

Introduction to Logical Foundations

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0.1 Judgment

Analytic judgments are those that become evident by conceptual analysis.

$$\frac{J_1 \quad \dots \quad J_n}{J_c}$$

1. **Syntax:** well-formed

E.g.

$$\frac{}{T \text{ wf}} \quad \frac{A \text{ wf} \quad B \text{ wf}}{A \circ B \text{ wf}}$$

2. **Semantics:** true

1. **I:** *introduce* a connective
2. **E:** *extract* info out of a pure connective

E.g.

$$\frac{A \quad B}{A \wedge B} \wedge I \quad \frac{A \wedge B}{A} \wedge E_1$$

0.2 Hypothetical Reasoning

Given P, Q holds.

1. $\Rightarrow I$: Internalizing a reasoning process.

E.g.

$$\frac{\frac{P_1 \quad P_2}{\dots} \quad Q}{P_1, P_2 \Rightarrow Q}$$

Note that P s and Q s cease to exist in the conclusion, thus “internalized”.

1. $\Rightarrow E$: modus ponens

0.3 Properties of assumptions (structural)

Weakening: assumptions can be unused

$$\frac{\frac{\frac{A}{\text{---}u} \quad (\text{unused}) \quad \frac{B}{\text{---}w}}{B \Rightarrow A} \Rightarrow I^w}{A \Rightarrow B \Rightarrow A} \Rightarrow I^u$$

Contraction: assumptions can be used multiple times

Substitution: TODO

0.4 Context

Notice the two dimensional rule of $\Rightarrow I$:

$$\frac{\frac{P_1 \quad P_2}{\dots} \quad Q}{P_1, P_2 \Rightarrow Q}$$

It's kind of awkward to keep this hypothetical structure around. Instead, we write

$$\frac{\Gamma, h_1 : P_1, h_2 : P_2 \vdash Q}{\Gamma \vdash P_1, P_2 \Rightarrow Q}$$

Note that we declare

$$\frac{x : A \in \Gamma}{\Gamma \vdash A} x$$

By following the same principle, we can rewrite **Weakening** and **Contraction**.

Weakening:

$$\frac{\Gamma \vdash B}{\Gamma, x : A \vdash B}$$

Contraction:

$$\frac{\Gamma, x : A \vdash B}{\Gamma, x : A, y : A \vdash B}$$

Substitution:

$$\frac{\Gamma, x : A \vdash C \quad \Gamma \vdash A}{\Gamma \vdash C}$$

0.5 Local Soundness/Completeness

Local in the sense that these properties only discuss a **single connective**, not the whole system. It's a weak witness that this system makes sense.

1. **Local Soundness**: the combination of intro and elim is not too strong, i.e. they don't allow us to infer more than what's already known.

E.g. the proof

$$\frac{\frac{\Gamma \vdash A \quad \Gamma \vdash B}{\Gamma \vdash A \times B} \times I}{\Gamma \vdash A} \times E_1$$

collapses to

$$\frac{\Gamma \vdash A}{\Gamma \vdash A}$$

so there's no additional information provided by the intro and elim rules.

2. **Local Completeness**: the combination of intro and elim is sufficiently strong, in terms of rebuilding the info we have.

E.g. there's no information loss in the rebuild process of the connective $A \times B$

$$\frac{\frac{\Gamma \vdash A \times B}{\Gamma \vdash A} \times E_1 \quad \frac{\Gamma \vdash A \times B}{\Gamma \vdash B} \times E_2}{\Gamma \vdash A \times B} \times I$$

0.6 C.H.

- Propositions - Types
- Proof - Programs
- Nat. Ded. - λ -calculus

Importance:

1. Guiding program language design
2. Basis of Type Theory
3. Proving logic consistency by looking at programs

0.6.1 Typing Judgment

$$\boxed{\Gamma \vdash M : A}$$

Given some assumptions in the context Γ ,

- M is a proof term corresponding to the proposition A .
- M is a program that has a type A .

C.H.: $\Gamma \vdash A$ iff $\Gamma \vdash M : A$

Example: conjunction

$$\frac{\Gamma \vdash M : A \quad \Gamma \vdash N : B}{\Gamma \vdash \langle M, N \rangle : A \wedge B} \wedge I \quad \frac{\Gamma \vdash M : A \wedge B}{\Gamma \vdash M.1 : A} \quad \frac{\Gamma \vdash M : A \wedge B}{\Gamma \vdash M.2 : B}$$

Example: implication

$$\frac{\Gamma, x : A \vdash \lambda x : A. M : B}{\Gamma \vdash M : A \rightarrow B} \Rightarrow I^x \quad \frac{\Gamma \vdash M : A \rightarrow B \quad \Gamma \vdash N : A}{\Gamma \vdash MN : B} \Rightarrow E$$

Thm (Local Soundness)

$$\frac{\Gamma \vdash M : A \quad \Gamma \vdash N : B}{\Gamma \vdash \langle M, N \rangle : A \wedge B}$$

$$\frac{\Gamma \vdash \langle M, N \rangle : A \wedge B}{\Gamma \vdash \langle M, N \rangle.1 : A} \text{ collapses to } \Gamma \vdash M : A$$

$$\frac{\Gamma, x : A \vdash M : B}{\Gamma \vdash \lambda x : A. M : A \rightarrow B} \Rightarrow I^x$$

$$\frac{\Gamma \vdash \lambda x : A. M : A \rightarrow B \quad \Gamma \vdash N : A}{\Gamma \vdash (\lambda x : A. M)N : B} \Rightarrow E \text{ collapses to } \Gamma \vdash M[N/x] : B$$

1. **Logic:** not gaining any information through this intro and elim detour.
2. **Program:** type is **preserved** through this detour.

The “collapse” can then be written as:

Reduction $\langle M, N \rangle.1 \Rightarrow M$ and $(\lambda x : A. M)N \Rightarrow M[N/x]$.

Thm (Subject Reduction)

If $\Gamma \vdash M : A$ and $M \Rightarrow M'$, then $\Gamma \vdash M' : A$

Thm (Local Completeness)

$$\frac{\Gamma \vdash M : A \wedge B \text{ expands to } \frac{\Gamma \vdash M.1 : A \quad \Gamma \vdash M.2 : B}{\Gamma \vdash \langle M.1, M.2 \rangle : A \wedge B} \wedge I}{\Gamma \vdash M : A \wedge B} \wedge E_1 \quad \frac{\Gamma \vdash M : A \wedge B}{\Gamma \vdash M.1 : A} \wedge E_2$$

$$\frac{\Gamma \vdash M : A \rightarrow B \text{ } (\eta)\text{-expands to } \frac{\Gamma, x : A \vdash Mx : B}{\Gamma \vdash \lambda x : A. Mx : A \rightarrow B} \Rightarrow I^x}{\Gamma \vdash M : A \rightarrow B} \Rightarrow E$$

This **exhibits the actual structure** (i.e. **expands its internal term/proof structure**) of M while preserving the type.

Insight:

- Proof Reduction - Program Reduction
- Normalizing Proofs - Normalizing Programs

Compare both proofs

TODO fill in the blanks

$$\vdash \lambda x : A \wedge A. (\lambda y : A. y)x.2 : A \wedge A \rightarrow A$$

0.7 Disjunction

Let's now expand the previous example to disjunction.

0.7.1 Rules

$$\begin{array}{c}
 \frac{\Gamma \vdash M : A}{\Gamma \vdash \iota_1 M : A \vee B} \vee I_1 \\
 \\
 \frac{\Gamma \vdash M : B}{\Gamma \vdash \iota_2 M : A \vee B} \vee I_2 \quad \frac{\Gamma \vdash M : A \vee B \quad \Gamma, x : A \vdash N_1 : C \quad \Gamma, x : B \vdash N_2 : C}{\Gamma \vdash \text{cases } M \text{ of } \iota_1 x \Rightarrow N_1 \mid \iota_2 x \Rightarrow N_2 : C} \vee E
 \end{array}$$

0.8 Local Soundness

TODO Fill in the blanks

$\Gamma \vdash \text{case}$

1 Modal Logic S4

Truth is living in the moment - here and now.

Validity is living forever and everywhere.

— Brigitte Pientka

“The world is full of possibilities, but not today.”

1.1 Necessity Modality $\Box A$

> Note what I originally wrote as $\Gamma \vdash A$ is now $\Gamma \vdash A$ true to make a clear distinction between **validity** and **true**.

1.1.1 Validity

- If $\varepsilon \vdash A$ true then A valid
- If A valid then $\Gamma \vdash A$ true

Notice how the second rule allows weakening while the first rule does not. This means that **validity does not depend on any local assumptions**.

1.1.2 Judgment

$\Delta; \Gamma \vdash A$ true

- Δ - the **global** context. It contains valid assumptions that holds **forever**.
- Γ - the **local** context. It contains assumptions that hold **here and now**.

So, the definition of validity can be written as:

$$\frac{y : A \text{ true} \in \Gamma}{\Delta; \Gamma \vdash A \text{ true}} \quad \frac{x : A \text{ valid} \in \Delta}{\Delta; \Gamma \vdash A \text{ true}}$$

Now we start to introduce the modality \Box :

$$\frac{\Delta; \cdot \vdash A \text{ true}}{\Delta; \Gamma \vdash \Box A \text{ true}} \Box I$$

Just as \rightarrow is internalizing reasoning on implication, \Box is internalizing reasoning on validity.

T law (*reflexivity*).

$$\frac{\vdash; x : \Box A \vdash A \text{ true}}{\vdash; \cdot \vdash \Box A \rightarrow A \text{ true}} \rightarrow I^x$$

i.e. If it's true everywhere and forever, then it's also true here and now.

A detour

One may be tempted to define \Box_E as such

$$\frac{\Delta; \Gamma \vdash \Box A}{\Delta; \Gamma \vdash A}$$

Let's see if it's locally complete as a sanity check.

$$\overline{\Delta; \Gamma \vdash \Box A \text{ true}}$$

should be able to expand to

$$\frac{\overline{\Delta; \Gamma \vdash \Box A \text{ true}}}{\overline{\Delta; \cdot \vdash A \text{ true}}} \text{ ???} \quad \frac{\overline{\Delta; \cdot \vdash A \text{ true}}}{\Delta; \Gamma \vdash \Box A \text{ true}} \Box I$$

Boom!

The correct solution

A let-style definition!

$$\frac{\Delta; \Gamma \vdash \Box A \text{ true} \quad \Delta, u : A \text{ valid}; \Gamma \vdash C \text{ true}}{\Delta; \Gamma \vdash C \text{ true}} \Box E \quad \frac{\Delta; \cdot \vdash A \text{ true}}{\Delta; \Gamma \vdash \Box A \text{ true}} \Box I$$

Let's see if it's locally sound.

$$\frac{\overline{\Delta; \cdot \vdash A \text{ true}}}{\Delta; \Gamma \vdash \Box A \text{ true}} \Box I \quad \frac{\overline{\Delta; \cdot \vdash A \text{ true}} \quad \Delta, u : A \text{ valid}; \Gamma \vdash C \text{ true}}{\Delta; \Gamma \vdash C \text{ true}} \Box E^u$$

($\Delta; \cdot \vdash A \text{ true}$ goes to $\Delta, u : A \text{ valid}; \Gamma \vdash C \text{ true}$ via *modal substitution*)

collapses to

$$\Delta; \Gamma \vdash C \text{ true}$$

Lemma.

1. (*Substitution*) If $\Delta; \Gamma, x : A \text{ true} \vdash C \text{ true}$ and $\Delta; \Gamma \vdash A \text{ true}$, then $\Delta; \Gamma \vdash C \text{ true}$.
2. (*Modal Substitution*) If $\Delta, y : A \text{ valid}; \Gamma \vdash C \text{ true}$ and $\Delta; \cdot \vdash A \text{ true}$, then $\Delta; \Gamma \vdash C \text{ true}$.

Thm (T). \Box satisfies *reflexivity*.

–

Thm (*Distributivity*). \Box satisfies *distributivity*.

$$\Box(A \rightarrow B) \rightarrow \Box A \rightarrow \Box B$$

Thm (4). \Box satisfies *transitivity*.

$$\Box A \rightarrow \Box \Box A$$

To introduce a \Box , one may attempt to use \Box_I , but this would leave us with an empty Γ which is not good. So, we need to first preserve x forever, which leads us to the use of \Box_E - saving it to Δ .

NOTE We usually put something to eternality via \Box_E rule. Note that we are gaining information via \Box_E while we give up information via \Box_I .

$$\frac{\frac{\frac{}{u : A \text{ valid}; \cdot \vdash A \text{ true}}{u : A \text{ valid}; \cdot \vdash \Box A \text{ true}} \Box_I}{\cdot; x : \Box A \text{ true} \vdash \Box A \text{ true}} \Box_I \quad \frac{}{u : A \text{ valid}; x : \Box A \text{ true} \vdash \Box \Box A \text{ true}} \Box_E^u}{\cdot; x : \Box A \text{ true} \vdash \Box \Box A \text{ true} \rightarrow I^x} \rightarrow I^x$$

$$\frac{}{\cdot; \cdot \vdash \Box A \rightarrow \Box \Box A \text{ true}}$$

1.2 Syntax

Terms $M \mid \lambda x : A. M \mid M N \mid \langle M, N \rangle \mid M.1 \mid M.2 \mid u \mid \text{box } M$

NOTE u for valid assumptions.

Now let's add proof terms to logic rules.

$$\frac{\Delta; \cdot \vdash M : A \text{ true}}{\Delta; \Gamma \vdash \text{box } M : \Box A \text{ true}} \Box_I \quad (M \text{ is a closed term w.r.t. local (runtime) assumptions})$$

$$\frac{\Delta; \Gamma \vdash M : \Box A \text{ true} \quad \Delta, u : A \text{ valid}; \Gamma \vdash N : C \text{ true}}{\Delta; \Gamma \vdash \text{let box } u := M \text{ in } N : C \text{ true}} \Box_E$$

$$\frac{x : A \text{ true} \in \Gamma}{\Delta; \Gamma \vdash x : A \text{ true}} \quad \frac{u : A \text{ valid} \in \Delta}{\Delta; \Gamma \vdash u : A \text{ true}}$$

And now we have

1. (Substitution) If $\Delta; \Gamma, x : A \text{ true} \vdash C \text{ true}$ and $\Delta; \Gamma \vdash A \text{ true}$, then $\Delta; \Gamma \vdash C \text{ true}$. e.g.

$$(\text{box } N)[M/x] = \text{box } N$$

2. (Modal Substitution) If $\Delta, u : A \text{ valid}; \Gamma \vdash C \text{ true}$ and $\Delta; \cdot \vdash A \text{ true}$, then $\Delta; \Gamma \vdash C \text{ true}$. e.g.

$$(\text{box } N)[[M/u]] = \text{box } (N[M/u])$$

Now let's try to rephrase *locally soundness*


$$\frac{\frac{\Delta; \cdot \vdash M : A \text{ true}}{\Delta; \Gamma \vdash \text{box } M : \Box A \text{ true}} \Box_I \quad \Delta, u : A \text{ valid}; \Gamma \vdash N : C \text{ true}}{\Delta; \Gamma \vdash \text{let box } u := \text{box } M \text{ in } N : C \text{ true}} \Box_E^u$$

collapses to

$$\Delta; \Gamma \vdash N[M/u] : C$$

1.3 Real Programming Example

```
1 nth: int -> (bool_vec -> bool)
```

 Haskell


This function does not do anything if you only pass it an integer. It just sits there, not producing anything meaningful.

How to avoid this situation and force it generate a real function?

```

1 nth: int -> □(bool_vec -> bool)
2 nth 0 = box (fun v -> hd v)
3 nth (S n) =
4   let box r = nth n in box (fun v -> r (tl v))

```

 Haskell


In this case, box makes sure the function generated does not depend on int.

Compare

```

1 nth 1
2 = fun v -> tl (nth 0 v)
3 = fun v -> tl (hd v)

```


 Haskell

with

```

1 nth 1
2 = let box r = nth 0 in box (fun v -> r (tl v))
3 = let box r = box (fun v -> hd v) in (fun v -> r (tl v))
4 = box (fun v -> (fun v0 -> hd v0) (tl v))

```

 Haskell

Notice how the returned function is not a closure over n .

However, if you compare these two functions you still find the latter one not satisfying cuz it's returning a redex and it's in a box so it get stuck.

Contextual types to the rescue!

1.4 Contextual types

Previously, we wrote $\Box A$ to mean A starts with an empty context, which is not sufficient in many cases. So instead, let's allow specifying a context Γ for A .

1.4.1 Examples

Cooking metaphor

1. Add eggs, flour, sugar
2. Add \Box (a liquid)

To type \Box , it's eggs, flour, sugar \Vdash liquid

Theorem prover

Holes in programs:

$\text{fun } x \rightarrow \Box +_{\text{int}} x$, you can see the hole here accepts an $x : \text{int} \Vdash \text{int}$

Or $\lambda x. \lambda y. \Box y. 2 : (A \rightarrow B \rightarrow C) \rightarrow (A \times B) \rightarrow C$, where the hole accepts an $x : A \rightarrow B \rightarrow C, y : A \times B \Vdash B \rightarrow C$

1.4.2 Syntax

| | |
|----------|--|
| Types | $A[?] \dots \mid \Box(\psi \Vdash A)$ |
| Terms | $M[?] \dots \mid \text{box } (\psi.M)$ |
| Contexts | $\Gamma, \psi[?] \dots$ |

E.g. $\text{box } (x : \text{int}. x + x) : \Box(x : \text{int} \Vdash \text{int})$

NOTE But how to keep this thing stable under renaming?

$$\begin{array}{c}
\frac{\Delta; \psi \vdash M : A \text{ true}}{\Delta; \Gamma \vdash \text{box } (\psi.M) : \Box(\psi \Vdash A) \text{ true}} \Box I \\
\\
\frac{\Delta; \Gamma \vdash M : \Box(\psi \Vdash A) \text{ true} \quad \Delta, u : A \text{ valid}; \Gamma \vdash N : C \text{ true}}{\Delta; \Gamma \vdash \text{let box } u := M \text{ in } N : C \text{ true}} \Box E \\
\\
\frac{x : A \text{ true} \in \Gamma}{\Delta; \Gamma \vdash x : A \text{ true}} \quad \frac{u : \psi \Vdash A \text{ valid} \in \Delta \quad \Delta, \Gamma \vdash \sigma : \psi}{\Delta; \Gamma \vdash \text{clo}(u, \sigma) : A \text{ true}}
\end{array}$$

Notes

- σ - substitution from ψ to Δ, Γ i.e.

$$\frac{\Delta; \Gamma \vdash \sigma : \psi \quad \Delta; \Gamma \vdash M : A}{\Delta; \Gamma \vdash (\sigma, M/x) : \psi, x : A}$$

- $\text{clo}(u, \sigma)$ - delayed substitution σ that can be applied once u is available.

NOTE Computation rules for `clo`

Recall how we have

$$(\text{box } N)[M/x] = \text{box } N$$

$$(\text{box } N)[[M/u]] = \text{box } (N[M/u])$$

Now also,

$$\text{clo}(u, \sigma)[[\psi.M/u]] = M[\sigma]$$

Beware that $M[\sigma]$ is a **local** substitution.

E.g.

$$\lambda x. \text{let box } u := x \text{ in box } (\lambda y. \lambda z. u \ y) : \Box(C \rightarrow A) \rightarrow \Box(C \rightarrow D \rightarrow A)$$


$$\lambda x. \text{let box } u := x \text{ in box } (y : C, z : D. \text{clo}(u, y/x')) : \Box(x' : C \Vdash A) \rightarrow \Box(y : C, z : D \Vdash A)$$

With this, we can revise our `nth` example

```

1 nth: int -> Box (bool_vec -> bool)
2 nth 0 = box (fun v -> hd v)
3 nth (S n) =
4   let box r =
5     nth n in box (fun v -> r (tl v))

```


 Haskell

into this

```

1 nth: int -> Box (v: bool_vec => int)
2 nth 0 = box (v: bool_vec. hd v)
3 nth (S n) =
4   let box u = nth n in
5     box (v: bool_vec. clo(u, (tl v)/v))

```


 Haskell

then we make

```

1 nth 1

```

 Haskell

```
2 = let box r = nth 0 in box (fun v -> r (tl v))
3 = let box r = box (fun v -> hd v) in (fun v -> r (tl v))
4 = box (fun v -> (fun v0 -> hd v0) (tl v))
```

into this

```
1 nth 1
2 = let box u = nth 0 in
3   box (v: bool_vec. clo(u, (tl v)/v))
4 = let box u = box (v: bool_vec. hd v) in
5   box (v: bool_vec. clo(u, (tl v)/v))
6 = box (v: bool_vec. clo(hd v0, (tl v)/v0))
7 = box (v: bool_vec. hd (tl v))
```

[Haskell](#)

Notice how the nested evaluation is eager.

TODO What's the difference between functions and `clo`?