

$$H.1] \quad D_H = D_T + D_V, \quad \dot{z} = \{z, H\}, \quad H = T(p) + V(q), \quad z = \begin{pmatrix} q \\ p \end{pmatrix}$$

$$D_T z = \{z, T\}, \quad D_V z = \{z, V\} = \sum_i \left(\frac{\partial z}{\partial q_i} \frac{\partial V}{\partial p_i} - \frac{\partial z}{\partial p_i} \frac{\partial V}{\partial q_i} \right)$$

$$= + \sum_i \frac{\partial z}{\partial q_i} \frac{\partial T}{\partial p_i} \quad \quad \quad = - \sum_i \frac{\partial z}{\partial p_i} \frac{\partial V}{\partial q_i}$$

$$a) \quad D_T^2 z = D_T \{z, T\} = \{ \{z, T\}, T \}$$

$$= \sum_i \frac{\partial \{z, T\}}{\partial q_i} \frac{\partial T}{\partial p_i}$$

$$= \sum_i \frac{\partial}{\partial q_i} \left(\sum_j \frac{\partial z}{\partial q_j} \frac{\partial T}{\partial p_j} \right) \frac{\partial T}{\partial p_i}$$

$$= \sum_{ij} \left(\frac{\partial^2 z}{\partial q_i \partial q_j} \frac{\partial T}{\partial p_j} + 0 \right) \frac{\partial T}{\partial p_i} = 0$$

\uparrow
 $= 0$ SINCE q_i 's ARE CANONICAL

$$D_V^2 z = \{ \{z, V\}, V \}$$

$$= - \sum_i \frac{\partial}{\partial p_i} \left(\sum_j \frac{\partial z}{\partial p_j} \frac{\partial V}{\partial q_j} \right) \frac{\partial V}{\partial q_i}$$

$$= \sum_{ij} \left(\frac{\partial^2 z}{\partial p_i \partial p_j} \frac{\partial V}{\partial q_j} + 0 \right) \frac{\partial V}{\partial q_i} = 0$$

\uparrow
 $= 0$

$$b) \quad T = \frac{p^2}{2m} \Rightarrow D_T z = \sum_i \frac{\partial z}{\partial q_i} \frac{p_i}{m}$$

$$[D_V, D_T] z = \{ D_T z, V \} - \{ D_V z, T \} =$$

$$[D_V, [D_V, D_T]] z = D_V^2 D_T z - \cancel{D_V D_T D_V z} - \cancel{D_V D_T D_V z} + D_T \underbrace{D_V^2 z}_{=0}$$

$$= D_V^2 D_T z - 2 D_V D_T D_V z$$

$$[D_V, D_V, [D_V, D_T]] z = D_V^3 D_T z - 2 D_V^2 D_T D_V z - D_V^2 D_T D_V z + \underbrace{2 D_V D_T D_V^2 z}_{=0}$$

$$= D_V^3 D_T z - 3 D_V^2 D_T D_V z$$

$$D_V D_T z = - \sum_{ij} \frac{\partial z}{\partial q_j} \frac{\partial^2 T}{\partial q_i \partial p_j} \frac{\partial V}{\partial q_i}$$

$$= \delta_{ij} \frac{1}{m}$$

$$\sum_{ij} \frac{\partial z}{\partial q_j} \left(- \frac{\partial z}{\partial p_j} \frac{\partial V}{\partial q_i} \right) \frac{\partial T}{\partial p_i} = \sum_{ij} \frac{\partial z}{\partial p_j} \frac{\partial^2 V}{\partial q_i \partial q_j} \frac{\partial T}{\partial p_i}$$

$$= \frac{p_i}{m}$$

$$\begin{aligned}
 D_V^3 D_T z &= \left\{ \left\{ - \sum_i \frac{1}{m} \frac{\partial z}{\partial q_i} \frac{\partial V}{\partial q_i}, V \right\}, V \right\} \\
 &= - \sum_j \frac{\partial}{\partial p_j} \left\{ - \sum_i \frac{1}{m} \frac{\partial V}{\partial q_i}, V \right\} \frac{\partial V}{\partial q_j} \\
 &= \sum_{ik} \frac{\partial}{\partial p_k} \left(\frac{1}{m} \frac{\partial V}{\partial q_i} \right) \frac{\partial V}{\partial q_k} \\
 &= - \sum_{ijk} \frac{\partial}{\partial p_j} \left(\frac{\partial}{\partial p_k} \left(\frac{1}{m} \frac{\partial V}{\partial q_i} \right) \frac{\partial V}{\partial q_k} \right) \frac{\partial V}{\partial q_j} \\
 &= - \sum_{ijk} \frac{\partial}{\partial p_j} \frac{1}{m} (0 + 0) \frac{\partial V}{\partial q_j} = 0
 \end{aligned}$$

$$\begin{aligned}
 D_V^2 D_T D_V z &= \left\{ \left\{ - \sum_{ij} \frac{\partial z}{\partial p_j} \frac{\partial^2 V}{\partial q_i \partial q_j} \frac{p_i}{m}, V \right\}, V \right\} \\
 &= - \sum_k \frac{\partial}{\partial p_k} \left\{ - \sum_{ij} \frac{\partial z}{\partial p_j} \frac{\partial^2 V}{\partial q_i \partial q_j} \frac{p_i}{m}, V \right\} \frac{\partial V}{\partial q_k} \\
 &= \sum_{ijk} \frac{\partial}{\partial p_k} \left(\frac{\partial^2 V}{\partial q_i \partial q_j} \frac{p_i}{m} \right) \frac{\partial V}{\partial q_k} \\
 &= \sum_{ijk} \frac{\partial}{\partial p_k} \left(\frac{\partial^2 V}{\partial q_i \partial q_j} \frac{1}{m} \delta_{il} \right) \frac{\partial V}{\partial q_k} \\
 &= - \sum_k \frac{\partial}{\partial p_k} \left(\sum_{ij} \frac{\partial^2 V}{\partial q_i \partial q_j} \frac{1}{m} \frac{\partial V}{\partial q_i} \right) \frac{\partial V}{\partial q_k} \\
 &= - \sum_{ijk} \left(\frac{\partial^2 V}{\partial q_i \partial q_j} \frac{1}{m} \cdot 0 + 0 \right) \frac{\partial V}{\partial q_j} = 0
 \end{aligned}$$

$$\Rightarrow [D_V, [D_V, [D_V, D_T]]] = 0$$