

# MICROS 32 BITS

## STM – TIMERS

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```

#include <stdio.h>
#include "stm32f7xx.h"

int main(void){
    RCC -> AHB1ENR = 0X2; //PUERTO B
    RCC -> APB1ENR = 0X1; //TIMER 2
    GPIOB -> MODER = 0X10004001; //COLOCAR EN SALIDA PARA ENCENDER LOS LEDS
    GPIOB -> OTYPER = 0X0; //PUSH PULL
    GPIOB -> OSPEEDR = 0X10004001; //VELOCIDAD MEDIA
    GPIOB -> PUPDR = 0X10004001; //PULL UP
    TIM2 -> CR1 = 0X1; //CONTADOR HABILITADO, DIVISION X1
    TIM2 -> ARR = 0xFFFFFFFF; //VALOR DE RESET
    TIM2 -> PSC = 20000; //PRE-ESCALER DE TIEMPO

    while(1){

        if (TIM2 -> CNT <10){
            GPIOB -> ODR = 0X0080;    }
        else if (TIM2 -> CNT > 200 & TIM2 -> CNT <500){
            GPIOB -> ODR = 0X0001;    }
        else if (TIM2 -> CNT > 500 & TIM2 -> CNT <700 ){
            GPIOB -> ODR = 0X4000;    }
        else if (TIM2 -> CNT > 900){
            TIM2 -> EGR = 1;    }
    }
}

```

```

#include <stdio.h>
#include "stm32f7xx.h"

int main(void){
    RCC -> AHB1ENR = 0X2; //PUERTO B
    RCC -> APB1ENR = 0X1; //TIMER 2
    GPIOB -> MODER = 0X10004001; //COLOCAR EN SALIDA PARA ENCENDER LOS LEDS
    GPIOB -> OTYPER = 0X0; //PUSH PULL
    GPIOB -> OSPEEDR = 0X10004001; //VELOCIDAD MEDIA
    GPIOB -> PUPDR = 0X10004001; //PULL UP

    TIM2 -> CR1 = 0X1; //CONTADOR HABILITADO, DIVISION X1
    TIM2 -> ARR = 800; //VALOR DE RESET
    TIM2 -> PSC = 20000; //PRE-ESCALER DE TIEMPO

    while(1){
        if (TIM2 -> CNT <10){
            GPIOB -> ODR = 0X0080;
        }
        else if (TIM2 -> CNT > 200 & TIM2 -> CNT <500){
            GPIOB -> ODR = 0X0001;
        }
        else if (TIM2 -> CNT > 500){
            GPIOB -> ODR = 0X4000;
        }
    }
}

```

////////////////////////////////////

```
#include <stdio.h>
#include "stm32f7xx.h"
```

```
int main(void) {
    int temp=0;
    RCC -> AHB1ENR = 0X6; //PUERTO B
    RCC -> APB1ENR = 0X1; //TIMER 2
    GPIOC -> MODER = 0;
    GPIOB -> MODER = 0X10004001; //COLOCAR EN SALIDA PARA ENCENDER LOS LEDS
    GPIOB -> OTYPER = 0X0; //PUSH PULL
    GPIOB -> OSPEEDR = 0X10004001; //VELOCIDAD MEDIA
    GPIOB -> PUPDR = 0X10004001; //PULL UP
    TIM2 -> CR1 = 0X1; //CONTADOR HABILITADO, DIVISION X1
    TIM2 -> ARR = 0X500; //VALOR DE RESET
    TIM2 -> PSC = 20000; //PRE-ESCALER DE TIEMPO

    while(1) {
        if ((GPIOC-> IDR & 0X2000)== 0X2000) {
            temp= TIM2 -> CNT;
            if (temp <10){
                GPIOB -> ODR = 0X0080;
            }
            else if (temp > 500 & temp <700 ){
                GPIOB -> ODR = 0X4000;
            }
        }
    }
}
```

////////////////////////////////////

```
#include <stdio.h>
#include "stm32f7xx.h"
```

```
int main(void){
    int temp=0;
    RCC -> AHB1ENR = 0X6; //PUERTO B
    RCC -> APB1ENR = 0X1; //TIMER 2
    GPIOC -> MODER = 0;
    GPIOB -> MODER = 0X10004001; //COLOCAR EN SALIDA PARA ENCENDER LOS LEDS
    GPIOB -> OTYPER = 0X0; //PUSH PULL
    GPIOB -> OSPEEDR = 0X10004001; //VELOCIDAD MEDIA
    GPIOB -> PUPDR = 0X10004001; //PULL UP
    TIM2 -> CR1 = 0X1;
    TIM2 -> ARR = 0X550000; //VALOR DE RESET
    TIM2 -> PSC = 20000; //PRE-ESCALER DE TIEMPO

    while(1){
        if ((GPIOC-> IDR & 0X2000)== 0X2000){
            TIM2 -> EGR = 1;
            while ((GPIOC-> IDR & 0X2000)== 0X2000);
            temp= (TIM2 -> CNT)/2;
            if (temp <500){
                GPIOB -> ODR = 0X0080;    }
            else if (temp > 600 & temp <900 ){
                GPIOB -> ODR = 0X4000;    }
            else GPIOB -> ODR = 0X4081;
        }
    }
}
```

## Timer 1 seg ON

```
1  #include <stdio.h>
2  #include "stm32f7xx.h"
3
4  int main(void) {
5      RCC -> AHB1ENR = 0X2; //PUERTO B
6      RCC -> APB1ENR = 0X1; //TIMER 2
7      GPIOB -> MODER = 0X10004001; //COLOCAR EN SALIDA PARA ENCENDER LOS LEDS
8      GPIOB -> OTYPER = 0X0; //PUSH PULL
9      GPIOB -> OSPEEDR = 0X10004001; //VELOCIDAD MEDIA
10     GPIOB -> PUPDR = 0X10004001; //PULL UP
11
12     TIM2 -> CR1 = 0X1; //CONTADOR HABILITADO, DIVISION X1
13     TIM2 -> DIER = 0X1; //HABILITAR LA INTERRUPCION AL TERMINAR CADA CONTEO
14     TIM2 -> ARR = 800; //CALCULAR CON TIMER CALCULATOR
15     TIM2 -> PSC = 20000; //CALCULAR CON TIMER CALCULATOR 1HZ
16     NVIC_EnableIRQ(TIM2_IRQn);
17
18     while(1) {
19
20     }
21 }
22
23 extern "C" {
24
25     void TIM2_IRQHandler(void)
26     {
27         TIM2->SR &= ~(1<<0);
28         GPIOB -> ODR ^= 0X4081; //INTERMITENCIA DE LOS LEDS
29     }
30
31 }
```