## 1 Euler-Lagrange Equations for UWT Fluid Dynamics Lagrangian

The Lagrangian for UWT's scalar-driven fluid dynamics is:

$$L = \frac{1}{2}\rho(u_r^2 + u_\theta^2 + u_z^2) + \frac{1}{2}(\partial_t \Phi_1)^2 + \frac{1}{2}(\partial_t \Phi_2)^2 - \left[\lambda(|\Phi_1 \Phi_2| - v^2)^2 + k_U(2\Phi_1^2 + \Phi_1 \Phi_2 + 2\Phi_2^2) + g_m|\Phi_1 \Phi_2|\rho + g_{\text{wave}}\varepsilon|\Phi_1 \Phi_2|^2 R + k_{\text{damp}}(\Phi_1^2 + \Phi_2^2) + \nu|\nabla \mathbf{u}|^2 + \lambda_R(|\Phi_1 - \Phi_{1,\text{prev}}|^2 + |\Phi_2 - \Phi_{2,\text{prev}}|^2)\right]$$
(1)

Parameters:  $\rho = 1000 \,\mathrm{kg/m^3}$ ,  $\lambda = 1$ ,  $v = 0.226/6.242 \times 10^{18} \,\mathrm{kg}$ ,  $k_U = 2 \times 10^8 \,\mathrm{kg^{-1}m^3s^{-2}}$ ,  $g_m = 0.01$ ,  $g_{\mathrm{wave}} = 19.5$ ,  $\varepsilon = 10^{-30} \,\mathrm{m^2}$ ,  $k_{\mathrm{damp}} = 0.001 \,\mathrm{s^{-1}}$ ,  $\nu = 10^{-5} \,\mathrm{m^2/s}$ ,  $\lambda_R = 10^{-6}$ ,  $R \approx 1/r^2 \,\mathrm{m^{-2}}$ .

## 1.1 For Scalar Field $\Phi_1$

$$\frac{\partial^2 \Phi_1}{\partial t^2} = \lambda \left[ 2|\Phi_1 \Phi_2| \left( \Phi_2 \partial_t \Phi_1 + \Phi_1 \partial_t \Phi_2 \right) - 4v^2 \Phi_1 \Phi_2 \right] + k_U (4\Phi_1 + \Phi_2) 
+ g_m \Phi_2 \rho + g_{\text{wave}} \varepsilon 2|\Phi_1 \Phi_2| \Phi_2 R - k_{\text{damp}} \Phi_1 + \nu \nabla^2 \Phi_1 + 2\lambda_R (\Phi_1 - \Phi_{1,\text{prev}}) \quad (2)$$

## 1.2 For Scalar Field $\Phi_2$

$$\frac{\partial^2 \Phi_2}{\partial t^2} = \lambda \left[ 2|\Phi_1 \Phi_2| \left( \Phi_2 \partial_t \Phi_1 + \Phi_1 \partial_t \Phi_2 \right) - 4v^2 \Phi_1 \Phi_2 \right] + k_U (\Phi_1 + 4\Phi_2) 
+ g_m \Phi_1 \rho + g_{\text{wave}} \varepsilon 2|\Phi_1 \Phi_2| \Phi_1 R - k_{\text{damp}} \Phi_2 + \nu \nabla^2 \Phi_2 + 2\lambda_R (\Phi_2 - \Phi_{2,\text{prev}}) \quad (3)$$

## 1.3 For Velocity Field $\mathbf{u} = (u_r, u_\theta, u_z)$

$$\rho \frac{\partial \mathbf{u}}{\partial t} = -\nabla p + \nu \nabla^2 \mathbf{u} - g_m |\Phi_1 \Phi_2| \nabla \rho \tag{4}$$

Incompressibility constraint:  $\nabla \cdot \mathbf{u} = 0$ .