
if previous_r2 is None or abs(resistance - previous_r2) > 1000:
```

```
    logging.debug(f"Resistance change detected: {resistance:.2f} Ohm")
```

```
# Publish new resistance value when it changes by more than 1k $\Omega$ 
```

```
client.publish(MQTT_TOPIC_R2, f"Resistance: {resistance:.2f} Ohm")
```

```
previous_r2 = resistance
```

```
# Sleep before next reading
```

```
time.sleep(2)
```

```
def lab_2_ldr():
```

```
    global previous_green_led
```

```
    ch_ldr = 1
```

```
    while True:
```

```
        adc_value = read_spi(ch_ldr)
```

```
        voltage = calculate_voltage(adc_value)
```

```
        led_status = 1 if voltage > 2 else 0
```

```
        GPIO.output(GREEN_LED, led_status)
```

```
    if previous_green_led is None or previous_green_led != led_status:
```

```
        status = "ON" if led_status else "OFF"
```

```
        logging.debug(f"Green LED status changed to {status}")
```

```
# Publish the LED status change (ON/OFF)
```

```
client.publish(MQTT_TOPIC_LDR, f"{status}")
```

```
previous_green_led = led_status
```

```
time.sleep(2)
```

```
def lab_3_potentiometer():
```

```
    global previous_duty_cycle
```

```
    ch_pot = 2
```

```
    while True:
```

```
        adc_value = read_spi(ch_pot)
```

```
        voltage = calculate_voltage(adc_value)
```

```
        duty_cycle = (adc_value / 1023) * 100
```

```
        pwm.ChangeDutyCycle(duty_cycle)
```

```
        logging.debug(f"Potentiometer: Voltage = {voltage:.2f} V | Duty Cycle = {duty_cycle:.2f}%")
```

```
        if previous_duty_cycle is None or abs(duty_cycle - previous_duty_cycle) > 1:
```

```
            logging.debug(f"Red LED brightness change detected: {duty_cycle:.2f}%")
```

```
            # Publish new brightness value when it changes by more than 1%
```

```
            client.publish(MQTT_TOPIC_DIM, f"Red LED Brightness: {duty_cycle:.2f}%")
```

```
            previous_duty_cycle = duty_cycle
```

```
    time.sleep(1)
```

```
# ---Main Function---#
```

```
if __name__ == '__main__':
```

```
    try:
```

```
        # Start MQTT in a separate thread
```

```
        thread_mqtt = threading.Thread(target=mqtt_loop, daemon=True)
```

```
thread_mqtt.start()
```

```
# Create and start other threads
```

```
thread_lab1 = threading.Thread(target=lab_1_r2, daemon=True)
```

```
thread_lab2 = threading.Thread(target=lab_2_ldr, daemon=True)
```

```
thread_lab3 = threading.Thread(target=lab_3_potentiometer, daemon=True)
```

```
thread_lab1.start()
```

```
thread_lab2.start()
```

```
thread_lab3.start()
```

```
# Keep the main program running
```

```
while True:
```

```
    time.sleep(0.1)
```

```
except KeyboardInterrupt:
```

```
    spi.close()
```

```
    pwm.stop()
```

```
    GPIO.cleanup()
```

```
    client.disconnect()
```

```
    logging.info("SPI closed, MQTT disconnected, and GPIO cleaned up. Exiting...")
```