

lecture 18: loss functions and regression

statistical inference tells us how to infer parameters from data

learning goals

- interpret loss functions
- solve a simple regression problem

common approach is through minimization of a loss function

$$\min_{\theta} L(\theta|x) \quad \text{parameters } \theta, \text{ data } x$$

example: linear regression

say we are measuring force on a spring vs. distance
relationship should be linear,

$$Y = -kX + b$$

↑ ↑
force stretch

if measurements were perfect we would only need a single point, but in reality there is noise

$$\min_k \sum_i |Y_i + kX_i|^2$$

"ordinary least squares" - OLS

find the spring constant by making multiple measurements and finding the best fit line

in this special case we can solve exactly

$$\hat{k} = \underbrace{(X^T X)^{-1} X^T Y}_{\text{OLS estimate of } k} \quad (\text{general form valid if measuring multiple variables})$$

regularization

what if our data is very noisy, so that we don't have too much confidence in small # of measurements?

we can regularize to control the estimate how could we do this?

example: add parameter estimates to the loss function

$$\min_k \sum_i |Y_i + kX_i|^2 + \lambda k^2$$

Tikhonov or L_2 regularization

$$\rightarrow \text{solution is } \hat{k} = (X^T X + \lambda I)^{-1} X^T Y$$

note scaling, as # measurements $\rightarrow \infty$
effect of regularization vanishes

* notebook example