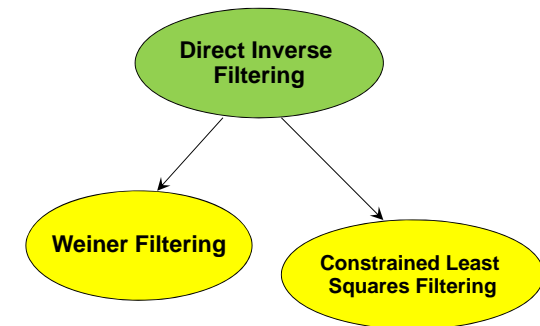


# Image Processing

## Image Restoration (Part II)

Pattern Recognition and Image Processing Laboratory (Since 2012)

## Approaches for Image Restoration



Note: - These approaches are **linear image restoration**.  
- PSF (Point Spread Function) is available.

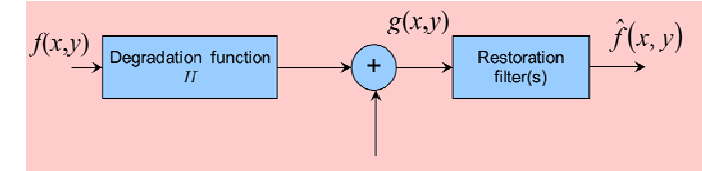
## Approaches for Image Restoration

Lucy-Richardson Algorithm

Blind Deconvolution

Note: - These approaches are **nonlinear image restoration**.  
- PSF is **NOT** available.

## Direct Invert Filtering



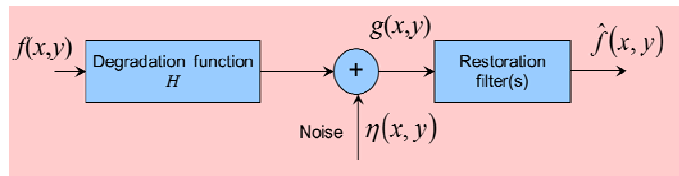
Degradation Eq

$$G(u,v) = H(u,v)F(u,v)$$

$$\hat{F}(u,v) = \frac{G(u,v)}{H(u,v)}$$

Restoration Eq

## Direct Invert Filtering



Degradation Eq

$$G(u, v) = H(u, v)F(u, v) + N(u, v)$$

$$\hat{F}(u, v) = F(u, v) + \frac{N(u, v)}{H(u, v)}$$

Restoration Eq

## Wiener Filtering

$$\hat{F}(u, v) = \left[ \frac{1}{H(u, v)} \frac{|H(u, v)|^2}{|H(u, v)|^2 + S_\eta(u, v)/S_f(u, v)} \right] G(u, v)$$

$$\hat{F}(u, v) = \frac{G(u, v)}{H(u, v)}$$

Direct Inverse Filtering

## Wiener Filtering

```
>> fr = deconwnr(g, PSF) % Direct Inverse Filter
>> fr = deconwnr(g, PSF, NSPR) % Parametric Weiner Filter
>> fr = deconwnr(g, PSF, NACORR, FACORR) % Weiner Filter with
                                         % Autocorrelation
```

```
>> degrad5_5 % See demonstration
```

## Constrained Least Squares Filtering

$$\hat{F}(u, v) = \left[ \frac{H^*(u, v)}{|H(u, v)|^2 + \gamma |P(u, v)|^2} \right] G(u, v)$$

$$\hat{F}(u, v) = \frac{G(u, v)}{H(u, v)}$$

Direct Inverse Filtering



## Iterative Nonlinear Restoration Using the Lucy-Richardson Algorithm

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>> degrad5\_9 % See demonstration



## Blind Deconvolution

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One of the most difficult problems in image restoration is obtaining a suitable estimation of the PSF to use in restoration algorithm.



## Blind Deconvolution

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Image restoration methods that are **NOT** based on specific knowledge of the PSF are called “blind deconvolution” algorithm.



## Blind Deconvolution

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>> degrad5\_10 % See demonstration

