

GIMONS DEVELOPER WORKS / RaSCSI

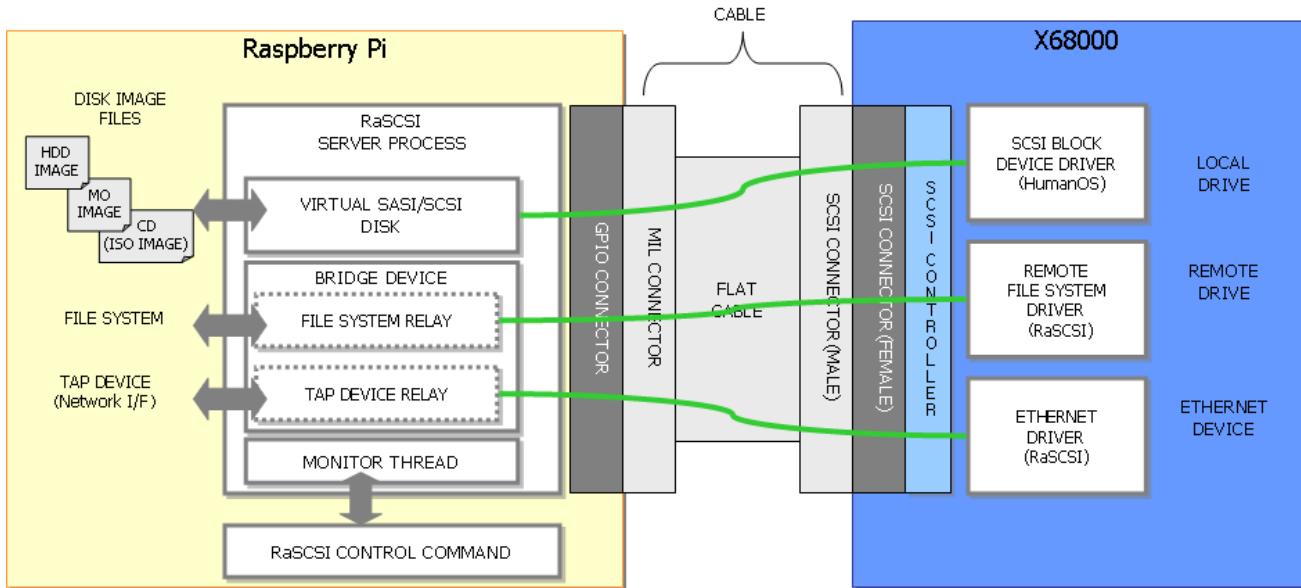
Last Updated: April 26, 2018

SCSI device emulator RaSCSI

-Raspberry pi As a SCSI target device emulator for X68000-

Introduction

RaSCSI is a type of emulator that virtually reproduces SCSI devices (hard disk, MO, CD-ROM) that have been converted into past relics. It was developed using SCSI control of XM6 Type G. By introducing it to Raspberry Pi (hereinafter referred to as RPI), RPI behaves like a SCSI device. Use 18 RPI GPIOs + 1 GND instead of SCSI connector. In order to connect RPI to X68000 (SUPER or later SCSI machine), you need to make your own conversion cable. By the way, RaSCSI performs various functions expansion by combining with X68000, but I think that it can be used with other retro PC adopting SCSI such as FM TOWNS when using it as a simple SCSI hard disk.



Characteristic

Virtual disk device (HDD, MO, CD)

Emulate SCSI connected hard disk, magneto-optical (MO) disk, CD-ROM. On the RPI side, the disk image file that can be created with XM 6 is recognized as a virtual SCSI disk device, but on the X68000 side a physical device is recognized as being present. I also officially supported SASI from version 1.24.

Ethernet communication

By installing the Ethernet driver provided by RaSCSI on the X68000 side, communication using the TAP device (virtual network I / F) can be performed through the RPI side bridge device. The X68000 side driver can be replaced with the Neptune - X driver.

Remote drive

By installing the remote file system driver provided by RaSCSI on the X68000 side, RPI file system can be recognized as a drive through RPI side bridge device as it is. It provides the same function as Windmill's XM6 Windrv XM on the actual machine.

Initiator mode

You can use the initiator mode to control SCSI devices (host side). This allows applications such as dumping and restoring physically connected SCSI hard disks etc. However, it is necessary to use a conversion board which can be used directly or initiator mode explained later.

Connection method (conversion board edition)

Recently, there are people who mainly produce conversion board for RaSCSI through Twitter neighborhood. Since it is consigned to sell in Akihabara somehow please get it. Please refer to the connection method below (direct connection) if you are directly connected at risk prejudice.

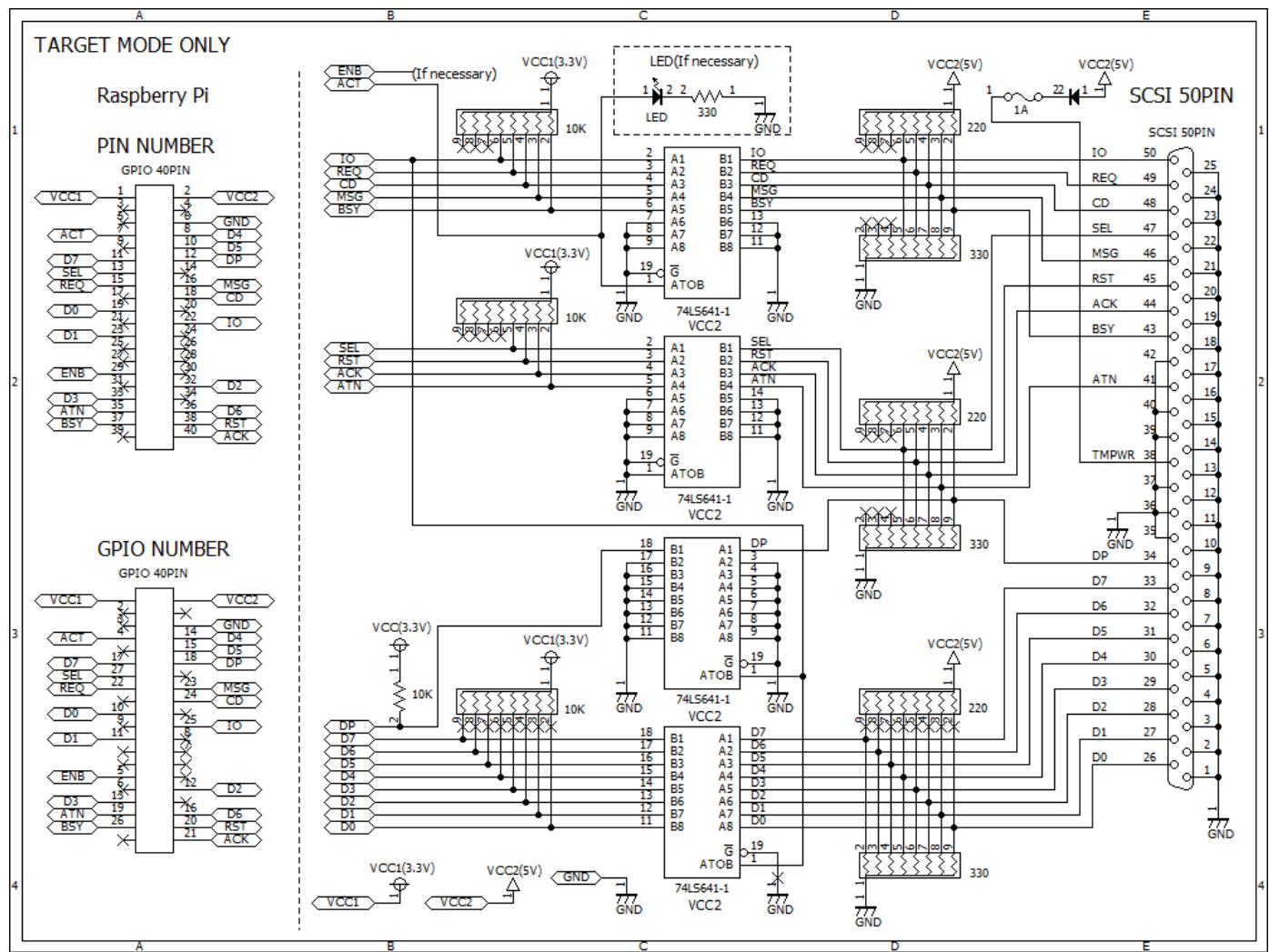
[KENCHAN daughter hard \(kit\) of household appliances is recommended](#)



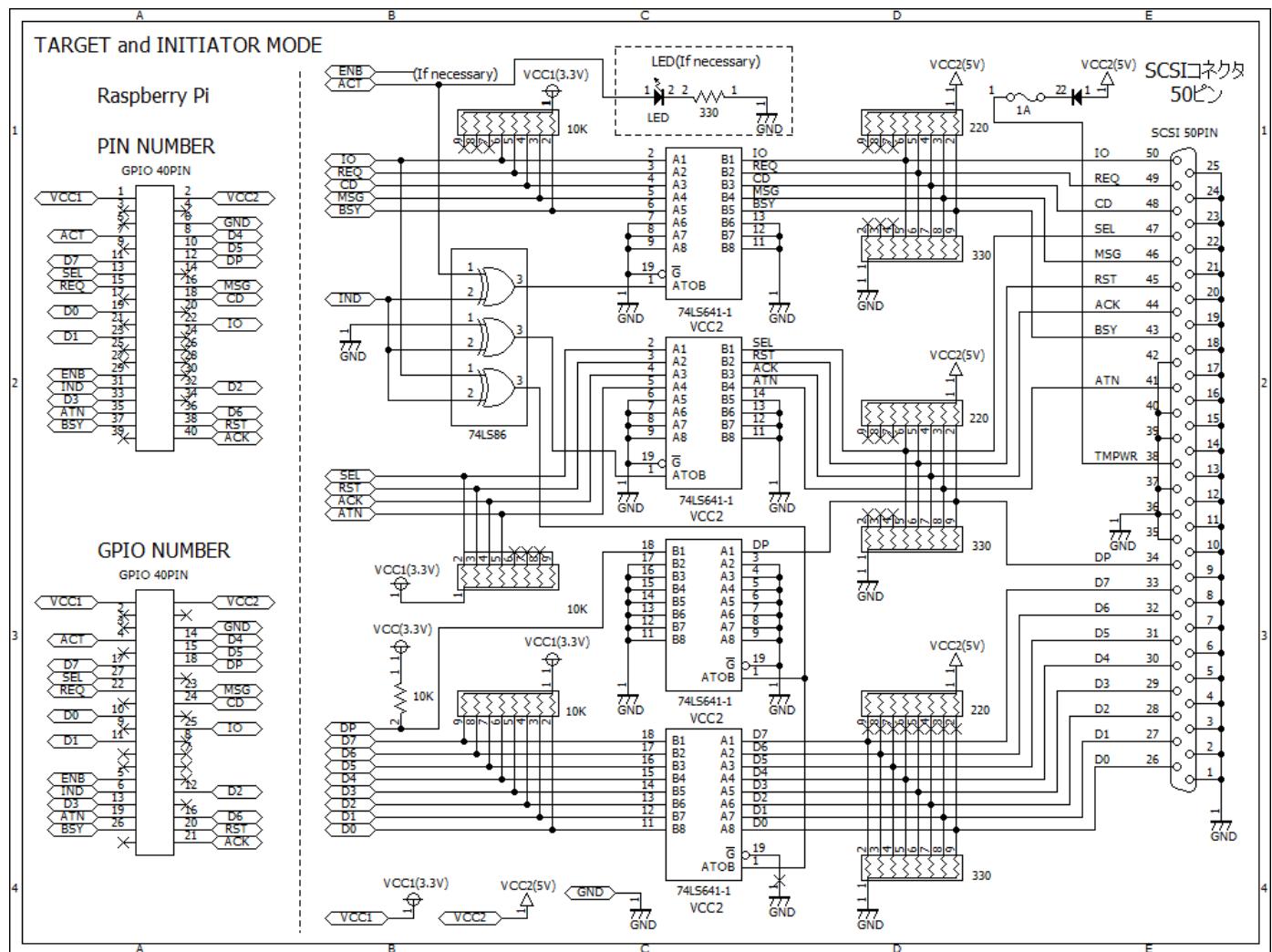
Circuit design of conversion board

For amateurs who want to create their own conversion boards, it is amateurs but I will write reference information. At the TTL level, 5 V is divided at $220\ \Omega$ and $330\ \Omega$ at the TTL level (in the case of passive terminator), so that the state where the voltage slightly less than 3 V is applied to each signal line is in a steady state (signal negatively). When trying to assert the signal ($= 0\ V$) by the initiator side or the target side, the total current of $5000 \div 220 \times 2 = 45\ mA$ will flow from the terminators at both ends (the data sheet of MB 88352 which is the SCSI controller of X68000 It is $I_{OL} 48\ mA$ as a sink current when looking). RPI GPIO can not absorb such large sink current. In order to make an electrically safe connection, it is necessary to make conversion board with general purpose logic IC etc. For general-purpose logic ICs, we use high power type open collector such as 74LS06 or 07 which can withstand 48mA sink current. The authors confirmed that it operates without any problems by performing basic SCSI direction control with 74 HC 541 $\times 3$, 74 HC 126 $\times 1,74$ HC 0 4 $\times 1$ and further combining circuits that drive the bus using 74 LS 07 $\times 3$. In addition, if you use 74LS641-1 which is a derivative version of 74LS641, the circuit can be constructed simply. Unlike normal products, it is not necessary to use 74LS07 because the sink current is 48mA compatible. But availability is not that good.

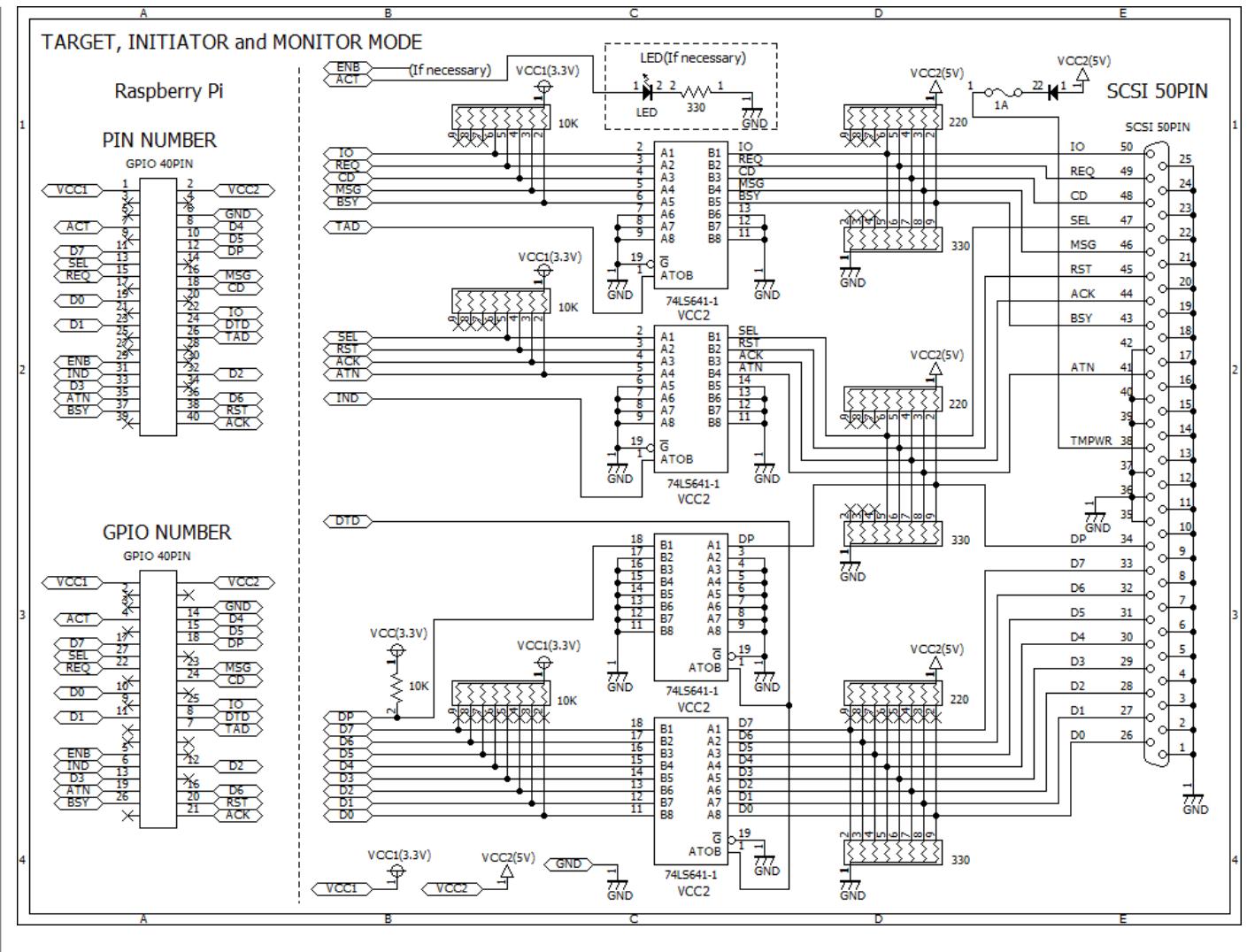
This is a circuit diagram example of a conversion board that supports target mode (HDD, MO, CD, etc.). There are many conversion boards developed based on this circuit diagram (GAMERnium.com version etc.).



This is a circuit diagram example of a conversion board that supports the initiator mode (host function) in addition to the target mode (HDD, MO, CD etc.). We will use one more GPIO to control the initiator mode. Also, 74LS86 is required to invert the direction control. There is no conversion board currently based on this circuit diagram.



This is a circuit diagram example of a conversion board that supports target modes (HDD, MO, CD etc.), initiator mode (host function), monitor mode (SCSI signal monitoring). We use three GPIOs. The direction control of all 74LS641-1 is controlled from the RaSCSI side. There is no conversion board currently based on this circuit diagram. The Aibomu version using a dedicated driver IC is close to this.



Connection method (direct connection)

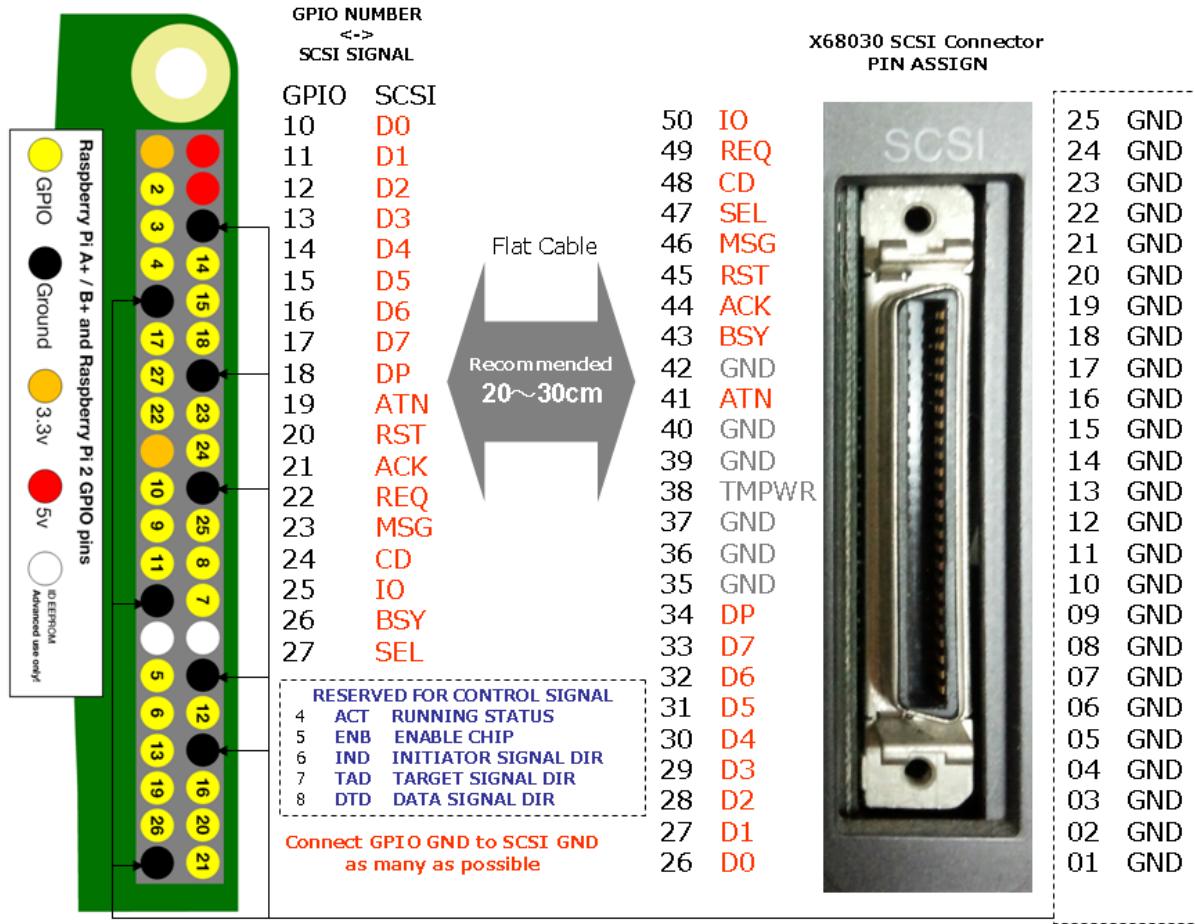
warning!

Due to the difference in electrical specifications between GPIO and SCSI, there is risk involved in direct connection. Conversion boards must be used to make an electrically safe connection. People who can not understand this risk should give up. Your X68000 is probably okay but Raspberry Pi has an unexpected load. The unexpected load is the sink current explained at the conversion board. Since there is no terminator in direct connection, a sink current of about 22 mA will be generated but since it exceeds the maximum drive capability of GPIO, it will not be able to drive up to near 0 V with low sink current. Incidentally, RaSCSI is running for several months, but it has not yet become a failure. Even if it breaks down, it is not an expensive item, so please consider it as a consumable item.

Cable connection diagram
Raspberry Pi (GPIO) <=> Connection (conversion) cable <=> (external SCSI connector) X68000

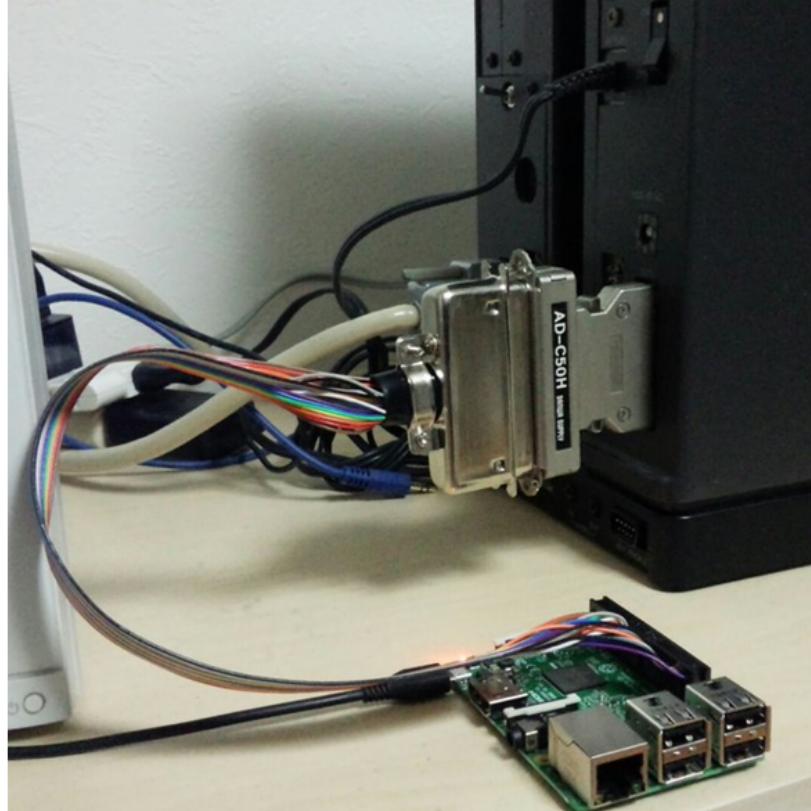
RASCSI PIN ASSIGN

UPDATE 2017/9/2



It seems to be stable when pulling out the GND on the SCSI connector side as much as possible (preferably 8 wires) and connecting it to the RPI side GND.

Cable production example



The material used was a 40-pin MIL connector, Centronics 50 pin male, flat cable. It is advisable to keep the flat cable within 30 cm (there is no track

record over this length). For SCSI connectors X68030 and XVI Compact are half size male (ribbon type) and other SCSI machines will be full size male. There is also the use of a conversion adapter like the photo. GPIP pins are not lined up beautifully, but because they are using jumping pins on top of making applications, it is a troubling place as to which to adjust the connection. I soldered the SCSI connector side normally and crimped the wiring one by one on the MIL side.

Example of directly connected substrate



There is also a direct connection board. Basically it is the same as the directly connected cable, but it is electrically stable or it does not seem to be a problem even if using the SCSI cable.

Operating environment (RPI)

It operates in the following operating environment.

Raspberry Pi

Raspberry Pi 3 Model B is recommended.

It is thought that Raspberry Pi 2 Model B and Zero also work. There is also a report that you changed pin assignment independently and operated it with Raspberry Pi 1.

Supported OS

Developed and tested with RASPBIAN STRETCH. It is updated with sudo apt-get update and sudo apt-get upgrade. At the time of writing this document, the kernel version is Linux raspberrypi 4.9.59 - v 7 +. Since RaSCSI controls the SCSI signal using GPIO, it is necessary to use it with low latency as much as possible. Therefore we recommend using it in CUI mode. Please stop unnecessary service as much as possible.

Operating environment (X68000)

It operates in the following operating environment.

X68000

SCSI machine after SUPER is recommended. Even models with SCSI boards added have a track record of operation.

Only SASI hard disk emulation can be used with SASI machines such as the first generation, ACE, EXPERT, PRO, etc. SxSI is not confirmed so much, so it will be appreciated if you can report the operation. Incidentally, since parity is not used, it is not necessary to add a parity circuit.

Supported OS

Since Ethernet function and remote drive function provide only Human's device driver, Human 3.02 is recommended for using all functions. If it is only SCSI storage, it will not be a problem with NetBSD etc.

Disk image

RaSCSI itself is a derivative of XM6 Type G which is an X68000 emulator. Therefore, it is assumed that creation of a disk image is done from the "Tools" menu of XM6 TypeG. Of course, it is possible to create an empty image file with dd etc. according to the following specifications.

SCSI hard disk

HDS file format (extension HDS / HDN / HDI / NHD / HDA extension)

File size is arbitrary size (in 512 byte units) in the range of 10 MB or more and 4095 MB or less.

When the extension is "HDN", NEC genuine hard disk emulation for PC9800 series PC-9801-55 board is performed. There is a difference in the

information returned by INQUIRY or MODE SENSE. When the extension is "HDI" or "NHD", they use SCSI hard disk images of PC98 emulators Anex 86 and T 98 Next, respectively. As with HDN, some information is converted for NEC (Thansk sava).

When the extension is "HDA", APPLE genuine hard disk emulation for Macintosh is performed. There is a difference in the information returned by INQUIRY and MODE SENSE.

SASI hard disk

HDF file format (extension HDF)

File size is 10441728 bytes, 20748288 bytes, or 41496576 bytes (corresponding to 10 MB drive, 20 MB drive, 40 MB drive respectively).

SCSI magneto-optical (MO) disk

MOS file format (extension MOS)

The file size is one of the following four types.

- 128 MB type (127398912 bytes)
 - 230 MB type (228518400 bytes)
 - 540 MB type (533248 000 bytes)
 - 640 MB type (635600896 bytes)
- 128 MB, 230 MB, 540 MB is 512 bytes / sector, 640 MB is 2048 bytes / sector.

SCSI CD-ROM

ISO file format (extension ISO, ISO 9660 solid image)

Mode 1 (2048 bytes / sector) corresponds to both data stored only in file and file recorded in RAW format.

download

RaSCSI (version 1.34)

RaSCSI RPI side program and X68000 driver and documentation. The source code of each program is also included in the archive. Since it is about one year since RASPBIAN STRETCH release, the JESSIE version is abolished.

[Download RaSCSI version 1.34 for RASPBIAN STRETCH \(1,082,580 bytes\)](#)

Download (past)

RaSCSI (version 1.33)

[Download RaSCSI version 1.33 for RASPBIAN STRETCH \(1,074,944 bytes\)](#)
[Download RaSCSI version 1.33 for RASPBIAN JESSIE \(1,075,771 bytes\)](#)

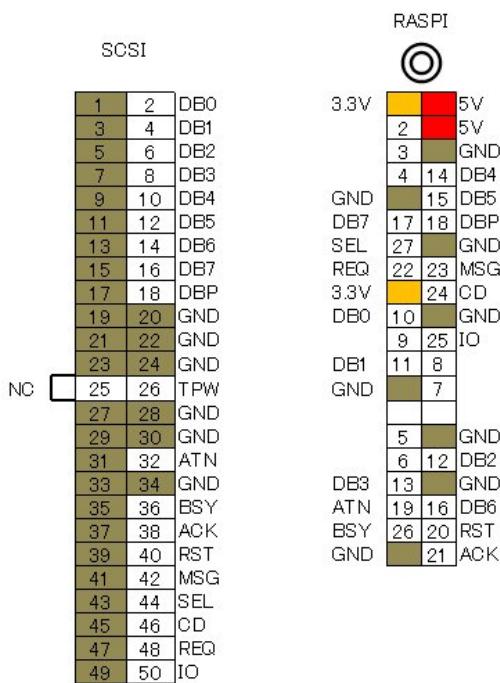
RaSCSI (version 1.32)

[Download RaSCSI version 1.32 for RASPBIAN STRETCH \(1,075,741 bytes\)](#)
[Download RaSCSI version 1.32 for RASPBIAN JESSIE \(1,076,378 bytes\)](#)

Reference information

SCSI Flat cable signal line

上から見た図



It is the information received from the RaSCSI fighter connected by the SCSI flat cable.

screenshot

Full Disk

SCSI ID can be freely assigned from 0 to 7. Normally the PC main body adds an ID with an initiator, so it is actually up to 7 units.



You can also use it as a boot disk boot device.



DSKBENCH

Benchmarks will also beat out numerical values. It is not inferior to physical HDD (SCSI 1 though).



I could use FM TOWNS II

I developed it for X68000, but I used it normally for FM TOWNS as well.



The power of RASDRV which can taste Windrv XM mood even though it is a real machine that uses the file of Raspai as it is.



It also comes with an Ethernet connection

During TELNET from X68000 to RPI. I do not need Neptune-X any more.

```

root     812  1  0 04:32 ttym1    00:00:00 /sbin/agetty --noclear ttym1 linux
root     932  740  0 04:35 ?      00:00:00 sshd: pi [priv]
pi      938  862  0 04:35 ?      00:00:00 sshd: pi@pts/0
pi      870  868  0 04:35 pts/0   00:00:00 -bash
root     898  2  0 04:35 ?      00:00:00 [kworker/0:1H]
root     962  740  0 04:41 ?      00:00:00 sshd: pi [priv]
root     966  2  0 04:41 ?      00:00:01 [kworker/3:0]
pi      971  962  0 04:41 ?      00:00:00 sshd: pi@pts/1
pi      975  971  0 04:41 pts/1   00:00:00 -bash
root    1081  2  0 04:57 ?      00:00:04 [kworker/u8:1]
pi     1711  870  0 06:25 pts/0   00:00:02 ftp 192.168.3.13
root    2164  2  0 07:15 ?      00:00:01 [kworker/u8:4]
root    2757  2  0 07:23 ?      00:00:00 [kworker/1:1]
pi     3005  1711  0 07:28 pts/0   00:00:00 bash
root    3014  2  0 07:28 ?      00:00:00 [kworker/u8:0]
root    3015  2  0 07:28 ?      00:00:00 [kworker/3:2]
root    3020  973  0 07:28 pts/1   00:00:00 sudo ./rascsi -ID0 SCSIHD2.HDS -ID2 ETHER
root    3024  3020  38 07:28 pts/1  00:02:45 ./rascsi -ID0 SCSIHD2.HDS -ID2 ETHER
root    3091  2  0 07:29 ?      00:00:00 [kworker/2:0]
root    3135  2  0 07:34 ?      00:00:00 [kworker/u8:0]
telnetd 3136  414  0 07:35 ?      00:00:00 in.telnetd: 192.168.68.3
root    3137  3136  0 07:35 pts/2   00:00:00 login -h 192.168.68.3 ~
root    3138  2  0 07:35 ?      00:00:00 [kworker/1:0]
pi     3145  3137  1 07:35 pts/2   00:00:00 -bash
pi     3172  3145  0 07:35 pts/2   00:00:00 ps -ef
pi@raspberrypi:~$
```

MITSUBISHI

History

2018/4/26 Version 1.34 is released (rasdump improvement, 256 bytes / sector is released experimentally with HDN and HDI, merge NetBSD compatible patch)

Published 2018/2/10 Version 1.33 (GAMERNium.com full spec version compatible, timing correction)

Release 2017/12/3 Version 1.32 (strengthen support for PC 98, timing improvement, full spec version binary addition, other bug fixes)

Release 2017/9/5 Version 1.31 (Initiator mode compatible, RASDRV improved)

2017/7/1 Version 1.30 released (PC-9801-55 genuine NEC HD compatible, Apple genuine HD compatible for Macintosh)

Published 2017/6/25 Version 1.26 (Expansion for 55 boards for PC 98, Experiment on MAC)

Published 2017/6/18 Version 1.25L10 (urgent response to RASPBIAN's cpuminfo specification change)

Publish 2017/6/18 Version 1.25 (Transfer error processing and RST signal reception processing are modified)

Release 2017/6/17 Version 1.24 (Improve stability by kernel driver)

2017/5/21 Version 1.23 is released (55 board compatible experiment for PC 98, SASI hard disk compatible experiment, @ 132 sync version, tomcat version converted binary addition)

Publish 2017/5/1 Version 1.22 (Correct processing when receiving ATN signal, add output of ENABLE signal, add SCSI control logic for conversion board * recompile required)

2017/4/10 Version 1.21 is released (deletion of unnecessary code, correspondence of pin assignment, addition of output of ACTIVE signal, correction of bug of host file system)

Circuit design is added to 2017/4/9 "Consideration of electrically safe connection method"

2017/3/23 "Consideration of electrically safe connection method" etc. added

[EOF]