# Correctness Proofs of Transformation Schemas

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#### Abstract

Schema-based logic program transformation has proven to be an effective technique for the optimization of programs. Some transformation schemas were given in [3]; they pre-compile some widely used transformation techniques from an input program schema that abstracts a particular family of programs into an output program schema that abstracts another family of programs.

This report presents the correctness proofs of these transformation schemas, based on a correctness definition of transformation schemas. A transformation schema is *correct* iff the templates of its input and output program schemas are equivalent wrt the specification of the top-level relation defined in these program schemas, under the applicability conditions of this transformation schema.

## 1 Introduction

In this introductory section, we give the definitions of the notions that are needed to prove the correctness of the transformation schemas in [3]. The transformation schemas proved in this report are pre-compilations of the accumulation strategy [2], of tupling generalization, which is a special case of structural generalization [4], of a combination of the previous two techniques, and of the first duality law of the fold operators in functional programming [1]. For a detailed explanation of these transformation schemas and examples of the definitions below, the reader is invited to consult [3].

Throughout this report, the word program (resp. procedure) is used to mean typed definite program (resp. procedure). An open program is a program where some of the relations appearing in the clause bodies are not appearing in any heads of clauses, and these relations are called undefined (or open) relations. If all the relations appearing in the program are defined, then the program is called a closed program. A formal specification of a program for a relation r of arity 2 is a first-order formula written in the format:

$$\forall X : \mathcal{X} : \forall Y : \mathcal{Y} : \mathcal{I}_r(X) \Rightarrow [r(X,Y) \Leftrightarrow \mathcal{O}_r(X,Y)]$$

where  $\mathcal{X}$  and  $\mathcal{Y}$  are the sorts (or: types) of X and Y, respectively,  $\mathcal{I}_r(X)$  denotes the *input condition* that must be fulfilled before the execution of the program, and  $\mathcal{O}_r(X,Y)$  denotes the *output condition* that will be fulfilled after the execution. All the definitions are given only for programs in closed frameworks. So, we first give the definition of frameworks.

#### Definition 1 (Frameworks)

A framework  $\mathcal{F}$  is a full first-order logical theory (with identity) with an intended model. An open framework consists of:

- \* a (many-sorted) signature of
  - both defined and open sort names;
  - function declarations, for declaring both defined and open constant and function names;
  - relation declarations, for declaring both defined and open relation names;
- \* a set of first-order axioms each for the (declared) defined and open function and relation names, the former possibly containing induction schemas;
- \* a set of theorems.

An open framework  $\mathcal{F}$  is also denoted by  $\mathcal{F}(\Pi)$ , where  $\Pi$  are the open names, or parameters, of  $\mathcal{F}$ . The definition of a closed framework is the same as the definition of an open framework, except that a closed framework has no open names. Therefore, a closed framework is just an extreme case of an open one, namely where  $\Pi$  is empty.

Now, we give the definitions of correctness of a logic program and equivalence of two programs, which will be used in the equivalence definition of two program schemas.

### Definition 2 (Correctness of a Closed Program)

Let P be a closed program for relation r in a closed framework  $\mathcal{F}$ . We say that P is (totally) correct wrt its specification  $S_r$  iff, for any ground term t of  $\mathcal{X}$  such that  $\mathcal{I}_r(t)$  holds, the following condition holds:  $P \vdash r(t, u)$  iff  $\mathcal{F} \models \mathcal{O}_r(t, u)$ , for every ground term u of  $\mathcal{Y}$ .

If we replace 'iff' by 'implies' in the condition above, then P is said to be partially correct wrt  $S_r$ , and if we replace 'iff' by 'if', then P is said to be complete wrt  $S_r$ .

This kind of correctness is not entirely satisfactory, for two reasons. First, it defines the correctness of P in terms of the procedures for the relations in its clause bodies, rather than in terms of their specifications. Second, P must be a closed program, even though it might be desirable to discuss the correctness of P without having to fully implement it. So, the abstraction achieved through the introduction (and specification) of the relations in its clause bodies is wasted. This leads us to the notion of steadfastness (also known as parametric correctness) [5] (also see [4]).

## Definition 3 (Steadfastness of an Open Program in a Set of Specifications)

In a closed framework  $\mathcal{F}$ , let:

- P be an open program for relation r
- $q_1, \ldots, q_m$  be all the undefined relation names appearing in P
- $S_1, \ldots, S_m$  be the specifications of  $q_1, \ldots, q_m$ .

We say that P is steadfast wrt its specification  $S_r$  in  $\{S_1, \ldots, S_m\}$  iff the (closed) program  $P \cup P_S$  is correct wrt  $S_r$ , where  $P_S$  is any closed program such that

- $P_S$  is correct wrt each specification  $S_j$   $(1 \le j \le m)$
- $\bullet$   $P_S$  contains no occurrences of the relations defined in P.

The steadfastness definition has the following interesting property, which is actually a high-level recursive algorithm to check the steadfastness of an open program.

### **Property 1** In a closed framework $\mathcal{F}$ , let:

- P be an open program for relation r of the specification  $S_r$
- $p_1, \ldots, p_t$  be all the defined relation names appearing in P (including r thus)
- $q_1, \ldots, q_m$  be all the undefined relation names appearing in P
- $S_1, \ldots, S_m$  be the specifications of  $q_1, \ldots, q_m$ .

For  $t \geq 2$ , the program P is steadfast wrt  $S_r$  in  $\{S_1, \ldots, S_m\}$  iff every  $P_i$   $(1 \leq i \leq t)$  is steadfast wrt the specification of  $p_i$  in the set of the specifications of all undefined relations in  $P_i$ , where  $P_i$  is a program for  $p_i$ , such that  $P = \bigcup_{i=1}^t P_i$ . When t = 1, the definition of steadfastness is directly used, since the only defined relation is the relation r. Thus, t = 1 is the stopping case of this recursive algorithm.

For program equivalence, we do not require the two programs to have the same models, because this would not make much sense in some program transformation settings where the transformed program features relations that were not in the initially given program. That is why our program equivalence criterion establishes equivalence wrt the specification of a common relation (usually the root of their call-hierarchies).

#### Definition 4 (Equivalence of Two Open Programs)

In a closed framework  $\mathcal{F}$ , let P and Q be two open programs for a relation r. We say that P is equivalent to Q wrt the specification  $S_r$  iff the following two conditions hold:

- (a) P is steadfast wrt  $S_r$  in  $\{S_1, \ldots, S_m\}$ , where  $S_1, \ldots, S_m$  are the specifications of  $p_1, \ldots, p_m$ , which are all the undefined relation names appearing in P
- (b) Q is steadfast wrt  $S_r$  in  $\{S'_1, \ldots, S'_t\}$ , where  $S'_1, \ldots, S'_t$  are the specifications of  $q_1, \ldots, q_t$ , which are all the undefined relation names appearing in Q.

Since the 'is equivalent to' relation is symmetric, we also say that P and Q are equivalent wrt  $S_r$ .

Sometimes, in program transformation settings, there exist some conditions that have to be verified related to some parts of the initial and/or transformed program in order to have a transformed program that is equivalent to the initially given program wrt the specification of the top-level relation. Hence the following definition.

#### Definition 5 (Conditional Equivalence of Two Open Programs)

In a closed framework  $\mathcal{F}$ , let P and Q be two open programs for a relation r. We say that P is equivalent to Q wrt the specification  $S_r$  under conditions C iff P is equivalent to Q wrt  $S_r$  provided that C hold.

Before we define the notions of transformation schema and correctness of transformation schemas, we have to define the notions of program schema, schema pattern, and particularization.

**Definition 6** In a closed framework  $\mathcal{F}$ , a program schema for a relation r is a pair  $\langle T, C \rangle$ , where T is an open program for r, called the *template*, and C is the set of specifications of the open relations of T in terms of each other and the input/output conditions of the closed relations of T. The specifications in C, called the *steadfastness constraints*, are such that, in  $\mathcal{F}$ , T is steadfast wrt its specification  $S_r$  in C.

Sometimes, a series of schemas are quite similar, in the sense that they only differ in the number of arguments of some relations, or in the number of calls to some relations, etc. For this purpose, rather than having a proliferation of similar schemas, we introduce the notions of schema pattern and particularization.

**Definition 7** A schema pattern is a schema where term, conjunct, and disjunct ellipses are allowed in the template and in the steadfastness constraints.

For instance,  $TX_1, \ldots, TX_t$  is a term ellipsis, and  $\bigwedge_{i=1}^t r(TX_i, TY_i)$  is a conjunct ellipsis.

**Definition 8** A particularization of a schema pattern is a schema obtained by eliminating the ellipses, i.e., by binding the (mathematical) variables denoting their lower and upper bounds to natural numbers.

Finally, we give the definition of transformation schemas and their correctness definition.

**Definition 9** A transformation schema encoding a transformation technique is a 5-tuple  $\langle S_1, S_2, A, O_{12}, O_{21} \rangle$ , where  $S_1$  and  $S_2$  are program schemas (or schema patterns), A is a set of applicability conditions, which ensure the equivalence of the templates of  $S_1$  and  $S_2$  wrt the specification of the top-level relation, and  $O_{12}$  (respectively,  $O_{21}$ ) is a set of optimizability conditions when  $S_2$  (respectively,  $S_1$ ) is the output program schema (or schema pattern).

If the transformation schema embodies some generalization technique, then it is called a generalization schema. The generalization methods that we pre-compile in our transformation schemas are tupling generalization, which is a special case of structural generalization where the structure of some parameter is generalized, and descending generalization, which is a special case of computational generalization where the general state of computation is generalized in terms of what remains to be done. We also introduce a new method, called simultaneous tupling-and-descending generalization, which can be thought of as applying descending generalization to a tupling generalized problem. Transformation schemas that simulate and extend a basic theorem in functional programming (the first duality law of the fold operators) for logic programs are called duality schemas.

**Definition 10** A transformation schema  $\langle S_1, S_2, A, O_{12}, O_{21} \rangle$  is *correct* iff the templates of program schemas (or schema patterns)  $S_1$  and  $S_2$  are equivalent wrt the specification of the top-level relation under A.

In program transformation, for proving the correctness of a transformation schema  $\langle S_1, S_2, A, O_{12}, O_{21} \rangle$ , we have to prove the equivalence of  $T_1$  and  $T_2$ , which are the templates of  $S_1 = \langle T_1, C_1 \rangle$  and  $S_2 = \langle T_2, C_2 \rangle$ . We assume that the template  $T_i$  of the input program schema  $S_i = \langle T_i, C_i \rangle$  (where i = 1, 2) is steadfast wrt the specification of the top-level relation, say  $S_r$ , in  $C_i$ ; then the correctness of the transformation schema is proven by establishing the steadfastness of the template  $T_j$  of the output program schema (or schema pattern)  $S_j = \langle T_j, C_j \rangle$  (where j = 1, 2 and  $j \neq i$ ) wrt  $S_r$  in  $C_j$  using the applicability conditions A.

In the remainder of this report, first the tupling generalization schemas are proved to be correct, in Section 2. In Section 3, the correctness proofs of the descending generalization schemas, which are a pre-compilation of the accumulation strategy, are given. The correctness proofs of the simultaneous tupling-and descending generalization schemas are given in Section 4. Before we conclude in Section 6, we will give the correctness proofs of the duality schemas in Section 5.

# 2 Proofs of the Tupling Generalization Schemas

**Theorem 1** The generalization schema  $TG_1$ , which is given below, is correct.

```
TG_1: \langle DCLR, TG, A_{t1}, O_{t112}, O_{t121} \rangle \text{ where } \\ A_{t1}: (1) \ compose \ \text{is associative} \\ (2) \ compose \ \text{has } e \ \text{as the left and right identity element} \\ (3) \ \forall X: \mathcal{X}. \ \mathcal{I}_r(X) \wedge minimal(X) \Rightarrow \mathcal{O}_r(X, e) \\ (4) \ \forall X: \mathcal{X}. \ \mathcal{I}_r(X) \Rightarrow [\neg minimal(X) \Leftrightarrow nonMinimal(X)] \\ O_{t112}: \text{ partial evaluation of the conjunction} \\ process(HX, HY), compose(HY, TY, Y) \\ \text{results in the introduction of a non-recursive relation} \\ O_{t121}: \text{ partial evaluation of the conjunction} \\ process(HX, HY), compose(I_{p-1}, HY, I_p) \\ \text{results in the introduction of a non-recursive relation} \\ \end{cases}
```

where the templates DCLR and TG are Logic Program Templates 1 and 2 below:

## Logic Program Template 1

```
\begin{split} \mathbf{r}(\mathtt{X},\mathtt{Y}) &\leftarrow \\ & \texttt{minimal}(\mathtt{X}), \\ & \texttt{solve}(\mathtt{X},\mathtt{Y}) \\ \mathbf{r}(\mathtt{X},\mathtt{Y}) &\leftarrow \\ & \texttt{nonMinimal}(\mathtt{X}), \\ & \texttt{decompose}(\mathtt{X},\mathtt{HX},\mathtt{TX}_1,\ldots,\mathtt{TX}_t), \\ & \mathbf{r}(\mathtt{TX}_1,\mathtt{TY}_1),\ldots,\mathbf{r}(\mathtt{TX}_t,\mathtt{TY}_t), \\ & \mathtt{I}_0 = \mathtt{e}, \\ & \texttt{compose}(\mathtt{I}_0,\mathtt{TY}_1,\mathtt{I}_1),\ldots,\texttt{compose}(\mathtt{I}_{p-2},\mathtt{TY}_{p-1},\mathtt{I}_{p-1}), \\ & \texttt{process}(\mathtt{HX},\mathtt{HY}), \texttt{compose}(\mathtt{I}_{p-1},\mathtt{HY},\mathtt{I}_p), \\ & \texttt{compose}(\mathtt{I}_p,\mathtt{TY}_p,\mathtt{I}_{p+1}),\ldots,\texttt{compose}(\mathtt{I}_t,\mathtt{TY}_t,\mathtt{I}_{t+1}), \\ & \mathtt{Y} = \mathtt{I}_{t+1} \end{split}
```

#### Logic Program Template 2

```
r(X,Y) \leftarrow
     r_tupling([X], Y)
r_tupling(Xs,Y) \leftarrow
     Xs = [],
     Y = e
r_tupling(Xs,Y) \leftarrow
     Xs = [X|TXs],
     minimal(X),
     r_tupling(TXs, TY),
     solve(X, HY),
     compose(HY, TY, Y)
r_{tupling}(Xs, Y) \leftarrow
     Xs = [X|TXs],
     nonMinimal(X)
     decompose(X, HX, TX_1, ..., TX_t),
     minimal(TX<sub>1</sub>),...,minimal(TX<sub>t</sub>),
     r_tupling(TXs, TY),
     process(HX, HY),
```

```
compose(HY, TY, Y)
r\_tupling(Xs,Y) \leftarrow
      Xs = [X|TXs],
     nonMinimal(X)
      \mathtt{decompose}(\mathtt{X},\mathtt{HX},\mathtt{TX}_1,\ldots,\mathtt{TX}_{\mathtt{t}}),
     minimal(TX_1), \ldots, minimal(TX_{p-1}),
      (nonMinimal(TX_p); ...; nonMinimal(TX_t)),
      r_{tupling}([TX_{p}, ..., TX_{t}|TX_{s}], TY),
      process(HX, HY),
      compose(HY, TY, Y)
r_tupling(Xs, Y) \leftarrow
      Xs = [X|TXs],
     nonMinimal(X),
      decompose(X, HX, TX_1, ..., TX_t),
      (nonMinimal(TX_1); ...; nonMinimal(TX_{D-1})),
      minimal(TXp), ..., minimal(TXt),
     \mathtt{minimal}(\mathtt{U}_1), \ldots, \mathtt{minimal}(\mathtt{U}_{p-1}),
      \mathtt{decompose}(\mathtt{N},\mathtt{HX},\mathtt{U_1},\ldots,\mathtt{U_{p-1}},\mathtt{TX_p},\ldots,\mathtt{TX_t}),
      r_{tupling}([TX_1, ..., TX_{p-1}, N|TXs], Y)
r_tupling(Xs, Y) \leftarrow
      Xs = [X|TXs],
     nonMinimal(X)
      decompose(X, HX, TX_1, ..., TX_t),
      (nonMinimal(TX_1); ...; nonMinimal(TX_{D-1})),
      (nonMinimal(TX_p); ...; nonMinimal(TX_t)),
      minimal(U_1), \ldots, minimal(U_t),
      decompose(N, HX, U_1, \dots, U_t),
      r_{tupling}([TX_1, \dots, TX_{p-1}, N, TX_p, \dots, TX_t | TX_s], Y)
```

and the specification  $S_r$  of relation r is:

$$\forall X : \mathcal{X}, \forall Y : \mathcal{Y}. \ \mathcal{I}_r(X) \Rightarrow [r(X,Y) \Leftrightarrow \mathcal{O}_r(X,Y)]$$

and the specification  $S_{r\_tupling}$  of relation  $r\_tupling$  is:

```
\forall Xs : list \ of \ \mathcal{X}, \forall Y : \mathcal{Y}. \ (\forall X : \mathcal{X}. \ X \in Xs \Rightarrow \mathcal{I}_r(X)) \Rightarrow [r \ \textit{fupling}(Xs, Y) \Leftrightarrow (Xs = [] \land Y = e) \\ \lor (Xs = [X_1, \dots, X_q] \land \ \bigwedge_{i=1}^q \mathcal{O}_r(X_i, Y_i) \ \land I_1 = Y_1 \land \ \bigwedge_{i=2}^q \mathcal{O}_c(I_{i-1}, Y_i, I_i) \ \land Y = I_q)]
```

where  $\mathcal{O}_c$  is the output condition of *compose* and  $q \geq 1$ .

**Proof 1** To prove the correctness of the generalization schema  $TG_1$ , by Definition 10, we have to prove that templates DCLR and TG are equivalent wrt  $S_r$  under the applicability conditions  $A_{t1}$ . By Definition 5, the templates DCLR and TG are equivalent wrt  $S_r$  under the applicability conditions  $A_{t1}$  iff DCLR is equivalent to TG wrt the specification  $S_r$  provided that the conditions in  $A_{t1}$  hold. By Definition 4, DCLR is equivalent to TG wrt the specification  $S_r$  iff the following two conditions hold:

- (a) DCLR is steadfast wrt  $S_r$  in  $S = \{S_{minimal}, S_{nonMinimal}, S_{solve}, S_{decompose}, S_{process}, S_{compose}\}$ , where  $S_{minimal}, S_{nonMinimal}, S_{solve}, S_{decompose}, S_{process}, S_{compose}$  are the specifications of minimal, nonMinimal, solve, decompose, process, compose, which are all the undefined relation names appearing in DCLR.
- (b) TG is also steadfast wrt  $S_r$  in S.

Note that the sets  $\{S_1, \ldots, S_m\}$  and  $\{S'_1, \ldots, S'_t\}$  in Definition 4 are equal to  $\mathcal{S}$  when Q is obtained by tupling generalization of P.

In program transformation, we assume that the input program, here template DCLR, is steadfast wrt  $S_r$  in S, so condition (a) always holds.

To prove equivalence, we have to prove condition (b). We will use the following property of stead-fastness: TG is steadfast wrt  $S_r$  in S if  $P_{r\_tupling}$  is steadfast wrt  $S_{r\_tupling}$  in S, where  $P_{r\_tupling}$  is the procedure for  $r\_tupling$ , and  $P_r$  is steadfast wrt  $S_r$  in  $\{S_{r\_tupling}\}$ , where  $P_r$  is the procedure for r.

To prove that  $P_{r\_tupling}$  is steadfast wrt  $S_{r\_tupling}$  in  $\mathcal{S}$ , we do a constructive forward proof that we begin with  $S_{r\_tupling}$  and from which we try to obtain  $P_{r\_tupling}$ .

If we separate the cases of  $q \geq 1$  by  $q = 1 \vee q \geq 2$ , then  $S_{r\_tupling}$  becomes:

```
\forall Xs: list \ of \ \mathcal{X}, \forall Y: \mathcal{Y}. \ (\forall X: \mathcal{X}. \ X \in Xs \Rightarrow \mathcal{I}_r(X)) \Rightarrow [r \ \mathit{Jupling}(Xs, Y) \Leftrightarrow (Xs = [] \land Y = e) \\ \lor (Xs = [X_1] \land \mathcal{O}_r(X_1, Y_1) \land Y_1 = I_1 \land Y = I_1) \\ \lor (Xs = [X_1, X_2, \dots, X_q] \land \ \bigwedge_{i=1}^q \mathcal{O}_r(X_i, Y_i) \ \land I_1 = Y_1 \land \ \bigwedge_{i=2}^q \mathcal{O}_c(I_{i-1}, Y_i, I_i) \ \land Y = I_q)]
```

where  $q \geq 2$ .

By using applicability conditions (1) and (2):

```
 \forall Xs: list \ of \ \mathcal{X}, \forall Y: \mathcal{Y}: \ \mathcal{Y}. \ \ (\forall X: \mathcal{X}: X \in Xs \Rightarrow \mathcal{I}_r(X)) \Rightarrow [r \, \exists upling(Xs, Y) \Leftrightarrow (Xs = [] \land Y = e)   \lor (Xs = [X_1 | TXs] \land TXs = [] \land \mathcal{O}_r(X_1, Y_1) \land Y_1 = I_1 \land TY = e \land \mathcal{O}_c(I_1, TY, Y))   \lor (Xs = [X_1 | TXs] \land TXs = [X_2, \dots, X_q] \land \ \ \bigwedge_{i=1}^q \mathcal{O}_r(X_i, Y_i) \ \ \land \ Y_1 = I_1 \land Y_2 = I_2 \land \ \bigwedge_{i=3}^q \mathcal{O}_c(I_{i-1}, Y_i, I_i) \ \ \land \ TY = I_q \land \mathcal{O}_c(I_1, TY, Y))]
```

where q > 2.

By folding using  $S_{r_{-tupling}}$ , and renaming:

```
\forall Xs : list \ of \ \mathcal{X}, \forall Y : \mathcal{Y}. \ (\forall X : \mathcal{X}. \ X \in Xs \Rightarrow \mathcal{I}_r(X)) \Rightarrow [r \ \textit{tupling}(Xs, Y) \Leftrightarrow (Xs = [] \land Y = e) \\ \lor (Xs = [X|TXs] \land \mathcal{O}_r(X, HY) \land r \ \textit{tupling}(TXs, TY) \land \mathcal{O}_c(HY, TY, Y))]
```

By taking the 'decompletion':

```
clause 1: r \exists upling(Xs, Y) \leftarrow Xs = [], Y = e

clause 2: r \exists upling(Xs, Y) \leftarrow Xs = [X|TXs], r(X, HY), r \exists upling(TXs, TY), compose(HY, TY, Y)
```

By unfolding clause 2 wrt r(X, HY) using DCLR, and using the assumption that DCLR is steadfast wrt  $S_r$  in S:

```
clause 3: r 	ext{-}upling(Xs,Y) \leftarrow Xs = [X|TXs],
	minimal(X),
	r 	ext{-}upling(TXs,TY),
	solve(X,HY),compose(HY,TY,Y)
	clause 4: r 	ext{-}upling(Xs,Y) \leftarrow Xs = [X|TXs],
	nonMinimal(X),decompose(X,HX,TX_1,...,TX_t),
	r(TX_1,TY_1),...,r(TX_t,TY_t),
	I_0 = e,
	compose(I_0,TY_1,I_1),...,compose(I_{p-2},TY_{p-1},I_{p-1}),
	process(HX,HHY),compose(I_{p-1},HHY,I_p),
	compose(I_p,TY_p,I_{p+1}),...,compose(I_t,TY_t,I_{t+1}),
	HY = I_{t+1},r 	ext{-}upling(TXs,TY),compose(HY,TY,Y)
```

By introducing

```
(minimal(TX_1) \land \ldots \land minimal(TX_t)) \lor
              ((minimal(TX_1) \land ... \land minimal(TX_{p-1})) \land (nonMinimal(TX_p) \lor ... \lor nonMinimal(TX_t))) \lor
              ((nonMinimal(TX_1) \lor ... \lor nonMinimal(TX_{p-1})) \land (minimal(TX_p) \land ... \land minimal(TX_t))) \lor
   ((nonMinimal(TX_1) \lor ... \lor nonMinimal(TX_{p-1})) \land (nonMinimal(TX_p) \lor ... \lor nonMinimal(TX_t)))
in clause 4, using applicability condition (4):
   clause 5: r 	ext{-}tupling(Xs, Y) \leftarrow
                                                    Xs = [X|TXs],
                                                    nonMinimal(X), decompose(X, HX, TX_1, \dots, TX_t),
                                                    minimal(TX_1), \ldots, minimal(TX_t),
                                                    r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                                                    I_0 = e,
                                                    compose(I_0, TY_1, I_1), \ldots, compose(I_{p-2}, TY_{p-1}, I_{p-1}),
                                                    process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                                                    compose(I_p, TY_p, I_{p+1}), \ldots, compose(I_t, TY_t, I_{t+1}),
                                                     HY = I_{t+1}, r \perp tupling(TXs, TY), compose(HY, TY, Y)
   clause 6: r 	ext{ } 	ext{ } 
                                                     Xs = [X|TXs],
                                                    nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                                                    minimal(TX_1), \ldots, minimal(TX_{p-1}),
                                                    (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                                                    r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                                                    I_0 = e
                                                    compose(I_0, TY_1, I_1), \ldots, compose(I_{p-2}, TY_{p-1}, I_{p-1}),
                                                    process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                                                    compose(I_p, TY_p, I_{p+1}), \ldots, compose(I_t, TY_t, I_{t+1}),
                                                    HY = I_{t+1}, r \perp upling(TXs, TY), compose(HY, TY, Y)
   clause 7: r 	ext{-}tupling(Xs, Y) \leftarrow
                                                     Xs = [X|TXs],
                                                    nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                                                    (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                                                    minimal(TX_p), \ldots, minimal(TX_t),
                                                    r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                                                    I_0 = e
                                                    compose(I_0, TY_1, I_1), \ldots, compose(I_{p-2}, TY_{p-1}, I_{p-1}),
                                                    process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                                                    compose(I_p, TY_p, I_{p+1}), \ldots, compose(I_t, TY_t, I_{t+1}),
                                                     HY = I_{t+1}, r \operatorname{Iupling}(TXs, TY), compose(HY, TY, Y)
   clause 8: r 	ext{ } 	ext{ } 
                                                     Xs = [X|TXs],
                                                    nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                                                    (nonMinimal(TX_1); ...; nonMinimal(TX_{p-1})),
                                                    (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                                                    r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                                                     I_0 = e,
                                                    compose(I_0, TY_1, I_1), \ldots, compose(I_{p-2}, TY_{p-1}, I_{p-1}),
                                                    process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                                                    compose(I_p, TY_p, I_{p+1}), \ldots, compose(I_t, TY_t, I_{t+1}),
                                                    HY = I_{t+1}, r \perp tupling(TXs, TY), compose(HY, TY, Y)
```

By t times unfolding clause 5 wrt  $r(TX_1, TY_1), \ldots, r(TX_t, TY_t)$  using DCLR, and simplifying using condition (4):

```
clause 9: r 	ext{ } 	ext{ } 
                                      Xs = [X|TXs],
                                     nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                                     minimal(TX_1), \ldots, minimal(TX_t),
                                     minimal(TX_1), \ldots, minimal(TX_t).
                                     solve(TX_1, TY_1), \ldots, solve(TX_t, TY_t)
                                     I_0 = e
                                     compose(I_0, TY_1, I_1), \ldots, compose(I_{p-2}, TY_{p-1}, I_{p-1}),
                                     process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                                     compose(I_p, TY_p, I_{p+1}), \ldots, compose(I_t, TY_t, I_{t+1}),
                                     HY = I_{t+1}, r \perp tupling(TXs, TY), compose(HY, TY, Y)
By using applicability condition (3):
  clause 10: r \perp upling(Xs, Y) \leftarrow
                                        Xs = [X|TXs].
                                        nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                                        minimal(TX_1), \ldots, minimal(TX_t),
                                        minimal(TX_1), \ldots, minimal(TX_t),
                                       solve(TX_1, e), \ldots, solve(TX_t, e),
                                        I_0 = e,
                                       compose(I_0, e, I_1), \ldots, compose(I_{p-2}, e, I_{p-1}),
                                       process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                                       compose(I_p, e, I_{p+1}), \ldots, compose(I_t, e, I_{t+1}),
                                       HY = I_{t+1}, r \rfloor tupling(TXs, TY), compose(HY, TY, Y)
By deleting one of the minimal(TX_1), \ldots, minimal(TX_t) atoms in clause 10:
  clause 11: r \perp tupling(Xs, Y) \leftarrow
                                       Xs = [X|TXs],
                                        nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                                        minimal(TX_1), \ldots, minimal(TX_t),
                                       solve(TX_1, e), \ldots, solve(TX_t, e),
                                        I_0 = e,
                                       compose(I_0, e, I_1), \ldots, compose(I_{p-2}, e, I_{p-1}),
                                       process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                                       compose(I_p, e, I_{p+1}), \ldots, compose(I_t, e, I_{t+1}),
                                        HY = I_{t+1}, r \perp upling(TXs, TY), compose(HY, TY, Y)
By using applicability condition (2):
  clause 12: r \pm upling(Xs, Y) \leftarrow
                                        Xs = [X|TXs].
                                       nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                                       minimal(TX_1), \ldots, minimal(TX_t),
                                       solve(TX_1, e), \ldots, solve(TX_t, e),
                                       I_0 = e,
                                       I_1 = I_0, \ldots, I_{p-1} = I_{p-2},
                                       process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                                       I_{p+1} = I_p, \ldots, I_{t+1} = I_t,
                                       HY = I_{t+1}, r \operatorname{dupling}(TXs, TY), compose(HY, TY, Y)
By simplification:
  clause 13: r \perp upling(Xs, Y) \leftarrow
                                        Xs = [X|TXs],
                                        nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                                       minimal(TX_1), \ldots, minimal(TX_t),
                                       r 	ext{-}tupling(TXs, TY),
                                       process(HX, HY), compose(HY, TY, Y)
```

By p-1 times unfolding clause 6 wrt  $r(TX_1, TY_1), \ldots, r(TX_{p-1}, TY_{p-1})$  using DCLR, and simplifying using condition (4):

```
clause 14: r \perp upling(Xs, Y) \leftarrow
                    Xs = [X|TXs]
                    nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                    minimal(TX_1), \ldots, minimal(TX_{p-1}),
                    (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                    minimal(TX_1), \ldots, minimal(TX_{p-1}),
                    solve(TX_1, TY_1), \ldots, solve(TX_{p-1}, TY_{p-1}),
                    r(TX_p, TY_p), \ldots, r(TX_t, TY_t)
                    I_0 = e
                    compose(I_0, TY_1, I_1), \ldots, compose(I_{p-2}, TY_{p-1}, I_{p-1}),
                    process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                    compose(I_p, TY_p, I_{p+1}), \ldots, compose(I_t, TY_t, I_{t+1}),
                    HY = I_{t+1}, r \operatorname{tupling}(TXs, TY), compose(HY, TY, Y)
By deleting one of the minimal(TX_1), \ldots, minimal(TX_{p-1}) atoms in clause 14:
 clause 15: r 	ext{tupling}(Xs, Y) \leftarrow
                    Xs = [X|TXs]
                    nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                    minimal(TX_1), \ldots, minimal(TX_{p-1}),
                    (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                    solve(TX_1, TY_1), \ldots, solve(TX_{p-1}, TY_{p-1}),
                    r(TX_p, TY_p), \ldots, r(TX_t, TY_t)
                    I_0 = e
                    compose(I_0, TY_1, I_1), \ldots, compose(I_{p-2}, TY_{p-1}, I_{p-1}),
                    process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                    compose(I_p, TY_p, I_{p+1}), \ldots, compose(I_t, TY_t, I_{t+1}),
                    HY = I_{t+1}, r \operatorname{Lupling}(TXs, TY), compose(HY, TY, Y)
By rewriting clause 15 using applicability condition (1):
 clause 16: r \pm upling(Xs, Y) \leftarrow
                    Xs = [X|TXs]
                    nonMinimal(X), decompose(X, HX, TX_1, \dots, TX_t),
                    minimal(TX_1), \ldots, minimal(TX_{p-1}),
                    (nonMinimal(TX_n); \ldots; nonMinimal(TX_t)),
                    solve(TX_1, TY_1), \ldots, solve(TX_{p-1}, TY_{p-1}),
                    r(TX_p, TY_p), \ldots, r(TX_t, TY_t)
                    I_0 = e,
                    compose(I_0, TY_1, I_1), \ldots, compose(I_{p-2}, TY_{p-1}, I_{p-1}),
                    process(HX, HHY), compose(I_{p-1}, HHY, I_p), HY = I_p,
                    compose(TY_p, TY_{p+1}, I_{p+1}),
                    compose(I_{p+1}, TY_{p+2}, I_{p+2}), \ldots, compose(I_{t-1}, TY_t, I_t),
                    r \perp upling(TXs, TTY), compose(I_t, TTY, TY),
                    compose(HY, TY, Y)
By t-p times folding clause 16 using clauses 1 and 2:
 clause 17: r 	ext{ } tupling(Xs, Y) \leftarrow
                    Xs = [X|TXs],
                    nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                    minimal(TX_1), \ldots, minimal(TX_{p-1}),
                    (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                    solve(TX_1, TY_1), \ldots, solve(TX_{p-1}, TY_{p-1}),
                    r \perp tupling([TX_p, \ldots, TX_t | TXs], TY),
                    I_0 = e
                    compose(I_0, TY_1, I_1), \ldots, compose(I_{p-2}, TY_{p-1}, I_{p-1}),
                    process(HX, HHY), compose(I_{p-1}, HHY, I_p), HY = I_p,
                    compose(HY, TY, Y)
```

By using applicability condition (3):

```
clause 18: r \perp upling(Xs, Y) \leftarrow
                        Xs = [X|TXs]
                        nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                        minimal(TX_1), \ldots, minimal(TX_{p-1}),
                        (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                        solve(TX_1, e), \ldots, solve(TX_{p-1}, e),
                        r \operatorname{tupling}([TX_p, \ldots, TX_t | TXs], TY),
                        I_0 = e,
                        compose(I_0, e, I_1), \ldots, compose(I_{p-2}, e, I_{p-1}),
                        process(HX, HHY), compose(I_{p-1}, HHY, I_p), HY = I_p,
                        compose(HY, TY, Y)
   By using applicability condition (2):
     clause 19: r \perp upling(Xs, Y) \leftarrow
                        Xs = [X|TXs],
                        nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                        minimal(TX_1), \ldots, minimal(TX_{p-1}),
                        (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                        solve(TX_1, e), \ldots, solve(TX_{p-1}, e),
                        r 	ext{-}tupling([TX_p, \ldots, TX_t | TXs], TY),
                        I_0 = e,
                        I_1 = I_0, \ldots, I_{p-1} = I_{p-2},
                        process(HX, HHY), compose(I_{p-1}, HHY, I_p), HY = I_p,
                        compose(HY, TY, Y)
   By simplification:
    clause 20 : r \pm upling(Xs, Y) \leftarrow
                        Xs = [X|TXs],
                        nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                        minimal(TX_1), \ldots, minimal(TX_{p-1}),
                        (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                        r 	ext{-}tupling([TX_p, \ldots, TX_t|TXs], TY),
                        process(HX, HY), compose(HY, TY, Y)
   By introducing atoms minimal(U_1), \ldots, minimal(U_{p-1}) (with new, i.e. existentially quantified, vari-
ables U_1, \ldots, U_{p-1} in clause 7:
     clause 21: r 	ext{ } tupling(Xs, Y) \leftarrow
                        Xs = [X|TXs],
                        nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                        (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                        minimal(TX_p), \ldots, minimal(TX_t),
                        minimal(U_1), \ldots, minimal(U_{p-1}),
                        r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                        compose(I_0, TY_1, I_1), \ldots, compose(I_{p-2}, TY_{p-1}, I_{p-1}),
                        process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                        compose(I_p, TY_p, I_{p+1}), \ldots, compose(I_t, TY_t, I_{t+1}),
                        HY = I_{t+1}, r \perp tupling(TXs, TY), compose(HY, TY, Y)
```

By using applicability condition (3):

```
clause 22: r \perp upling(Xs, Y) \leftarrow
                     Xs = [X|TXs]
                     nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                     (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                    minimal(TX_p), \ldots, minimal(TX_t),
                     minimal(U_1), \ldots, minimal(U_{p-1}),
                     r(U_1,e),\ldots,r(U_{p-1},e),
                     r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                     I_0 = e
                    compose(I_0, TY_1, I_1), \ldots, compose(I_{p-2}, TY_{p-1}, I_{p-1}),
                    process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                    compose(I_p, TY_p, I_{p+1}), \ldots, compose(I_t, TY_t, I_{t+1}),
                     HY = I_{t+1}, r \perp tupling(TXs, TY), compose(HY, TY, Y)
By using applicability condition (2):
 clause 23: r \perp upling(Xs, Y) \leftarrow
                     Xs = [X|TXs].
                     nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                     (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                    minimal(TX_p), \ldots, minimal(TX_t),
                     minimal(U_1), \ldots, minimal(U_{p-1}),
                    r(U_1,e),\ldots,r(U_{p-1},e),
                    r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                    I_0 = e,
                    compose(I_0, TY_1, I_1), \ldots, compose(I_{p-2}, TY_{p-1}, I_{p-1}),
                    compose(I_{p-1}, e, K_1), compose(K_1, e, K_2), \dots, compose(K_{p-2}, e, K_{p-1}),
                    process(HX, HHY), compose(K_{p-1}, HHY, I_p),
                    compose(I_p, TY_p, I_{p+1}), \ldots, compose(I_t, TY_t, I_{t+1}),
                     HY = I_{t+1}, r \perp upling(TXs, TY), compose(HY, TY, Y)
By using applicability conditions (1) and (2):
 clause 24: r 	ext{ } tupling(Xs, Y) \leftarrow
                     Xs = [X|TXs].
                    nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                     (nonMinimal(TX_1); ...; nonMinimal(TX_{p-1})),
                     minimal(TX_p), \ldots, minimal(TX_t),
                     minimal(U_1), \ldots, minimal(U_{p-1}),
                     r(U_1, e), \ldots, r(U_{p-1}, e),
                    r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                    I_0 = e,
                    compose(I_0, e, I_1), \ldots, compose(I_{p-2}, e, I_{p-1}),
                    process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                    compose(I_p, TY_p, I_{p+1}), \ldots, compose(I_t, TY_t, I_{t+1}),
                     HY = I_{t+1}, r \operatorname{tupling}(TXs, TY), compose(HY, TY, TI),
                    compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \dots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                    compose(K_{p-2}, TI, Y)
```

By introducing new, i.e. existentially quantified, variables  $YU_1, \ldots, YU_{p-1}$  in place of some occurrences of e:

```
clause 25 : r \perp upling(Xs, Y) \leftarrow
                         Xs = [X|TXs]
                         nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                         (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                         minimal(TX_p), \ldots, minimal(TX_t),
                         minimal(U_1), \ldots, minimal(U_{p-1}),
                         r(U_1, YU_1), \ldots, r(U_{p-1}, YU_{p-1}),
                         r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                         I_0 = e
                        compose(I_0, YU_1, I_1), \ldots, compose(I_{p-2}, YU_{p-1}, I_{p-1}),
                        process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                        compose(I_p, TY_p, I_{p+1}), \ldots, compose(I_t, TY_t, I_{t+1}),
                         HY = I_{t+1}, r \perp tupling(TXs, TY), compose(HY, TY, TI),
                        compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \dots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                        compose(K_{p-2}, TI, Y)
   By introducing nonMinimal(N) and decompose(N, HX, U_1, \dots, U_{p-1}, TX_p, \dots, TX_t), since
                \exists N: \mathcal{X}.nonMinimal(N) \land decompose(N, HX, U_1, \dots, U_{p-1}, TX_p, \dots, TX_t)
always holds (because N is existentially quantified):
     clause 26: r \pm upling(Xs, Y) \leftarrow
                         Xs = [X|TXs],
                         nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                         (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                         minimal(TX_p), \ldots, minimal(TX_t),
                         minimal(U_1), \ldots, minimal(U_{p-1}),
                         r(U_1, YU_1), \ldots, r(U_{p-1}, YU_{p-1}),
                         nonMinimal(N), decompose(N, HX, U_1, \ldots, U_{p-1}, TX_p, \ldots, TX_t),
                        r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                         I_0 = e,
                        compose(I_0, YU_1, I_1), \ldots, compose(I_{p-2}, YU_{p-1}, I_{p-1}),
                        process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                        compose(I_p, TY_p, I_{p+1}), \ldots, compose(I_t, TY_t, I_{t+1}),
                         HY = I_{t+1}, r \perp tupling(TXs, TY), compose(HY, TY, TI),
                         compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \dots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                        compose(K_{p-2}, TI, Y)
   By duplicating goal decompose(N, HX, U_1, \ldots, U_{p-1}, TX_p, \ldots, TX_t):
     clause 27: r \perp upling(Xs, Y) \leftarrow
                         Xs = [X|TXs],
                         nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                         (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                         minimal(TX_p), \ldots, minimal(TX_t),
                         minimal(U_1), \ldots, minimal(U_{p-1}),
                         r(U_1, YU_1), \ldots, r(U_{p-1}, YU_{p-1}),
                         nonMinimal(N), decompose(N, HX, U_1, \dots, U_{p-1}, TX_p, \dots, TX_t),
                         decompose(N, HX, U_1, \ldots, U_{p-1}, TX_p, \ldots, TX_t),
                        r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                         I_0 = e
                        compose(I_0, YU_1, I_1), \ldots, compose(I_{p-2}, YU_{p-1}, I_{p-1}),
                        process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                        compose(I_p, TY_p, I_{p+1}), \ldots, compose(I_t, TY_t, I_{t+1}),
                         HY = I_{t+1}, r \perp tupling(TXs, TY), compose(HY, TY, TI),
                        compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \dots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                        compose(K_{p-2}, TI, Y)
```

By folding clause 27 using DCLR:

```
clause 28: r \pm upling(Xs, Y) \leftarrow
                        Xs = [X|TXs]
                        nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                        (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                        minimal(TX_p), \ldots, minimal(TX_t),
                        minimal(U_1), \ldots, minimal(U_{p-1}),
                        decompose(N, HX, U_1, \ldots, U_{p-1}, TX_p, \ldots, TX_t),
                        r(TX_1, TY_1), \ldots, r(TX_{p-1}, TY_{p-1}), r(N, HY),
                        r 	ext{-}tupling(TXs, TY), compose(HY, TY, TI),
                        compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \dots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                        compose(K_{p-2}, TI, Y)
   By folding clause 28 using clauses 1 and 2:
     clause 29: r 	ext{ } tupling(Xs, Y) \leftarrow
                        Xs = [X|TXs].
                        nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                        (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                        minimal(TX_p), \ldots, minimal(TX_t),
                        minimal(U_1), \ldots, minimal(U_{p-1}),
                        decompose(N, HX, U_1, \ldots, U_{p-1}, TX_p, \ldots, TX_t),
                        r(TX_1, TY_1), \ldots, r(TX_{p-1}, TY_{p-1}),
                        r \perp tupling([N|TXs], TI),
                        compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \dots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                        compose(K_{p-2}, TI, Y)
   By p-1 times folding clause 29 using clauses 1 and 2:
    clause 30: r \perp tupling(Xs, Y) \leftarrow
                        Xs = [X|TXs],
                        nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                        (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                        minimal(TX_p), \ldots, minimal(TX_t),
                        minimal(U_1), \ldots, minimal(U_{p-1}),
                        decompose(N, HX, U_1, \ldots, U_{p-1}, TX_p, \ldots, TX_t),
                        r 	ext{-tupling}([TX_1, \dots, TX_{p-1}, N|TXs], Y)
   By introducing atoms minimal(U_1), \ldots, minimal(U_t) (with new, i.e. existentially quantified, vari-
ables U_1, \ldots, U_t) in clause 8:
     clause 31: r \perp tupling(Xs, Y) \leftarrow
                        Xs = [X|TXs],
                        nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                        (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                        (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                        minimal(U_1), \ldots, minimal(U_t),
                        r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                        I_0 = e
                        compose(I_0, TY_1, I_1), \ldots, compose(I_{p-2}, TY_{p-1}, I_{p-1}),
                        process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                        compose(I_p, TY_p, I_{p+1}), \ldots, compose(I_t, TY_t, I_{t+1}),
                        HY = I_{t+1}, r \perp upling(TXs, TY), compose(HY, TY, Y)
```

By using applicability condition (3):

```
clause 32: r 	ext{ } tupling(Xs, Y) \leftarrow
                                        Xs = [X|TXs]
                                        nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                                        (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                                        (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                                        minimal(U_1), \ldots, minimal(U_t),
                                        r(U_1,e),\ldots,r(U_t,e),
                                        r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                                        I_0 = e
                                       compose(I_0, TY_1, I_1), \ldots, compose(I_{p-2}, TY_{p-1}, I_{p-1}),
                                       process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                                       compose(I_p, TY_p, I_{p+1}), \ldots, compose(I_t, TY_t, I_{t+1}),
                                        HY = I_{t+1}, r \perp tupling(TXs, TY), compose(HY, TY, Y)
By using applicability condition (2):
  clause 33: r \perp upling(Xs, Y) \leftarrow
                                        Xs = [X|TXs]
                                        nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                                        (nonMinimal(TX_1); \dots; nonMinimal(TX_{p-1})),
                                        (nonMinimal(TX_p); \dots; nonMinimal(TX_t)),
                                        minimal(U_1), \ldots, minimal(U_t),
                                        r(U_1,e),\ldots,r(U_t,e),
                                        r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                                       I_0 = e,
                                       compose(I_0, TY_1, I_1), \ldots, compose(I_{p-2}, TY_{p-1}, I_{p-1}),
                                       compose(I_{p-1}, e, K_1), compose(K_1, e, K_2), \ldots, compose(K_{p-2}, e, K_{p-1}),
                                       process(HX, HHY), compose(K_{p-1}, HHY, K_p),
                                       compose(K_p, e, K_{p+1}), \ldots, compose(K_t, e, K_{t+1}), compose(K_{t+1}, e, I_p),
                                       compose(I_p, TY_p, I_{p+1}), \ldots, compose(I_t, TY_t, I_{t+1}),
                                       HY = I_{t+1}, r \perp tupling(TXs, TY), compose(HY, TY, Y)
By using applicability conditions (1) and (2):
  clause 34: r 	ext{ } 	ext{ }
                                        Xs = [X|TXs],
                                        nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                                        (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                                        (nonMinimal(TX_p); \dots; nonMinimal(TX_t)),
                                        minimal(U_1), \ldots, minimal(U_t),
                                        r(U_1,e),\ldots,r(U_t,e),
                                        r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                                       compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \dots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                                       I_0 = e
                                       compose(I_0, e, I_1), \ldots, compose(I_{p-2}, e, I_{p-1}),
                                       process(HX, HHY), compose(I_{p-1}, HHY, I_p)
                                       compose(I_p, e, I_{p+1}), \ldots, compose(I_t, e, I_{t+1}),
                                        NHY = I_{t+1}
                                        compose(TY_p, TY_{p+1}, K_p), compose(K_p, TY_{p+2}, K_{p+1}), \dots, compose(K_{t-2}, TY_t, K_{t-1}),
                                       compose(K_{p-2}, NHY, TI), compose(TI, K_{t-1}, HY),
                                        r 	ext{-}tupling(TXs, TY), compose(HY, TY, Y)
```

By introducing new, i.e. existentially quantified, variables  $YU_1, \ldots, YU_t$  in place of some occurrences of e:

```
clause 35: r \perp upling(Xs, Y) \leftarrow
                        Xs = [X|TXs]
                        nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                        (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                        (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                        minimal(U_1), \ldots, minimal(U_t),
                        r(U_1, YU_1), \ldots, r(U_t, YU_t),
                        r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                        compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \dots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                        I_0 = e,
                        compose(I_0, YU_1, I_1), \ldots, compose(I_{p-2}, YU_{p-1}, I_{p-1}),
                        process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                        compose(I_p, YU_p, I_{p+1}), \ldots, compose(I_t, YU_t, I_{t+1}),
                        NHY = I_{t+1},
                        compose(TY_p, TY_{p+1}, K_p), compose(K_p, TY_{p+2}, K_{p+1}), \ldots, compose(K_{t-2}, TY_t, K_{t-1}),
                        compose(K_{p-2}, NHY, TI), compose(TI, K_{t-1}, HY),
                        r \perp tupling(TXs, TY), compose(HY, TY, Y)
   By introducing nonMinimal(N) and decompose(N, HX, U_1, \ldots, U_t), since
                         \exists N : \mathcal{X}.nonMinimal(N) \land decompose(N, HX, U_1, \ldots, U_t)
always holds (because N is existentially quantified):
     clause 36: r \pm upling(Xs, Y) \leftarrow
                        Xs = [X|TXs],
                        nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                        (nonMinimal(TX_1); ...; nonMinimal(TX_{p-1})),
                        (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                        minimal(U_1), \ldots, minimal(U_t),
                        r(U_1, YU_1), \ldots, r(U_t, YU_t),
                        nonMinimal(N), decompose(N, HX, U_1, \ldots, U_t),
                        r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                        compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \ldots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                        I_0 = e,
                        compose(I_0, YU_1, I_1), \ldots, compose(I_{p-2}, YU_{p-1}, I_{p-1}),
                        process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                        compose(I_p, YU_p, I_{p+1}), \ldots, compose(I_t, YU_t, I_{t+1}),
                        NHY = I_{t+1},
                        compose(TY_p, TY_{p+1}, K_p), compose(K_p, TY_{p+2}, K_{p+1}), \ldots, compose(K_{t-2}, TY_t, K_{t-1}),
                        compose(K_{p-2}, NHY, TI), compose(TI, K_{t-1}, HY),
                        r 	ext{-}tupling(TXs, TY), compose(HY, TY, Y)
```

By duplicating goal  $decompose(N, HX, U_1, \ldots, U_t)$ :

```
clause 37 : r \perp upling(Xs, Y) \leftarrow
                                                           Xs = [X|TXs]
                                                           nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                                                           (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                                                           (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                                                           minimal(U_1), \ldots, minimal(U_t),
                                                           r(U_1, YU_1), \ldots, r(U_t, YU_t),
                                                           nonMinimal(N), decompose(N, HX, U_1, \ldots, U_t),
                                                           decompose(N, HX, U_1, \ldots, U_t),
                                                           r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                                                          compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \ldots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                                                          I_0 = e
                                                          compose(I_0, YU_1, I_1), \ldots, compose(I_{p-2}, YU_{p-1}, I_{p-1}),
                                                          process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                                                          compose(I_p, YU_p, I_{p+1}), \ldots, compose(I_t, YU_t, I_{t+1}),
                                                           NHY = I_{t+1}
                                                           compose(TY_p, TY_{p+1}, K_p), compose(K_p, TY_{p+2}, K_{p+1}), \ldots, compose(K_{t-2}, TY_t, K_{t-1}),
                                                          compose(K_{p-2}, NHY, TI), compose(TI, K_{t-1}, HY),
                                                           r \perp tupling(TXs, TY), compose(HY, TY, Y)
By folding clause 37 using DCLR:
   clause 38: r \operatorname{Iupling}(Xs, Y) \leftarrow
                                                          Xs = [X|TXs],
                                                           nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                                                           (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                                                           (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                                                           minimal(U_1), \ldots, minimal(U_t),
                                                          decompose(N, HX, U_1, \ldots, U_t),
                                                           r(TX_1, TY_1), \ldots, r(TX_t, TY_t), r(N, NHY),
                                                          compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \dots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                                                          compose(TY_p, TY_{p+1}, K_p), compose(K_p, TY_{p+2}, K_{p+1}), \ldots, compose(K_{t-2}, TY_t, K_{t-1}), \ldots
                                                          compose(K_{p-2}, NHY, TI), compose(TI, K_{t-1}, HY),
                                                           r \perp tupling(TXs, TY), compose(HY, TY, Y)
By using applicability condition (1):
   clause 39 : r 	ext{ } 	ext{ 
                                                           Xs = [X|TXs],
                                                           nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                                                           (nonMinimal(TX_1); ...; nonMinimal(TX_{p-1})),
                                                           (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                                                           minimal(U_1), \ldots, minimal(U_t),
                                                          decompose(N, HX, U_1, \ldots, U_t),
                                                          r(TX_1, TY_1), \ldots, r(TX_t, TY_t), r(N, NHY),
                                                          compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \ldots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                                                           compose(TY_p, TY_{p+1}, K_p), compose(K_p, TY_{p+2}, K_{p+1}), \ldots, compose(K_{t-2}, TY_t, K_{t-1}),
                                                           compose(K_{p-2}, TI_2, Y), compose(NHY, TI_1, TI_2),
                                                          r\_tupling(TXs, TY), compose(K_{t-1}, TY, TI_1)
```

By t - p + 1 times folding clause 39 using clauses 1 and 2:

```
 clause \ 40: \ r \sharp upling(Xs,Y) \leftarrow \\ Xs = [X|TXs], \\ nonMinimal(X), decompose(X,HX,TX_1,\ldots,TX_t), \\ (nonMinimal(TX_1);\ldots;nonMinimal(TX_{p-1})), \\ (nonMinimal(TX_p);\ldots;nonMinimal(TX_t)), \\ minimal(U_1),\ldots,minimal(U_t), \\ decompose(N,HX,U_1,\ldots,U_t), \\ r(TX_1,TY_1),\ldots,r(TX_{p-1},TY_{p-1}),r(N,NHY), \\ compose(TY_1,TY_2,K_1),compose(K_1,TY_3,K_2),\ldots,compose(K_{p-3},TY_{p-1},K_{p-2}), \\ compose(K_{p-2},TI_2,Y),compose(NHY,TI_1,TI_2), \\ r \sharp upling([TX_p,\ldots,TX_t|TXs],TI_1)
```

By folding clause 40 using clauses 1 and 2:

By p-1 times folding clause 41 using clauses 1 and 2:

```
 clause \ 42: \ r \sharp upling(Xs,Y) \leftarrow \\ Xs = [X|TXs], \\ nonMinimal(X), decompose(X,HX,TX_1,\ldots,TX_t), \\ (nonMinimal(TX_1);\ldots;nonMinimal(TX_{p-1})), \\ (nonMinimal(TX_p);\ldots;nonMinimal(TX_t)), \\ minimal(U_1),\ldots,minimal(U_t), \\ decompose(N,HX,U_1,\ldots,U_t), \\ r \sharp upling([TX_1,\ldots,TX_{p-1},N,TX_p,\ldots,TX_t|TXs],TI_1)
```

Clauses 1, 3, 13, 20, 30 and 42 are the clauses of  $P_{r\_tupling}$ . Therefore  $P_{r\_tupling}$  is steadfast wrt  $S_{r\_tupling}$  in S.

To prove that  $P_r$  is steadfast wrt  $S_r$  in  $\{S_{r\_tupling}\}$ , we do a backward proof that we begin with  $P_r$  in TG and from which we try to obtain  $S_r$ .

The procedure  $P_r$  for r in TG is:

$$r(X,Y) \leftarrow r\_tupling([X],Y)$$

By taking the 'completion':

$$\forall X: \mathcal{X}, \forall Y: \mathcal{Y}. \ \mathcal{I}_r(X) \Rightarrow [r(X,Y) \Leftrightarrow r\_tupling([X],Y)]$$

By unfolding the 'completion' above wrt  $r \perp tupling([X], Y)$  using  $S_{r \perp tupling}$ :

$$\forall X: \mathcal{X}, \forall Y: \mathcal{Y}. \quad \mathcal{I}_r(X) \Rightarrow [r(X,Y) \Leftrightarrow \exists Y_1, I_1: \mathcal{Y}. \quad \mathcal{O}_r(X,Y_1) \land I_1 = Y_1 \land Y = I_1]$$

By simplification:

$$\forall X: \mathcal{X}, \forall Y: \mathcal{Y}. \ \mathcal{I}_r(X)) \Rightarrow [r(X,Y) \Leftrightarrow \mathcal{O}_r(X,Y)]$$

We obtain  $S_r$ , so  $P_r$  is steadfast wrt  $S_r$  in  $\{S_{r\_tupling}\}$ . Therefore, TG is also steadfast wrt  $S_r$  in S.

**Theorem 2** The generalization schema  $TG_2$ , which is given below, is correct.

```
TG_2: \langle \ DCRL, \ TG, \ A_{t2}, \ O_{t212}, \ O_{t221} \ \rangle \ \text{where}
A_{t2}: \ (1) \ compose \ \text{is associative}
(2) \ compose \ \text{has } e \ \text{as the left and right identity element, where } e \ \text{appears in } DCRL
(3) \ \forall X: \mathcal{X}. \ \mathcal{I}_r(X) \land minimal(X) \Rightarrow \mathcal{O}_r(X, e)
(4) \ \forall X: \mathcal{X}. \ \mathcal{I}_r(X) \Rightarrow [\neg minimal(X) \Leftrightarrow nonMinimal(X)]
O_{t212}: \ \text{partial evaluation of the conjunction}
process(HX, HY), compose(HY, TY, Y)
results \ \text{in the introduction of a non-recursive relation}
O_{t221}: \ \text{partial evaluation of the conjunction}
process(HX, HY), compose(HY, I_p, I_{p-1})
results \ \text{in the introduction of a non-recursive relation}
```

where the template TG is Logic Program Template 2 in Theorem 1 and the template DCRL is Logic Program Template 3 below:

### Logic Program Template 3

```
\begin{split} \mathbf{r}(\mathbf{X},\mathbf{Y}) &\leftarrow \\ & & \texttt{minimal}(\mathbf{X}), \\ & & \texttt{solve}(\mathbf{X},\mathbf{Y}) \\ \mathbf{r}(\mathbf{X},\mathbf{Y}) &\leftarrow \\ & & \texttt{nonMinimal}(\mathbf{X}), \\ & & & \texttt{decompose}(\mathbf{X},\mathbf{H}\mathbf{X},\mathbf{T}\mathbf{X}_1,\ldots,\mathbf{T}\mathbf{X}_t), \\ & & & & & & & & \\ & & & & & & & & \\ & & & & & & & & \\ & & & & & & & & \\ & & & & & & & & \\ & & & & & & & & \\ & & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & \\ & & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & \\ & & & & \\ & & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\
```

and the specification  $S_r$  of relation r is:

$$\forall X : \mathcal{X}, \forall Y : \mathcal{Y}. \ \mathcal{I}_r(X) \Rightarrow [r(X,Y) \Leftrightarrow \mathcal{O}_r(X,Y)]$$

and the specification  $S_{r\_tupling}$  of relation  $r\_tupling$  is:

```
\forall Xs : list \ of \ \mathcal{X}, \forall Y : \mathcal{Y}. \ (\forall X : \mathcal{X}. \ X \in Xs \Rightarrow \mathcal{I}_r(X)) \Rightarrow [r \ \mathit{fupling}(Xs, Y) \Leftrightarrow (Xs = [] \land Y = e) \\ \lor (Xs = [X_1, \dots, X_q] \land \ \bigwedge_{i=1}^q \mathcal{O}_r(X_i, Y_i) \ \land I_1 = Y_1 \land \ \bigwedge_{i=2}^q \mathcal{O}_c(I_{i-1}, Y_i, I_i) \ \land Y = I_q)]
```

**Proof 2** To prove the correctness of the generalization schema  $TG_2$ , by Definition 10, we have to prove that templates DCRL and TG are equivalent wrt  $S_r$  under the applicability conditions  $A_{t2}$ . By Definition 5, the templates DCRL and TG are equivalent wrt  $S_r$  under the applicability conditions  $A_{t2}$  iff DCRL is equivalent to TG wrt the specification  $S_r$  provided that the conditions in  $A_{t2}$  hold. By Definition 4, DCRL is equivalent to TG wrt the specification  $S_r$  iff the following two conditions hold:

- (a) DCRL is steadfast wrt  $S_r$  in  $S = \{S_{minimal}, S_{nonMinimal}, S_{solve}, S_{decompose}, S_{process}, S_{compose}\}$ , where  $S_{minimal}, S_{nonMinimal}, S_{solve}, S_{decompose}, S_{process}, S_{compose}$  are the specifications of minimal, nonMinimal, solve, decompose, process, compose, which are all the undefined relation names appearing in DCRL.
- (b) TG is also steadfast wrt  $S_r$  in S.

Note that the sets  $\{S_1, \ldots, S_m\}$  and  $\{S'_1, \ldots, S'_t\}$  in Definition 4 are equal to  $\mathcal{S}$  when Q is obtained by tupling generalization of P.

In program transformation, we assume that the input program, here template DCRL, is steadfast wrt  $S_r$  in S, so condition (a) always holds.

To prove equivalence, we have to prove condition (b). We will use the following property of stead-fastness: TG is steadfast wrt  $S_r$  in S if  $P_{r\_tupling}$  is steadfast wrt  $S_{r\_tupling}$  in S, where  $P_{r\_tupling}$  is the procedure for  $r\_tupling$ , and  $P_r$  is steadfast wrt  $S_r$  in  $\{S_{r\_tupling}\}$ , where  $P_r$  is the procedure for r.

To prove that  $P_{r\_tupling}$  is steadfast wrt  $S_{r\_tupling}$  in  $\mathcal{S}$ , we do a constructive forward proof that we begin with  $S_{r\_tupling}$  and from which we try to obtain  $P_{r\_tupling}$ .

If we separate the cases of  $q \ge 1$  by  $q = 1 \lor q \ge 2$ , then  $S_{r\_tupling}$  becomes:

```
 \forall Xs: list \ of \ \mathcal{X}, \forall Y: \mathcal{Y}. \ (\forall X: \mathcal{X}. \ X \in Xs \Rightarrow \mathcal{I}_r(X)) \Rightarrow [r \ \mathit{Jupling}(Xs, Y) \Leftrightarrow (Xs = [] \land Y = e) 
 \lor (Xs = [X_1] \land \mathcal{O}_r(X_1, Y_1) \land Y_1 = I_1 \land Y = I_1) 
 \lor (Xs = [X_1, X_2, \dots, X_q] \land \ \bigwedge_{i=1}^q \mathcal{O}_r(X_i, Y_i) \ \land I_1 = Y_1 \land \ \bigwedge_{i=2}^q \mathcal{O}_c(I_{i-1}, Y_i, I_i) \ \land Y = I_q)]
```

where  $q \geq 2$ .

By using applicability conditions (1) and (2):

```
\forall Xs: list \ of \ \mathcal{X}, \forall Y: \mathcal{Y}. \ (\forall X: \mathcal{X}. \ X \in Xs \Rightarrow \mathcal{I}_r(X)) \Rightarrow [r \ \mathit{fupling}(Xs, Y) \Leftrightarrow (Xs = [] \land Y = e) \\ \lor (Xs = [X_1 | TXs] \land TXs = [] \land \mathcal{O}_r(X_1, Y_1) \land Y_1 = I_1 \land TY = e \land \mathcal{O}_c(I_1, TY, Y)) \\ \lor (Xs = [X_1 | TXs] \land TXs = [X_2, \dots, X_q] \land \bigwedge_{i=1}^q \mathcal{O}_r(X_i, Y_i) \land Y_1 = I_1 \land Y_2 = I_2 \land \bigwedge_{i=3}^q \mathcal{O}_c(I_{i-1}, Y_i, I_i) \land TY = I_q \land \mathcal{O}_c(I_1, TY, Y))]
```

where  $q \geq 2$ .

By folding using  $S_{r\_tupling}$ , and renaming:

```
\forall Xs : list \ of \ \mathcal{X}, \forall Y : \mathcal{Y}. \ (\forall X : \mathcal{X}. \ X \in Xs \Rightarrow \mathcal{I}_r(X)) \Rightarrow [r \, \text{$\pm upling}(Xs, Y) \Leftrightarrow (Xs = [] \land Y = e) \\ \lor (Xs = [X|TXs] \land \mathcal{O}_r(X, HY) \land r \, \text{$\pm upling}(TXs, TY) \land \mathcal{O}_c(HY, TY, Y))]
```

By taking the 'decompletion':

clause 3:  $r ext{ } tupling(Xs, Y) \leftarrow$ 

```
clause 1: r 	ext{-upling}(Xs, Y) \leftarrow Xs = [], Y = e

clause 2: r 	ext{-upling}(Xs, Y) \leftarrow Xs = [X|TXs], r(X, HY),

r 	ext{-upling}(TXs, TY), compose(HY, TY, Y)
```

By unfolding clause 2 wrt r(X, HY) using DCRL, and using the assumption that DCRL is steadfast wrt  $S_r$  in S:

```
Xs = [X|TXs],
minimal(X),
r \exists upling(TXs, TY),
solve(X, HY), compose(HY, TY, Y)
clause \ 4: \ r \exists upling(Xs, Y) \leftarrow
Xs = [X|TXs],
nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
r(TX_1, TY_1), ..., r(TX_t, TY_t),
I_{t+1} = e,
compose(TY_t, I_{t+1}, I_t), ..., compose(TY_p, I_{p+1}, I_p),
process(HX, HHY), compose(HHY, I_p, I_{p-1}),
compose(TY_{p-1}, I_{p-1}, I_{p-2}), ..., compose(TY_1, I_1, I_0),
HY = I_0, r \exists upling(TXs, TY), compose(HY, TY, Y)
```

By introducing

```
(minimal(TX_1) \land \ldots \land minimal(TX_t)) \lor \\ ((minimal(TX_1) \land \ldots \land minimal(TX_{p-1})) \land (nonMinimal(TX_p) \lor \ldots \lor nonMinimal(TX_t))) \lor \\ ((nonMinimal(TX_1) \lor \ldots \lor nonMinimal(TX_{p-1})) \land (minimal(TX_p) \land \ldots \land minimal(TX_t))) \lor \\ ((nonMinimal(TX_1) \lor \ldots \lor nonMinimal(TX_{p-1})) \land (nonMinimal(TX_p) \lor \ldots \lor nonMinimal(TX_t))) \\ in clause 4, using applicability condition (4):
```

```
clause 5: r 	ext{ } 	ext{ } 
                                                             Xs = [X|TXs],
                                                            nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                                                            minimal(TX_1), \ldots, minimal(TX_t),
                                                            r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                                                            I_{t+1}=e,
                                                            compose(TY_t, I_{t+1}, I_t), \ldots, compose(TY_p, I_{p+1}, I_p),
                                                            process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                                                            compose(TY_{p-1}, I_{p-1}, I_{p-2}), \ldots, compose(TY_1, I_1, I_0),
                                                             HY = I_0, r tupling(TXs, TY), compose(HY, TY, Y)
             clause 6: r \perp tupling(Xs, Y) \leftarrow
                                                            Xs = [X|TXs],
                                                            nonMinimal(X), decompose(X, HX, TX_1, \dots, TX_t),
                                                            minimal(TX_1), \ldots, minimal(TX_{p-1}),
                                                            (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                                                            r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                                                            I_{t+1} = e,
                                                            compose(TY_t, I_{t+1}, I_t), \ldots, compose(TY_p, I_{p+1}, I_p),
                                                            process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                                                            compose(TY_{p-1}, I_{p-1}, I_{p-2}), \ldots, compose(TY_1, I_1, I_0),
                                                            HY = I_0, r \operatorname{Jupling}(TXs, TY), compose(HY, TY, Y)
             clause 7: r 	ext{ } 	ext{ } 
                                                            Xs = [X|TXs],
                                                            nonMinimal(X), decompose(X, HX, TX_1, TX_2),
                                                            (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                                                            minimal(TX_p), \ldots, minimal(TX_t),
                                                            r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                                                            I_{t+1} = e,
                                                            compose(TY_t, I_{t+1}, I_t), \ldots, compose(TY_p, I_{p+1}, I_p),
                                                            process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                                                            compose(TY_{p-1}, I_{p-1}, I_{p-2}), \ldots, compose(TY_1, I_1, I_0),
                                                            HY = I_0, r \perp upling(TXs, TY), compose(HY, TY, Y)
             clause 8: r 	ext{-tupling}(Xs, Y) \leftarrow
                                                            Xs = [X|TXs],
                                                            nonMinimal(X), decompose(X, HX, TX_1, TX_2),
                                                            (nonMinimal(TX_1); ...; nonMinimal(TX_{p-1})),
                                                            (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                                                            r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                                                            I_{t+1} = e
                                                            compose(TY_t, I_{t+1}, I_t), \ldots, compose(TY_p, I_{p+1}, I_p),
                                                            process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                                                            compose(TY_{p-1}, I_{p-1}, I_{p-2}), \ldots, compose(TY_1, I_1, I_0),
                                                            HY = I_0, r \perp tupling(TXs, TY), compose(HY, TY, Y)
          By t times unfolding clause 5 wrt r(TX_1, TY_1), \ldots, r(TX_t, TY_t) using DCRL, and simplifying using
condition (4):
             clause 9: r \perp tupling(Xs, Y) \leftarrow
                                                             Xs = [X|TXs],
                                                            nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                                                            minimal(TX_1), \ldots, minimal(TX_t),
                                                            minimal(TX_1), \ldots, minimal(TX_t),
                                                            solve(TX_1, TY_1), \ldots, solve(TX_t, TY_t),
                                                            I_{t+1} = e
                                                            compose(TY_t, I_{t+1}, I_t), \ldots, compose(TY_p, I_{p+1}, I_p),
                                                            process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                                                            compose(TY_{p-1}, I_{p-1}, I_{p-2}), \ldots, compose(TY_1, I_1, I_0),
                                                            HY = I_0, r \perp tupling(TXs, TY), compose(HY, TY, Y)
```

```
By using applicability condition (3):
            clause 10 : r 	ext{ } 	ext{ 
                                                                                                                                                                                                                                     Xs = [X|TXs].
                                                                                                                                                                                                                                       nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                                                                                                                                                                                                                                       minimal(TX_1), \ldots, minimal(TX_t),
```

 $minimal(TX_1), \ldots, minimal(TX_t),$  $solve(TX_1, e), \ldots, solve(TX_t, e),$  $I_{t+1} = e,$  $compose(e, I_{t+1}, I_t), \ldots, compose(e, I_{p+1}, I_p),$  $process(HX, HHY), compose(HHY, I_p, I_{p-1}),$ 

 $compose(e, I_{p-1}, I_{p-2}), \ldots, compose(e, I_1, I_0),$ 

 $HY = I_0, r \perp tupling(TXs, TY), compose(HY, TY, Y)$ 

By deleting one of the  $minimal(TX_1), \ldots, minimal(TX_t)$  atoms in clause 10:

```
clause 11: r 	ext{-}upling(Xs, Y) \leftarrow
                   Xs = [X|TXs],
                    nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                    minimal(TX_1), \ldots, minimal(TX_t),
                   solve(TX_1, e), \ldots, solve(TX_t, e),
                   I_{t+1} = e,
                   compose(e, I_{t+1}, I_t), \ldots, compose(e, I_{p+1}, I_p),
                   process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                   compose(e, I_{p-1}, I_{p-2}), \ldots, compose(e, I_1, I_0),
                   HY = I_0, r \operatorname{Iupling}(TXs, TY), compose(HY, TY, Y)
```

By using applicability condition (2):

```
clause 12: r \perp tupling(Xs, Y) \leftarrow
                    Xs = [X|TXs],
                   nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                    minimal(TX_1), \ldots, minimal(TX_t),
                   solve(TX_1, e), \ldots, solve(TX_t, e),
                   I_{t+1} = e,
                   I_t = I_{t+1}, \ldots, I_p = I_{p+1},
                   process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                   I_{p-2} = I_{p-1}, \ldots, I_0 = I_1,
                   HY = I_0, r \perp tupling(TXs, TY), compose(HY, TY, Y)
```

By simplification:

```
clause 13: r \perp tupling(Xs, Y) \leftarrow
                  Xs = [X|TXs],
                  nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                  minimal(TX_1), \ldots, minimal(TX_t),
                  r \perp tupling(TXs, TY),
                 process(HX, HY), compose(HY, TY, Y)
```

By p-1 times unfolding clause 6 wrt  $r(TX_1, TY_1), \ldots, r(TX_{p-1}, TY_{p-1})$  using DCRL, and simplifying using condition (4):

```
clause 14: r \perp upling(Xs, Y) \leftarrow
                    Xs = [X|TXs]
                    nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                    minimal(TX_1), \ldots, minimal(TX_{p-1}),
                    (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                    minimal(TX_1), \ldots, minimal(TX_{p-1}),
                    solve(TX_1, TY_1), \ldots, solve(TX_{p-1}, TY_{p-1}),
                    r(TX_p, TY_p), \ldots, r(TX_t, TY_t)
                    I_{t+1} = e,
                    compose(TY_t, I_{t+1}, I_t), \ldots, compose(TY_p, I_{p+1}, I_p),
                    process(HX, HY), compose(HY, I_p, I_{p-1}),
                    compose(TY_{p-1}, I_{p-1}, I_{p-2}), \ldots, compose(TY_1, I_1, I_0),
                    HY = I_0, r \perp tupling(TXs, TY), compose(HY, TY, Y)
By deleting one of the minimal(TX_1), \ldots, minimal(TX_{p-1}) atoms in clause 14:
 clause 15: r 	ext{tupling}(Xs, Y) \leftarrow
                    Xs = [X|TXs]
                    nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                    minimal(TX_1), \ldots, minimal(TX_{p-1}),
                    (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                    solve(TX_1, TY_1), \ldots, solve(TX_{p-1}, TY_{p-1}),
                    r(TX_p, TY_p), \ldots, r(TX_t, TY_t)
                    I_{t+1} = e
                    compose(TY_t, I_{t+1}, I_t), \ldots, compose(TY_p, I_{p+1}, I_p),
                    process(HX, HY), compose(HY, I_p, I_{p-1}),
                    compose(TY_{p-1}, I_{p-1}, I_{p-2}), \ldots, compose(TY_1, I_1, I_0),
                    HY = I_0, r \perp tupling(TXs, TY), compose(HY, TY, Y)
By rewriting clause 15 using applicability conditions (1) and (2):
 clause 16: r \pm upling(Xs, Y) \leftarrow
                    Xs = [X|TXs].
                    nonMinimal(X), decompose(X, HX, TX_1, \dots, TX_t),
                    minimal(TX_1), \ldots, minimal(TX_{p-1}),
                    (nonMinimal(TX_n); \ldots; nonMinimal(TX_t)),
                    solve(TX_1, TY_1), \ldots, solve(TX_{p-1}, TY_{p-1}),
                    r(TX_p, TY_p), \ldots, r(TX_t, TY_t)
                    I_0 = e,
                    compose(I_0, TY_1, I_1), \ldots, compose(I_{p-2}, TY_{p-1}, I_{p-1}),
                    process(HX, HHY), compose(I_{p-1}, HHY, I_p), HY = I_p,
                    compose(TY_p, TY_{p+1}, I_{p+1}),
                    compose(I_{p+1}, TY_{p+2}, I_{p+2}), \ldots, compose(I_{t-1}, TY_t, I_t),
                    r \perp upling(TXs, TTY), compose(I_t, TTY, TY),
                    compose(HY, TY, Y)
By t-p times folding clause 16 using clauses 1 and 2:
 clause 17: r 	ext{ } tupling(Xs, Y) \leftarrow
                    Xs = [X|TXs],
                    nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                    minimal(TX_1), \ldots, minimal(TX_{p-1}),
                    (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                    solve(TX_1, TY_1), \ldots, solve(TX_{p-1}, TY_{p-1}),
                    r \perp tupling([TX_p, \ldots, TX_t | TXs], TY),
                    I_0 = e
                    compose(I_0, TY_1, I_1), \ldots, compose(I_{p-2}, TY_{p-1}, I_{p-1}),
                    process(HX, HHY), compose(I_{p-1}, HHY, I_p), HY = I_p,
                    compose(HY, TY, Y)
```

By using applicability condition (3):

```
clause 18: r \perp upling(Xs, Y) \leftarrow
                        Xs = [X|TXs]
                        nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                        minimal(TX_1), \ldots, minimal(TX_{p-1}),
                        (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                        solve(TX_1, e), \ldots, solve(TX_{p-1}, e),
                        r \operatorname{tupling}([TX_p, \ldots, TX_t | TXs], TY),
                        I_0 = e,
                        compose(I_0, e, I_1), \ldots, compose(I_{p-2}, e, I_{p-1}),
                        process(HX, HHY), compose(I_{p-1}, HHY, I_p), HY = I_p,
                        compose(HY, TY, Y)
   By using applicability condition (2):
     clause 19: r \perp upling(Xs, Y) \leftarrow
                        Xs = [X|TXs],
                        nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                        minimal(TX_1), \ldots, minimal(TX_{p-1}),
                        (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                        solve(TX_1, e), \ldots, solve(TX_{p-1}, e),
                        r 	ext{-}tupling([TX_p, \ldots, TX_t | TXs], TY),
                        I_0 = e,
                        I_1 = I_0, \ldots, I_{p-1} = I_{p-2},
                        process(HX, HHY), compose(I_{p-1}, HHY, I_p), HY = I_p,
                        compose(HY, TY, Y)
   By simplification:
    clause 20 : r \pm upling(Xs, Y) \leftarrow
                        Xs = [X|TXs],
                        nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                        minimal(TX_1), \ldots, minimal(TX_{p-1}),
                        (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                        r 	ext{-}tupling([TX_p, \ldots, TX_t|TXs], TY),
                        process(HX, HY), compose(HY, TY, Y)
   By introducing atoms minimal(U_1), \ldots, minimal(U_{p-1}) (with new, i.e. existentially quantified, vari-
ables U_1, \ldots, U_{p-1} in clause 7:
     clause 21: r 	ext{ } tupling(Xs, Y) \leftarrow
                        Xs = [X|TXs],
                        nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                        (nonMinimal(TX_1); ...; nonMinimal(TX_{p-1})),
                        minimal(TX_p), \ldots, minimal(TX_t),
                        minimal(U_1), \ldots, minimal(U_{p-1}),
                        r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                        I_{t+1} = e,
                        compose(TY_t, I_{t+1}, I_t), \ldots, compose(TY_p, I_{p+1}, I_p),
                        process(HX, HY), compose(HY, I_p, I_{p-1}),
                        compose(TY_{p-1}, I_{p-1}, I_{p-2}), \ldots, compose(TY_1, I_1, I_0),
```

By using applicability condition (3):

 $HY = I_0, r \operatorname{Iupling}(TXs, TY), compose(HY, TY, Y)$ 

```
clause 22: r \perp upling(Xs, Y) \leftarrow
                     Xs = [X|TXs]
                     nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                     (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                    minimal(TX_p), \ldots, minimal(TX_t),
                     minimal(U_1), \ldots, minimal(U_{p-1}),
                     r(U_1,e),\ldots,r(U_{p-1},e),
                     r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                     I_{t+1} = e
                    compose(TY_t, I_{t+1}, I_t), \ldots, compose(TY_p, I_{p+1}, I_p),
                    process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                    compose(TY_{p-1}, I_{p-1}, I_{p-2}), \ldots, compose(TY_1, I_1, I_0),
                     HY = I_0, r \perp tupling(TXs, TY), compose(HY, TY, Y)
By using applicability condition (2):
 clause 23: r \perp upling(Xs, Y) \leftarrow
                     Xs = [X|TXs].
                     nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                     (nonMinimal(TX_1); \ldots; nonMinimal(TX_{n-1})),
                    minimal(TX_p), \ldots, minimal(TX_t),
                     minimal(U_1), \ldots, minimal(U_{p-1}),
                     r(U_1,e),\ldots,r(U_{p-1},e),
                     r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                     I_{t+1} = e,
                    compose(TY_t, I_{t+1}, I_t), \ldots, compose(TY_p, I_{p+1}, I_p),
                    process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                    compose(e, I_{p-1}, K_1), compose(e, K_1, K_2), \ldots, compose(e, K_{p-2}, K_{p-1}),
                    compose(TY_{p-1}, K_{p-1}, I_{p-2}), \ldots, compose(TY_1, I_1, I_0),
                     HY = I_0, r \perp upling(TXs, TY), compose(HY, TY, Y)
By using applicability conditions (1) and (2):
 clause 24: r 	ext{ } tupling(Xs, Y) \leftarrow
                     Xs = [X|TXs].
                    nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                     (nonMinimal(TX_1); ...; nonMinimal(TX_{p-1})),
                     minimal(TX_p), \ldots, minimal(TX_t),
                     minimal(U_1), \ldots, minimal(U_{p-1}),
                     r(U_1, e), \ldots, r(U_{p-1}, e),
                    r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                    I_{t+1} = e,
                    compose(TY_t, I_{t+1}, I_t), \ldots, compose(TY_p, I_{p+1}, I_p),
                    process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                    compose(e, I_{p-1}, I_{p-2}), \ldots, compose(e, I_1, I_0),
                     HY = I_0, r \perp tupling(TXs, TY), compose(HY, TY, TI),
                    compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \dots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                    compose(K_{p-2}, TI, Y)
```

By introducing new, i.e. existentially quantified, variables  $YU_1, \ldots, YU_{p-1}$  in place of some occurrences of e:

```
clause 25 : r \perp upling(Xs, Y) \leftarrow
                         Xs = [X|TXs]
                         nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                         (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                         minimal(TX_p), \ldots, minimal(TX_t),
                         minimal(U_1), \ldots, minimal(U_{n-1}),
                         r(U_1, YU_1), \ldots, r(U_{p-1}, YU_{p-1}),
                         r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                         I_{t+1} = e
                        compose(TY_t, I_{t+1}, I_t), \ldots, compose(TY_p, I_{p+1}, I_p),
                        process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                        compose(YU_{p-1}, I_{p-1}, I_{p-2}), \ldots, compose(YU_1, I_1, I_0),
                         HY = I_0, r \perp tupling(TXs, TY), compose(HY, TY, TI),
                        compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \ldots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                        compose(K_{p-2}, TI, Y)
   By introducing nonMinimal(N) and decompose(N, HX, U_1, \dots, U_{p-1}, TX_p, \dots, TX_t), since
                \exists N: \mathcal{X}.nonMinimal(N) \land decompose(N, HX, U_1, \dots, U_{p-1}, TX_p, \dots, TX_t)
always holds (because N is existentially quantified):
     clause 26: r \pm upling(Xs, Y) \leftarrow
                         Xs = [X|TXs],
                         nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                         (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                         minimal(TX_p), \ldots, minimal(TX_t),
                         minimal(U_1), \ldots, minimal(U_{p-1}),
                         r(U_1, YU_1), \ldots, r(U_{p-1}, YU_{p-1}),
                         nonMinimal(N), decompose(N, HX, U_1, \ldots, U_{p-1}, TX_p, \ldots, TX_t),
                        r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                         I_{t+1} = e,
                        compose(TY_t, I_{t+1}, I_t), \ldots, compose(TY_p, I_{p+1}, I_p),
                        process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                        compose(Y U_{p-1}, I_{p-1}, I_{p-2}), \ldots, compose(Y U_1, I_1, I_0),
                         HY = I_0, r \perp tupling(TXs, TY), compose(HY, TY, TI),
                         compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \dots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                        compose(K_{p-2}, TI, Y)
   By duplicating goal decompose(N, HX, U_1, \ldots, U_{p-1}, TX_p, \ldots, TX_t):
     clause 27: r \perp upling(Xs, Y) \leftarrow
                         Xs = [X|TXs],
                         nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                         (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                         minimal(TX_p), \ldots, minimal(TX_t),
                         minimal(U_1), \ldots, minimal(U_{n-1}),
                         r(U_1, YU_1), \ldots, r(U_{p-1}, YU_{p-1}),
                         nonMinimal(N), decompose(N, HX, U_1, \dots, U_{p-1}, TX_p, \dots, TX_t),
                         decompose(N, HX, U_1, \ldots, U_{p-1}, TX_p, \ldots, TX_t),
                        r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                         I_{t+1} = e,
                        compose(TY_t, I_{t+1}, I_t), \ldots, compose(TY_p, I_{p+1}, I_p),
                        process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                        compose(Y U_{p-1}, I_{p-1}, I_{p-2}), \ldots, compose(Y U_1, I_1, I_0),
                         HY = I_0, r \perp tupling(TXs, TY), compose(HY, TY, TI),
                        compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \ldots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                        compose(K_{p-2}, TI, Y)
```

By folding clause 27 using DCRL:

```
clause 28: r \pm upling(Xs, Y) \leftarrow
                        Xs = [X|TXs]
                        nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                        (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                        minimal(TX_p), \ldots, minimal(TX_t),
                        minimal(U_1), \ldots, minimal(U_{p-1}),
                        decompose(N, HX, U_1, \ldots, U_{p-1}, TX_p, \ldots, TX_t),
                        r(TX_1, TY_1), \ldots, r(TX_{p-1}, TY_{p-1}), r(N, HY),
                        r 	ext{-}tupling(TXs, TY), compose(HY, TY, TI),
                        compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \dots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                        compose(K_{p-2}, TI, Y)
   By folding clause 28 using clauses 1 and 2:
     clause 29: r 	ext{ } tupling(Xs, Y) \leftarrow
                        Xs = [X|TXs].
                        nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                        (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                        minimal(TX_p), \ldots, minimal(TX_t),
                        minimal(U_1), \ldots, minimal(U_{p-1}),
                        decompose(N, HX, U_1, \ldots, U_{p-1}, TX_p, \ldots, TX_t),
                        r(TX_1, TY_1), \ldots, r(TX_{p-1}, TY_{p-1}),
                        r \perp tupling([N|TXs], TI),
                        compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \ldots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                        compose(K_{p-2}, TI, Y)
   By p-1 times folding clause 29 using clauses 1 and 2:
    clause 30: r \perp tupling(Xs, Y) \leftarrow
                        Xs = [X|TXs],
                        nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                        (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                        minimal(TX_p), \ldots, minimal(TX_t),
                        minimal(U_1), \ldots, minimal(U_{p-1}),
                        decompose(N, HX, U_1, \ldots, U_{p-1}, TX_p, \ldots, TX_t),
                        r 	ext{-tupling}([TX_1, \dots, TX_{p-1}, N|TXs], Y)
   By introducing atoms minimal(U_1), \ldots, minimal(U_t) (with new, i.e. existentially quantified, vari-
ables U_1, \ldots, U_t) in clause 8:
     clause 31: r \perp tupling(Xs, Y) \leftarrow
                        Xs = [X|TXs],
                        nonMinimal(X), decompose(X, HX, TX_1, TX_2),
                        (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                        (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                        minimal(U_1), \ldots, minimal(U_t),
                        r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                        I_{t+1} = e,
                        compose(TY_t, I_{t+1}, I_t), \ldots, compose(TY_p, I_{p+1}, I_p),
                        process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                        compose(TY_{p-1}, I_{p-1}, I_{p-2}), \ldots, compose(TY_1, I_1, I_0),
                        HY = I_0, r \perp tupling(TXs, TY), compose(HY, TY, Y)
```

By using applicability condition (3):

```
clause 32: r 	ext{ } tupling(Xs, Y) \leftarrow
                    Xs = [X|TXs]
                    nonMinimal(X), decompose(X, HX, TX_1, TX_2),
                    (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                    (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                    minimal(U_1), \ldots, minimal(U_t),
                    r(U_1,e),\ldots,r(U_t,e),
                    r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                    I_{t+1} = e
                    compose(TY_t, I_{t+1}, I_t), \ldots, compose(TY_p, I_{p+1}, I_p),
                    process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                    compose(TY_{p-1}, I_{p-1}, I_{p-2}), \ldots, compose(TY_1, I_1, I_0),
                    HY = I_0, r \perp tupling(TXs, TY), compose(HY, TY, Y)
By using applicability condition (2):
 clause 33: r \perp upling(Xs, Y) \leftarrow
                    Xs = [X|TXs].
                    nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                    (nonMinimal(TX_1); \dots; nonMinimal(TX_{p-1})),
                    (nonMinimal(TX_p); \dots; nonMinimal(TX_t)),
                    minimal(U_1), \ldots, minimal(U_{p-1}),
                    r(U_1,e),\ldots,r(U_t,e),
                    r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                    I_{t+1} = e,
                    compose(TY_t, I_{t+1}, I_t), \ldots, compose(TY_p, I_{p+1}, I_p),
                    compose(e, I_p, K_{t+1}),
                    compose(e, K_{t+1}, K_t), \ldots, compose(e, K_{p+1}, K_p),
                    process(HX, HHY), compose(HHY, K_p, K_{p-1}),
                    compose(e, K_{p-1}, K_{p-2}), \ldots, compose(e, K_1, K_0),
                    compose(e, K_0, I_{p-1}),
                    compose(TY_{p-1}, I_{p-1}, I_{p-2}), \ldots, compose(TY_1, I_1, I_0),
                    HY = I_0, r \perp tupling(TXs, TY), compose(HY, TY, Y)
By using applicability conditions (1) and (2):
 clause 34: r \perp upling(Xs, Y) \leftarrow
                    Xs = [X|TXs],
                    nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                    (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                    (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                    minimal(U_1), \ldots, minimal(U_t),
                    r(U_1,e),\ldots,r(U_t,e),
                    r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                    I_{t+1} = e,
                    compose(e, I_{t+1}, I_t), \ldots, compose(e, I_{p+1}, I_p),
                    process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                    compose(e, I_{p-1}, I_{p-2}), \ldots, compose(e, I_1, I_0),
                    NHY = I_0,
                    compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \dots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                    compose(TY_p, TY_{p+1}, K_p), compose(K_p, TY_{p+2}, K_{p+1}), \ldots, compose(K_{t-2}, TY_t, K_{t-1}),
                    compose(K_{p-2}, NHY, TI), compose(TI, K_{t-1}, HY),
                    r \perp tupling(TXs, TY), compose(HY, TY, Y)
```

By introducing new, i.e. existentially quantified, variables  $YU_1, \ldots, YU_t$  in place of some occurrences of e:

```
clause 35: r \perp upling(Xs, Y) \leftarrow
                        Xs = [X|TXs]
                        nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                        (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                        (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                        minimal(U_1), \ldots, minimal(U_t),
                        r(U_1, YU_1), \ldots, r(U_t, YU_t),
                        r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                        I_{t+1} = e,
                        compose(YU_t, I_{t+1}, I_t), \ldots, compose(YU_p, I_{p+1}, I_p),
                        process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                        compose(Y U_{p-1}, I_{p-1}, I_{p-2}), \ldots, compose(Y U_1, I_1, I_0),
                        NHY = I_0,
                        compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \dots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                        compose(TY_p, TY_{p+1}, K_p), compose(K_p, TY_{p+2}, K_{p+1}), \dots, compose(K_{t-2}, TY_t, K_{t-1}),
                        compose(K_{p-2}, NHY, TI), compose(TI, K_{t-1}, HY),
                        r \perp tupling(TXs, TY), compose(HY, TY, Y)
   By introducing nonMinimal(N) and decompose(N, HX, U_1, \ldots, U_t), since
                         \exists N : \mathcal{X}.nonMinimal(N) \land decompose(N, HX, U_1, \ldots, U_t)
always holds (because N is existentially quantified):
     clause 36: r \pm upling(Xs, Y) \leftarrow
                        Xs = [X|TXs],
                        nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                        (nonMinimal(TX_1); ...; nonMinimal(TX_{p-1})),
                        (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                        minimal(U_1), \ldots, minimal(U_t),
                        r(U_1, YU_1), \ldots, r(U_t, YU_t),
                        nonMinimal(N), decompose(N, HX, U_1, \ldots, U_t),
                        r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                        I_{t+1} = e,
                        compose(YU_t, I_{t+1}, I_t), \ldots, compose(YU_p, I_{p+1}, I_p),
                        process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                        compose(Y U_{p-1}, I_{p-1}, I_{p-2}), \ldots, compose(Y U_1, I_1, I_0),
                        NHY = I_0,
                        compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \ldots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                        compose(TY_p, TY_{p+1}, K_p), compose(K_p, TY_{p+2}, K_{p+1}), \ldots, compose(K_{t-2}, TY_t, K_{t-1}),
                        compose(K_{p-2}, NHY, TI), compose(TI, K_{t-1}, HY),
                        r \perp tupling(TXs, TY), compose(HY, TY, Y)
```

By duplicating goal  $decompose(N, HX, U_1, \ldots, U_t)$ :

```
clause 37 : r \perp upling(Xs, Y) \leftarrow
                                                           Xs = [X|TXs]
                                                           nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                                                           (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                                                           (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                                                           minimal(U_1), \ldots, minimal(U_t),
                                                           decompose(N, HX, U_1, \ldots, U_t),
                                                           r(U_1, YU_1), \ldots, r(U_t, YU_t),
                                                           nonMinimal(N), decompose(N, HX, U_1, \ldots, U_t),
                                                           r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                                                           I_{t+1} = e,
                                                          compose(YU_t, I_{t+1}, I_t), \ldots, compose(YU_p, I_{p+1}, I_p),
                                                          process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                                                          compose(YU_{p-1}, I_{p-1}, I_{p-2}), \ldots, compose(YU_1, I_1, I_0),
                                                           NHY = I_0,
                                                          compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \ldots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                                                           compose(TY_p, TY_{p+1}, K_p), compose(K_p, TY_{p+2}, K_{p+1}), \ldots, compose(K_{t-2}, TY_t, K_{t-1}),
                                                          compose(K_{p-2}, NHY, TI), compose(TI, K_{t-1}, HY),
                                                           r \perp tupling(TXs, TY), compose(HY, TY, Y)
By folding clause 37 using DCRL:
   clause 38: r \operatorname{Iupling}(Xs, Y) \leftarrow
                                                           Xs = [X|TXs],
                                                           nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                                                           (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                                                           (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                                                           minimal(U_1), \ldots, minimal(U_t),
                                                          decompose(N, HX, U_1, \ldots, U_t),
                                                           r(TX_1, TY_1), \ldots, r(TX_t, TY_t), r(N, NHY),
                                                          compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \dots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                                                          compose(TY_p, TY_{p+1}, K_p), compose(K_p, TY_{p+2}, K_{p+1}), \ldots, compose(K_{t-2}, TY_t, K_{t-1}), \ldots
                                                          compose(K_{p-2}, NHY, TI), compose(TI, K_{t-1}, HY),
                                                           r \perp tupling(TXs, TY), compose(HY, TY, Y)
By using applicability condition (1):
   clause 39 : r 	ext{ } 	ext{ 
                                                           Xs = [X|TXs],
                                                           nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                                                           (nonMinimal(TX_1); ...; nonMinimal(TX_{p-1})),
                                                           (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                                                           minimal(U_1), \ldots, minimal(U_t),
                                                          decompose(N, HX, U_1, \ldots, U_t),
                                                          r(TX_1, TY_1), \ldots, r(TX_t, TY_t), r(N, NHY),
                                                          compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \ldots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                                                           compose(TY_p, TY_{p+1}, K_p), compose(K_p, TY_{p+2}, K_{p+1}), \ldots, compose(K_{t-2}, TY_t, K_{t-1}),
                                                           compose(K_{p-2}, TI_2, Y), compose(NHY, TI_1, TI_2),
                                                          r\_tupling(TXs, TY), compose(K_{t-1}, TY, TI_1)
```

By t - p + 1 times folding clause 39 using clauses 1 and 2:

```
clause 40 : r \perp upling(Xs, Y) \leftarrow
                                                   Xs = [X|TXs]
                                                   nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                                                   (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                                                   (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                                                   minimal(U_1), \ldots, minimal(U_t),
                                                   decompose(N, HX, U_1, \ldots, U_t)
                                                   r(TX_1, TY_1), \ldots, r(TX_{p-1}, TY_{p-1}), r(N, NHY),
                                                   compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \dots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                                                   compose(K_{p-2}, TI_2, Y), compose(NHY, TI_1, TI_2),
                                                   r \perp tupling([TX_p, \ldots, TX_t | TX_s], TI_1)
By folding clause 40 using clauses 1 and 2:
   clause 41: r \perp upling(Xs, Y) \leftarrow
                                                   Xs = [X|TXs].
                                                   nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                                                   (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                                                   (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                                                   minimal(U_1), \ldots, minimal(U_t)
                                                  decompose(N, HX, U_1, \ldots, U_t),
                                                   r(TX_1, TY_1), \ldots, r(TX_{p-1}, TY_{p-1}),
                                                  compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \ldots, compose(K_{p-3}, TY_{p-1}, K_{p-2}), \ldots, compose(K_{p-3}, TY_{p-1}, K_{p-2}, K_{p-2}), \ldots, compose(K_{p-3}, TY_{p-1}, K_{p-2}, K_{p-2}, K_{p-2}), \ldots, compose(K_{p-3}, TY_{p-1}, K_{p-2}, 
                                                   compose(K_{n-2}, TI_2, Y),
                                                  r 	ext{-}tupling([N, TX_p, \ldots, TX_t | TXs], TI_1)
By p-1 times folding clause 41 using clauses 1 and 2:
  clause 42: r \perp tupling(Xs, Y) \leftarrow
                                                   Xs = [X|TXs],
                                                   nonMinimal(X), decompose(X, HX, TX_1, \dots, TX_t),
                                                   (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                                                   (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                                                   minimal(U_1), \ldots, minimal(U_t),
                                                   decompose(N, HX, U_1, \ldots, U_t),
```

To prove that  $P_r$  is steadfast wrt  $S_r$  in  $\{S_{r\_tupling}\}$ , we do a backward proof that we begin with  $P_r$  in TG and from which we try to obtain  $S_r$ .

The procedure  $P_r$  for r in TG is:

$$r(X,Y) \leftarrow r\_tupling([X],Y)$$

By taking the 'completion':

$$\forall X: \mathcal{X}, \forall Y: \mathcal{Y}. \ \mathcal{I}_r(X) \Rightarrow [r(X,Y) \Leftrightarrow r \bot upling([X],Y)]$$

By unfolding the 'completion' above wrt  $r\_tupling([X], Y)$  using  $S_{r\_tupling}$ :

$$\forall X: \mathcal{X}, \forall Y: \mathcal{Y}. \ \mathcal{I}_r(X) \Rightarrow [r(X,Y) \Leftrightarrow \exists Y_1, I_1: \mathcal{Y}. \ \mathcal{O}_r(X,Y_1) \land I_1 = Y_1 \land Y = I_1]$$

By simplification:

 $S_{r\_tupling}$  in S

$$\forall X : \mathcal{X}, \forall Y : \mathcal{Y}. \ \mathcal{I}_r(X)) \Rightarrow [r(X,Y) \Leftrightarrow \mathcal{O}_r(X,Y)]$$

We obtain  $S_r$ , so  $P_r$  is steadfast wrt  $S_r$  in  $\{S_{r\_tupling}\}$ . Therefore, TG is also steadfast wrt  $S_r$  in S.

# 3 Proofs of the Descending Generalization Schemas

**Theorem 3** The generalization schema  $DG_1$ , which is given below, is correct.

```
DG_1: \left\langle \begin{array}{c} DCLR, DGLR, A_{dg1}, O_{dg112}, O_{dg121} \right\rangle \text{ where} \\ A_{dg1}: (1) \ compose \ \text{is associative} \\ (2) \ compose \ \text{has} \ e \ \text{as} \ \text{the left identity element}, \\ \text{where} \ e \ \text{appears in} \ DCLR \ \text{and} \ DGLR \\ O_{dg112}: \ - \ compose \ \text{has} \ e \ \text{as} \ \text{the right identity element}, \\ \text{where} \ e \ \text{appears in} \ DCLR \ \text{and} \ DGLR \\ \text{and} \ \mathcal{I}_r(X) \wedge minimal(X) \Rightarrow \mathcal{O}_r(X, e) \\ \text{- partial evaluation of the conjunction} \\ process(HX, HY), compose(A_{p-1}, HY, A_p) \\ \text{results in the introduction of a non-recursive relation} \\ O_{dg121}: \ - \ \text{partial evaluation of the conjunction} \\ process(HX, HY), compose(I_{p-1}, HY, I_p) \\ \text{results in the introduction of a non-recursive relation} \\ \end{array}
```

where the template DCLR is Logic Program Template 1 in Section 2 and the template DGLR is Logic Program Template 4 below:

### Logic Program Template 4

```
\begin{split} \mathbf{r}(\mathtt{X},\mathtt{Y}) &\leftarrow \\ \mathbf{r}\_\mathtt{descending}_1(\mathtt{X},\mathtt{Y},\mathtt{e}) \\ \mathbf{r}\_\mathtt{descending}_1(\mathtt{X},\mathtt{Y},\mathtt{A}) &\leftarrow \\ &\min(\mathtt{X}), \\ &\operatorname{solve}(\mathtt{X},\mathtt{S}), \operatorname{compose}(\mathtt{A},\mathtt{S},\mathtt{Y}) \\ \mathbf{r}\_\mathtt{descending}_1(\mathtt{X},\mathtt{Y},\mathtt{A}) &\leftarrow \\ &\operatorname{nonMinimal}(\mathtt{X}), \\ &\operatorname{decompose}(\mathtt{X},\mathtt{HX},\mathtt{TX}_1,\ldots,\mathtt{TX}_t), \\ &\operatorname{compose}(\mathtt{A},\mathtt{e},\mathtt{A}_0), \\ &\mathbf{r}\_\mathtt{descending}_1(\mathtt{TX}_1,\mathtt{A}_1,\mathtt{A}_0),\ldots,\mathbf{r}\_\mathtt{descending}_1(\mathtt{TX}_{p-1},\mathtt{A}_{p-1},\mathtt{A}_{p-2}), \\ &\operatorname{process}(\mathtt{HX},\mathtt{HY}), \operatorname{compose}(\mathtt{A}_{p-1},\mathtt{HY},\mathtt{A}_p), \\ &\mathbf{r}\_\mathtt{descending}_1(\mathtt{TX}_p,\mathtt{A}_{p+1},\mathtt{A}_p),\ldots,\mathbf{r}\_\mathtt{descending}_1(\mathtt{TX}_t,\mathtt{A}_{t+1},\mathtt{A}_t), \\ &\mathtt{Y} = \mathtt{A}_{t+1} \end{split}
```

and the specification  $S_r$  of relation r is:

$$\forall X: \mathcal{X}. \ \forall Y: \mathcal{Y}. \ \mathcal{I}_r(X) \Rightarrow [r(X,Y) \Leftrightarrow \mathcal{O}_r(X,Y)]$$

and the specification  $S_{r\_descending_1}$  of relation  $r\_descending_1$  is:

$$\forall X: \mathcal{X}. \ \forall Y, A: \mathcal{Y}. \ \mathcal{I}_r(X) \Rightarrow [r\_descending_1(X,Y,A) \Leftrightarrow \exists S: \mathcal{Y}. \ \mathcal{O}_r(X,S) \land \mathcal{O}_c(A,S,Y)]$$

**Proof 3** To prove the correctness of the generalization schema  $DG_1$ , by Definition 10, we have to prove that templates DCLR and DGLR are equivalent wrt  $S_r$  under the applicability conditions  $A_{dg1}$ . By Definition 5, the templates DCLR and DGLR are equivalent wrt  $S_r$  under the applicability conditions  $A_{dg1}$  iff DCLR is equivalent to DGLR wrt the specification  $S_r$  provided that the conditions in  $A_{dg1}$  hold. By Definition 4, DCLR is equivalent to DGLR wrt the specification  $S_r$  iff the following two conditions hold:

- (a) DCLR is steadfast wrt  $S_r$  in  $\mathcal{S} = \{S_{minimal}, S_{nonMinimal}, S_{solve}, S_{decompose}, S_{process}, S_{compose}\}$ , where  $S_{minimal}, S_{nonMinimal}, S_{solve}, S_{process}, S_{decompose}, S_{compose}$  are the specifications of minimal, nonMinimal, solve, decompose, process, compose, which are all the undefined relation names appearing in DCLR.
- (b) DGLR is also steadfast wrt  $S_r$  in S.

Note that the sets  $\{S_1, \ldots, S_m\}$  and  $\{S'_1, \ldots, S'_t\}$  in Definition 4 are equal to  $\mathcal{S}$  when Q is obtained by descending generalization of P.

In program transformation, we assume that the input program, here template DCLR, is steadfast wrt  $S_r$  in S, so condition (a) always holds.

To prove equivalence, we have to prove condition (b). We will use the following property of stead-fastness: DGLR is steadfast wrt  $S_r$  in S if  $P_{r\_descending_1}$  is steadfast wrt  $S_{r\_descending_1}$  in S, where  $P_{r\_descending_1}$  is the procedure for  $r\_descending_1$ , and  $P_r$  is steadfast wrt  $S_r$  in  $\{S_{r\_descending_1}\}$ , where  $P_r$  is the procedure for r.

To prove that  $P_{r\_descending_1}$  is steadfast wrt  $S_{r\_descending_1}$  in  $\mathcal{S}$ , we do a constructive forward proof that we begin with  $S_{r\_descending_1}$  and from which we try to obtain  $P_{r\_descending_1}$ .

By taking the 'decompletion' of  $S_{r\_descending_1}$ :

```
clause 1: r\_descending_1(X, Y, A) \leftarrow r(X, S), compose(A, S, Y)
```

By unfolding clause 1 wrt r(X, S) using DCLR, and using the assumption that DCLR is steadfast wrt  $S_r$  in S:

```
\begin{array}{ll} clause \ 2: & r \_descending_1(X,Y,A) \leftarrow \\ & minimal(X), \\ & solve(X,S), compose(A,S,Y) \\ clause \ 3: & r \_descending_1(X,Y,A) \leftarrow \\ & nonMinimal(X), decompose(X,HX,TX_1,\ldots,TX_t), \\ & r(TX_1,TS_1),\ldots,r(TX_t,TS_t), \\ & I_0 = e, \\ & compose(I_0,TS_1,I_1),\ldots,compose(I_{p-2},TS_{p-1},I_{p-1}), \\ & process(HX,HS),compose(I_{p-1},HS,I_p), \\ & compose(I_p,TS_p,I_{p+1}),\ldots,compose(I_t,TS_t,I_{t+1}), \\ & S = I_{t+1},compose(A,S,Y) \end{array}
```

By using applicability condition (1) on clause 3:

```
clause 4: r_descending<sub>1</sub>(X, Y, A) \leftarrow nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t), \\ r(TX_1, TS_1), ..., r(TX_t, TS_t), \\ compose(A, e, A_0), \\ compose(A_0, TS_1, A_1), ..., compose(A_{p-2}, TS_{p-1}, A_{p-1}), \\ process(HX, HS), compose(A_{p-1}, HS, A_p), \\ compose(A_p, TS_p, A_{p+1}), ..., compose(A_t, TS_t, A_{t+1}), \\ Y = A_{t+1}
```

By t times folding clause 4 using clause 1:

```
clause 5: r \cdot descending_1(X, Y, A) \leftarrow nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
compose(A, e, A_0),
r \cdot descending_1(TX_1, A_1, A_0), ..., r \cdot descending_1(TX_{p-1}, A_{p-1}, A_{p-2}),
process(HX, HY), compose(A_{p-1}, HY, A_p),
r \cdot descending_1(TX_p, A_{p+1}, A_p), ..., r \cdot descending_1(TX_t, A_{t+1}, A_t),
Y = A_{t+1}
```

Clauses 2 and 5 are the clauses of the  $P_{r\_descending_1}$ . Therefore  $P_{r\_descending_1}$  is steadfast wrt  $S_{r\_descending_1}$  in S.

To prove that  $P_r$  is steadfast wrt  $S_r$  in  $\{S_{r\_descending_1}\}$ , we do a backward proof that we begin with  $P_r$  in DGLR and from which we try to obtain  $S_r$ .

The procedure  $P_r$  for r in DGLR is:

$$r(X,Y) \leftarrow r\_descending_1(X,Y,e)$$

By taking the 'completion':

$$\forall X : \mathcal{X}, \forall Y : \mathcal{Y}. \ \mathcal{I}_r(X) \Rightarrow [r(X,Y) \Leftrightarrow r\_descending_1(X,Y,e)]$$

By unfolding the 'completion' above wrt  $r\_descending_1(X,Y,e)$  using  $S_{r\_descending_1}$ :

$$\forall X: \mathcal{X}, \forall Y: \mathcal{Y}. \quad \mathcal{I}_r(X) \Rightarrow [r(X,Y) \Leftrightarrow \exists S: \mathcal{Y}. \quad \mathcal{O}_r(X,S) \land \mathcal{O}_c(e,S,Y)]$$

By using applicability condition (2):

$$\forall X : \mathcal{X}, \forall Y : \mathcal{Y}. \ \mathcal{I}_r(X) \Rightarrow [r(X,Y) \Leftrightarrow \exists S : \mathcal{Y}. \ \mathcal{O}_r(X,S) \land S = Y]$$

By simplification:

$$\forall X : \mathcal{X}, \forall Y : \mathcal{Y}. \ \mathcal{I}_r(X) \Rightarrow [r(X,Y) \Leftrightarrow \mathcal{O}_r(X,Y)]$$

We obtain  $S_r$ , so  $P_r$  is steadfast wrt  $S_r$  in  $\{S_{r\_descending_1}\}$ . Therefore, DGLR is also steadfast wrt  $S_r$  in S.

**Theorem 4** The generalization schema  $DG_2$ , which is given below, is correct.

```
\begin{array}{l} DG_2: \left\langle \ DCLR, \ DGRL, \ A_{dg2}, \ O_{dg212}, \ O_{dg221} \ \right\rangle \ \text{where} \\ A_{dg2}: (1) \ compose \ \text{is associative} \\ (2) \ compose \ \text{has } e \ \text{as the left and right identity element,} \\ \text{where } e \ \text{appears in } DCLR \ \text{and } DGRL \\ O_{dg212}: -\mathcal{I}_r(X) \land minimal(X) \Rightarrow \mathcal{O}_r(X,e) \\ - \ \text{partial evaluation of the conjunction} \\ process(HX,HY), compose(HY,A_p,A_{p-1}) \\ \text{results in the introduction of a non-recursive relation} \\ O_{dg221}: - \ \text{partial evaluation of the conjunction} \\ process(HX,HY), compose(I_{p-1},HY,I_p) \\ \text{results in the introduction of a non-recursive relation} \end{array}
```

where the template DCLR is Logic Program Template 1 in Section 2 and the template DGRL is Logic Program Template 5 below:

## Logic Program Template 5

```
\begin{split} \mathbf{r}(\mathtt{X},\mathtt{Y}) &\leftarrow \\ \mathbf{r}\_\mathtt{descending}_2(\mathtt{X},\mathtt{Y},\mathtt{e}) \\ \mathbf{r}\_\mathtt{descending}_2(\mathtt{X},\mathtt{Y},\mathtt{A}) &\leftarrow \\ &\min(\mathtt{x}), \\ &\operatorname{solve}(\mathtt{X},\mathtt{S}), \operatorname{compose}(\mathtt{S},\mathtt{A},\mathtt{Y}) \\ \mathbf{r}\_\mathtt{descending}_2(\mathtt{X},\mathtt{Y},\mathtt{A}) &\leftarrow \\ &\operatorname{nonMinimal}(\mathtt{X}), \\ &\operatorname{decompose}(\mathtt{X},\mathtt{HX},\mathtt{TX}_1,\ldots,\mathtt{TX}_t), \\ &\operatorname{compose}(\mathtt{e},\mathtt{A},\mathtt{A}_{t+1}), \\ &\operatorname{r}\_\mathtt{descending}_2(\mathtt{TX}_t,\mathtt{A}_t,\mathtt{A}_{t+1}),\ldots,\mathbf{r}\_\mathtt{descending}_2(\mathtt{TX}_p,\mathtt{A}_p,\mathtt{A}_{p+1}), \\ &\operatorname{process}(\mathtt{HX},\mathtt{HY}), \operatorname{compose}(\mathtt{HY},\mathtt{A}_p,\mathtt{A}_{p-1}), \\ &\operatorname{r}\_\mathtt{descending}_2(\mathtt{TX}_{p-1},\mathtt{A}_{p-2},\mathtt{A}_{p-1}),\ldots,\mathbf{r}\_\mathtt{descending}_2(\mathtt{TX}_1,\mathtt{A}_0,\mathtt{A}_1), \\ &\operatorname{Y} = \mathtt{A}_0 \end{split}
```

and the specification  $S_r$  of relation r is:

$$\forall X : \mathcal{X} . \ \forall Y : \mathcal{Y} . \ \mathcal{I}_r(X) \Rightarrow [r(X,Y) \Leftrightarrow \mathcal{O}_r(X,Y)]$$

and the specification  $S_{r\_descending_2}$  of relation  $r\_descending_2$  is:

$$\forall X: \mathcal{X}. \ \forall Y, A: \mathcal{Y}. \ \mathcal{I}_r(X) \Rightarrow [r \ descending_2(X,Y,A) \Leftrightarrow \exists S: \mathcal{Y}. \ \mathcal{O}_r(X,S) \land \mathcal{O}_c(S,A,Y)]$$

**Proof 4** To prove the correctness of the generalization schema  $DG_2$ , by Definition 10, we have to prove that templates DCLR and DGRL are equivalent wrt  $S_r$  under the applicability conditions  $A_{dg2}$ . By Definition 5, the templates DCLR and DGRL are equivalent wrt  $S_r$  under the applicability conditions  $A_{dg2}$  iff DCLR is equivalent to DGRL wrt the specification  $S_r$  provided that the conditions in  $A_{dg2}$  hold. By Definition 4, DCLR is equivalent to DGRL wrt the specification  $S_r$  iff the following two conditions hold:

(a) DCLR is steadfast wrt  $S_r$  in  $S = \{S_{minimal}, S_{nonMinimal}, S_{solve}, S_{decompose}, S_{process}, S_{compose}\}$ , where  $S_{minimal}, S_{nonMinimal}, S_{solve}, S_{process}, S_{decompose}, S_{compose}$  are the specifications of minimal, nonMinimal, solve, decompose, process, compose, which are all the undefined relation names appearing in DCLR.

(b) DGRL is also steadfast wrt  $S_r$  in S.

Note that the sets  $\{S_1, \ldots, S_m\}$  and  $\{S'_1, \ldots, S'_t\}$  in Definition 4 are equal to  $\mathcal{S}$  when Q is obtained by descending generalization of P.

In program transformation, we assume that the input program, here template DCLR, is steadfast wrt  $S_r$  in S, so condition (a) always holds.

To prove equivalence, we have to prove condition (b). We will use the following property of stead-fastness: DGRL is steadfast wrt  $S_r$  in S if  $P_{r\_descending_2}$  is steadfast wrt  $S_{r\_descending_2}$  in S, where  $P_{r\_descending_2}$  is the procedure for  $r\_descending_2$ , and  $P_r$  is steadfast wrt  $S_r$  in  $\{S_{r\_descending_2}\}$ , where  $P_r$  is the procedure for r.

To prove that  $P_{r\_descending_2}$  is steadfast wrt  $S_{r\_descending_2}$  in  $\mathcal{S}$ , we do a constructive forward proof that we begin with  $S_{r\_descending_2}$  and from which we try to obtain  $P_{r\_descending_2}$ .

By taking the 'decompletion' of  $S_{r\_descending_2}$ :

```
clause 1: r\_descending_2(X, Y, A) \leftarrow r(X, S), compose(S, A, Y)
```

By unfolding clause 1 wrt r(X, S) using DCLR, and using the assumption that DCLR is steadfast wrt  $S_r$  in S:

```
\begin{array}{ll} clause \ 2: & r . descending_2(X,Y,A) \leftarrow \\ & minimal(X), \\ & solve(X,S), compose(S,A,Y) \\ clause \ 3: & r . descending_2(X,Y,A) \leftarrow \\ & nonMinimal(X), decompose(X,HX,TX_1,\ldots,TX_t), \\ & r(TX_1,TS_1),\ldots,r(TX_t,TS_t), \\ & I_0 = e, \\ & compose(I_0,TS_1,I_1),\ldots,compose(I_{p-2},TS_{p-1},I_{p-1}), \\ & process(HX,HS), compose(I_{p-1},HS,I_p), \\ & compose(I_p,TS_p,I_{p+1}),\ldots,compose(I_t,TS_t,I_{t+1}), \\ & S = I_{t+1}, compose(S,A,Y) \end{array}
```

By using applicability condition (1) on clause 3:

```
clause 4: r_descending<sub>2</sub>(X, Y, A) \leftarrow nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t), \\ r(TX_1, TS_1), ..., r(TX_t, TS_t), \\ compose(TS_t, A, A_t), ..., compose(TS_p, A_{p+1}, A_p), \\ process(HX, HY), compose(HY, A_p, A_{p-1}), \\ compose(TS_{p-1}, A_{p-1}, A_{p-2}), ..., compose(TS_1, A_1, A_0), \\ compose(e, A_0, Y)
```

By using applicability condition (2) on clause 4:

```
clause 5: r \cdot descending_2(X, Y, A) \leftarrow nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t), \\ r(TX_1, TS_1), ..., r(TX_t, TS_t), \\ compose(TS_t, A, A_t), ..., compose(TS_p, A_{p+1}, A_p), \\ process(HX, HY), compose(HY, A_p, A_{p-1}), \\ compose(TS_{p-1}, A_{p-1}, A_{p-2}), ..., compose(TS_1, A_1, A_0), \\ Y = A_0
```

By using applicability condition (2) on clause 5 and introducing a new, i.e. existentially quantified, variable  $A_{t+1}$ :

```
clause 6: r 	ext{\_descending}_2(X, Y, A) \leftarrow \\ nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t), \\ r(TX_1, TS_1), ..., r(TX_t, TS_t), \\ compose(e, A, A_{t+1}), \\ compose(TS_t, A_{t+1}, A_t), ..., compose(TS_p, A_{p+1}, A_p), \\ process(HX, HY), compose(HY, A_p, A_{p-1}), \\ compose(TS_{p-1}, A_{p-1}, A_{p-2}), ..., compose(TS_1, A_1, A_0), \\ Y = A_0
```

By t times folding clause 6 using clause 1:

```
clause 7: r\_descending_2(X, Y, A) \leftarrow
                  nonMinimal(X), decompose(X, HX, TX_1, \dots, TX_t),
                  compose(e, A, A_{t+1}),
                  r\_descending_2(TX_t, A_t, A_{t+1}), \ldots, r\_descending_2(TX_p, A_p, A_{p+1}),
                  process(HX, HY), compose(HY, A_p, A_{p-1}),
                  r\_descending_2(TX_{p-1}, A_{p-2}, A_{p-1}), \ldots, r\_descending_2(TX_1, A_0, A_1),
```

Clauses 2 and 7 are the clauses of  $P_{r\_descending_2}$ . Therefore  $P_{r\_descending_2}$  is steadfast wrt  $S_{r\_descending_2}$ in S.

To prove that  $P_r$  is steadfast wrt  $S_r$  in  $\{S_{r\_descending_2}\}$ , we do a backward proof that we begin with  $P_r$  in DGRL and from which we try to obtain  $S_r$ .

The procedure  $P_r$  for r in DGRL is:

$$r(X,Y) \leftarrow r\_descending_2(X,Y,e)$$

By taking the 'completion':

$$\forall X: \mathcal{X}, \forall Y: \mathcal{Y}. \ \mathcal{I}_r(X) \Rightarrow [r(X,Y) \Leftrightarrow r\_descending_2(X,Y,e)]$$

By unfolding the 'completion' above wrt  $r\_descending_2(X,Y,e)$  using  $S_{r\_descending_2}$ :

$$\forall X : \mathcal{X}, \forall Y : \mathcal{Y}. \ \mathcal{I}_r(X) \Rightarrow [r(X,Y) \Leftrightarrow \exists S : \mathcal{Y}. \ \mathcal{O}_r(X,S) \land \mathcal{O}_c(S,e,Y)]$$

By using applicability condition (2):

$$\forall X : \mathcal{X}, \forall Y : \mathcal{Y}. \ \mathcal{I}_r(X) \Rightarrow [r(X,Y) \Leftrightarrow \exists S : \mathcal{Y}. \ \mathcal{O}_r(X,S) \land S = Y]$$

By simplification:

$$\forall X : \mathcal{X}, \forall Y : \mathcal{Y}. \ \mathcal{I}_r(X) \Rightarrow [r(X,Y) \Leftrightarrow \mathcal{O}_r(X,Y)]$$

We obtain  $S_r$ , so  $P_r$  is steadfast wrt  $S_r$  in  $\{S_{r\_descending_2}\}$ . Therefore, DGRL is also steadfast wrt  $S_r$  in S.

**Theorem 5** The generalization schema  $DG_3$ , which is given below, is correct.

```
DG_3: \langle DCRL, DGRL, A_{dg3}, O_{dg312}, O_{dg321} \rangle where
```

 $A_{dq3}$ : (1) compose is associative

(2) compose has e as the right identity element,

where e appears in DCRL and DGRL

 $O_{dg312}$ : - compose has e as the left identity element, where e appears in DCLR and DGRL

and  $\mathcal{I}_r(X) \wedge minimal(X) \Rightarrow \mathcal{O}_r(X, e)$ 

- partial evaluation of the conjunction

 $process(HX, HY), compose(HY, A_p, A_{p-1})$ 

results in the introduction of a non-recursive relation

 $O_{dg321}$ : - partial evaluation of the conjunction  $process(HX, HY), compose(HY, I_p, I_{p-1})$ 

results in the introduction of a non-recursive relation

where the template DGRL is Logic Program Template 5 in Theorem 4 and the template DCRL is Logic Program Template 3 in Section 2.

The specification  $S_r$  of relation r is:

$$\forall X : \mathcal{X} . \ \forall Y : \mathcal{Y} . \ \mathcal{I}_r(X) \Rightarrow [r(X,Y) \Leftrightarrow \mathcal{O}_r(X,Y)]$$

The specification  $S_{r\_des\,cendin\,g_2}$  of relation  $r\_des\,cendin\,g_2$  is:

$$\forall X: \mathcal{X}. \ \forall Y, A: \mathcal{Y}. \ \mathcal{I}_r(X) \Rightarrow [r \_descending_2(X, Y, A) \ \Leftrightarrow \ \exists S: \mathcal{Y}. \ \mathcal{O}_r(X, S) \land \mathcal{O}_c(S, A, Y)]$$

**Proof 5** To prove the correctness of the generalization schema  $DG_3$ , by Definition 10, we have to prove that templates DCRL and DGRL are equivalent wrt  $S_r$  under the applicability conditions  $A_{dg3}$ . By Definition 5, the templates DCRL and DGRL are equivalent wrt  $S_r$  under the applicability conditions  $A_{dg3}$  iff DCRL is equivalent to DGRL wrt the specification  $S_r$  provided that the conditions in  $A_{dg3}$  hold. By Definition 4, DCRL is equivalent to DGRL wrt the specification  $S_r$  iff the following two conditions hold:

- (a) DCRL is steadfast wrt  $S_r$  in  $S = \{S_{minimal}, S_{nonMinimal}, S_{solve}, S_{decompose}, S_{process}, S_{compose}\}$ , where  $S_{minimal}, S_{nonMinimal}, S_{solve}, S_{process}, S_{decompose}, S_{compose}$  are the specifications of minimal, nonMinimal, solve, decompose, process, compose, which are all the undefined relation names appearing in DCRL.
- (b) DGRL is also steadfast wrt  $S_r$  in S.

Note that the sets  $\{S_1, \ldots, S_m\}$  and  $\{S'_1, \ldots, S'_t\}$  in Definition 4 are equal to  $\mathcal{S}$  when Q is obtained by descending generalization of P.

In program transformation, we assume that the input program, here template DCRL, is steadfast wrt  $S_r$  in S, so condition (a) always holds.

To prove equivalence, we have to prove condition (b). We will use the following property of stead-fastness: DGRL is steadfast wrt  $S_r$  in S if  $P_{r\_descending_2}$  is steadfast wrt  $S_{r\_descending_2}$  in S, where  $P_{r\_descending_2}$  is the procedure for  $r\_descending_2$ , and  $P_r$  is steadfast wrt  $S_r$  in  $\{S_{r\_descending_2}\}$ , where  $P_r$  is the procedure for r.

To prove that  $P_{r\_descending_2}$  is steadfast wrt  $S_{r\_descending_2}$  in  $\mathcal{S}$ , we do a constructive forward proof that we begin with  $S_{r\_descending_2}$  and from which we try to obtain  $P_{r\_descending_2}$ .

By taking the 'decompletion' of  $S_{r\_descending_2}$ :

```
clause 1: r\_descending_2(X, Y, A) \leftarrow r(X, S), compose(S, A, Y)
```

By unfolding clause 1 wrt r(X,S) using DCRL, and using the assumption that DCRL is steadfast wrt  $S_r$  in S:

```
\begin{array}{ll} clause \ 2: & r \_descending_2(X,Y,A) \leftarrow \\ & minimal(X), \\ & solve(X,S), compose(S,A,Y) \\ clause \ 3: & r \_descending_2(X,Y,A) \leftarrow \\ & nonMinimal(X), decompose(X,HX,TX_1,\ldots,TX_t), \\ & r(TX_1,TS_1),\ldots,r(TX_t,TS_t), \\ & I_{t+1} = e, \\ & compose(TS_t,I_{t+1},I_t),\ldots,compose(TS_p,I_{p+1},I_p), \\ & process(HX,HS), compose(HS,I_p,I_{p-1}), \\ & compose(TS_{p-1},I_{p-1},I_{p-2}),\ldots,compose(TS_1,I_1,I_0), \\ & S = I_0, compose(S,A,Y) \end{array}
```

By using applicability condition (1) on clause 3:

```
clause 4: r_descending<sub>2</sub>(X, Y, A) \leftarrow nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t), \\ r(TX_1, TS_1), ..., r(TX_t, TS_t), \\ compose(e, A, A_{t+1}), \\ compose(TS_t, A_{t+1}, A_t), ..., compose(TS_p, A_{p+1}, A_p), \\ process(HX, HY), compose(HY, A_p, A_{p-1}), \\ compose(TS_{p-1}, A_{p-1}, A_{p-2}), ..., compose(TS_1, A_1, A_0), \\ Y = A_0
```

By t times folding clause 4 using clause 1:

```
 clause \ 5: \ r \_descending_2(X,Y,A) \leftarrow \\ nonMinimal(X), decompose(X,HX,TX_1,\ldots,TX_t), \\ compose(e,A,A_{t+1}), \\ r \_descending_2(TX_t,A_t,A_{t+1}),\ldots,r \_descending_2(TX_p,A_p,A_{p+1}), \\ process(HX,HY), compose(HY,A_p,A_{p-1}), \\ r \_descending_2(TX_{p-1},A_{p-2},A_{p-1}),\ldots,r \_descending_2(TX_1,A_0,A_1), \\ Y = A_0
```

Clauses 2 and 5 are the clauses of  $P_{r\_descending_2}$ . Therefore  $P_{r\_descending_2}$  is steadfast wrt  $S_{r\_descending_2}$  in S.

To prove that  $P_r$  is steadfast wrt  $S_r$  in  $\{S_{r\_descending_2}\}$ , we do a backward proof that we begin with  $P_r$  in DGRL and from which we try to obtain  $S_r$ .

The procedure  $P_r$  for r in DGRL is:

$$r(X,Y) \leftarrow r\_descending_2(X,Y,e)$$

By taking the 'completion':

$$\forall X : \mathcal{X}, \forall Y : \mathcal{Y}. \ \mathcal{I}_r(X) \Rightarrow [r(X,Y) \Leftrightarrow r\_descending_2(X,Y,e)]$$

By unfolding the 'completion' above wrt  $r\_descending_2(X,Y,e)$  using  $S_{r\_descending_2}$ :

$$\forall X : \mathcal{X}, \forall Y : \mathcal{Y}. \ \mathcal{I}_r(X) \Rightarrow [r(X,Y) \Leftrightarrow \exists S : \mathcal{Y}. \ \mathcal{O}_r(X,S) \land \mathcal{O}_c(S,e,Y)]$$

By using applicability condition (2):

$$\forall X : \mathcal{X}, \forall Y : \mathcal{Y}. \ \mathcal{I}_r(X) \Rightarrow [r(X,Y) \Leftrightarrow \exists S : \mathcal{Y}. \ \mathcal{O}_r(X,S) \land S = Y]$$

By simplification:

$$\forall X : \mathcal{X}, \forall Y : \mathcal{Y}. \ \mathcal{I}_r(X) \Rightarrow [r(X,Y) \Leftrightarrow \mathcal{O}_r(X,Y)]$$

We obtain  $S_r$ , so  $P_r$  is steadfast wrt  $S_r$  in  $\{S_{r\_descending_2}\}$ . Therefore, DGRL is also steadfast wrt  $S_r$  in S.

**Theorem 6** The generalization schema  $DG_4$ , which is given below, is correct.

 $DG_4$ :  $\langle DCRL, DGLR, A_{dg4}, O_{dg412}, O_{dg421} \rangle$  where

 $A_{dg4}$ : - compose is associative

- compose has e as the left and right identity element,

where e appears in DCRL and DGLR

 $O_{d_{q}412}: -\mathcal{I}_r(X) \wedge minimal(X) \Rightarrow \mathcal{O}_r(X, e)$ 

- partial evaluation of the conjunction  $process(HX, HY), compose(A_{p-1}, HY, A_p)$ 

results in the introduction of a non-recursive relation

 $O_{dg421}$ : - partial evaluation of the conjunction  $process(HX, HY), compose(HY, I_p, I_{p-1})$ 

results in the introduction of a non-recursive relation

where the template DCRL is Logic Program Template 3 in Section 2 and the template DGLR is Logic Program Template 4 in Theorem 3.

The specification  $S_r$  of relation r is:

$$\forall X: \mathcal{X}. \ \forall Y: \mathcal{Y}. \ \mathcal{I}_r(X) \Rightarrow [r(X,Y) \Leftrightarrow \mathcal{O}_r(X,Y)]$$

The specification  $S_{r\_des\,cendin\,q_1}$  of relation  $r\_des\,cendin\,q_1$  is:

$$\forall X: \mathcal{X} : \forall Y, A: \mathcal{Y} : \mathcal{I}_r(X) \Rightarrow [r \cdot descending_1(X,Y,A) \Leftrightarrow \exists S: \mathcal{Y} : \mathcal{O}_r(X,S) \land \mathcal{O}_c(A,S,Y)]$$

**Proof 6** To prove the correctness of the generalization schema  $DG_4$ , by Definition 10, we have to prove that templates DCRL and DGLR are equivalent wrt  $S_r$  under the applicability conditions  $A_{dg4}$ . By Definition 5, the templates DCRL and DGLR are equivalent wrt  $S_r$  under the applicability conditions  $A_{dg4}$  iff DCRL is equivalent to DGLR wrt the specification  $S_r$  provided that the conditions in  $A_{dg4}$  hold. By Definition 4, DCRL is equivalent to DGLR wrt the specification  $S_r$  iff the following two conditions hold:

(a) DCRL is steadfast wrt  $S_r$  in  $\mathcal{S} = \{S_{minimal}, S_{nonMinimal}, S_{solve}, S_{decompose}, S_{process}, S_{compose}\}$ , where  $S_{minimal}, S_{nonMinimal}, S_{solve}, S_{process}, S_{decompose}, S_{compose}$  are the specifications of minimal, nonMinimal, solve, decompose, process, compose, which are all the undefined relation names appearing in DCRL.

(b) DGLR is also steadfast wrt  $S_r$  in S.

Note that the sets  $\{S_1, \ldots, S_m\}$  and  $\{S'_1, \ldots, S'_t\}$  in Definition 4 are equal to  $\mathcal{S}$  to  $\mathcal{S}$  when Q is obtained by descending generalization of P.

In program transformation, we assume that the input program, here template DCRL, is steadfast wrt  $S_r$  in S, so condition (a) always holds.

To prove equivalence, we have to prove condition (b). We will use the following property of stead-fastness: DGLR is steadfast wrt  $S_r$  in S if  $P_{r\_descending_1}$  is steadfast wrt  $S_{r\_descending_1}$  in S, where  $P_{r\_descending_1}$  is the procedure for  $r\_descending_1$ , and  $P_r$  is steadfast wrt  $S_r$  in  $\{S_{r\_descending_1}\}$ , where  $P_r$  is the procedure for r.

To prove that  $P_{r\_descending_1}$  is steadfast wrt  $S_{r\_descending_1}$  in S, we do a constructive forward proof that we begin with  $S_{r\_descending_1}$  and from which we try to obtain  $P_{r\_descending_1}$ .

By taking the 'decompletion' of  $S_{r\_descending_1}$ :

```
clause 1: r\_descending_1(X, Y, A) \leftarrow r(X, S), compose(A, S, Y)
```

By unfolding clause 1 wrt r(X, S) using DCRL, and using the assumption that DCLR is steadfast wrt  $S_r$  in S:

```
\begin{array}{ll} clause \ 2: & r.descending_1(X,Y,A) \leftarrow \\ & minimal(X), \\ & solve(X,S), compose(A,S,Y) \\ clause \ 3: & r.descending_1(X,Y,A) \leftarrow \\ & nonMinimal(X), decompose(X,HX,TX_1,\ldots,TX_t), \\ & r(TX_1,TS_1),\ldots,r(TX_t,TS_t), \\ & I_{t+1}=e, \\ & compose(TS_t,I_{t+1},I_t),\ldots,compose(TS_p,I_{p+1},I_p), \\ & process(HX,HS), compose(HS,I_p,I_{p-1}), \\ & compose(TS_{p-1},I_{p-1},I_{p-2}),\ldots,compose(TS_1,I_1,I_0), \\ & S=I_0, compose(A,S,Y) \end{array}
```

By using applicability condition (1) on clause 3:

```
clause 4: r.descending_1(X, Y, A) \leftarrow nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t), \\ r(TX_1, TS_1), ..., r(TX_t, TS_t), \\ compose(A, TS_1, A_1), ..., compose(A_{p-2}, TS_{p-1}, A_{p-1}), \\ process(HX, HS), compose(A_{p-1}, HS, A_p), \\ compose(A_p, TS_p, A_{p+1}), ..., compose(A_t, TS_t, A_{t+1}), \\ compose(A_{t+1}, e, Y)
```

By using applicability condition (2) on clause 4:

```
clause 5: r.descending_1(X, Y, A) \leftarrow nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t), \\ r(TX_1, TS_1), ..., r(TX_t, TS_t), \\ compose(A, TS_1, A_1), ..., compose(A_{p-2}, TS_{p-1}, A_{p-1}), \\ process(HX, HS), compose(A_{p-1}, HS, A_p), \\ compose(A_p, TS_p, A_{p+1}), ..., compose(A_t, TS_t, A_{t+1}), \\ Y = A_{t+1}
```

By using applicability condition (2) on clause 5 and introducing a new, i.e. existentially quantified, variable  $A_0$ :

```
clause 6: r 	ext{\_descending}_1(X, Y, A) \leftarrow \\ nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t), \\ r(TX_1, TS_1), ..., r(TX_t, TS_t), \\ compose(A, e, A_0), \\ compose(A_0, TS_1, A_1), ..., compose(A_{p-2}, TS_{p-1}, A_{p-1}), \\ process(HX, HS), compose(A_{p-1}, HS, A_p), \\ compose(A_p, TS_p, A_{p+1}), ..., compose(A_t, TS_t, A_{t+1}), \\ Y = A_{t+1} \end{cases}
```

By t times folding clause 6 using clause 1:

```
 clause \ 7: \ r \cdot descending_1(X,Y,A) \leftarrow \\ nonMinimal(X), decompose(X,HX,TX_1,\ldots,TX_t), \\ compose(A,e,A_0), \\ r \cdot descending_1(TX_1,A_1,A_0),\ldots, r \cdot descending_1(TX_{p-1},A_{p-1},A_{p-2}), \\ process(HX,HY), compose(A_{p-1},HY,A_p), \\ r \cdot descending_1(TX_p,A_{p+1},A_p),\ldots, r \cdot descending_1(TX_t,A_{t+1},A_t), \\ Y = A_{t+1}
```

Clauses 2 and 7 are the clauses of the  $P_{r\_descending_1}$ . Therefore  $P_{r\_descending_1}$  is steadfast wrt  $S_{r\_descending_1}$  in S.

To prove that  $P_r$  is steadfast wrt  $S_r$  in  $\{S_{r\_descending_1}\}$ , we do a backward proof that we begin with  $P_r$  in DGLR and from which we try to obtain  $S_r$ .

The procedure  $P_r$  for r in DGLR is:

$$r(X,Y) \leftarrow r\_descending_1(X,Y,e)$$

By taking the 'completion':

$$\forall X: \mathcal{X}, \forall Y: \mathcal{Y}. \ \mathcal{I}_r(X) \Rightarrow [r(X,Y) \Leftrightarrow r\_descending_1(X,Y,e)]$$

By unfolding the 'completion' above wrt  $r\_descending_1(X,Y,e)$  using  $S_{r\_descending_1}$ :

$$\forall X: \mathcal{X}, \forall Y: \mathcal{Y}. \ \mathcal{I}_r(X) \Rightarrow [r(X,Y) \Leftrightarrow \exists S: \mathcal{Y}. \ \mathcal{O}_r(X,S) \land \mathcal{O}_c(e,S,Y)]$$

By using applicability condition (2):

$$\forall X : \mathcal{X}, \forall Y : \mathcal{Y}. \ \mathcal{I}_r(X) \Rightarrow [r(X,Y) \Leftrightarrow \exists S : \mathcal{Y}. \ \mathcal{O}_r(X,S) \land S = Y]$$

By simplification:

$$\forall X : \mathcal{X}, \forall Y : \mathcal{Y}. \ \mathcal{I}_r(X) \Rightarrow [r(X,Y) \Leftrightarrow \mathcal{O}_r(X,Y)]$$

We obtain  $S_r$ , so  $P_r$  is steadfast wrt  $S_r$  in  $\{S_{r\_descending_1}\}$ . Therefore, DGLR is also steadfast wrt  $S_r$  in S.

## 4 Proofs of the Simultaneous Tupling-and-Descending Generalization Schemas

**Theorem 7** The generalization schema  $TDG_1$ , which is given below, is correct.

```
TDG_1: \langle DCLR, TDGLR, A_{td1}, O_{td112}, O_{td121} \rangle where
```

 $A_{td1}$ : (1) compose is associative

- (2) compose has e as the left and right identity element
- (3)  $\forall X : \mathcal{X} : \mathcal{I}_r(X) \land minimal(X) \Rightarrow \mathcal{O}_r(X, e)$
- (4)  $\forall X : \mathcal{X} \cdot \mathcal{I}_r(X) \Rightarrow [\neg minimal(X) \Leftrightarrow nonMinimal(X)]$

 $O_{td112}$ : partial evaluation of the conjunction

process(HX, HY), compose(A, HY, NewA)

results in the introduction of a non-recursive relation

 $O_{td121}$ : partial evaluation of the conjunction

 $process(HX, HY), compose(I_{p-1}, HY, I_p)$ 

results in the introduction of a non-recursive relation

where the template DCLR is Logic Program Template 1 in Section 2 and the template TDGLR is Logic Program Template 6 below:

## Logic Program Template 6

```
r(X, Y) \leftarrow
      r_td_1([X], Y, e)
r_td_1(Xs,Y,A) \leftarrow
      Xs = [],
      Y = A
r_td_1(Xs,Y,A) \leftarrow
      Xs = [X|TXs],
      minimal(X),
      solve(X, HY),
      compose(A, HY, NewA),
      r_td<sub>1</sub>(TXs, Y, NewA)
r_{td_1}(Xs, Y, A) \leftarrow
      Xs = [X|TXs],
      nonMinimal(X),
      decompose(X, HX, TX_1, ..., TX_t),
      minimal(TX_1), \ldots, minimal(TX_t),
      process(HX, HY), compose(A, HY, NewA),
      r_td_1(TXs, Y, NewA)
r_td_1(Xs, Y, A) \leftarrow
      Xs = [X|TXs],
      nonMinimal(X),
      decompose(X, HX, TX_1, ..., TX_t),
      \mathtt{minimal}(\mathtt{TX}_1), \ldots, \mathtt{minimal}(\mathtt{TX}_{p-1}),
      (nonMinimal(TX_p); ...; nonMinimal(TX_t)),
      process(HX, HY), compose(A, HY, NewA),
      \mathtt{r\_td}_1([\mathtt{TX}_p,\ldots,\mathtt{TX}_t|\mathtt{TX}\mathtt{s}],\mathtt{Y},\mathtt{NewA})
r_td_1(Xs, Y, A) \leftarrow
      Xs = [X|TXs],
      nonMinimal(X),
      decompose(X, HX, TX_1, ..., TX_t),
      (\mathtt{nonMinimal}(\mathtt{TX}_1); \ldots; \mathtt{nonMinimal}(\mathtt{TX}_{\mathtt{D}-1})),
      minimal(TX_D), \ldots, minimal(TX_t),
      minimal(U_1), \ldots, minimal(U_{p-1}),
      \mathtt{decompose}(\mathtt{N},\mathtt{HX},\mathtt{U_1},\ldots,\mathtt{U_{p-1}},\mathtt{TX}_p,\ldots,\mathtt{TX}_\mathtt{t}),
      \mathtt{r\_td}_1([\mathtt{TX}_1,\ldots,\mathtt{TX}_{\mathtt{D}-1},\mathtt{N}|\mathtt{TXs}],\mathtt{Y},\mathtt{A})
r_td_1(Xs,Y,A) \leftarrow
      Xs = [X|TXs],
      nonMinimal(X),
      decompose(X, HX, TX_1, \dots, TX_t),
      (nonMinimal(TX_1); ...; nonMinimal(TX_{p-1})),
      (nonMinimal(TX_p); ...; nonMinimal(TX_t)),
      minimal(U_1), \ldots, minimal(U_t),
      decompose(N, HX, U_1, \ldots, U_t),
      \mathtt{r\_td}_1([\mathtt{TX}_1,\ldots,\mathtt{TX}_{\mathtt{p}-1},\mathtt{N},\mathtt{TX}_{\mathtt{p}},\ldots,\mathtt{TX}_{\mathtt{t}}|\mathtt{TXs}],\mathtt{Y},\mathtt{A})
```

and the specification  $S_r$  of relation r is:

$$\forall X : \mathcal{X}, \forall Y : \mathcal{Y}. \ \mathcal{I}_r(X) \Rightarrow [r(X,Y) \Leftrightarrow \mathcal{O}_r(X,Y)]$$

and the specification  $S_{r-td_1}$ :

$$\forall Xs: list \ of \ \mathcal{X}, \forall Y, A: \mathcal{Y}. \quad (\forall X: \mathcal{X}. \ X \in Xs \Rightarrow \mathcal{I}_r(X)) \Rightarrow [r \bot td_1(Xs, Y, A) \Leftrightarrow (Xs = [] \land Y = A) \\ \lor (Xs = [X_1, X_2, \dots, X_q] \land \bigwedge_{i=1}^q \mathcal{O}_r(X_i, Y_i) \quad \land I_1 = Y_1 \land \bigwedge_{i=2}^q \mathcal{O}_c(I_{i-1}, Y_i, I_i) \\ \land \mathcal{O}_c(A, I_q, I_{q+1}) \land Y = I_{q+1})]$$

**Proof 7** To prove the correctness of the generalization schema  $TDG_1$ , by Definition 10, we have to prove that templates DCLR and TDGLR are equivalent wrt  $S_r$  under the applicability conditions  $A_{td1}$ . By Definition 5, the templates DCLR and TDGLR are equivalent wrt  $S_r$  under the applicability conditions  $A_{td1}$  iff DCLR is equivalent to TDGLR wrt the specification  $S_r$  provided that the conditions in  $A_{td1}$  hold. By Definition 4, DCLR is equivalent to TDGLR wrt the specification  $S_r$  iff the following two conditions hold:

- (a) DCLR is steadfast wrt  $S_r$  in  $\mathcal{S} = \{S_{minimal}, S_{nonMinimal}, S_{solve}, S_{decompose}, S_{process}, S_{compose}\}$ , where  $S_{minimal}, S_{nonMinimal}, S_{solve}, S_{decompose}, S_{process}, S_{compose}$  are the specifications of minimal, nonMinimal, solve, decompose, process, compose, which are all the undefined relation names appearing in DCLR.
- (b) TDGLR is also steadfast wrt  $S_r$  in S.

Note that the sets  $\{S_1, \ldots, S_m\}$  and  $\{S'_1, \ldots, S'_t\}$  in Definition 4 are equal to  $\mathcal{S}$  when Q is obtained by simultaneous tupling-and-descending generalization of P.

In program transformation, we assume that the input program, here template DCLR, is steadfast wrt  $S_r$  in S, so condition (a) always holds.

To prove equivalence, we have to prove condition (b). We will use the following property of steadfastness: TDGLR is steadfast wrt  $S_r$  in S if  $P_{r\_td_1}$  is steadfast wrt  $S_{r\_td_1}$  in S, where  $P_{r\_td_1}$  is the procedure for  $r\_td_1$ , and  $P_r$  is steadfast wrt  $S_r$  in  $\{S_{r\_td_1}\}$ , where  $P_r$  is the procedure for r.

To prove that  $P_{r_{-}td_{1}}$  is steadfast wrt  $S_{r_{-}td_{1}}$  in S, we do a constructive forward proof that we begin with  $S_{r_{-}td_{1}}$  and from which we try to obtain  $P_{r_{-}td_{1}}$ .

If we separate the cases of  $q \ge 1$  by  $q = 1 \lor q \ge 2$ , then  $S_{r\_td_1}$  becomes:

```
\begin{array}{l} \forall Xs: list\ of\ \mathcal{X}, \forall Y: \mathcal{Y}.\ (\forall X: \mathcal{X}.\ X \in Xs \Rightarrow \mathcal{I}_r(X)) \Rightarrow [r \, \mathcal{I}d_1(Xs,Y,A) \Leftrightarrow \\ (Xs = [] \wedge Y = A) \\ \vee (Xs = [X_1] \wedge \mathcal{O}_r(X_1,Y_1) \wedge Y_1 = I_1 \wedge \mathcal{O}_c(A,I_1,I_2) \wedge Y = I_2) \\ \vee (Xs = [X_1,X_2,\ldots,X_q] \wedge \bigwedge_{i=1}^q \mathcal{O}_r(X_i,Y_i) \wedge I_1 = Y_1 \wedge \bigwedge_{i=2}^q \mathcal{O}_c(I_{i-1},Y_i,I_i) \wedge \\ \mathcal{O}_c(A,I_q,I_{q+1}) \wedge Y = I_{q+1})] \end{array}
```

where  $q \geq 2$ .

By using applicability conditions (1) and (2):

```
 \forall Xs: list \ of \ \mathcal{X}, \forall Y: \mathcal{Y}: \ (\forall X: \mathcal{X}: X \in Xs \Rightarrow \mathcal{I}_r(X)) \Rightarrow [r \, \mathcal{I}d_1(Xs,Y,A) \Leftrightarrow (Xs = [] \wedge Y = A) \\ \vee (Xs = [X_1 | TXs] \wedge TXs = [] \wedge \mathcal{O}_r(X_1,Y_1) \wedge Y_1 = I_1 \wedge TY = A \wedge \mathcal{O}_c(A,I_1,NA) \wedge \mathcal{O}_c(NA,TY,Y)) \\ \vee (Xs = [X_1 | TXs] \wedge TXs = [X_2,\ldots,X_q] \wedge \bigwedge_{i=1}^q \mathcal{O}_r(X_i,Y_i) \wedge Y_1 = I_1 \wedge Y_2 = I_2 \wedge \bigwedge_{i=3}^q \mathcal{O}_c(I_{i-1},Y_i,I_i) \wedge TY = I_q \wedge \mathcal{O}_c(A,I_1,NA) \wedge \mathcal{O}_c(NA,TY,Y))]
```

where q > 2.

By folding using  $S_{r\_td_1}$ , and renaming:

```
\forall Xs : list \ of \ \mathcal{X}, \forall Y : \mathcal{Y}. \ (\forall X : \mathcal{X}. \ X \in Xs \Rightarrow \mathcal{I}_r(X)) \Rightarrow [r \, \mathcal{I}d_1(Xs, Y, A) \Leftrightarrow (Xs = [] \land Y = A) \\ \lor (Xs = [X|TXs] \land \mathcal{O}_r(X, HY) \land \mathcal{O}_c(A, HY, NA) \land r \, \mathcal{I}d_1(TXs, Y, NA))]
```

By taking the 'decompletion':

```
clause 1: r \sharp d_1(Xs, Y, A) \leftarrow Xs = [], Y = A

clause 2: r \sharp d_1(Xs, Y, A) \leftarrow Xs = [X|TXs], r(X, HY),

compose(A, HY, NA), r \sharp d_1(TXs, Y, NA)
```

By unfolding clause 2 wrt r(X, HY) using DCLR, and using the assumption that DCLR is steadfast wrt  $S_r$  in S:

```
clause 3: r \not = d_1(Xs, Y, A) \leftarrow
                   Xs = [X|TXs],
                   minimal(X),
                   solve(X, HY), compose(A, HY, NA),
                   r\_td_1(TXs, Y, NA)
 clause 4: r \not d_1(Xs, Y, A) \leftarrow
                   Xs = [X|TXs],
                   nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                   r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                   I_0 = e,
                   compose(I_0, TY_1, I_1), \ldots, compose(I_{p-2}, TY_{p-1}, I_{p-1}),
                   process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                   compose(I_p, TY_p, I_{p+1}), \ldots, compose(I_t, TY_t, I_{t+1}),
                   HY = I_{t+1}, compose(A, HY, NA),
                   r \perp td_1(TXs, Y, NA)
By introducing
                                    (minimal(TX_1) \land \ldots \land minimal(TX_t)) \lor
     ((minimal(TX_1) \land ... \land minimal(TX_{p-1})) \land (nonMinimal(TX_p) \lor ... \lor nonMinimal(TX_t))) \lor
     ((nonMinimal(TX_1) \lor ... \lor nonMinimal(TX_{p-1})) \land (minimal(TX_p) \land ... \land minimal(TX_t))) \lor
 ((nonMinimal(TX_1) \lor ... \lor nonMinimal(TX_{p-1})) \land (nonMinimal(TX_p) \lor ... \lor nonMinimal(TX_t)))
in clause 4, using applicability condition (4):
 clause 5: r td_1(Xs, Y, A) \leftarrow
                   Xs = [X|TXs],
                   nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                   minimal(TX_1), \ldots, minimal(TX_t),
                   r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                   I_0 = e,
                   compose(I_0, TY_1, I_1), \ldots, compose(I_{p-2}, TY_{p-1}, I_{p-1}),
                   process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                   compose(I_p, TY_p, I_{p+1}), \ldots, compose(I_t, TY_t, I_{t+1}),
                   HY = I_{t+1}, compose(A, HY, NA),
                   r \perp td_1(TXs, Y, NA)
 clause 6: r \pm d_1(Xs, Y, A) \leftarrow
                   Xs = [X|TXs],
                   nonMinimal(X), decompose(X, HX, TX_1, \dots, TX_t),
                   minimal(TX_1), \ldots, minimal(TX_{p-1}),
                   (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                   r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                   I_0 = e
                   compose(I_0, TY_1, I_1), \ldots, compose(I_{p-2}, TY_{p-1}, I_{p-1}),
                   process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                   compose(I_p, TY_p, I_{p+1}), \ldots, compose(I_t, TY_t, I_{t+1}),
                   HY = I_{t+1}, compose(A, HY, NA),
                   r\_td_1(TXs, Y, NA)
```

```
clause 7: r \pm d_1(Xs, Y, A) \leftarrow
                       Xs = [X|TXs],
                      nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                      (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                      minimal(TX_p), \ldots, minimal(TX_t),
                      r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                       I_0 = e
                      compose(I_0, TY_1, I_1), \ldots, compose(I_{p-2}, TY_{p-1}, I_{p-1}),
                      process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                      compose(I_p, TY_p, I_{p+1}), \ldots, compose(I_t, TY_t, I_{t+1}),
                      HY = I_{t+1}, compose(A, HY, NA),
                      r\_td_1(TXs, Y, NA)
     clause 8: r td_1(Xs, Y, A) \leftarrow
                      Xs = [X|TXs],
                      nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                      (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                      (nonMinimal(TX_p); \dots; nonMinimal(TX_t)),
                      r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                       I_0 = e
                      compose(I_0, TY_1, I_1), \ldots, compose(I_{p-2}, TY_{p-1}, I_{p-1}),
                      process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                      compose(I_p, TY_p, I_{p+1}), \ldots, compose(I_t, TY_t, I_{t+1}),
                      HY = I_{t+1}, compose(A, HY, NA),
                      r_{\perp}td_{1}(TXs, Y, NA)
   By t times unfolding clause 5 wrt r(TX_1, TY_1), \ldots, r(TX_t, TY_t) using DCLR, and simplifying using
condition (4):
    clause 9: r 1d_1(Xs, Y, A) \leftarrow
                       Xs = [X|TXs],
                      nonMinimal(X), decompose(X, HX, TX_1, \dots, TX_t),
                      minimal(TX_1), \ldots, minimal(TX_t),
                      minimal(TX_1), \ldots, minimal(TX_t)
                      solve(TX_1, TY_1), \ldots, solve(TX_t, TY_t),
                      compose(I_0, TY_1, I_1), \ldots, compose(I_{p-2}, TY_{p-1}, I_{p-1}),
                      process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                      compose(I_p, TY_p, I_{p+1}), \ldots, compose(I_t, TY_t, I_{t+1}),
                      HY = I_{t+1}, compose(A, HY, NA),
                      r \perp td_1(TXs, Y, NA)
   By using applicability condition (3):
    clause 10: r \pm d_1(Xs, Y, A) \leftarrow
                        Xs = [X|TXs].
                        nonMinimal(X), decompose(X, HX, TX_1, \dots, TX_t),
                        minimal(TX_1), \ldots, minimal(TX_t),
                        minimal(TX_1), \ldots, minimal(TX_t),
                        solve(TX_1, e), \ldots, solve(TX_t, e),
                        I_0 = e
                        compose(I_0, e, I_1), \ldots, compose(I_{p-2}, e, I_{p-1}),
                        process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                        compose(I_p, e, I_{p+1}), \ldots, compose(I_t, e, I_{t+1}),
                        HY = I_{t+1}, compose(A, HY, NA),
                        r \perp td_1(TXs, Y, NA)
```

By deleting one of the  $minimal(TX_1), \ldots, minimal(TX_t)$  atoms in clause 10:

```
clause 11: r \perp d_1(Xs, Y, A) \leftarrow
                        Xs = [X|TXs]
                        nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                        minimal(TX_1), \ldots, minimal(TX_t),
                        solve(TX_1, e), \ldots, solve(TX_t, e),
                        I_0 = e,
                        compose(I_0, e, I_1), \ldots, compose(I_{p-2}, e, I_{p-1}),
                        process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                        compose(I_p, e, I_{p+1}), \ldots, compose(I_t, e, I_{t+1}),
                        HY = I_{t+1}, compose(A, HY, NA),
                        r \perp td_1(TXs, Y, NA)
   By using applicability condition (2):
     clause 12: r \pm d_1(Xs, Y, A) \leftarrow
                        Xs = [X|TXs]
                        nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                        minimal(TX_1), \ldots, minimal(TX_t),
                        solve(TX_1, e), \ldots, solve(TX_t, e),
                        I_0 = e,
                        I_1 = I_0, \ldots, I_{p-1} = I_{p-2},
                        process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                        I_{p+1} = I_p, \dots, I_{t+1} = I_t,
                        HY = I_{t+1}, compose(A, HY, NA),
                        r \perp td_1(TXs, Y, NA)
   By simplification:
     clause 13: r \pm d_1(Xs, Y, A) \leftarrow
                        Xs = [X|TXs]
                        nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                        minimal(TX_1), \ldots, minimal(TX_t),
                        process(HX, HY), compose(A, HY, NA),
                        r \perp td_1(TXs, Y, NA)
   By p-1 times unfolding clause 6 wrt r(TX_1, TY_1), \ldots, r(TX_{p-1}, TY_{p-1}) using DCLR, and simplifying
using condition (4):
     clause 14: r \not = d_1(Xs, Y, A) \leftarrow
                        Xs = [X|TXs]
                        nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                        minimal(TX_1), \ldots, minimal(TX_{p-1}),
                        (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                        minimal(TX_1), \ldots, minimal(TX_{p-1}),
                        solve(TX_1, TY_1), \ldots, solve(TX_{p-1}, TY_{p-1}),
                        r(TX_p, TY_p), \ldots, r(TX_t, TY_t)
                        I_0 = e,
                        compose(I_0, TY_1, I_1), \ldots, compose(I_{p-2}, TY_{p-1}, I_{p-1}),
                        process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                        compose(I_p, TY_p, I_{p+1}), \ldots, compose(I_t, TY_t, I_{t+1}),
```

By deleting one of the  $minimal(TX_1), \ldots, minimal(TX_{p-1})$  atoms in clause 14:

 $HY = I_{t+1}, compose(A, HY, NA),$ 

 $r \perp td_1(TXs, Y, NA)$ 

```
clause 15: r \perp d_1(Xs, Y, A) \leftarrow
                    Xs = [X|TXs]
                    nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                    minimal(TX_1), \ldots, minimal(TX_{p-1}),
                    (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                    solve(TX_1, TY_1), \ldots, solve(TX_{p-1}, TY_{p-1}),
                    r(TX_p, TY_p), \ldots, r(TX_t, TY_t)
                    I_0 = e,
                    compose(I_0, TY_1, I_1), \ldots, compose(I_{p-2}, TY_{p-1}, I_{p-1}),
                    process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                    compose(I_p, TY_p, I_{p+1}), \ldots, compose(I_t, TY_t, I_{t+1}),
                    HY = I_{t+1}, compose(A, HY, NA),
                    r \perp td_1(TXs, Y, NA)
By rewriting clause 15 using applicability condition (1):
 clause 16: r \not = d_1(Xs, Y, A) \leftarrow
                    Xs = [X|TXs]
                    nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                    minimal(TX_1), \ldots, minimal(TX_{p-1}),
                    (nonMinimal(TX_p); ...; nonMinimal(TX_t)),
                    solve(TX_1, TY_1), \ldots, solve(TX_{p-1}, TY_{p-1}),
                    r(TX_p, TY_p), \ldots, r(TX_t, TY_t)
                    I_0 = e
                    compose(I_0, TY_1, I_1), \ldots, compose(I_{p-2}, TY_{p-1}, I_{p-1}),
                    process(HX, HHY), compose(I_{p-1}, HHY, I_p), HY = I_p,
                    compose(A, HY, NA),
                    compose(TY_p, TY_{p+1}, I_{p+1}),
                    compose(I_{p+1}, TY_{p+2}, I_{p+2}), \ldots, compose(I_{t-1}, TY_t, I_t),
                    compose(NA, I_t, NNA),
                    r \perp t d_1(TXs, Y, NNA)
By t-p times folding clause 16 using clauses 1 and 2:
 clause 17: r \pm d_1(Xs, Y, A) \leftarrow
                    Xs = [X|TXs],
                    nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                    minimal(TX_1), \ldots, minimal(TX_{p-1}),
                    (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                    solve(TX_1, TY_1), \ldots, solve(TX_{p-1}, TY_{p-1}),
                    compose(I_0, TY_1, I_1), \ldots, compose(I_{p-2}, TY_{p-1}, I_{p-1}),
                    process(HX, HHY), compose(I_{p-1}, HHY, I_p), HY = I_p,
                    compose(A, HY, NA),
                    r \not\perp td_1([TX_p, \ldots, TX_t|TXs], Y, NA)
By using applicability condition (3):
 clause 18: r \pm d_1(Xs, Y, A) \leftarrow
                    Xs = [X|TXs],
                    nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                    minimal(TX_1), \ldots, minimal(TX_{p-1}),
                    (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                    solve(TX_1, e), \ldots, solve(TX_{p-1}, e),
                    I_0 = e
                    compose(I_0, e, I_1), \ldots, compose(I_{p-2}, e, I_{p-1}),
                    process(HX, HHY), compose(I_{p-1}, HHY, I_p), HY = I_p,
                    compose(A, HY, NA),
                    r \perp td_1([TX_p, \ldots, TX_t|TXs], Y, NA)
```

By using applicability condition (2):

```
clause 19: r \perp d_1(Xs, Y, A) \leftarrow
                        Xs = [X|TXs]
                        nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                        minimal(TX_1), \ldots, minimal(TX_{p-1}),
                        (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                        solve(TX_1, e), \ldots, solve(TX_{p-1}, e),
                        I_0 = e,
                        I_1 = I_0, \ldots, I_{p-1} = I_{p-2},
                        process(HX, HHY), compose(I_{p-1}, HHY, I_p), HY = I_p,
                        compose(A, HY, NA),
                        r \perp t d_1([TX_p, \ldots, TX_t|TX_s], Y, NA)
   By simplification:
     clause 20: r t d_1(Xs, Y, A) \leftarrow
                        Xs = [X|TXs]
                        nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                        minimal(TX_1), \ldots, minimal(TX_{p-1}),
                        (nonMinimal(TX_p); \dots; nonMinimal(TX_t)),
                        process(HX, HY), compose(A, HY, NA),
                        r \not\perp td_1([TX_p, \ldots, TX_t|TXs], Y, NA)
   By introducing atoms minimal(U_1), \ldots, minimal(U_{p-1}) (with new, i.e. existentially quantified, vari-
ables U_1, \ldots, U_{p-1}) in clause 7:
     clause 21: r t d_1(Xs, Y, A) \leftarrow
                        Xs = [X|TXs]
                        nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                        (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                        minimal(TX_p), \ldots, minimal(TX_t),
                        minimal(U_1), \ldots, minimal(U_{p-1}),
                        r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                        I_0 = e,
                        compose(I_0, TY_1, I_1), \ldots, compose(I_{p-2}, TY_{p-1}, I_{p-1}),
                        process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                       compose(I_p, TY_p, I_{p+1}), \ldots, compose(I_t, TY_t, I_{t+1}),
                        HY = I_{t+1}, compose(A, HY, NA),
                        r \perp td_1(TXs, Y, NA)
   By using applicability condition (3):
     clause 22: r t d_1(Xs, Y, A) \leftarrow
                        Xs = [X|TXs]
                        nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                        (nonMinimal(TX_1); \dots; nonMinimal(TX_{p-1})),
```

```
 clause \ 22: \ r \sharp d_1(Xs,Y,A) \leftarrow \\ Xs = [X|TXs], \\ nonMinimal(X), decompose(X,HX,TX_1,...,TX_t), \\ (nonMinimal(TX_1);...;nonMinimal(TX_{p-1})), \\ minimal(TX_p),...,minimal(TX_t), \\ minimal(U_1),...,minimal(U_{p-1}), \\ r(U_1,e),...,r(U_{p-1},e), \\ r(TX_1,TY_1),...,r(TX_t,TY_t), \\ I_0 = e, \\ compose(I_0,TY_1,I_1),...,compose(I_{p-2},TY_{p-1},I_{p-1}), \\ process(HX,HHY),compose(I_{p-1},HHY,I_p), \\ compose(I_p,TY_p,I_{p+1}),...,compose(I_t,TY_t,I_{t+1}), \\ HY = I_{t+1},compose(A,HY,NA), \\ r \sharp d_1(TXs,Y,NA)
```

By using applicability condition (2):

```
clause 23: r \perp d_1(Xs, Y, A) \leftarrow
                        Xs = [X|TXs]
                        nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                        (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                        minimal(TX_p), \ldots, minimal(TX_t),
                        minimal(U_1), \ldots, minimal(U_{p-1}),
                        r(U_1,e),\ldots,r(U_{p-1},e),
                        r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                        I_0 = e
                        compose(I_0, TY_1, I_1), \ldots, compose(I_{p-2}, TY_{p-1}, I_{p-1}),
                        compose(I_{p-1}, e, K_1), compose(K_1, e, K_2), \ldots, compose(K_{p-2}, e, K_{p-1}),
                        process(HX, HHY), compose(K_{p-1}, HHY, I_p),
                        compose(I_p, TY_p, I_{p+1}), \ldots, compose(I_t, TY_t, I_{t+1}),
                        HY = I_{t+1}, compose(A, HY, NA),
                        r \perp td_1(TXs, Y, NA)
   By using applicability conditions (1) and (2):
     clause 24: r td_1(Xs, Y, A) \leftarrow
                        Xs = [X|TXs].
                        nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                        (nonMinimal(TX_1); \dots; nonMinimal(TX_{p-1})),
                        minimal(TX_p), \ldots, minimal(TX_t),
                        minimal(U_1), \ldots, minimal(U_{n-1}),
                        r(U_1, e), \ldots, r(U_{p-1}, e),
                        r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                        compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \dots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                        compose(A, K_{p-2}, NA),
                        I_0 = e
                        compose(I_0, e, I_1), \ldots, compose(I_{p-2}, e, I_{p-1}),
                        process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                        compose(I_p, TY_p, I_{p+1}), \ldots, compose(I_t, TY_t, I_{t+1}),
                        HY = I_{t+1}, compose(NA, HY, NNA),
                        r \perp td_1(TXs, Y, NNA)
   By introducing new, i.e. existentially quantified, variables YU_1, \ldots, YU_{p-1} in place of some occur-
rences of e:
     clause 25: r \pm d_1(Xs, Y, A) \leftarrow
                        Xs = [X|TXs]
                        nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                        (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                        minimal(TX_p), \ldots, minimal(TX_t),
                        minimal(U_1), \ldots, minimal(U_{p-1}),
                        r(U_1, YU_1), \ldots, r(U_{p-1}, YU_{p-1}),
                        r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                        compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \ldots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                        compose(A, K_{p-2}, NA),
                        I_0 = e
                        compose(I_0, YU_1, I_1), \ldots, compose(I_{p-2}, YU_{p-1}, I_{p-1}),
                        process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                        compose(I_p, TY_p, I_{p+1}), \ldots, compose(I_t, TY_t, I_{t+1}),
                        HY = I_{t+1}, compose(NA, HY, NNA),
                        r \perp t d_1(TXs, Y, NNA)
   By introducing nonMinimal(N) and decompose(N, HX, U_1, \ldots, U_{p-1}, TX_p, \ldots, TX_t), since
               \exists N: \mathcal{X}.nonMinimal(N) \land decompose(N, HX, U_1, \ldots, U_{p-1}, TX_p, \ldots, TX_t)
```

always holds (because N is existentially quantified):

```
clause 26: r \perp d_1(Xs, Y, A) \leftarrow
                    Xs = [X|TXs]
                    nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                    (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                    minimal(TX_p), \ldots, minimal(TX_t),
                    minimal(U_1), \ldots, minimal(U_{p-1}),
                    r(U_1, YU_1), \ldots, r(U_{p-1}, YU_{p-1}),
                    nonMinimal(N), decompose(N, HX, U_1, \dots, U_{p-1}, TX_p, \dots, TX_t),
                    r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                    compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \dots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                    compose(A, K_{p-2}, NA),
                    I_0 = e,
                    compose(I_0, YU_1, I_1), \ldots, compose(I_{p-2}, YU_{p-1}, I_{p-1}),
                    process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                    compose(I_p, TY_p, I_{p+1}), \ldots, compose(I_t, TY_t, I_{t+1}),
                    HY = I_{t+1}, compose(NA, HY, NNA),
                    r \perp td_1(TXs, Y, NNA)
By duplicating goal decompose(N, HX, U_1, \ldots, U_{p-1}, TX_p, \ldots, TX_t):
 clause 27: r \not = d_1(Xs, Y, A) \leftarrow
                    Xs = [X|TXs]
                    nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                    (nonMinimal(TX_1); \ldots; nonMinimal(TX_{n-1})),
                    minimal(TX_p), \ldots, minimal(TX_t),
                    minimal(U_1), \ldots, minimal(U_{p-1}),
                    r(U_1, YU_1), \ldots, r(U_{p-1}, YU_{p-1}),
                    nonMinimal(N), decompose(N, HX, U_1, \ldots, U_{p-1}, TX_p, \ldots, TX_t),
                    decompose(N, HX, U_1, \ldots, U_{p-1}, TX_p, \ldots, TX_t),
                    r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                    compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \ldots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                    compose(A, K_{p-2}, NA),
                    I_0 = e,
                    compose(I_0, YU_1, I_1), \ldots, compose(I_{p-2}, YU_{p-1}, I_{p-1}),
                    process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                    compose(I_p, TY_p, I_{p+1}), \ldots, compose(I_t, TY_t, I_{t+1}),
                    HY = I_{t+1}, compose(NA, HY, NNA),
                    r \perp t d_1(TXs, Y, NNA)
By folding clause 27 using DCLR:
 clause 28: r \pm d_1(Xs, Y, A) \leftarrow
                    Xs = [X|TXs]
                    nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                    (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                    minimal(TX_p), \ldots, minimal(TX_t),
                    minimal(U_1), \ldots, minimal(U_{p-1}),
                    decompose(N, HX, U_1, \ldots, U_{p-1}, TX_p, \ldots, TX_t),
                    r(TX_1, TY_1), \ldots, r(TX_{p-1}, TY_{p-1}), r(N, HY),
                    compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \dots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                    compose(A, K_{p-2}, NA), compose(NA, HY, NNA),
                    r \perp td_1(TXs, Y, NNA)
```

By folding clause 28 using clauses 1 and 2:

```
clause 29: r \perp d_1(Xs, Y, A) \leftarrow
                        Xs = [X|TXs]
                        nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                        (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                        minimal(TX_p), \ldots, minimal(TX_t),
                        minimal(U_1), \ldots, minimal(U_{p-1}),
                        decompose(N, HX, U_1, \ldots, U_{p-1}, TX_p, \ldots, TX_t),
                        r(TX_1, TY_1), \ldots, r(TX_{p-1}, TY_{p-1}),
                        compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \dots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                        compose(A, K_{p-2}, NA),
                        r \perp td_1([N|TXs], Y, NA)
   By p-1 times folding clause 29 using clauses 1 and 2:
     clause 30: r \pm d_1(Xs, Y, A) \leftarrow
                        Xs = [X|TXs]
                        nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                        (nonMinimal(TX_1); ...; nonMinimal(TX_{p-1})),
                        minimal(TX_p), \ldots, minimal(TX_t),
                        minimal(U_1), \ldots, minimal(U_{p-1}),
                        decompose(N, HX, U_1, \ldots, U_{p-1}, TX_p, \ldots, TX_t),
                        r t d_1([TX_1, ..., TX_{p-1}, N|TXs], Y, A)
   By introducing atoms minimal(U_1), \ldots, minimal(U_t) (with new, i.e. existentially quantified, vari-
ables U_1, \ldots, U_t) in clause 8:
     clause 31: r \pm d_1(Xs, Y, A) \leftarrow
                        Xs = [X|TXs]
                        nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                        (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                        (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                        minimal(U_1), \ldots, minimal(U_t),
                        r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                        I_0 = e,
                        compose(I_0, TY_1, I_1), \ldots, compose(I_{p-2}, TY_{p-1}, I_{p-1}),
                        process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                        compose(I_p, TY_p, I_{p+1}), \ldots, compose(I_t, TY_t, I_{t+1}),
                        HY = I_{t+1}, compose(A, HY, NA),
                        r \perp td_1(TXs, Y, NA)
   By using applicability condition (3):
     clause 32: r t d_1(Xs, Y, A) \leftarrow
                        Xs = [X|TXs]
                        nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                        (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                        (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                        minimal(U_1), \ldots, minimal(U_t),
                        r(U_1,e),\ldots,r(U_t,e),
                        r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                        I_0 = e
                        compose(I_0, TY_1, I_1), \ldots, compose(I_{p-2}, TY_{p-1}, I_{p-1}),
                        process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                        compose(I_p, TY_p, I_{p+1}), \ldots, compose(I_t, TY_t, I_{t+1}),
                        HY = I_{t+1}, compose(A, HY, NA),
```

By using applicability condition (2):

 $r \perp td_1(TXs, Y, NA)$ 

```
clause 33: r \perp d_1(Xs, Y, A) \leftarrow
                        Xs = [X|TXs]
                        nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                        (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                        (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                        minimal(U_1), \ldots, minimal(U_t),
                        r(U_1,e),\ldots,r(U_t,e),
                        r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                        I_0 = e,
                        compose(I_0, TY_1, I_1), \ldots, compose(I_{p-2}, TY_{p-1}, I_{p-1}),
                        compose(I_{p-1}, e, K_1), compose(K_1, e, K_2), \ldots, compose(K_{p-2}, e, K_{p-1}),
                        process(HX, HHY), compose(K_{p-1}, HHY, K_p),
                        compose(K_p, e, K_{p+1}), \ldots, compose(K_t, e, K_{t+1}), compose(K_{t+1}, e, I_p),
                        compose(I_p, TY_p, I_{p+1}), \ldots, compose(I_t, TY_t, I_{t+1}),
                        HY = I_{t+1}, compose(A, HY, NA),
                        r \perp td_1(TXs, Y, NA)
   By using applicability conditions (1) and (2):
    clause 34: r t d_1(Xs, Y, A) \leftarrow
                        Xs = [X|TXs]
                        nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                        (nonMinimal(TX_1); ...; nonMinimal(TX_{p-1})),
                        (nonMinimal(TX_p); \dots; nonMinimal(TX_t)),
                        minimal(U_1), \ldots, minimal(U_t),
                        r(U_1,e),\ldots,r(U_t,e),
                        r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                        compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \dots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                        I_0 = e
                        compose(I_0, e, I_1), \ldots, compose(I_{p-2}, e, I_{p-1}),
                        process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                        compose(I_p, e, I_{p+1}), \ldots, compose(I_t, e, I_{t+1}),
                        NHY = I_{t+1}
                        compose(TY_p, TY_{p+1}, K_p), compose(K_p, TY_{p+2}, K_{p+1}), \ldots, compose(K_{t-2}, TY_t, K_{t-1}),
                        compose(A, K_{p-2}, NA), compose(NA, NHY, NA_1),
                        compose(NA_1, K_{t-1}, NA_2), r 1d_1(TXs, Y, NA_2)
   By introducing new, i.e. existentially quantified, variables YU_1, \ldots, YU_t in place of some occurrences
of e:
     clause 35: r \pm d_1(Xs, Y, A) \leftarrow
                        Xs = [X|TXs].
                        nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                        (nonMinimal(TX_1); \dots; nonMinimal(TX_{p-1})),
                        (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                        minimal(U_1), \ldots, minimal(U_t),
                        r(U_1, YU_1), \ldots, r(U_t, YU_t),
                        r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                        compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \dots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                        I_0 = e,
                        compose(I_0, YU_1, I_1), \ldots, compose(I_{p-2}, YU_{p-1}, I_{p-1}),
                        process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                        compose(I_p, YU_p, I_{p+1}), \ldots, compose(I_t, YU_t, I_{t+1}),
                        NHY = I_{t+1},
                        compose(TY_p, TY_{p+1}, K_p), compose(K_p, TY_{p+2}, K_{p+1}), \ldots, compose(K_{t-2}, TY_t, K_{t-1}),
                        compose(A, K_{p-2}, NA), compose(NA, NHY, NA_1),
                        compose(NA_1, K_{t-1}, NA_2), r 1d_1(TX_s, Y, NA_2)
   By introducing nonMinimal(N) and decompose(N, HX, U_1, ..., U_t), since
```

 $\exists N : \mathcal{X}.nonMinimal(N) \land decompose(N, HX, U_1, \ldots, U_t)$ 

always holds (because N is existentially quantified):

```
clause 36: r \pm d_1(Xs, Y, A) \leftarrow
                                      Xs = [X|TXs]
                                      nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                                      (nonMinimal(TX_1); \dots; nonMinimal(TX_{p-1})),
                                      (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                                      minimal(U_1), \ldots, minimal(U_t),
                                      r(U_1, YU_1), \ldots, r(U_t, YU_t),
                                      nonMinimal(N), decompose(N, HX, U_1, ..., U_t),
                                      r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                                      compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \dots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                                      I_0 = e,
                                      compose(I_0, YU_1, I_1), \ldots, compose(I_{p-2}, YU_{p-1}, I_{p-1}),
                                      process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                                      compose(I_p, YU_p, I_{p+1}), \ldots, compose(I_t, YU_t, I_{t+1}),
                                      NHY = I_{t+1}
                                      compose(TY_p, TY_{p+1}, K_p), compose(K_p, TY_{p+2}, K_{p+1}), \ldots, compose(K_{t-2}, TY_t, K_{t-1}), \ldots
                                      compose(A, K_{p-2}, NA), compose(NA, NHY, NA_1),
                                      compose(NA_1, K_{t-1}, NA_2), r 1d_1(TX_s, Y, NA_2)
By duplicating goal decompose(N, HX, U_1, \ldots, U_t):
  clause 37: r t d_1(Xs, Y, A) \leftarrow
                                      Xs = [X|TXs]
                                      nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                                      (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                                      (nonMinimal(TX_p); \dots; nonMinimal(TX_t)),
                                      minimal(U_1), \ldots, minimal(U_t),
                                      r(U_1, YU_1), \ldots, r(U_t, YU_t),
                                      nonMinimal(N), decompose(N, HX, U_1, ..., U_t),
                                      decompose(N, HX, U_1, \ldots, U_t),
                                      r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                                      compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \ldots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                                      I_0 = e,
                                      compose(I_0, YU_1, I_1), \ldots, compose(I_{p-2}, YU_{p-1}, I_{p-1}),
                                      process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                                      compose(I_p, YU_p, I_{p+1}), \ldots, compose(I_t, YU_t, I_{t+1}),
                                      NHY = I_{t+1}
                                      compose(TY_p, TY_{p+1}, K_p), compose(K_p, TY_{p+2}, K_{p+1}), \ldots, compose(K_{t-2}, TY_t, K_{t-1}),
                                      compose(A, K_{p-2}, NA), compose(NA, NHY, NA_1),
                                      compose(NA_1, K_{t-1}, NA_2), r \bot d_1(TX_s, Y, NA_2)
By folding clause 37 using DCLR:
  clause 38: r t d_1(Xs, Y, A) \leftarrow
                                      Xs = [X|TXs]
                                      nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                                      (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                                      (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                                      minimal(U_1), \ldots, minimal(U_t),
                                      decompose(N, HX, U_1, \ldots, U_t),
                                      r(TX_1, TY_1), \ldots, r(TX_t, TY_t), r(N, NHY),
                                      compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \dots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                                      compose(TY_p, TY_{p+1}, K_p), compose(K_p, TY_{p+2}, K_{p+1}), \ldots, compose(K_{t-2}, TY_t, K_{t-1}),
                                      compose(A, K_{p-2}, NA), compose(NA, NHY, NA_1),
                                      compose(NA_1, K_{t-1}, NA_2), r \bot d_1(TX_s, Y, NA_2)
```

By t - p + 1 times folding clause 38 using clauses 1 and 2:

```
clause 39: r \sharp d_1(Xs,Y,A) \leftarrow Xs = [X|TXs],

nonMinimal(X), decompose(X,HX,TX_1,\ldots,TX_t),

(nonMinimal(TX_1);\ldots;nonMinimal(TX_{p-1})),

(nonMinimal(TX_p);\ldots;nonMinimal(TX_t)),

minimal(U_1),\ldots,minimal(U_t),

decompose(N,HX,U_1,\ldots,U_t),

r(TX_1,TY_1),\ldots,r(TX_{p-1},TY_{p-1}),r(N,NHY),

compose(TY_1,TY_2,K_1),compose(K_1,TY_3,K_2),\ldots,compose(K_{p-3},TY_{p-1},K_{p-2}),

compose(A,K_{p-2},NA),compose(NA,NHY,NA_1),

r \sharp d_1([TX_p,\ldots,TX_t|TXs],Y,NA_1)
```

By folding clause 39 using clauses 1 and 2:

```
clause \ 40: \ r \sharp d_1(Xs,Y,A) \leftarrow \\ Xs = [X|TXs], \\ nonMinimal(X), decompose(X,HX,TX_1,\ldots,TX_t), \\ (nonMinimal(TX_1);\ldots;nonMinimal(TX_{p-1})), \\ (nonMinimal(TX_p);\ldots;nonMinimal(TX_t)), \\ minimal(U_1),\ldots,minimal(U_t), \\ decompose(N,HX,U_1,\ldots,U_t), \\ r(TX_1,TY_1),\ldots,r(TX_{p-1},TY_{p-1}), \\ compose(TY_1,TY_2,K_1), compose(K_1,TY_3,K_2),\ldots,compose(K_{p-3},TY_{p-1},K_{p-2}), \\ compose(A,K_{p-2},NA), \\ r \sharp d_1([N,TX_p,\ldots,TX_t|TXs],Y,NA)
```

By p-1 times folding clause 40 using clauses 1 and 2:

```
 \begin{aligned} clause \ 41: & r\sharp d_1(Xs,Y,A) \leftarrow \\ & Xs = [X|TXs], \\ & nonMinimal(X), decompose(X,HX,TX_1,\ldots,TX_t), \\ & (nonMinimal(TX_1);\ldots;nonMinimal(TX_{p-1})), \\ & (nonMinimal(TX_p);\ldots;nonMinimal(TX_t)), \\ & minimal(U_1),\ldots,minimal(U_t), \\ & decompose(N,HX,U_1,\ldots,U_t), \\ & r\sharp d_1([TX_1,\ldots,TX_{p-1},N,TX_p,\ldots,TX_t|TXs],Y,A) \end{aligned}
```

Clauses 1, 3, 13, 20, 30 and 41 are the clauses of  $P_{r_{-td_1}}$ . Therefore  $P_{r_{-td_1}}$  is steadfast wrt  $S_{r_{-td_1}}$  in S.

To prove that  $P_r$  is steadfast wrt  $S_r$  in  $\{S_{r-td_1}\}$ , we do a backward proof that we begin with  $P_r$  in TDGLR and from which we try to obtain  $S_r$ .

The procedure  $P_r$  for r in TDGLR is:

$$r(X,Y) \leftarrow r\_td_1([X],Y,e)$$

By taking the 'completion':

$$\forall X: \mathcal{X}, \forall Y: \mathcal{Y}. \ \mathcal{I}_r(X) \Rightarrow [r(X,Y) \Leftrightarrow r \perp td_1([X],Y,e)]$$

By unfolding the 'completion' above wrt  $r \perp d_1([X], Y, e)$  using  $S_{r \perp td_1}$ :

$$\forall X: \mathcal{X}, \forall Y: \mathcal{Y}. \quad \mathcal{I}_r(X) \Rightarrow [r(X,Y) \Leftrightarrow \exists Y_1, I_1: \mathcal{Y}. \quad \mathcal{O}_r(X,Y_1) \land I_1 = Y_1 \land \mathcal{O}_c(e,I_1,Y)]$$

By using applicability condition (2):

$$\forall X: \mathcal{X}, \forall Y: \mathcal{Y}. \ \mathcal{I}_r(X) \Rightarrow [r(X,Y) \Leftrightarrow \exists Y_1, I_1: \mathcal{Y}. \ \mathcal{O}_r(X,Y_1) \land I_1 = Y_1 \land Y = I_1]$$

By simplification:

$$\forall X : \mathcal{X}, \forall Y : \mathcal{Y}. \ \mathcal{I}_r(X)) \Rightarrow [r(X,Y) \Leftrightarrow \mathcal{O}_r(X,Y)]$$

We obtain  $S_r$ , so  $P_r$  is steadfast wrt  $S_r$  in  $\{S_{r\_td_1}\}$ . Therefore, TDGLR is also steadfast wrt  $S_r$  in S.

**Theorem 8** The generalization schema  $TDG_2$ , which is given below, is correct.

```
TDG_2: \langle \ DCLR, \ TDGRL, \ A_{td2} \ O_{td212}, \ O_{td221} \ \rangle \ \text{where}
A_{td2}: (1) \ compose \ \text{is associative}
(2) \ compose \ \text{has } e \ \text{as the left and right identity element}
(3) \ \forall X: \mathcal{X}. \ \mathcal{I}_r(X) \land minimal(X) \Rightarrow \mathcal{O}_r(X, e)
(4) \ \forall X: \mathcal{X}. \ \mathcal{I}_r(X) \Rightarrow [\neg minimal(X) \Leftrightarrow nonMinimal(X)]
O_{td212}: \ \text{partial evaluation of the conjunction}
process(HX, HY), compose(HY, A, NewA)
\text{results in the introduction of a non-recursive relation}
O_{td221}: \ \text{partial evaluation of the conjunction}
process(HX, HY), compose(I_{p-1}, HY, I_p)
\text{results in the introduction of a non-recursive relation}
```

where the template DCLR is Logic Program Template 1 in Section 2 and the template TDGRL is Logic Program Template 7 below.

## Logic Program Template 7

```
r(X, Y) \leftarrow
     r_td_2([X], Y, e)
r_td_2(Xs,Y,A) \leftarrow
     Xs = []
     {\tt Y}={\tt A}
r_td_2(Xs, Y, A) \leftarrow
     Xs = [X|TXs],
     minimal(X),
     r_{td_2}(TXs, NewA, A),
     solve(X, HY),
     compose(HY, NewA, Y)
r_td_2(Xs, Y, A) \leftarrow
     Xs = [X|TXs],
     nonMinimal(X),
     decompose(X, HX, TX_1, ..., TX_t),
     minimal(TX_1), \dots, minimal(TX_t),
     r_td_2(TXs, NewA, A),
     process(HX, HY), compose(HY, NewA, Y)
r_td_2(Xs, Y, A) \leftarrow
     Xs = [X|TXs],
     nonMinimal(X),
     decompose(X, HX, TX_1, ..., TX_t),
     {\tt minimal}({\tt TX}_1), \ldots, {\tt minimal}({\tt TX}_{\tt D-1}),
     (nonMinimal(TX_p); ...; nonMinimal(TX_t)),
     r_{td_2}([TX_D, ..., TX_t|TX_s], NewA, A),
     process(HX, HY), compose(HY, NewA, Y)
r_td_2(Xs, Y, A) \leftarrow
     Xs = [X|TXs],
     nonMinimal(X),
     decompose(X, HX, TX_1, ..., TX_t),
     (nonMinimal(TX_1); ...; nonMinimal(TX_{p-1})),
     minimal(TXp), ..., minimal(TXt),
     minimal(U_1), \ldots, minimal(U_{p-1}),
```

$$\begin{split} & \texttt{decompose}(\textbf{N}, \texttt{HX}, \texttt{U}_1, \dots, \texttt{U}_{p-1}, \texttt{TX}_p, \dots, \texttt{TX}_t), \\ & r\_\texttt{td}_2([\texttt{TX}_1, \dots, \texttt{TX}_{p-1}, \texttt{N}|\texttt{TX}_s], \texttt{Y}, \texttt{A}) \\ & r\_\texttt{td}_2(\texttt{Xs}, \texttt{Y}, \texttt{A}) \leftarrow \\ & \texttt{Xs} = [\texttt{X}|\texttt{TXs}], \\ & \texttt{nonMinimal}(\texttt{X}), \\ & \texttt{decompose}(\texttt{X}, \texttt{HX}, \texttt{TX}_1, \dots, \texttt{TX}_t), \\ & (\texttt{nonMinimal}(\texttt{TX}_1); \dots; \texttt{nonMinimal}(\texttt{TX}_{p-1})), \\ & (\texttt{nonMinimal}(\texttt{TX}_p); \dots; \texttt{nonMinimal}(\texttt{TX}_t)), \\ & \texttt{minimal}(\texttt{U}_1), \dots, \texttt{minimal}(\texttt{U}_t), \\ & \texttt{decompose}(\texttt{N}, \texttt{HX}, \texttt{U}_1, \dots, \texttt{U}_t), \\ & r\_\texttt{td}_2([\texttt{TX}_1, \dots, \texttt{TX}_{p-1}, \texttt{N}, \texttt{TX}_p, \dots, \texttt{TX}_t|\texttt{TXs}], \texttt{Y}, \texttt{A}) \end{split}$$

and the specification  $S_r$  of relation r is:

$$\forall X : \mathcal{X}, \forall Y : \mathcal{Y}. \ \mathcal{I}_r(X) \Rightarrow [r(X,Y) \Leftrightarrow \mathcal{O}_r(X,Y)]$$

and the specification of  $r \perp d_2$ , namely  $S_{r \perp td_2}$ , is:

$$\forall Xs: list \ of \ \mathcal{X}, \forall Y, A: \mathcal{Y}. \quad (\forall X: \mathcal{X}. \ X \in Xs \Rightarrow \mathcal{I}_r(X)) \Rightarrow [r \pm d_2(Xs, Y, A) \Leftrightarrow (Xs = [] \land Y = A) \\ \lor (Xs = [X_1, X_2, \dots, X_q] \land \bigwedge_{i=1}^q \mathcal{O}_r(X_i, Y_i) \quad \land I_1 = Y_1 \land \bigwedge_{i=2}^q \mathcal{O}_c(I_{i-1}, Y_i, I_i) \\ \land \mathcal{O}_c(I_q, A, I_{q+1}) \land Y = I_{q+1})]$$

**Proof 8** To prove the correctness of the generalization schema  $TDG_2$ , by Definition 10, we have to prove that templates DCLR and TDGRL are equivalent wrt  $S_r$  under the applicability conditions  $A_{td2}$ . By Definition 5, the templates DCLR and TDGRL are equivalent wrt  $S_r$  under the applicability conditions  $A_{td2}$  iff DCLR is equivalent to TDGRL wrt the specification  $S_r$  provided that the conditions in  $A_{td2}$  hold. By Definition 4, DCLR is equivalent to TDGRL wrt the specification  $S_r$  iff the following two conditions hold:

- (a) DCLR is steadfast wrt  $S_r$  in  $S = \{S_{minimal}, S_{nonMinimal}, S_{solve}, S_{decompose}, S_{process}, S_{compose}\}$ , where  $S_{minimal}, S_{nonMinimal}, S_{solve}, S_{decompose}, S_{process}, S_{compose}$  are the specifications of minimal, nonMinimal, solve, decompose, process, compose, which are all the undefined relation names appearing in DCLR.
- (b) TDGRL is also steadfast wrt  $S_r$  in S.

Note that the sets  $\{S_1, \ldots, S_m\}$  and  $\{S'_1, \ldots, S'_t\}$  in Definition 4 are equal to  $\mathcal{S}$  when Q is obtained by simultaneous tupling-and-descending generalization of P.

In program transformation, we assume that the input program, here template DCLR, is steadfast wrt  $S_r$  in S, so condition (a) always holds.

To prove equivalence, we have to prove condition (b). We will use the following property of steadfastness: TDGRL is steadfast wrt  $S_r$  in  $\mathcal{S}$  if  $P_{r\_td_2}$  is steadfast wrt  $S_{r\_td_2}$  in  $\mathcal{S}$ , where  $P_{r\_td_2}$  is the procedure for  $r\_td_2$ , and  $P_r$  is steadfast wrt  $S_r$  in  $\{S_{r\_td_2}\}$ , where  $P_r$  is the procedure for r.

To prove that  $P_{r_{-}td_2}$  is steadfast wrt  $S_{r_{-}td_2}$  in S, we do a constructive forward proof that we begin with  $S_{r_{-}td_2}$  and from which we try to obtain  $P_{r_{-}td_2}$ .

If we separate the cases of  $q \ge 1$  by  $q = 1 \lor q \ge 2$ , then  $S_{r\_td_2}$  becomes:

```
\begin{array}{l} \forall Xs: \mathit{list of } \mathcal{X}, \forall Y: \mathcal{Y}: \mathcal{Y}. \  \, (\forall X: \mathcal{X}. \ X \in Xs \Rightarrow \mathcal{I}_r(X)) \Rightarrow [r \, \mathcal{I} d_2(Xs, Y, A) \Leftrightarrow \\ (Xs = [] \land Y = A) \\ \lor (Xs = [X_1] \land \mathcal{O}_r(X_1, Y_1) \land Y_1 = I_1 \land \mathcal{O}_c(I_1, A, I_2) \land Y = I_2) \\ \lor (Xs = [X_1, X_2, \ldots, X_q] \land \bigwedge_{i=1}^q \mathcal{O}_r(X_i, Y_i) \  \, \land I_1 = Y_1 \land \bigwedge_{i=2}^q \mathcal{O}_c(I_{i-1}, Y_i, I_i) \  \, \land \\ \mathcal{O}_c(I_q, A, I_{q+1}) \land Y = I_{q+1})] \end{array}
```

By using applicability conditions (1) and (2):

where  $q \geq 2$ .

```
 \forall Xs: list \ of \ \mathcal{X}, \forall Y: \mathcal{Y}: \ (\forall X: \mathcal{X}: X \in Xs \Rightarrow \mathcal{I}_r(X)) \Rightarrow [r \, \mathcal{I}d_2(Xs, Y, A) \Leftrightarrow (Xs = [] \land Y = A)   \forall (Xs = [X_1 \mid TXs] \land TXs = [] \land \mathcal{O}_r(X_1, Y_1) \land Y_1 = I_1 \land TY = A \land \mathcal{O}_c(TY, A, NA) \land \mathcal{O}_c(I_1, NA, Y))   \forall (Xs = [X_1 \mid TXs] \land TXs = [X_2, \dots, X_q] \land \ \bigwedge_{i=1}^q \mathcal{O}_r(X_i, Y_i) \ \land Y_1 = I_1 \land Y_2 = I_2 \land   \bigwedge_{i=3}^q \mathcal{O}_c(I_{i-1}, Y_i, I_i) \ \land TY = I_q \land \mathcal{O}_c(TY, A, NA) \land \mathcal{O}_c(I_1, NA, Y)) ]
```

```
where q \geq 2.
```

By folding using  $S_{r-td_2}$ , and renaming:

```
\forall Xs : list \ of \ \mathcal{X}, \forall Y : \mathcal{Y}. \ (\forall X : \mathcal{X}. \ X \in Xs \Rightarrow \mathcal{I}_r(X)) \Rightarrow [r \, \mathcal{I}d_2(Xs, Y, A) \Leftrightarrow (Xs = [] \land Y = A) \\ \lor (Xs = [X|TXs] \land \mathcal{O}_r(X, HY) \land r \, \mathcal{I}d_2(TXs, NA, A) \land \mathcal{O}_c(HY, NA, Y))]
```

By taking the 'decompletion':

```
\begin{array}{ll} clause \ 1: & r \not \bot d_2(Xs,Y,A) \leftarrow \\ & Xs = [],Y = A \\ clause \ 2: & r \not \bot d_2(Xs,Y,A) \leftarrow \\ & Xs = [X|TXs],r(X,HY), \\ & r \not \bot d_2(TXs,NA,A),compose(HY,NA,Y) \end{array}
```

By unfolding clause 2 wrt r(X, HY) using DCLR, and using the assumption that DCLR is steadfast wrt  $S_r$  in S:

```
clause 3: r \pm d_2(Xs, Y, A) \leftarrow Xs = [X|TXs],

minimal(X),

solve(X, HY),

r \pm d_2(TXs, NA, A), compose(HY, NA, Y)

clause 4: r \pm d_2(Xs, Y, A) \leftarrow Xs = [X|TXs],

nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),

r(TX_1, TY_1), ..., r(TX_t, TY_t),

I_0 = e,

compose(I_0, TY_1, I_1), ..., compose(I_{p-2}, TY_{p-1}, I_{p-1}),

process(HX, HHY), compose(I_{p-1}, HHY, I_p),

compose(I_p, TY_p, I_{p+1}), ..., compose(I_t, TY_t, I_{t+1}),

HY = I_{t+1},

r \pm d_2(TXs, NA, A), compose(HY, NA, Y)
```

By introducing

```
(minimal(TX_1) \land \ldots \land minimal(TX_t)) \lor \\ ((minimal(TX_1) \land \ldots \land minimal(TX_{p-1})) \land (nonMinimal(TX_p) \lor \ldots \lor nonMinimal(TX_t))) \lor \\ ((nonMinimal(TX_1) \lor \ldots \lor nonMinimal(TX_{p-1})) \land (minimal(TX_p) \land \ldots \land minimal(TX_t))) \lor \\ ((nonMinimal(TX_1) \lor \ldots \lor nonMinimal(TX_{p-1})) \land (nonMinimal(TX_p) \lor \ldots \lor nonMinimal(TX_t))) \\ \text{in clause 4, using applicability condition (4):}
```

```
clause 5: r \pm d_2(Xs, Y, A) \leftarrow Xs = [X|TXs],

nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),

minimal(TX_1), ..., minimal(TX_t),

r(TX_1, TY_1), ..., r(TX_t, TY_t),

I_0 = e,

compose(I_0, TY_1, I_1), ..., compose(I_{p-2}, TY_{p-1}, I_{p-1}),

process(HX, HHY), compose(I_{p-1}, HHY, I_p),

compose(I_p, TY_p, I_{p+1}), ..., compose(I_t, TY_t, I_{t+1}),

HY = I_{t+1},

r \pm d_2(TXs, NA, A), compose(HY, NA, Y)
```

```
Xs = [X|TXs],
                      nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                      minimal(TX_1), \ldots, minimal(TX_{p-1}),
                      (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                      r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                      I_0 = e
                      compose(I_0, TY_1, I_1), \ldots, compose(I_{p-2}, TY_{p-1}, I_{p-1}),
                      process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                      compose(I_p, TY_p, I_{p+1}), \ldots, compose(I_t, TY_t, I_{t+1}),
                      HY = I_{t+1}
                      r\_td_2(TXs, NA, A), compose(HY, NA, Y)
    clause 7: rtd_2(Xs, Y, A) \leftarrow
                      Xs = [X|TXs],
                      nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                      (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                      minimal(TX_p), \ldots, minimal(TX_t),
                      r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                      I_0 = e
                      compose(I_0, TY_1, I_1), \ldots, compose(I_{p-2}, TY_{p-1}, I_{p-1}),
                      process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                      compose(I_p, TY_p, I_{p+1}), \ldots, compose(I_t, TY_t, I_{t+1}),
                      HY = I_{t+1}
                      r \perp td_2(TXs, NA, A), compose(HY, NA, Y)
     clause 8: r \not d_2(Xs, Y, A) \leftarrow
                      Xs = [X|TXs]
                      nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                      (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                      (nonMinimal(TX_p); \dots; nonMinimal(TX_t)),
                      r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                      I_0 = e
                      compose(I_0, TY_1, I_1), \ldots, compose(I_{p-2}, TY_{p-1}, I_{p-1}),
                      process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                      compose(I_p, TY_p, I_{p+1}), \ldots, compose(I_t, TY_t, I_{t+1}),
                      HY = I_{t+1}
                      r \perp td_2(TXs, NA, A), compose(HY, NA, Y)
   By t times unfolding clause 5 wrt r(TX_1, TY_1), \ldots, r(TX_t, TY_t) using DCLR, and simplifying using
condition (4):
     clause 9: r td_2(Xs, Y, A) \leftarrow
                       Xs = [X|TXs],
                      nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                      minimal(TX_1), \ldots, minimal(TX_t),
                      minimal(TX_1), \ldots, minimal(TX_t)
                      solve(TX_1, TY_1), \ldots, solve(TX_t, TY_t)
                      compose(I_0, TY_1, I_1), \ldots, compose(I_{p-2}, TY_{p-1}, I_{p-1}),
                      process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                      compose(I_p, TY_p, I_{p+1}), \ldots, compose(I_t, TY_t, I_{t+1}),
                      HY = I_{t+1},
                      r\_td_2(TXs, NA, A), compose(HY, NA, Y)
```

By using applicability condition (3):

clause 6:  $r \pm d_2(Xs, Y, A) \leftarrow$ 

```
clause 10: r \perp d_2(Xs, Y, A) \leftarrow
                    Xs = [X|TXs]
                    nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                    minimal(TX_1), \ldots, minimal(TX_t),
                    minimal(TX_1), \ldots, minimal(TX_t),
                    solve(TX_1, e), \ldots, solve(TX_t, e),
                    I_0 = e,
                    compose(I_0, e, I_1), \ldots, compose(I_{p-2}, e, I_{p-1}),
                    process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                    compose(I_p, e, I_{p+1}), \ldots, compose(I_t, e, I_{t+1}),
                    HY = I_{t+1}
                    r \perp td_2(TXs, NA, A), compose(HY, NA, Y)
By deleting one of the minimal(TX_1), \ldots, minimal(TX_t) atoms in clause 10:
 clause 11: r \pm d_2(Xs, Y, A) \leftarrow
                    Xs = [X|TXs],
                    nonMinimal(X), decompose(X, HX, TX_1, \dots, TX_t),
                    minimal(TX_1), \ldots, minimal(TX_t),
                    solve(TX_1, e), \ldots, solve(TX_t, e),
                    I_0 = e,
                    compose(I_0, e, I_1), \ldots, compose(I_{p-2}, e, I_{p-1}),
                    process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                    compose(I_p, e, I_{p+1}), \ldots, compose(I_t, e, I_{t+1}),
                    HY = I_{t+1},
                    r \perp td_2(TXs, NA, A), compose(HY, NA, Y)
By using applicability condition (2):
 clause 12: r \not = d_2(Xs, Y, A) \leftarrow
                    Xs = [X|TXs]
                    nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                    minimal(TX_1), \ldots, minimal(TX_t),
                    solve(TX_1, e), \ldots, solve(TX_t, e),
                    I_0 = e,
                    I_1 = I_0, \ldots, I_{p-1} = I_{p-2},
                    process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                    I_{p+1} = I_p, \ldots, I_{t+1} = I_t,
                    HY = I_{t+1},
                    r \perp td_2(TXs, NA, A), compose(HY, NA, Y)
By simplification:
 clause 13: r t d_2(Xs, Y, A) \leftarrow
                    Xs = [X|TXs],
                    nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                    minimal(TX_1), \ldots, minimal(TX_t),
                    r \perp td_2(TXs, NA, A),
                    process(HX, HY), compose(HY, NA, Y)
By p-1 times unfolding clause 6 wrt r(TX_1, TY_1), \ldots, r(TX_{p-1}, TY_{p-1}) using DCLR, and simplifying
```

using condition (4):

```
clause 14: r \perp d_2(Xs, Y, A) \leftarrow
                    Xs = [X|TXs]
                    nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                    minimal(TX_1), \ldots, minimal(TX_{p-1}),
                    (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                    minimal(TX_1), \ldots, minimal(TX_{p-1}),
                    solve(TX_1, TY_1), \ldots, solve(TX_{p-1}, TY_{p-1}),
                    r(TX_p, TY_p), \ldots, r(TX_t, TY_t),
                    I_0 = e
                    compose(I_0, TY_1, I_1), \ldots, compose(I_{p-2}, TY_{p-1}, I_{p-1}),
                    process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                    compose(I_p, TY_p, I_{p+1}), \ldots, compose(I_t, TY_t, I_{t+1}),
                    HY = I_{t+1}
                    r \perp td_2(TXs, NA, A), compose(HY, NA, Y)
By deleting one of the minimal(TX_1), \ldots, minimal(TX_{p-1}) atoms in clause 14:
 clause 15: r \pm d_2(Xs, Y, A) \leftarrow
                    Xs = [X|TXs],
                    nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                    minimal(TX_1), \ldots, minimal(TX_{p-1}),
                    (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                    solve(TX_1, TY_1), \ldots, solve(TX_{p-1}, TY_{p-1}),
                    r(TX_p, TY_p), \ldots, r(TX_t, TY_t),
                    I_0 = e,
                    compose(I_0, TY_1, I_1), \ldots, compose(I_{p-2}, TY_{p-1}, I_{p-1}),
                    process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                    compose(I_p, TY_p, I_{p+1}), \ldots, compose(I_t, TY_t, I_{t+1}),
                    HY = I_{t+1}
                    r \perp td_2(TXs, NA, A), compose(HY, NA, Y)
By rewriting clause 15 using applicability condition (1):
 clause 16: r \pm d_2(Xs, Y, A) \leftarrow
                    Xs = [X|TXs].
                    nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                    minimal(TX_1), \ldots, minimal(TX_{p-1}),
                    (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                    solve(TX_1, TY_1), \ldots, solve(TX_{p-1}, TY_{p-1}),
                    r(TX_p, TY_p), \ldots, r(TX_t, TY_t),
                    I_0 = e
                    compose(I_0, TY_1, I_1), \ldots, compose(I_{p-2}, TY_{p-1}, I_{p-1}),
                    process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                    HY = I_p, compose(HY, NA, Y),
                    compose(TY_p, I_{p+1}, NA),
                    compose(TY_{p+1}, I_{p+2}, I_{p+1}), \ldots, compose(TY_{t-1}, I_t, I_{t-1}),
                    compose(TY_t, NNA, I_t),
                    r \perp td_2(TXs, NNA, A)
```

By t-p times folding clause 16 using clauses 1 and 2:

```
clause 17: r \perp d_2(Xs, Y, A) \leftarrow
                    Xs = [X|TXs]
                    nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                    minimal(TX_1), \ldots, minimal(TX_{p-1}),
                    (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                    solve(TX_1, TY_1), \ldots, solve(TX_{p-1}, TY_{p-1}),
                    compose(I_0, TY_1, I_1), \ldots, compose(I_{p-2}, TY_{p-1}, I_{p-1}),
                    process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                    HY = I_p,
                    r \perp td_2([TX_p, \ldots, TX_t|TXs], NA, A), compose(HY, NA, Y)
By using applicability condition (3):
 clause 18: r \pm d_2(Xs, Y, A) \leftarrow
                    Xs = [X|TXs]
                    nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                    minimal(TX_1), \ldots, minimal(TX_{p-1}),
                    (nonMinimal(TX_p); \dots; nonMinimal(TX_t)),
                    solve(TX_1,e),\ldots,solve(TX_{p-1},e),
                    compose(I_0, e, I_1), \ldots, compose(I_{p-2}, e, I_{p-1}),
                    process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                    r \perp td_2([TX_p, \ldots, TX_t|TXs], NA, A), compose(HY, NA, Y)
By using applicability condition (2):
 clause 19: r t d_2(Xs, Y, A) \leftarrow
                    Xs = [X|TXs]
                    nonMinimal(X), decompose(X, HX, TX_1, \dots, TX_t),
                    minimal(TX_1), \ldots, minimal(TX_{p-1}),
                    (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                    solve(TX_1, e), \ldots, solve(TX_{p-1}, e),
                    I_0 = e,
                    I_1 = I_0, \ldots, I_{p-1} = I_{p-2},
                    process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                    HY = I_{p},
                    r \perp td_2([TX_p, \ldots, TX_t|TXs], NA, A), compose(HY, NA, Y)
By simplification:
 clause 20 : r t d_2(Xs, Y, A) \leftarrow
                    Xs = [X|TXs].
                    nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                    minimal(TX_1), \ldots, minimal(TX_{p-1}),
                    (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                    r \pm d_2([TX_p, \ldots, TX_t|TXs], NA, A),
                    process(HX, HY), compose(HY, NA, Y)
```

By introducing atoms  $minimal(U_1), \ldots, minimal(U_{p-1})$  (with new, i.e. existentially quantified, variables  $U_1, \ldots, U_{p-1}$ ) in clause 7:

```
clause 21: r \perp d_2(Xs, Y, A) \leftarrow
                    Xs = [X|TXs]
                    nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                    (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                    minimal(TX_p), \ldots, minimal(TX_t),
                    minimal(U_1), \ldots, minimal(U_{p-1}),
                    r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                    I_0 = e,
                    compose(I_0, TY_1, I_1), \ldots, compose(I_{p-2}, TY_{p-1}, I_{p-1}),
                    process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                    compose(I_p, TY_p, I_{p+1}), \ldots, compose(I_t, TY_t, I_{t+1}),
                    HY = I_{t+1}
                    r \pm t d_2(TXs, NA, A), compose(HY, NA, Y)
By using applicability condition (3):
 clause 22: r t d_2(Xs, Y, A) \leftarrow
                    Xs = [X|TXs]
                    nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                    (nonMinimal(TX_1); \ldots; nonMinimal(TX_{n-1})),
                    minimal(TX_p), \ldots, minimal(TX_t),
                    minimal(U_1), \ldots, minimal(U_{p-1}),
                    r(U_1,e),\ldots,r(U_{p-1},e),
                    r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                    I_0 = e,
                    compose(I_0, TY_1, I_1), \ldots, compose(I_{p-2}, TY_{p-1}, I_{p-1}),
                    process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                    compose(I_p, TY_p, I_{p+1}), \ldots, compose(I_t, TY_t, I_{t+1}),
                    HY = I_{t+1},
                    r \perp td_2(TXs, NA, A), compose(HY, NA, Y)
By using applicability condition (2):
 clause 23: r t d_2(Xs, Y, A) \leftarrow
                    Xs = [X|TXs].
                    nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                    (nonMinimal(TX_1); ...; nonMinimal(TX_{p-1})),
                    minimal(TX_p), \ldots, minimal(TX_t),
                    minimal(U_1), \ldots, minimal(U_{p-1}),
                    r(U_1,e),\ldots,r(U_{p-1},e),
                    r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                    I_0 = e,
                    compose(I_0, TY_1, I_1), \ldots, compose(I_{p-2}, TY_{p-1}, I_{p-1}),
                    compose(I_{p-1}, e, K_1), compose(K_1, e, K_2), \ldots, compose(K_{p-2}, e, K_{p-1}),
                    process(HX, HHY), compose(K_{p-1}, HHY, I_p),
                    compose(I_p, TY_p, I_{p+1}), \ldots, compose(I_t, TY_t, I_{t+1}),
                    HY = I_{t+1}
                    r \perp td_2(TXs, NA, A), compose(HY, NA, Y)
```

By using applicability conditions (1) and (2):

```
clause 24: r \perp d_2(Xs, Y, A) \leftarrow
                        Xs = [X|TXs]
                        nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                        (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                        minimal(TX_p), \ldots, minimal(TX_t),
                        minimal(U_1), \ldots, minimal(U_{n-1}),
                        r(U_1,e),\ldots,r(U_{p-1},e),
                        r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                        compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \dots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                        compose(K_{p-2}, NA, Y),
                        I_0 = e,
                        compose(I_0, e, I_1), \ldots, compose(I_{p-2}, e, I_{p-1}),
                        process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                        compose(I_p, TY_p, I_{p+1}), \ldots, compose(I_t, TY_t, I_{t+1}),
                        HY = I_{t+1}, compose(HY, NNA, NA),
                        r \perp t d_2(TXs, NNA, A)
   By introducing new, i.e. existentially quantified, variables YU_1, \ldots, YU_{p-1} in place of some occur-
rences of e:
     clause 25: r \perp td_2(Xs, Y, A) \leftarrow
                        Xs = [X|TXs]
                        nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                        (nonMinimal(TX_1); \dots; nonMinimal(TX_{p-1})),
                        minimal(TX_p), \ldots, minimal(TX_t),
                        minimal(U_1), \ldots, minimal(U_{p-1}),
                        r(U_1, YU_1), \ldots, r(U_{p-1}, YU_{p-1}),
```

 $\begin{array}{l} {\it clause} \ 25: \ r {\it Id}_2(Xs,Y,A) \leftarrow \\ Xs = [X|TXs], \\ non Minimal(X), decompose(X,HX,TX_1,\ldots,TX_t), \\ (non Minimal(TX_1);\ldots;non Minimal(TX_{p-1})), \\ minimal(TX_p),\ldots,minimal(TX_t), \\ minimal(U_1),\ldots,minimal(U_{p-1}), \\ r(U_1,YU_1),\ldots,r(U_{p-1},YU_{p-1}), \\ r(TX_1,TY_1),\ldots,r(TX_t,TY_t), \\ compose(TY_1,TY_2,K_1), compose(K_1,TY_3,K_2),\ldots,compose(K_{p-3},TY_{p-1},K_{p-2}), \\ compose(K_{p-2},NA,Y), \\ I_0 = e, \\ compose(I_0,YU_1,I_1),\ldots,compose(I_{p-2},YU_{p-1},I_{p-1}), \\ process(HX,HHY),compose(I_{p-1},HHY,I_p), \\ compose(I_p,TY_p,I_{p+1}),\ldots,compose(I_t,TY_t,I_{t+1}), \\ HY = I_{t+1},compose(HY,NNA,NA), \\ r {\it Id}_2(TXs,NNA,A) \end{array}$ 

By introducing nonMinimal(N) and  $decompose(N, HX, U_1, \ldots, U_{p-1}, TX_p, \ldots, TX_t)$ , since

```
\exists N: \mathcal{X}.nonMinimal(N) \land decompose(N, HX, U_1, \ldots, U_{p-1}, TX_p, \ldots, TX_t)
```

always holds (because N is existentially quantified):

```
clause 26: r \not = d_2(Xs, Y, A) \leftarrow
                   Xs = [X|TXs],
                   nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                   (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                   minimal(TX_p), \ldots, minimal(TX_t),
                   nonMinimal(N), decompose(N, HX, U_1, \ldots, U_{p-1}, TX_p, \ldots, TX_t),
                   minimal(U_1), \ldots, minimal(U_{p-1}),
                   r(U_1, YU_1), \ldots, r(U_{p-1}, YU_{p-1}),
                   r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                   compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \dots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                   compose(K_{p-2}, NA, Y),
                   I_0 = e,
                   compose(I_0, YU_1, I_1), \ldots, compose(I_{p-2}, YU_{p-1}, I_{p-1}),
                   process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                   compose(I_p, TY_p, I_{p+1}), \ldots, compose(I_t, TY_t, I_{t+1}),
                   HY = I_{t+1}, compose(HY, NNA, NA),
                   r \perp td_2(TXs, NNA, A)
```

By duplicating goal  $decompose(N, HX, U_1, \ldots, U_{p-1}, TX_p, \ldots, TX_t)$ :

```
clause 27: r \perp d_2(Xs, Y, A) \leftarrow
                    Xs = [X|TXs]
                    nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                    (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                    minimal(TX_p), \ldots, minimal(TX_t),
                    nonMinimal(N), decompose(N, HX, U_1, \dots, U_{p-1}, TX_p, \dots, TX_t),
                    decompose(N, HX, U_1, \ldots, U_{p-1}, TX_p, \ldots, TX_t),
                    minimal(U_1), \ldots, minimal(U_{p-1}),
                    r(U_1, YU_1), \ldots, r(U_{p-1}, YU_{p-1}),
                    r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                    compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \ldots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                    compose(K_{p-2}, NA, Y),
                    I_0 = e,
                    compose(I_0, YU_1, I_1), \ldots, compose(I_{p-2}, YU_{p-1}, I_{p-1}),
                    process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                    compose(I_p, TY_p, I_{p+1}), \ldots, compose(I_t, TY_t, I_{t+1}),
                    HY = I_{t+1}, compose(HY, NNA, NA),
                    r \perp td_2(TXs, NNA, A)
By folding clause 27 using DCLR:
 clause 28: r \pm d_2(Xs, Y, A) \leftarrow
                    Xs = [X|TXs]
                    nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                    (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                    minimal(TX_p), \ldots, minimal(TX_t),
                    decompose(N, HX, U_1, \ldots, U_{p-1}, TX_p, \ldots, TX_t),
                    minimal(U_1), \ldots, minimal(U_{p-1}),
                    r(TX_1, TY_1), \ldots, r(TX_{p-1}, TY_{p-1}), r(N, HY),
                    compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \dots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                    compose(K_{p-2}, NA, Y), compose(HY, NNA, NA),
                    r \perp td_2(TXs, NNA, A)
By folding clause 28 using clauses 1 and 2:
 clause 29: r \pm d_2(Xs, Y, A) \leftarrow
                    Xs = [X|TXs],
                    nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                    (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                    minimal(TX_p), \ldots, minimal(TX_t),
                    decompose(N, HX, U_1, \ldots, U_{p-1}, TX_p, \ldots, TX_t),
                    minimal(U_1), \ldots, minimal(U_{p-1}),
                    r(TX_1, TY_1), \ldots, r(TX_{p-1}, TY_{p-1}), r(N, HY),
                    compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \ldots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                    compose(K_{p-2}, NA, Y),
                    r \perp td_2([N|TXs], NA, A)
By p-1 times folding clause 29 using clauses 1 and 2:
 clause 30: r \pm d_2(Xs, Y, A) \leftarrow
                    Xs = [X|TXs],
                    nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                    (nonMinimal(TX_1); \dots; nonMinimal(TX_{p-1})),
                    minimal(TX_p), \ldots, minimal(TX_t),
                    minimal(U_1), \ldots, minimal(U_{p-1}),
                    decompose(N, HX, U_1, \ldots, U_{p-1}, TX_p, \ldots, TX_t),
                    r \pm d_2([TX_1, \dots, TX_{p-1}, N|TXs], Y, A)
```

By introducing atoms  $minimal(U_1), \ldots, minimal(U_t)$  (with new, i.e. existentially quantified, variables  $U_1, \ldots, U_t$ ) in clause 8:

```
clause 31: r \perp d_2(Xs, Y, A) \leftarrow
                    Xs = [X|TXs]
                    nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                    (nonMinimal(TX_1); ...; nonMinimal(TX_{p-1})),
                    (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                    minimal(U_1), \ldots, minimal(U_t),
                    r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                    I_0 = e,
                    compose(I_0, TY_1, I_1), \ldots, compose(I_{p-2}, TY_{p-1}, I_{p-1}),
                    process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                    compose(I_p, TY_p, I_{p+1}), \ldots, compose(I_t, TY_t, I_{t+1}),
                    HY = I_{t+1}
                    r \pm t d_2(TXs, NA, A), compose(HY, NA, Y)
By using applicability condition (3):
 clause 32: r 1d_2(Xs, Y, A) \leftarrow
                    Xs = [X|TXs]
                    nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                    (nonMinimal(TX_1); \dots; nonMinimal(TX_{p-1})),
                    (nonMinimal(TX_p); \dots; nonMinimal(TX_t)),
                    minimal(U_1), \ldots, minimal(U_t),
                    r(U_1,e),\ldots,r(U_t,e),
                    r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                    I_0 = e,
                    compose(I_0, TY_1, I_1), \ldots, compose(I_{p-2}, TY_{p-1}, I_{p-1}),
                    process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                    compose(I_p, TY_p, I_{p+1}), \ldots, compose(I_t, TY_t, I_{t+1}),
                    HY = I_{t+1}
                    r \perp td_2(TXs, NA, A), compose(HY, NA, Y)
By using applicability condition (2):
 clause 33: r \pm d_2(Xs, Y, A) \leftarrow
                    Xs = [X|TXs].
                    nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                    (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                    (nonMinimal(TX_p); \dots; nonMinimal(TX_t)),
                    minimal(U_1), \ldots, minimal(U_t),
                    r(U_1,e),\ldots,r(U_t,e),
                    r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                    I_0 = e
                    compose(I_0, TY_1, I_1), \ldots, compose(I_{p-2}, TY_{p-1}, I_{p-1}),
                    compose(I_{p-1}, e, K_1), compose(K_1, e, K_2), \ldots, compose(K_{p-2}, e, K_{p-1}),
                    process(HX, HHY), compose(K_{p-1}, HHY, K_p),
                    compose(K_p, e, K_{p+1}), \ldots, compose(K_t, e, K_{t+1}), compose(K_{t+1}, e, I_p),
                    compose(I_p, TY_p, I_{p+1}), \ldots, compose(I_t, TY_t, I_{t+1}),
                    HY = I_{t+1}
                    r \perp td_2(TXs, NA, A), compose(HY, NA, Y)
```

By using applicability conditions (1) and (2):

```
clause 34: r \perp d_2(Xs, Y, A) \leftarrow
                                                                          Xs = [X|TXs]
                                                                          nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                                                                          (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                                                                          (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                                                                          minimal(U_1), \ldots, minimal(U_t),
                                                                          r(U_1,e),\ldots,r(U_t,e),
                                                                          r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                                                                         compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \dots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                                                                         I_0 = e,
                                                                         compose(I_0, e, I_1), \ldots, compose(I_{p-2}, e, I_{p-1}),
                                                                        process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                                                                         compose(I_p, e, I_{p+1}), \ldots, compose(I_t, e, I_{t+1}),
                                                                          NHY = I_{t+1},
                                                                         compose(TY_p, TY_{p+1}, K_p), compose(K_p, TY_{p+2}, K_{p+1}), \ldots, compose(K_{t-2}, TY_t, K_{t-1}), \ldots
                                                                         compose(K_{t-1}, NA, NA_1), compose(NHY, NA_1, NA_2),
                                                                         compose(K_{p-2}, NA_2, Y), r \perp td_2(TXs, NA, A)
```

By introducing new, i.e. existentially quantified, variables  $YU_1, \ldots, YU_t$  in place of some occurrences of e:

```
clause 35: r t d_2(Xs, Y, A) \leftarrow
                   Xs = [X|TXs]
                   nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                   (nonMinimal(TX_1); ...; nonMinimal(TX_{p-1})),
                   (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                   minimal(U_1), \ldots, minimal(U_t),
                   r(U_1, YU_1), \ldots, r(U_t, YU_t),
                   r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                   compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \dots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                   I_0 = e,
                   compose(I_0, YU_1, I_1), \ldots, compose(I_{p-2}, YU_{p-1}, I_{p-1}),
                   process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                   compose(I_p, YU_p, I_{p+1}), \ldots, compose(I_t, YU_t, I_{t+1}),
                   NHY = I_{t+1},
                   compose(TY_p, TY_{p+1}, K_p), compose(K_p, TY_{p+2}, K_{p+1}), \ldots, compose(K_{t-2}, TY_t, K_{t-1}),
                   compose(K_{t-1}, NA, NA_1), compose(NHY, NA_1, NA_2),
                   compose(K_{p-2}, NA_2, Y), r Id_2(TXs, NA, A)
```

By introducing nonMinimal(N) and  $decompose(N, HX, U_1, \ldots, U_t)$ , since

 $\exists N : \mathcal{X}.nonMinimal(N) \land decompose(N, HX, U_1, ..., U_t)$ 

always holds (because N is existentially quantified):

```
clause 36: r \perp d_2(Xs, Y, A) \leftarrow
                    Xs = [X|TXs]
                    nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                    (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                    (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                    minimal(U_1), \ldots, minimal(U_t),
                    nonMinimal(N), decompose(N, HX, U_1, \ldots, U_t),
                    r(U_1, YU_1), \ldots, r(U_t, YU_t),
                    r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                    compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \dots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                    I_0 = e,
                    compose(I_0, YU_1, I_1), \ldots, compose(I_{p-2}, YU_{p-1}, I_{p-1}),
                    process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                    compose(I_p, YU_p, I_{p+1}), \ldots, compose(I_t, YU_t, I_{t+1}),
                    NHY = I_{t+1},
                    compose(TY_p, TY_{p+1}, K_p), compose(K_p, TY_{p+2}, K_{p+1}), \ldots, compose(K_{t-2}, TY_t, K_{t-1}),
                    compose(K_{t-1}, NA, NA_1), compose(NHY, NA_1, NA_2),
                    compose(K_{p-2}, NA_2, Y), r \perp td_2(TXs, NA, A)
By duplicating goal decompose(N, HX, U_1, \ldots, U_t):
 clause 37: r t d_2(Xs, Y, A) \leftarrow
                    Xs = [X|TXs].
                    nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                    (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                    (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                    minimal(U_1), \ldots, minimal(U_t),
                    nonMinimal(N), decompose(N, HX, U_1, \ldots, U_t),
                    decompose(N, HX, U_1, \ldots, U_t),
                    r(U_1, YU_1), \ldots, r(U_t, YU_t),
                    r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                    compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \ldots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                    I_0 = e,
                    compose(I_0, YU_1, I_1), \ldots, compose(I_{p-2}, YU_{p-1}, I_{p-1}),
                    process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                    compose(I_p, YU_p, I_{p+1}), \ldots, compose(I_t, YU_t, I_{t+1}),
                    NHY = I_{t+1},
                    compose(TY_p, TY_{p+1}, K_p), compose(K_p, TY_{p+2}, K_{p+1}), \ldots, compose(K_{t-2}, TY_t, K_{t-1}),
                    compose(K_{t-1}, NA, NA_1), compose(NHY, NA_1, NA_2),
                    compose(K_{p-2}, NA_2, Y), r \perp d_2(TXs, NA, A)
By folding clause 37 using DCLR:
 clause 38: r t d_2(Xs, Y, A) \leftarrow
                    Xs = [X|TXs],
                    nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                    (nonMinimal(TX_1); \dots; nonMinimal(TX_{p-1})),
                    (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                    minimal(U_1), \ldots, minimal(U_t),
                    decompose(N, HX, U_1, \ldots, U_t),
                    r(TX_1, TY_1), \ldots, r(TX_t, TY_t), r(N, NHY),
                    compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \ldots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                    compose(TY_p, TY_{p+1}, K_p), compose(K_p, TY_{p+2}, K_{p+1}), \ldots, compose(K_{t-2}, TY_t, K_{t-1}),
                    compose(K_{t-1}, NA, NA_1), compose(NHY, NA_1, NA_2),
                    compose(K_{p-2}, NA_2, Y), r \perp d_2(TX_s, NA, A)
```

By t - p + 1 times folding clause 38 using clauses 1 and 2:

```
clause 39: r \sharp d_2(Xs,Y,A) \leftarrow Xs = [X|TXs],

nonMinimal(X), decompose(X,HX,TX_1,\ldots,TX_t),

(nonMinimal(TX_1);\ldots;nonMinimal(TX_{p-1})),

(nonMinimal(TX_p);\ldots;nonMinimal(TX_t)),

minimal(U_1),\ldots,minimal(U_t),

decompose(N,HX,U_1,\ldots,U_t),

r(TX_1,TY_1),\ldots,r(TX_{p-1},TY_{p-1}),r(N,NHY),

compose(TY_1,TY_2,K_1),compose(K_1,TY_3,K_2),\ldots,compose(K_{p-3},TY_{p-1},K_{p-2}),

compose(NHY,NA_1,NA_2),

compose(K_{p-2},NA_2,Y),r \sharp d_2([TX_p,\ldots,TX_t|TXs],NA_1,A)
```

By folding clause 39 using clauses 1 and 2:

```
clause \ 40: \ r \sharp d_2(Xs,Y,A) \leftarrow \\ Xs = [X|TXs], \\ nonMinimal(X), decompose(X,HX,TX_1,\ldots,TX_t), \\ (nonMinimal(TX_1);\ldots;nonMinimal(TX_{p-1})), \\ (nonMinimal(TX_p);\ldots;nonMinimal(TX_t)), \\ minimal(U_1),\ldots,minimal(U_t), \\ decompose(N,HX,U_1,\ldots,U_t), \\ r(TX_1,TY_1),\ldots,r(TX_{p-1},TY_{p-1}), \\ compose(TY_1,TY_2,K_1), compose(K_1,TY_3,K_2),\ldots,compose(K_{p-3},TY_{p-1},K_{p-2}), \\ compose(K_{p-2},NA_2,Y), r \sharp d_2([N,TX_p,\ldots,TX_t|TXs],NA_2,A)
```

By p-1 times folding clause 40 using clauses 1 and 2:

$$\begin{aligned} clause \ 41: & r\sharp d_2(Xs,Y,A) \leftarrow \\ & Xs = [X|TXs], \\ & nonMinimal(X), decompose(X,HX,TX_1,\ldots,TX_t), \\ & (nonMinimal(TX_1);\ldots;nonMinimal(TX_{p-1})), \\ & (nonMinimal(TX_p);\ldots;nonMinimal(TX_t)), \\ & minimal(U_1),\ldots,minimal(U_t), \\ & decompose(N,HX,U_1,\ldots,U_t), \\ & r\sharp d_2([TX_1,\ldots,TX_{p-1},N,TX_p,\ldots,TX_t|TXs],Y,A) \end{aligned}$$

Clauses 1, 3, 13, 20, 30 and 41 are the clauses of  $P_{r_{-td_2}}$ . Therefore  $P_{r_{-td_2}}$  is steadfast wrt  $S_{r_{-td_2}}$  in S.

To prove that  $P_r$  is steadfast wrt  $S_r$  in  $\{S_{r-td_2}\}$ , we do a backward proof that we begin with  $P_r$  in TDGRL and from which we try to obtain  $S_r$ .

The procedure  $P_r$  for r in TDGRL is:

$$r(X,Y) \leftarrow r t d_2([X],Y,e)$$

By taking the 'completion':

$$\forall X: \mathcal{X}, \forall Y: \mathcal{Y}. \ \mathcal{I}_r(X) \Rightarrow [r(X,Y) \Leftrightarrow r \bot td_2([X],Y,e)]$$

By unfolding the 'completion' above wrt  $r \pm d_2([X], Y, e)$  using  $S_{r \pm d_2}$ :

$$\forall X: \mathcal{X}, \forall Y: \mathcal{Y}: \mathcal{Y}. \quad \mathcal{I}_r(X) \Rightarrow [r(X,Y) \Leftrightarrow \exists Y_1, I_1: \mathcal{Y}. \quad \mathcal{O}_r(X,Y_1) \land I_1 = Y_1 \land \mathcal{O}_c(I_1,e,Y)]$$

By using applicability condition (2):

$$\forall X: \mathcal{X}, \forall Y: \mathcal{Y}. \quad \mathcal{I}_r(X) \Rightarrow [r(X,Y) \Leftrightarrow \exists Y_1, I_1: \mathcal{Y}. \quad \mathcal{O}_r(X,Y_1) \land I_1 = Y_1 \land Y = I_1]$$

By simplification:

$$\forall X : \mathcal{X}, \forall Y : \mathcal{Y}. \ \mathcal{I}_r(X)) \Rightarrow [r(X,Y) \Leftrightarrow \mathcal{O}_r(X,Y)]$$

We obtain  $S_r$ , so  $P_r$  is steadfast wrt  $S_r$  in  $\{S_{r\_td_2}\}$ Therefore, TDGRL is also steadfast wrt  $S_r$  in S.

**Theorem 9** The generalization schema  $TDG_3$ , which is given below, is correct.

 $TDG_3: \langle DCRL, TDGRL, A_{td3} \ O_{td312}, O_{td321} \rangle$  where  $A_{td3}: (1) \ compose$  is associative (2) compose has e as the left and right identity element (3)  $\mathcal{I}_r(X) \wedge minimal(X) \Rightarrow \mathcal{O}_r(X, e)$  (4)  $\mathcal{I}_r(X) \Rightarrow [\neg minimal(X) \Leftrightarrow nonMinimal(X)]$   $O_{td312}: \text{partial evaluation of the conjunction}$  process(HX, HY), compose(HY, A, New A)

 $O_{td321}$ : partial evaluation of the conjunction  $process(HX, HY), compose(HY, I_p, I_{p-1})$  results in the introduction of a non-recursive relation

results in the introduction of a non-recursive relation

where the template of DCRL is Logic Program Template 3 in Section 2 and the template TDGRL is Logic Program Template 7 in Theorem 8.

The specification  $S_r$  of relation r is:

$$\forall X : \mathcal{X}, \forall Y : \mathcal{Y}. \ \mathcal{I}_r(X) \Rightarrow [r(X,Y) \Leftrightarrow \mathcal{O}_r(X,Y)]$$

The specification of  $r_{\perp}td_2$ , namely  $S_{r_{\perp}td_2}$ , is:

```
\forall Xs : list \ of \ \mathcal{X}, \forall Y, A : \mathcal{Y}. \quad (\forall X : \mathcal{X} : X \in Xs \Rightarrow \mathcal{I}_r(X)) \Rightarrow [r \perp td_2(Xs, Y, A) \Leftrightarrow (Xs = [] \land Y = A) \\ \lor (Xs = [X_1, X_2, \dots, X_q] \land \bigwedge_{i=1}^q \mathcal{O}_r(X_i, Y_i) \quad \land I_1 = Y_1 \land \bigwedge_{i=2}^q \mathcal{O}_c(I_{i-1}, Y_i, I_i) \\ \land \mathcal{O}_c(I_q, A, I_{q+1}) \land Y = I_{q+1})]
```

**Proof 9** To prove the correctness of the generalization schema  $TDG_3$ , by Definition 10, we have to prove that templates DCRL and TDGRL are equivalent wrt  $S_r$  under the applicability conditions  $A_{td3}$ . By Definition 5, the templates DCRL and TDGRL are equivalent wrt  $S_r$  under the applicability conditions  $A_{td3}$  iff DCRL is equivalent to TDGRL wrt the specification  $S_r$  provided that the conditions in  $A_{td3}$  hold. By Definition 4, DCRL is equivalent to TDGRL wrt the specification  $S_r$  iff the following two conditions hold:

- (a) DCRL is steadfast wrt  $S_r$  in  $S = \{S_{minimal}, S_{nonMinimal}, S_{solve}, S_{decompose}, S_{process}, S_{compose}\}$ , where  $S_{minimal}, S_{nonMinimal}, S_{solve}, S_{decompose}, S_{process}, S_{compose}$  are the specifications of minimal, nonMinimal, solve, decompose, process, compose, which are all the undefined relation names appearing in DCRL.
- (b) TDGRL is also steadfast wrt  $S_r$  in S.

Note that the sets  $\{S_1, \ldots, S_m\}$  and  $\{S'_1, \ldots, S'_t\}$  in Definition 4 are equal to  $\mathcal{S}$  when Q is obtained by simultaneous tupling-and-descending generalization of P.

In program transformation, we assume that the input program, here template DCRL, is steadfast wrt  $S_r$  in S, so condition (a) always holds.

To prove equivalence, we have to prove condition (b). We will use the following property of steadfast-ness: TDGRL is steadfast wrt  $S_r$  in  $\mathcal{S}$  if  $P_{r\_td_2}$  is steadfast wrt  $S_{r\_td_2}$  in  $\mathcal{S}$ , where  $P_{r\_td_2}$  is the procedure for  $r\_td_2$ , and  $P_r$  is steadfast wrt  $S_r$  in  $\{S_{r\_td_2}\}$ , where  $P_r$  is the procedure for r.

To prove that  $P_{r_{-}td_2}$  is steadfast wrt  $S_{r_{-}td_2}$  in S, we do a constructive forward proof that we begin with  $S_{r_{-}td_2}$  and from which we try to obtain  $P_{r_{-}td_2}$ .

If we separate the cases of  $q \ge 1$  by  $q = 1 \lor q \ge 2$ , then  $S_{r\_td_2}$  becomes:

```
 \forall Xs: list \ of \ \mathcal{X}, \forall Y: \mathcal{Y}: \ \mathcal{Y}. \ (\forall X: \mathcal{X}. \ X \in Xs \Rightarrow \mathcal{I}_r(X)) \Rightarrow [r \, \mathcal{I}d_2(Xs, Y, A) \Leftrightarrow (Xs = [] \land Y = A)   \forall (Xs = [X_1] \land \mathcal{O}_r(X_1, Y_1) \land Y_1 = I_1 \land \mathcal{O}_c(I_1, A, I_2) \land Y = I_2)   \forall (Xs = [X_1, X_2, \dots, X_q] \land \bigwedge_{i=1}^q \mathcal{O}_r(X_i, Y_i) \land I_1 = Y_1 \land \bigwedge_{i=2}^q \mathcal{O}_c(I_{i-1}, Y_i, I_i) \land \mathcal{O}_c(I_q, A, I_{q+1}) \land Y = I_{q+1})]
```

where  $q \geq 2$ .

By using applicability conditions (1) and (2):

```
 \forall Xs: list \ of \ \mathcal{X}, \forall Y: \mathcal{Y}: \ (\forall X: \mathcal{X}: X \in Xs \Rightarrow \mathcal{I}_r(X)) \Rightarrow [r \, \mathcal{I}d_2(Xs, Y, A) \Leftrightarrow (Xs = [] \land Y = A) 
 \forall (Xs = [X_1 \mid TXs] \land TXs = [] \land \mathcal{O}_r(X_1, Y_1) \land Y_1 = I_1 \land TY = A \land \mathcal{O}_c(TY, A, NA) \land \mathcal{O}_c(I_1, NA, Y)) 
 \forall (Xs = [X_1 \mid TXs] \land TXs = [X_2, \dots, X_q] \land \ \bigwedge_{i=1}^q \mathcal{O}_r(X_i, Y_i) \quad \land Y_1 = I_1 \land Y_2 = I_2 \land 
 \bigwedge_{i=3}^q \mathcal{O}_c(I_{i-1}, Y_i, I_i) \quad \land TY = I_q \land \mathcal{O}_c(TY, A, NA) \land \mathcal{O}_c(I_1, NA, Y))]
```

```
where q \geq 2.
```

By folding using  $S_{r-td_2}$ , and renaming:

```
\forall Xs : list \ of \ \mathcal{X}, \forall Y : \mathcal{Y}. \ (\forall X : \mathcal{X}. \ X \in Xs \Rightarrow \mathcal{I}_r(X)) \Rightarrow [r \, \mathcal{I}d_2(Xs, Y, A) \Leftrightarrow (Xs = [] \land Y = A) \\ \lor (Xs = [X|TXs] \land \mathcal{O}_r(X, HY) \land r \, \mathcal{I}d_2(TXs, NA, A) \land \mathcal{O}_c(HY, NA, Y))]
```

By taking the 'decompletion':

```
 \begin{array}{ll} \mathit{clause} \ 1: & \mathit{r} \, \sharp \, d_2(Xs,Y,A) \leftarrow \\ & Xs = [],Y = A \\ \mathit{clause} \ 2: & \mathit{r} \, \sharp \, d_2(Xs,Y,A) \leftarrow \\ & Xs = [X|TXs], r(X,HY), \\ & \mathit{r} \, \sharp \, d_2(TXs,NA,A), \mathit{compose}(HY,NA,Y) \end{array}
```

By unfolding clause 2 wrt r(X, HY) using DCRL, and using the assumption that DCRL is steadfast wrt  $S_r$  in S:

```
clause 3: r \pm d_2(Xs, Y, A) \leftarrow Xs = [X|TXs],

minimal(X),

solve(X, HY),

r \pm d_2(TXs, NA, A), compose(HY, NA, Y)

clause 4: r \pm d_2(Xs, Y, A) \leftarrow Xs = [X|TXs],

nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),

r(TX_1, TY_1), ..., r(TX_t, TY_t),

I_{t+1} = e,

compose(TY_t, I_{t+1}, I_t), ..., compose(TY_p, I_{p+1}, I_p),

process(HX, HHY), compose(HHY, I_p, I_{p-1}),

compose(TY_{p-1}, I_{p-1}, I_{p-2}), ..., compose(TY_1, I_1, I_0),

HY = I_0,

r \pm d_2(TXs, NA, A), compose(HY, NA, Y)
```

By introducing

```
(minimal(TX_1) \land \ldots \land minimal(TX_t)) \lor \\ ((minimal(TX_1) \land \ldots \land minimal(TX_{p-1})) \land (nonMinimal(TX_p) \lor \ldots \lor nonMinimal(TX_t))) \lor \\ ((nonMinimal(TX_1) \lor \ldots \lor nonMinimal(TX_{p-1})) \land (minimal(TX_p) \land \ldots \land minimal(TX_t))) \lor \\ ((nonMinimal(TX_1) \lor \ldots \lor nonMinimal(TX_{p-1})) \land (nonMinimal(TX_p) \lor \ldots \lor nonMinimal(TX_t))) \\ \text{in clause 4, using applicability condition (4):}
```

```
clause 5: r \pm d_2(Xs, Y, A) \leftarrow Xs = [X|TXs],

nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),

minimal(TX_1), ..., minimal(TX_t),

r(TX_1, TY_1), ..., r(TX_t, TY_t),

I_{t+1} = e,

compose(TY_t, I_{t+1}, I_t), ..., compose(TY_p, I_{p+1}, I_p),

process(HX, HHY), compose(HHY, I_p, I_{p-1}),

compose(TY_{p-1}, I_{p-1}, I_{p-2}), ..., compose(TY_1, I_1, I_0),

HY = I_0,

r \pm d_2(TXs, NA, A), compose(HY, NA, Y)
```

```
clause 6: r \pm d_2(Xs, Y, A) \leftarrow
                       Xs = [X|TXs],
                      nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                      minimal(TX_1), \ldots, minimal(TX_{p-1}),
                      (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                      r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                      I_{t+1}=e,
                      compose(TY_t, I_{t+1}, I_t), \ldots, compose(TY_p, I_{p+1}, I_p),
                      process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                      compose(TY_{p-1}, I_{p-1}, I_{p-2}), \ldots, compose(TY_1, I_1, I_0),
                      HY = I_0,
                      r\_td_2(TXs, NA, A), compose(HY, NA, Y)
    clause 7: r td_2(Xs, Y, A) \leftarrow
                      Xs = [X|TXs]
                      nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                      (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                      minimal(TX_p), \ldots, minimal(TX_t),
                      r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                      I_{t+1} = e
                      compose(TY_t, I_{t+1}, I_t), \ldots, compose(TY_p, I_{p+1}, I_p),
                      process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                      compose(TY_{p-1}, I_{p-1}, I_{p-2}), \ldots, compose(TY_1, I_1, I_0),
                      HY = I_0,
                      r \perp td_2(TXs, NA, A), compose(HY, NA, Y)
     clause 8: r td_2(Xs, Y, A) \leftarrow
                      Xs = [X|TXs],
                      nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                      (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                      (nonMinimal(TX_p); \dots; nonMinimal(TX_t)),
                      r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                      I_{t+1} = e,
                      compose(TY_t, I_{t+1}, I_t), \ldots, compose(TY_p, I_{p+1}, I_p),
                      process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                      compose(TY_{p-1}, I_{p-1}, I_{p-2}), \ldots, compose(TY_1, I_1, I_0),
                      HY = I_0,
                      r \perp td_2(TXs, NA, A), compose(HY, NA, Y)
   By t times unfolding clause 5 wrt r(TX_1, TY_1), \ldots, r(TX_t, TY_t) using DCRL, and simplifying using
condition (4):
     clause 9: r td_2(Xs, Y, A) \leftarrow
                       Xs = [X|TXs],
                      nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                      minimal(TX_1), \ldots, minimal(TX_t),
                      minimal(TX_1), \ldots, minimal(TX_t)
                      solve(TX_1, TY_1), \ldots, solve(TX_t, TY_t)
                      I_{t+1}=e,
                      compose(TY_t, I_{t+1}, I_t), \ldots, compose(TY_p, I_{p+1}, I_p),
                      process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                      compose(TY_{p-1}, I_{p-1}, I_{p-2}), \ldots, compose(TY_1, I_1, I_0),
                      HY = I_0,
                      r\_td_2(TXs, NA, A), compose(HY, NA, Y)
```

By using applicability condition (3):

```
clause 10: r \perp d_2(Xs, Y, A) \leftarrow
                    Xs = [X|TXs]
                    nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                    minimal(TX_1), \ldots, minimal(TX_t),
                    minimal(TX_1), \ldots, minimal(TX_t),
                    solve(TX_1, e), \ldots, solve(TX_t, e),
                    I_{t+1}=e,
                    compose(e, I_{t+1}, I_t), \ldots, compose(e, I_{p+1}, I_p),
                    process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                    compose(e, I_{p-1}, I_{p-2}), \ldots, compose(e, I_1, I_0),
                    HY = I_0,
                    r \perp td_2(TXs, NA, A), compose(HY, NA, Y)
By deleting one of the minimal(TX_1), \ldots, minimal(TX_t) atoms in clause 10:
 clause 11: r t d_2(Xs, Y, A) \leftarrow
                    Xs = [X|TXs],
                    nonMinimal(X), decompose(X, HX, TX_1, \dots, TX_t),
                    minimal(TX_1), \ldots, minimal(TX_t),
                    solve(TX_1, e), \ldots, solve(TX_t, e),
                    I_{t+1} = e,
                    compose(e, I_{t+1}, I_t), \ldots, compose(e, I_{p+1}, I_p),
                    process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                    compose(e, I_{p-1}, I_{p-2}), \ldots, compose(e, I_1, I_0),
                    HY = I_0,
                    r \perp td_2(TXs, NA, A), compose(HY, NA, Y)
By using applicability condition (2):
 clause 12: r \not = d_2(Xs, Y, A) \leftarrow
                    Xs = [X|TXs]
                    nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                    minimal(TX_1), \ldots, minimal(TX_t),
                    solve(TX_1, e), \ldots, solve(TX_t, e),
                    I_{t+1} = e,
                    I_t = I_{t+1}, \ldots, I_p = I_{p+1},
                    process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                    I_{p-2} = I_{p-1}, \ldots, I_0 = I_1,
                    HY = I_0,
                    r \perp td_2(TXs, NA, A), compose(HY, NA, Y)
By simplification:
 clause 13: r t d_2(Xs, Y, A) \leftarrow
                    Xs = [X|TXs],
                    nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                    minimal(TX_1), \ldots, minimal(TX_t),
                    r \perp td_2(TXs, NA, A),
                    process(HX, HY), compose(HY, NA, Y)
```

By p-1 times unfolding clause 6 wrt  $r(TX_1, TY_1), \ldots, r(TX_{p-1}, TY_{p-1})$  using DCRL, and simplifying using condition (4):

```
clause 14: r \perp d_2(Xs, Y, A) \leftarrow
                    Xs = [X|TXs]
                    nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                    minimal(TX_1), \ldots, minimal(TX_{p-1}),
                    (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                    minimal(TX_1), \ldots, minimal(TX_{p-1}),
                    solve(TX_1, TY_1), \ldots, solve(TX_{p-1}, TY_{p-1}),
                    r(TX_p, TY_p), \ldots, r(TX_t, TY_t),
                    I_{t+1}=e,
                    compose(TY_t, I_{t+1}, I_t), \ldots, compose(TY_p, I_{p+1}, I_p),
                    process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                    compose(TY_{p-1}, I_{p-1}, I_{p-2}), \ldots, compose(TY_1, I_1, I_0),
                    HY = I_0,
                    r \perp td_2(TXs, NA, A), compose(HY, NA, Y)
By deleting one of the minimal(TX_1), \ldots, minimal(TX_{p-1}) atoms in clause 14:
 clause 15: r \pm d_2(Xs, Y, A) \leftarrow
                    Xs = [X|TXs],
                    nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                    minimal(TX_1), \ldots, minimal(TX_{p-1}),
                    (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                    solve(TX_1, TY_1), \ldots, solve(TX_{p-1}, TY_{p-1}),
                    r(TX_p, TY_p), \ldots, r(TX_t, TY_t),
                    I_{t+1}=e,
                    compose(TY_t, I_{t+1}, I_t), \ldots, compose(TY_p, I_{p+1}, I_p),
                    process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                    compose(TY_{p-1}, I_{p-1}, I_{p-2}), \ldots, compose(TY_1, I_1, I_0),
                    HY = I_0,
                    r \perp td_2(TXs, NA, A), compose(HY, NA, Y)
By rewriting clause 15 using applicability conditions (1) and (2):
 clause 16: r \pm d_2(Xs, Y, A) \leftarrow
                    Xs = [X|TXs].
                    nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                    minimal(TX_1), \ldots, minimal(TX_{p-1}),
                    (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                    solve(TX_1, TY_1), \ldots, solve(TX_{p-1}, TY_{p-1}),
                    r(TX_p, TY_p), \ldots, r(TX_t, TY_t),
                    I_0 = e
                    compose(I_0, TY_1, I_1), \ldots, compose(I_{p-2}, TY_{p-1}, I_{p-1}),
                    process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                    HY = I_p, compose(HY, NA, Y),
                    compose(TY_p, I_{p+1}, NA),
                    compose(TY_{p+1}, I_{p+2}, I_{p+1}), \ldots, compose(TY_{t-1}, I_t, I_{t-1}),
                    compose(TY_t, NNA, I_t),
                    r \perp td_2(TXs, NNA, A)
```

By t-p times folding clause 16 using clauses 1 and 2:

```
clause 17: r \perp d_2(Xs, Y, A) \leftarrow
                    Xs = [X|TXs]
                    nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                    minimal(TX_1), \ldots, minimal(TX_{p-1}),
                    (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                    solve(TX_1, TY_1), \ldots, solve(TX_{p-1}, TY_{p-1}),
                    compose(I_0, TY_1, I_1), \ldots, compose(I_{p-2}, TY_{p-1}, I_{p-1}),
                    process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                    HY = I_p,
                    r \perp td_2([TX_p, \ldots, TX_t|TXs], NA, A), compose(HY, NA, Y)
By using applicability condition (3):
 clause 18: r \pm d_2(Xs, Y, A) \leftarrow
                    Xs = [X|TXs]
                    nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                    minimal(TX_1), \ldots, minimal(TX_{p-1}),
                    (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                    solve(TX_1,e),\ldots,solve(TX_{p-1},e),
                    compose(I_0, e, I_1), \ldots, compose(I_{p-2}, e, I_{p-1}),
                    process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                    r \perp td_2([TX_p, \ldots, TX_t|TXs], NA, A), compose(HY, NA, Y)
By using applicability condition (2):
 clause 19: r t d_2(Xs, Y, A) \leftarrow
                    Xs = [X|TXs]
                    nonMinimal(X), decompose(X, HX, TX_1, \dots, TX_t),
                    minimal(TX_1), \ldots, minimal(TX_{p-1}),
                    (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                    solve(TX_1, e), \ldots, solve(TX_{p-1}, e),
                    I_0 = e,
                    I_1 = I_0, \ldots, I_{p-1} = I_{p-2},
                    process(HX, HHY), compose(I_{p-1}, HHY, I_p),
                    HY = I_{p},
                    r \perp td_2([TX_p, \ldots, TX_t|TXs], NA, A), compose(HY, NA, Y)
By simplification:
 clause 20 : r t d_2(Xs, Y, A) \leftarrow
                    Xs = [X|TXs].
                    nonMinimal(X), decompose(X, HX, TX_1, \dots, TX_t),
                    minimal(TX_1), \ldots, minimal(TX_{p-1}),
                    (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                    r \pm d_2([TX_p, \ldots, TX_t|TXs], NA, A),
                    process(HX, HY), compose(HY, NA, Y)
```

By introducing atoms  $minimal(U_1), \ldots, minimal(U_{p-1})$  (with new, i.e. existentially quantified, variables  $U_1, \ldots, U_{p-1}$ ) in clause 7:

```
clause 21: r \perp d_2(Xs, Y, A) \leftarrow
                    Xs = [X|TXs]
                    nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                    (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                    minimal(TX_p), \ldots, minimal(TX_t),
                    minimal(U_1), \ldots, minimal(U_{p-1}),
                    r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                    I_{t+1} = e,
                    compose(TY_t, I_{t+1}, I_t), \ldots, compose(TY_p, I_{p+1}, I_p),
                    process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                    compose(TY_{p-1}, I_{p-1}, I_{p-2}), \ldots, compose(TY_1, I_1, I_0),
                    HY = I_0,
                    r \pm t d_2(TXs, NA, A), compose(HY, NA, Y)
By using applicability condition (3):
 clause 22: r t d_2(Xs, Y, A) \leftarrow
                    Xs = [X|TXs]
                    nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                    (nonMinimal(TX_1); \ldots; nonMinimal(TX_{n-1})),
                    minimal(TX_p), \ldots, minimal(TX_t),
                    minimal(U_1), \ldots, minimal(U_{p-1}),
                    r(U_1,e),\ldots,r(U_{p-1},e),
                    r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                    I_{t+1} = e,
                    compose(TY_t, I_{t+1}, I_t), \ldots, compose(TY_p, I_{p+1}, I_p),
                    process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                    compose(TY_{p-1}, I_{p-1}, I_{p-2}), \ldots, compose(TY_1, I_1, I_0),
                    HY = I_0,
                    r \perp td_2(TXs, NA, A), compose(HY, NA, Y)
By using applicability condition (2):
 clause 23: r t d_2(Xs, Y, A) \leftarrow
                    Xs = [X|TXs].
                    nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                    (nonMinimal(TX_1); ...; nonMinimal(TX_{p-1})),
                    minimal(TX_p), \ldots, minimal(TX_t),
                    minimal(U_1), \ldots, minimal(U_{p-1}),
                    r(U_1,e),\ldots,r(U_{p-1},e),
                    r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                    I_{t+1} = e,
                    compose(TY_t, I_{t+1}, I_t), \ldots, compose(TY_p, I_{p+1}, I_p),
                    process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                    compose(e, I_{p-1}, K_1), compose(e, K_1, K_2), \ldots, compose(e, K_{p-2}, K_{p-1}),
                    compose(TY_{p-1}, K_{p-1}, I_{p-2}), \ldots, compose(TY_1, I_1, I_0),
                    HY = I_0,
                    r \perp td_2(TXs, NA, A), compose(HY, NA, Y)
```

By using applicability conditions (1) and (2):

```
clause 24: r \perp d_2(Xs, Y, A) \leftarrow
                         Xs = [X|TXs]
                         nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                         (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                        minimal(TX_p), \ldots, minimal(TX_t),
                         minimal(U_1), \ldots, minimal(U_{n-1}),
                         r(U_1,e),\ldots,r(U_{p-1},e),
                         r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                         I_{t+1}=e,
                        compose(TY_t, I_{t+1}, I_t), \ldots, compose(TY_p, I_{p+1}, I_p),
                        process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                        compose(e, I_{p-1}, I_{p-2}), \ldots, compose(e, I_1, I_0),
                         HY = I_0, r \perp td_2(TXs, NA, A), compose(HY, NA, NNA),
                        compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \dots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                        compose(K_{p-2}, NNA, Y)
   By introducing new, i.e. existentially quantified, variables YU_1, \ldots, YU_{p-1} in place of some occur-
rences of e:
     clause 25: r \not = d_2(Xs, Y, A) \leftarrow
                         Xs = [X|TXs],
                         nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                         (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                         minimal(TX_p), \ldots, minimal(TX_t),
                         minimal(U_1), \ldots, minimal(U_{p-1}),
                         r(U_1, YU_1), \ldots, r(U_{p-1}, YU_{p-1}),
                         r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                         I_{t+1}=e,
                        compose(TY_t, I_{t+1}, I_t), \ldots, compose(TY_p, I_{p+1}, I_p),
                        process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                        compose(YU_{p-1}, I_{p-1}, I_{p-2}), \ldots, compose(YU_1, I_1, I_0),
                         HY = I_0, r \perp d_2(TXs, NA, A), compose(HY, NA, NNA),
                        compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \dots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                        compose(K_{p-2}, NNA, Y)
   By introducing nonMinimal(N) and decompose(N, HX, U_1, \dots, U_{p-1}, TX_p, \dots, TX_t), since
                \exists N: \mathcal{X}.nonMinimal(N) \land decompose(N, HX, U_1, \ldots, U_{n-1}, TX_n, \ldots, TX_t)
     clause 26: r \pm d_2(Xs, Y, A) \leftarrow
```

always holds (because N is existentially quantified):

```
Xs = [X|TXs]
nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
(nonMinimal(TX_1); \ldots; nonMinimal(TX_{n-1})),
minimal(TX_p), \ldots, minimal(TX_t),
minimal(U_1), \ldots, minimal(U_{p-1}),
r(U_1, YU_1), \ldots, r(U_{p-1}, YU_{p-1}),
nonMinimal(N), decompose(N, HX, U_1, \ldots, U_{p-1}, TX_p, \ldots, TX_t),
r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
I_{t+1} = e,
compose(TY_t, I_{t+1}, I_t), \ldots, compose(TY_p, I_{p+1}, I_p),
process(HX, HHY), compose(HHY, I_p, I_{p-1}),
compose(YU_{p-1}, I_{p-1}, I_{p-2}), \ldots, compose(YU_1, I_1, I_0),
HY = I_0, r \perp t d_2(TXs, NA, A), compose(HY, NA, NNA),
compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \ldots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
compose(K_{p-2}, NNA, Y)
```

By duplicating goal  $decompose(N, HX, U_1, \ldots, U_{p-1}, TX_p, \ldots, TX_t)$ :

```
clause 27: r \perp d_2(Xs, Y, A) \leftarrow
                    Xs = [X|TXs]
                    nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                    (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                    minimal(TX_p), \ldots, minimal(TX_t),
                    minimal(U_1), \ldots, minimal(U_{p-1}),
                    r(U_1, YU_1), \ldots, r(U_{p-1}, YU_{p-1}),
                    nonMinimal(N), decompose(N, HX, U_1, \dots, U_{p-1}, TX_p, \dots, TX_t),
                    decompose(N, HX, U_1, \ldots, U_{p-1}, TX_p, \ldots, TX_t),
                    r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                    I_{t+1} = e,
                    compose(TY_t, I_{t+1}, I_t), \ldots, compose(TY_p, I_{p+1}, I_p),
                    process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                    compose(YU_{p-1}, I_{p-1}, I_{p-2}), \ldots, compose(YU_1, I_1, I_0),
                    HY = I_0, r \perp d_2(TXs, NA, A), compose(HY, NA, NNA),
                    compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \dots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                    compose(K_{p-2}, NNA, Y)
By folding clause 27 using DCRL:
 clause 28: r \perp td_2(Xs, Y, A) \leftarrow
                    Xs = [X|TXs]
                    nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                    (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                    minimal(TX_p), \ldots, minimal(TX_t),
                    minimal(U_1), \ldots, minimal(U_{p-1}),
                    decompose(N, HX, U_1, \ldots, U_{p-1}, TX_p, \ldots, TX_t),
                    r(TX_1, TY_1), \ldots, r(TX_{p-1}, TY_{p-1}), r(N, HY),
                    r \perp td_2(TXs, NA, A), compose(HY, NA, NNA),
                    compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \dots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                    compose(K_{p-2}, NNA, Y)
By folding clause 28 using clauses 1 and 2:
 clause 29: r \pm d_2(Xs, Y, A) \leftarrow
                    Xs = [X|TXs],
                    nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                    (nonMinimal(TX_1); \dots; nonMinimal(TX_{p-1})),
                    minimal(TX_n), \ldots, minimal(TX_t),
                    minimal(U_1), \ldots, minimal(U_{p-1}),
                    decompose(N, HX, U_1, \ldots, U_{p-1}, TX_p, \ldots, TX_t),
                    r(TX_1, TY_1), \ldots, r(TX_{p-1}, TY_{p-1}),
                    r \perp td_2([N|TXs], NNA, A),
                    compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \ldots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                    compose(K_{p-2}, NNA, Y)
By p-1 times folding clause 29 using clauses 1 and 2:
 clause 30: r t d_2(Xs, Y, A) \leftarrow
                    Xs = [X|TXs]
                    nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                    (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                    minimal(TX_p), \ldots, minimal(TX_t),
                    minimal(U_1), \ldots, minimal(U_{n-1}),
                    decompose(N, HX, U_1, \ldots, U_{p-1}, TX_p, \ldots, TX_t),
                    r \pm d_2([TX_1, \dots, TX_{p-1}, N|TXs], Y, A)
```

By introducing atoms  $minimal(U_1), \ldots, minimal(U_t)$  (with new, i.e. existentially quantified, variables  $U_1, \ldots, U_t$ ) in clause 8:

```
clause 31: r \perp d_2(Xs, Y, A) \leftarrow
                    Xs = [X|TXs]
                    nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                    (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                    (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                    r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                    minimal(U_1), \ldots, minimal(U_t)
                    I_{t+1} = e,
                    compose(TY_t, I_{t+1}, I_t), \ldots, compose(TY_p, I_{p+1}, I_p),
                    process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                    compose(TY_{p-1}, I_{p-1}, I_{p-2}), \ldots, compose(TY_1, I_1, I_0),
                    HY = I_0,
                    r \pm t d_2(TXs, NA, A), compose(HY, NA, Y)
By using applicability condition (3):
 clause 32: r 1d_2(Xs, Y, A) \leftarrow
                    Xs = [X|TXs]
                    nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                    (nonMinimal(TX_1); \dots; nonMinimal(TX_{p-1})),
                    (nonMinimal(TX_p); \dots; nonMinimal(TX_t)),
                    r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                    minimal(U_1), \ldots, minimal(U_t),
                    r(U_1,e),\ldots,r(U_t,e),
                    I_{t+1} = e,
                    compose(TY_t, I_{t+1}, I_t), \ldots, compose(TY_p, I_{p+1}, I_p),
                    process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                    compose(TY_{p-1}, I_{p-1}, I_{p-2}), \ldots, compose(TY_1, I_1, I_0),
                    HY = I_0,
                    r \perp td_2(TXs, NA, A), compose(HY, NA, Y)
By using applicability condition (2):
 clause 33: r \pm d_2(Xs, Y, A) \leftarrow
                    Xs = [X|TXs].
                    nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                    (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                    (nonMinimal(TX_p); \dots; nonMinimal(TX_t)),
                    r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                    minimal(U_1), \ldots, minimal(U_t),
                    r(U_1,e),\ldots,r(U_t,e),
                    I_{t+1} = e
                    compose(TY_t, I_{t+1}, I_t), \ldots, compose(TY_p, I_{p+1}, I_p),
                    compose(e, I_p, K_{t+1}),
                    compose(e, K_{t+1}, K_t), \ldots, compose(e, K_{p+1}, K_p),
                    process(HX, HHY), compose(HHY, K_p, K_{p-1}),
                    compose(e, K_{p-1}, K_{p-2}), \ldots, compose(e, K_1, K_0),
                    compose(e, K_0, I_{p-1}),
                    compose(TY_{p-1}, I_{p-1}, I_{p-2}), \ldots, compose(TY_1, I_1, I_0),
                    HY = I_0,
                    r \perp td_2(TXs, NA, A), compose(HY, NA, Y)
```

By using applicability conditions (1) and (2):

```
clause 34: r \perp d_2(Xs, Y, A) \leftarrow
                   Xs = [X|TXs]
                   nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                   (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                   (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                   r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                   minimal(U_1), \ldots, minimal(U_t),
                   r(U_1,e),\ldots,r(U_t,e),
                   I_{t+1} = e,
                   compose(e, I_{t+1}, I_t), \ldots, compose(e, I_{p+1}, I_p),
                   process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                   compose(e, I_{p-1}, I_{p-2}), \ldots, compose(e, I_1, I_0),
                   NHY = I_0
                   compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \dots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                   compose(TY_p, TY_{p+1}, K_p), compose(K_p, TY_{p+2}, K_{p+1}), \ldots, compose(K_{t-2}, TY_t, K_{t-1}),
                   r \perp td_2(TXs, NA, A), compose(K_{t-1}, NA, NA_1),
                   compose(NHY, NA_1, NA_2), compose(K_{p-2}, NA_2, Y)
```

By introducing new, i.e. existentially quantified, variables  $YU_1, \ldots, YU_t$  in place of some occurrences of e:

```
clause 35: r t d_2(Xs, Y, A) \leftarrow
                   Xs = [X|TXs]
                   nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                   (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                   (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                   r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                   minimal(U_1), \ldots, minimal(U_t),
                   r(U_1, YU_1), \ldots, r(U_t, YU_t),
                   I_{t+1} = e,
                   compose(Y U_t, I_{t+1}, I_t), \ldots, compose(Y U_p, I_{p+1}, I_p),
                   process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                   compose(YU_{p-1}, I_{p-1}, I_{p-2}), \ldots, compose(YU_1, I_1, I_0),
                   NHY = I_0,
                   compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \dots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                   compose(TY_p, TY_{p+1}, K_p), compose(K_p, TY_{p+2}, K_{p+1}), \ldots, compose(K_{t-2}, TY_t, K_{t-1}),
                   r \not\perp d_2(TXs, NA, A), compose(K_{t-1}, NA, NA_1),
                   compose(NHY, NA_1, NA_2), compose(K_{p-2}, NA_2, Y)
```

By introducing nonMinimal(N) and  $decompose(N, HX, U_1, \ldots, U_t)$ , since

 $\exists N : \mathcal{X}.nonMinimal(N) \land decompose(N, HX, U_1, ..., U_t)$ 

always holds (because N is existentially quantified):

```
clause 36: r \perp d_2(Xs, Y, A) \leftarrow
                    Xs = [X|TXs]
                    nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                    (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                    (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                    r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                    nonMinimal(N), decompose(N, HX, U_1, \ldots, U_t),
                    minimal(U_1), \ldots, minimal(U_t),
                    r(U_1, YU_1), \ldots, r(U_t, YU_t),
                    I_{t+1} = e,
                    compose(YU_t, I_{t+1}, I_t), \ldots, compose(YU_p, I_{p+1}, I_p),
                    process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                    compose(Y U_{p-1}, I_{p-1}, I_{p-2}), \ldots, compose(Y U_1, I_1, I_0),
                    NHY = I_0,
                    compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \dots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                    compose(TY_p, TY_{p+1}, K_p), compose(K_p, TY_{p+2}, K_{p+1}), \ldots, compose(K_{t-2}, TY_t, K_{t-1}),
                    r \perp td_2(TXs, NA, A), compose(K_{t-1}, NA, NA_1),
                    compose(NHY, NA_1, NA_2), compose(K_{p-2}, NA_2, Y)
By duplicating goal decompose(N, HX, U_1, \ldots, U_t):
 clause 37: r \pm d_2(Xs, Y, A) \leftarrow
                    Xs = [X|TXs]
                    nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                    (nonMinimal(TX_1); \dots; nonMinimal(TX_{p-1})),
                    (nonMinimal(TX_p); \dots; nonMinimal(TX_t)),
                    r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                    nonMinimal(N), decompose(N, HX, U_1, \ldots, U_t),
                    decompose(N, HX, U_1, \ldots, U_t),
                    minimal(U_1), \ldots, minimal(U_t),
                    r(U_1, YU_1), \ldots, r(U_t, YU_t),
                    I_{t+1} = e,
                    compose(Y U_t, I_{t+1}, I_t), \ldots, compose(Y U_p, I_{p+1}, I_p),
                    process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                    compose(YU_{p-1}, I_{p-1}, I_{p-2}), \ldots, compose(YU_1, I_1, I_0),
                    NHY = I_0,
                    compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \dots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                    compose(TY_p, TY_{p+1}, K_p), compose(K_p, TY_{p+2}, K_{p+1}), \ldots, compose(K_{t-2}, TY_t, K_{t-1}),
                    r \perp d_2(TXs, NA, A), compose(K_{t-1}, NA, NA_1),
                    compose(NHY, NA_1, NA_2), compose(K_{p-2}, NA_2, Y)
By folding clause 37 using DCRL:
 clause 38: r t d_2(Xs, Y, A) \leftarrow
                    Xs = [X|TXs],
                    nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                    (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                    (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                    r(TX_1, TY_1), \ldots, r(TX_t, TY_t), r(N, NHY),
                    decompose(N, HX, U_1, \ldots, U_t),
                    minimal(U_1), \ldots, minimal(U_t),
                    compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \dots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                    compose(TY_p, TY_{p+1}, K_p), compose(K_p, TY_{p+2}, K_{p+1}), \ldots, compose(K_{t-2}, TY_t, K_{t-1}),
                    r \perp td_2(TXs, NA, A), compose(K_{t-1}, NA, NA_1),
                    compose(NHY, NA_1, NA_2), compose(K_{p-2}, NA_2, Y)
```

By t-p+1 times folding clause 38 using clauses 1 and 2:

```
clause 39: r \not = d_2(Xs, Y, A) \leftarrow Xs = [X|TXs],

nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),

(nonMinimal(TX_1); ...; nonMinimal(TX_{p-1})),

(nonMinimal(TX_p); ...; nonMinimal(TX_t)),

r(TX_1, TY_1), ..., r(TX_{p-1}, TY_{p-1}), r(N, NHY),

decompose(N, HX, U_1, ..., U_t),

minimal(U_1), ..., minimal(U_t),

compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), ..., compose(K_{p-3}, TY_{p-1}, K_{p-2}),

r \not = d_2([TX_p, ..., TX_t|TXs], NA_1, A),

compose(NHY, NA_1, NA_2), compose(K_{p-2}, NA_2, Y)
```

By folding clause 39 using clauses 1 and 2:

```
clause \ 40: \ r \sharp d_2(Xs,Y,A) \leftarrow \\ Xs = [X|TXs], \\ nonMinimal(X), decompose(X,HX,TX_1,\ldots,TX_t), \\ (nonMinimal(TX_1);\ldots;nonMinimal(TX_{p-1})), \\ (nonMinimal(TX_p);\ldots;nonMinimal(TX_t)), \\ r(TX_1,TY_1),\ldots,r(TX_{p-1},TY_{p-1}), \\ decompose(N,HX,U_1,\ldots,U_t), \\ minimal(U_1),\ldots,minimal(U_t), \\ compose(TY_1,TY_2,K_1), compose(K_1,TY_3,K_2),\ldots,compose(K_{p-3},TY_{p-1},K_{p-2}), \\ r \sharp d_2([N,TX_p,\ldots,TX_t|TXs],NA_2,A), \\ compose(K_{p-2},NA_2,Y)
```

By p-1 times folding clause 40 using clauses 1 and 2:

```
 \begin{aligned} clause \ 41: & r\sharp d_2(Xs,Y,A) \leftarrow \\ & Xs = [X|TXs], \\ & nonMinimal(X), decompose(X,HX,TX_1,\ldots,TX_t), \\ & (nonMinimal(TX_1);\ldots;nonMinimal(TX_{p-1})), \\ & (nonMinimal(TX_p);\ldots;nonMinimal(TX_t)), \\ & decompose(N,HX,U_1,\ldots,U_t), \\ & minimal(U_1),\ldots,minimal(U_t), \\ & r\sharp d_2([TX_1,\ldots,TX_{p-1},N,TX_p,\ldots,TX_t|TXs],Y,A) \end{aligned}
```

Clauses 1, 3, 13, 20, 30 and 41 are the clauses of  $P_{r_{-td_2}}$ . Therefore  $P_{r_{-td_2}}$  is steadfast wrt  $S_{r_{-td_2}}$  in S.

To prove that  $P_r$  is steadfast wrt  $S_r$  in  $\{S_{r-td_2}\}$ , we do a backward proof that we begin with  $P_r$  in TDGRL and from which we try to obtain  $S_r$ .

The procedure  $P_r$  for r in TDGRL is:

$$r(X,Y) \leftarrow r\_td_2([X],Y,e)$$

By taking the 'completion':

$$\forall X: \mathcal{X}, \forall Y: \mathcal{Y}. \ \mathcal{I}_r(X) \Rightarrow [r(X,Y) \Leftrightarrow r\_td_2([X],Y,e)]$$

By unfolding the 'completion' above wrt  $r \perp d_2([X], Y, e)$  using  $S_{r \perp td_2}$ :

$$\forall X: \mathcal{X}, \forall Y: \mathcal{Y}. \ \mathcal{I}_r(X) \Rightarrow [r(X,Y) \Leftrightarrow \exists Y_1, I_1: \mathcal{Y}. \ \mathcal{O}_r(X,Y_1) \land I_1 = Y_1 \land \mathcal{O}_c(I_1,e,Y)]$$

By using applicability condition (2):

$$\forall X: \mathcal{X}, \forall Y: \mathcal{Y}. \quad \mathcal{I}_r(X) \Rightarrow [r(X,Y) \Leftrightarrow \exists Y_1, I_1: \mathcal{Y}. \quad \mathcal{O}_r(X,Y_1) \land I_1 = Y_1 \land Y = I_1]$$

By simplification:

$$\forall X : \mathcal{X}, \forall Y : \mathcal{Y}. \ \mathcal{I}_r(X)) \Rightarrow [r(X,Y) \Leftrightarrow \mathcal{O}_r(X,Y)]$$

We obtain  $S_r$ , so  $P_r$  is steadfast wrt  $S_r$  in  $\{S_{r\_td_2}\}$ . Therefore, TDGRL is also steadfast wrt  $S_r$  in S.

**Theorem 10** The generalization schema  $TDG_4$ , which is given below, is correct.

```
TDG_4: \langle \ DCRL, \ TDGLR, \ A_{td4}, \ O_{td412}, \ O_{td421} \ \rangle \ \text{where}
A_{td4}: (1) \ compose \ \text{is associative}
(2) \ compose \ \text{has } e \ \text{as the left and right identity element}
(3) \ \forall X: \mathcal{X}. \ \mathcal{I}_r(X) \land minimal(X) \Rightarrow \mathcal{O}_r(X, e)
(4) \ \forall X: \mathcal{X}. \ \mathcal{I}_r(X) \Rightarrow [\neg minimal(X) \Leftrightarrow nonMinimal(X)]
O_{td412}: \ \text{partial evaluation of the conjunction}
process(HX, HY), compose(A, HY, NewA)
\text{results in the introduction of a non-recursive relation}
O_{td421}: \ \text{partial evaluation of the conjunction}
process(HX, HY), compose(HY, I_p, I_{p-1})
```

where the template DCRL is Logic Program Template 3 in Section 2 and the template TDGLR is Logic Program Template 6 in Theorem 7.

The specification  $S_r$  of relation r is:

$$\forall X : \mathcal{X}, \forall Y : \mathcal{Y}. \ \mathcal{I}_r(X) \Rightarrow [r(X,Y) \Leftrightarrow \mathcal{O}_r(X,Y)]$$

results in the introduction of a non-recursive relation

The specification  $S_{r_{-t}d_1}$ :

$$\forall Xs: list \ of \ \mathcal{X}, \forall Y, A: \mathcal{Y}. \ \ (\forall X: \mathcal{X}. \ X \in Xs \Rightarrow \mathcal{I}_r(X)) \Rightarrow [r \pm d_1(Xs, Y, A) \Leftrightarrow (Xs = [] \land Y = A) \\ \lor (Xs = [X_1, X_2, \dots, X_q] \land \bigwedge_{i=1}^q \mathcal{O}_r(X_i, Y_i) \quad \land I_1 = Y_1 \land \bigwedge_{i=2}^q \mathcal{O}_c(I_{i-1}, Y_i, I_i) \\ \land \mathcal{O}_c(A, I_q, I_{q+1}) \land Y = I_{q+1})]$$

**Proof 10** To prove the correctness of the generalization schema  $TDG_4$ , by Definition 10, we have to prove that templates DCRL and TDGLR are equivalent wrt  $S_r$  under the applicability conditions  $A_{td4}$ . By Definition 5, the templates DCRL and TDGLR are equivalent wrt  $S_r$  under the applicability conditions  $A_{td4}$  iff DCRL is equivalent to TDGLR wrt the specification  $S_r$  provided that the conditions in  $A_{td4}$  hold. By Definition 4, DCRL is equivalent to TDGLR wrt the specification  $S_r$  iff the following two conditions hold:

- (a) DCRL is steadfast wrt  $S_r$  in  $S = \{S_{minimal}, S_{nonMinimal}, S_{solve}, S_{decompose}, S_{process}, S_{compose}\}$ , where  $S_{minimal}, S_{nonMinimal}, S_{solve}, S_{decompose}, S_{process}, S_{compose}$  are the specifications of minimal, nonMinimal, solve, decompose, process, compose, which are all the undefined relation names appearing in DCRL.
- (b) TDGLR is also steadfast wrt  $S_r$  in S.

Note that the sets  $\{S_1, \ldots, S_m\}$  and  $\{S'_1, \ldots, S'_t\}$  in Definition 4 are equal to  $\mathcal{S}$  when Q is obtained by simultaneous tupling-and-descending generalization of P.

In program transformation, we assume that the input program, here template DCRL, is steadfast wrt  $S_r$  in S, so condition (a) always holds.

To prove equivalence, we have to prove condition (b). We will use the following property of steadfastness: TDGLR is steadfast wrt  $S_r$  in S if  $P_{r\_td_1}$  is steadfast wrt  $S_{r\_td_1}$  in S, where  $P_{r\_td_1}$  is the procedure for  $r\_td_1$ , and  $P_r$  is steadfast wrt  $S_r$  in  $\{S_{r\_td_1}\}$ , where  $P_r$  is the procedure for r.

To prove that  $P_{r_{-}td_1}$  is steadfast wrt  $S_{r_{-}td_1}$  in  $\mathcal{S}$ , we do a constructive forward proof that we begin with  $S_{r_{-}td_1}$  and from which we try to obtain  $P_{r_{-}td_1}$ .

If we separate the cases of  $q \ge 1$  by  $q = 1 \lor q \ge 2$ , then  $S_{r_{-td_1}}$  becomes:

```
\forall Xs: list \ of \ \mathcal{X}, \forall Y: \mathcal{Y}: \ \mathcal{Y}. \ (\forall X: \mathcal{X}. \ X \in Xs \Rightarrow \mathcal{I}_r(X)) \Rightarrow [r \, \mathcal{I}d_1(Xs, Y, A) \Leftrightarrow (Xs = [] \land Y = A) \\ \lor (Xs = [X_1] \land \mathcal{O}_r(X_1, Y_1) \land Y_1 = I_1 \land \mathcal{O}_c(A, I_1, I_2) \land Y = I_2) \\ \lor (Xs = [X_1, X_2, \dots, X_q] \land \bigwedge_{i=1}^q \mathcal{O}_r(X_i, Y_i) \land I_1 = Y_1 \land \bigwedge_{i=2}^q \mathcal{O}_c(I_{i-1}, Y_i, I_i) \land \mathcal{O}_c(A, I_q, I_{q+1}) \land Y = I_{q+1})]
```

where q > 2.

By using applicability conditions (1) and (2):

```
\forall Xs : list \ of \ \mathcal{X}, \forall Y : \mathcal{Y}. \ (\forall X : \mathcal{X}. \ X \in Xs \Rightarrow \mathcal{I}_r(X)) \Rightarrow [r \, \mathcal{I} \, d_1(Xs, Y, A) \Leftrightarrow
             (Xs = [] \land Y = A)
             \forall (Xs = [X_1 | TXs] \land TXs = [] \land \mathcal{O}_r(X_1, Y_1) \land Y_1 = I_1 \land TY = A \land \mathcal{O}_c(A, I_1, NA) \land \mathcal{O}_c(NA, TY, Y))
             \forall (Xs = [X_1 | TXs] \land TXs = [X_2, \dots, X_q] \land \bigwedge_{i=1}^q \mathcal{O}_r(X_i, Y_i) \land Y_1 = I_1 \land Y_2 = I_2 \land I_1 \land I_2 \land I_2 \land I_3 \land I_4 \land I_4
             \bigwedge_{i=3}^{q} \mathcal{O}_c(I_{i-1}, Y_i, I_i) \wedge TY = I_q \wedge \mathcal{O}_c(A, I_1, NA) \wedge \mathcal{O}_c(NA, TY, Y))
where q > 2.
         By folding using S_{r-td_1}, and renaming:
            \forall Xs : list \ of \ \mathcal{X}, \forall Y : \mathcal{Y}. \ (\forall X : \mathcal{X}. \ X \in Xs \Rightarrow \mathcal{I}_r(X)) \Rightarrow [r \, \mathcal{I} \, d_1(Xs, Y, A) \Leftrightarrow
             (Xs = [] \land Y = A)
             \forall (Xs = [X|TXs] \land \mathcal{O}_r(X, HY) \land \mathcal{O}_c(A, HY, NA) \land r \bot d_1(TXs, Y, NA))]
         By taking the 'decompletion':
             clause 1: r \not = d_1(Xs, Y, A) \leftarrow
                                                            Xs = [], Y = A
             clause 2: r td_1(Xs, Y, A) \leftarrow
                                                           Xs = [X|TXs], r(X, HY),
                                                           compose(A, HY, NA), r \bot td_1(TXs, Y, NA)
          By unfolding clause 2 wrt r(X, HY) using DCRL, and using the assumption that DCRL is steadfast
wrt S_r in \mathcal{S}:
             clause 3: r \pm d_1(Xs, Y, A) \leftarrow
                                                            Xs = [X|TXs],
                                                           minimal(X),
                                                           solve(X, HY),
                                                           compose(A, HY, NA), r \bot td_1(TXs, Y, NA)
             clause 4: r td_1(Xs, Y, A) \leftarrow
                                                            Xs = [X|TXs],
                                                           nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                                                           r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                                                           I_{t+1} = e
                                                           compose(TY_t, I_{t+1}, I_t), \ldots, compose(TY_p, I_{p+1}, I_p),
                                                           process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                                                           compose(TY_{p-1}, I_{p-1}, I_{p-2}), \ldots, compose(TY_1, I_1, I_0),
                                                           HY = I_0,
                                                           compose(A, HY, NA), r\_td_1(TXs, Y, NA)
         By introducing
                                                                                                        (minimal(TX_1) \land \ldots \land minimal(TX_t)) \lor
                       ((minimal(TX_1) \land ... \land minimal(TX_{p-1})) \land (nonMinimal(TX_p) \lor ... \lor nonMinimal(TX_t)))\lor
                       ((nonMinimal(TX_1) \lor ... \lor nonMinimal(TX_{p-1})) \land (minimal(TX_p) \land ... \land minimal(TX_t))) \lor
            ((nonMinimal(TX_1) \lor ... \lor nonMinimal(TX_{p-1})) \land (nonMinimal(TX_p) \lor ... \lor nonMinimal(TX_t)))
         in clause 4, using applicability condition (4):
            clause 5: r \perp td_1(Xs, Y, A) \leftarrow
                                                            Xs = [X|TXs],
                                                           nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                                                           minimal(TX_1), \ldots, minimal(TX_t),
                                                           r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                                                           I_{t+1} = e,
                                                           compose(TY_t, I_{t+1}, I_t), \ldots, compose(TY_p, I_{p+1}, I_p),
                                                           process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                                                           compose(TY_{p-1}, I_{p-1}, I_{p-2}), \ldots, compose(TY_1, I_1, I_0),
                                                           HY = I_0,
```

 $compose(A, HY, NA), r \bot td_1(TXs, Y, NA)$ 

```
clause 6: r \pm d_1(Xs, Y, A) \leftarrow
                       Xs = [X|TXs],
                      nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                      minimal(TX_1), \ldots, minimal(TX_{p-1}),
                      (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                      r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                      I_{t+1} = e
                      compose(TY_t, I_{t+1}, I_t), \ldots, compose(TY_p, I_{p+1}, I_p),
                      process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                      compose(TY_{p-1}, I_{p-1}, I_{p-2}), \ldots, compose(TY_1, I_1, I_0),
                      HY = I_0,
                      compose(A, HY, NA), r\_td_1(TXs, Y, NA)
     clause 7: r \not = d_1(Xs, Y, A) \leftarrow
                      Xs = [X|TXs]
                      nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                      (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                      minimal(TX_p), \ldots, minimal(TX_t),
                      r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                      I_{t+1} = e
                      compose(TY_t, I_{t+1}, I_t), \ldots, compose(TY_p, I_{p+1}, I_p),
                      process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                      compose(TY_{p-1}, I_{p-1}, I_{p-2}), \ldots, compose(TY_1, I_1, I_0),
                      HY = I_0,
                      compose(A, HY, NA), r \bot td_1(TXs, Y, NA)
     clause 8: r td_1(Xs, Y, A) \leftarrow
                       Xs = [X|TXs],
                      nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                      (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                       (nonMinimal(TX_p); \dots; nonMinimal(TX_t)),
                      r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                      I_{t+1} = e,
                      compose(TY_t, I_{t+1}, I_t), \ldots, compose(TY_p, I_{p+1}, I_p),
                      process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                      compose(TY_{p-1}, I_{p-1}, I_{p-2}), \ldots, compose(TY_1, I_1, I_0),
                      HY = I_0,
                      compose(A, HY, NA), r\_td_1(TXs, Y, NA)
   By t times unfolding clause 5 wrt r(TX_1, TY_1), \ldots, r(TX_t, TY_t) using DCRL, and simplifying using
condition (4):
     clause 9: r td_1(Xs, Y, A) \leftarrow
                       Xs = [X|TXs],
                      nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                      minimal(TX_1), \ldots, minimal(TX_t),
                      minimal(TX_1), \ldots, minimal(TX_t)
                      solve(TX_1, TY_1), \ldots, solve(TX_t, TY_t)
                      I_{t+1}=e,
                      compose(TY_t, I_{t+1}, I_t), \ldots, compose(TY_p, I_{p+1}, I_p),
                      process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                      compose(TY_{p-1}, I_{p-1}, I_{p-2}), \ldots, compose(TY_1, I_1, I_0),
                      HY = I_0,
                      compose(A, HY, NA), r\_td_1(TXs, Y, NA)
```

By using applicability condition (3):

```
clause 10: r \perp d_1(Xs, Y, A) \leftarrow
                    Xs = [X|TXs]
                    nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                    minimal(TX_1), \ldots, minimal(TX_t),
                    minimal(TX_1), \ldots, minimal(TX_t),
                    solve(TX_1, e), \ldots, solve(TX_t, e),
                    I_{t+1}=e,
                    compose(e, I_{t+1}, I_t), \ldots, compose(e, I_{p+1}, I_p),
                    process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                    compose(e, I_{p-1}, I_{p-2}), \ldots, compose(e, I_1, I_0),
                    HY = I_0,
                    compose(A, HY, NA), r\_td_1(TXs, Y, NA)
By deleting one of the minimal(TX_1), \ldots, minimal(TX_t) atoms in clause 10:
 clause 11: r t d_1(Xs, Y, A) \leftarrow
                    Xs = [X|TXs],
                    nonMinimal(X), decompose(X, HX, TX_1, \dots, TX_t),
                    minimal(TX_1), \ldots, minimal(TX_t),
                    solve(TX_1, e), \ldots, solve(TX_t, e),
                    I_{t+1} = e,
                    compose(e, I_{t+1}, I_t), \ldots, compose(e, I_{p+1}, I_p),
                    process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                    compose(e, I_{p-1}, I_{p-2}), \ldots, compose(e, I_1, I_0),
                    HY = I_0,
                    compose(A, HY, NA), r t d_1(TXs, Y, NA)
By using applicability condition (2):
 clause 12: r \not = d_1(Xs, Y, A) \leftarrow
                    Xs = [X|TXs]
                    nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                    minimal(TX_1), \ldots, minimal(TX_t),
                    solve(TX_1, e), \ldots, solve(TX_t, e),
                    I_{t+1} = e,
                    I_t = I_{t+1}, \ldots, I_p = I_{p+1},
                    process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                    I_{p-2} = I_{p-1}, \ldots, I_0 = I_1,
                    HY = I_0,
                    compose(A, HY, NA), r \perp td_1(TXs, Y, NA)
By simplification:
 clause 13: r t d_1(Xs, Y, A) \leftarrow
                    Xs = [X|TXs],
                    nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                    minimal(TX_1), \ldots, minimal(TX_t),
                    process(HX, HY), compose(A, HY, NA),
                    r \perp td_1(TXs, Y, NA)
```

By p-1 times unfolding clause 6 wrt  $r(TX_1, TY_1), \ldots, r(TX_{p-1}, TY_{p-1})$  using DCRL, and simplifying using condition (4):

```
clause 14: r \perp d_1(Xs, Y, A) \leftarrow
                    Xs = [X|TXs]
                    nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                    minimal(TX_1), \ldots, minimal(TX_{p-1}),
                    (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                    minimal(TX_1), \ldots, minimal(TX_{p-1}),
                    solve(TX_1, TY_1), \ldots, solve(TX_{p-1}, TY_{p-1}),
                    r(TX_p, TY_p), \ldots, r(TX_t, TY_t),
                    I_{t+1}=e,
                    compose(TY_t, I_{t+1}, I_t), \ldots, compose(TY_p, I_{p+1}, I_p),
                    process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                    compose(TY_{p-1}, I_{p-1}, I_{p-2}), \ldots, compose(TY_1, I_1, I_0),
                    HY = I_0,
                    compose(A, HY, NA), r\_td_1(TXs, Y, NA)
By deleting one of the minimal(TX_1), \ldots, minimal(TX_{p-1}) atoms in clause 14:
 clause 15: r \pm d_1(Xs, Y, A) \leftarrow
                    Xs = [X|TXs],
                    nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                    minimal(TX_1), \ldots, minimal(TX_{p-1}),
                    (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                    solve(TX_1, TY_1), \ldots, solve(TX_{p-1}, TY_{p-1}),
                    r(TX_p, TY_p), \ldots, r(TX_t, TY_t),
                    I_{t+1}=e,
                    compose(TY_t, I_{t+1}, I_t), \ldots, compose(TY_p, I_{p+1}, I_p),
                    process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                    compose(TY_{p-1}, I_{p-1}, I_{p-2}), \ldots, compose(TY_1, I_1, I_0),
                    HY = I_0,
                    compose(A, HY, NA), r\_td_1(TXs, Y, NA)
By rewriting clause 15 using applicability conditions (1) and (2):
 clause 16: r t d_1(Xs, Y, A) \leftarrow
                    Xs = [X|TXs].
                    nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                    minimal(TX_1), \ldots, minimal(TX_{p-1}),
                    (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                    solve(TX_1, TY_1), \ldots, solve(TX_{p-1}, TY_{p-1}),
                    r(TX_p, TY_p), \ldots, r(TX_t, TY_t)
                    I_0 = e
                    compose(I_0, TY_1, I_1), \ldots, compose(I_{p-2}, TY_{p-1}, I_{p-1}),
                    process(HX, HHY), compose(I_{p-1}, HHY, I_p), HY = I_p,
                    compose(A, HY, NA),
                    compose(TY_p, TY_{p+1}, I_{p+1}),
                    compose(I_{p+1}, TY_{p+2}, I_{p+2}), \ldots, compose(I_{t-1}, TY_t, I_t),
                    compose(NA, I_t, NNA),
                    r \perp td_1(TXs, Y, NNA)
```

By t-p times folding clause 16 using clauses 1 and 2:

```
clause 17: r \perp d_1(Xs, Y, A) \leftarrow
                    Xs = [X|TXs]
                    nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                    minimal(TX_1), \ldots, minimal(TX_{p-1}),
                    (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                    solve(TX_1, TY_1), \ldots, solve(TX_{p-1}, TY_{p-1}),
                    compose(I_0, TY_1, I_1), \ldots, compose(I_{p-2}, TY_{p-1}, I_{p-1}),
                    process(HX, HHY), compose(I_{p-1}, HHY, I_p), HY = I_p,
                    compose(A, HY, NA),
                    r \perp t d_1([TX_p, \ldots, TX_t | TXs], Y, NA)
By using applicability condition (3):
 clause 18: r \pm d_1(Xs, Y, A) \leftarrow
                    Xs = [X|TXs]
                    nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                    minimal(TX_1), \ldots, minimal(TX_{p-1}),
                    (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                    solve(TX_1, e), \ldots, solve(TX_{p-1}, e),
                    I_0 = e,
                    compose(I_0, e, I_1), \ldots, compose(I_{p-2}, e, I_{p-1}),
                    process(HX, HHY), compose(I_{p-1}, HHY, I_p), HY = I_p,
                    compose(A, HY, NA),
                    r \perp td_1([TX_p, \ldots, TX_t|TXs], Y, NA)
By using applicability condition (2):
 clause 19: r t d_1(Xs, Y, A) \leftarrow
                    Xs = [X|TXs]
                    nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                    minimal(TX_1), \ldots, minimal(TX_{p-1}),
                    (nonMinimal(TX_p); \dots; nonMinimal(TX_t)),
                    solve(TX_1, e), \ldots, solve(TX_{p-1}, e),
                    I_0 = e,
                    I_1 = I_0, \ldots, I_{p-1} = I_{p-2},
                    process(HX, HHY), compose(I_{p-1}, HHY, I_p), HY = I_p,
                    compose(A, HY, NA),
                    r \perp t d_1([TX_p, \ldots, TX_t | TXs], Y, NA)
By simplification:
 clause 20 : r t d_1(Xs, Y, A) \leftarrow
                    Xs = [X|TXs].
                    nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                    minimal(TX_1), \ldots, minimal(TX_{p-1}),
                    (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                    process(HX, HY), compose(A, HY, NA),
                    r \perp t d_1([TX_p, \ldots, TX_t|TXs], Y, NA)
```

By introducing atoms  $minimal(U_1), \ldots, minimal(U_{p-1})$  (with new, i.e. existentially quantified, variables  $U_1, \ldots, U_{p-1}$ ) in clause 7:

```
clause 21: r \perp d_1(Xs, Y, A) \leftarrow
                    Xs = [X|TXs]
                    nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                    (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                    minimal(TX_p), \ldots, minimal(TX_t),
                    minimal(U_1), \ldots, minimal(U_{p-1}),
                    r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                    I_{t+1} = e,
                    compose(TY_t, I_{t+1}, I_t), \ldots, compose(TY_p, I_{p+1}, I_p),
                    process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                    compose(TY_{p-1}, I_{p-1}, I_{p-2}), \ldots, compose(TY_1, I_1, I_0),
                    HY = I_0,
                    compose(A, HY, NA), r\_td_1(TXs, Y, NA)
By using applicability condition (3):
 clause 22: r t d_1(Xs, Y, A) \leftarrow
                    Xs = [X|TXs]
                    nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                    (nonMinimal(TX_1); \ldots; nonMinimal(TX_{n-1})),
                    minimal(TX_p), \ldots, minimal(TX_t),
                    minimal(U_1), \ldots, minimal(U_{p-1}),
                    r(U_1,e),\ldots,r(U_{p-1},e),
                    r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                    I_{t+1} = e,
                    compose(TY_t, I_{t+1}, I_t), \ldots, compose(TY_p, I_{p+1}, I_p),
                    process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                    compose(TY_{p-1}, I_{p-1}, I_{p-2}), \ldots, compose(TY_1, I_1, I_0),
                    HY = I_0,
                    compose(A, HY, NA), r \perp td_1(TXs, Y, NA)
By using applicability condition (2):
 clause 23: r t d_1(Xs, Y, A) \leftarrow
                    Xs = [X|TXs].
                    nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                    (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                    minimal(TX_p), \ldots, minimal(TX_t),
                    minimal(U_1), \ldots, minimal(U_{p-1}),
                    r(U_1, e), \ldots, r(U_{p-1}, e),
                    r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                    I_{t+1} = e,
                    compose(TY_t, I_{t+1}, I_t), \ldots, compose(TY_p, I_{p+1}, I_p),
                    process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                    compose(e, I_{p-1}, K_1), compose(e, K_1, K_2), \ldots, compose(e, K_{p-2}, K_{p-1}),
                    compose(TY_{p-1}, K_{p-1}, I_{p-2}), \ldots, compose(TY_1, I_1, I_0),
                    HY = I_0,
                    compose(A, HY, NA), r \perp td_1(TXs, Y, NA)
```

By using applicability conditions (1) and (2):

```
clause 24: r \perp d_1(Xs, Y, A) \leftarrow
                   Xs = [X|TXs]
                   nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                   (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                   minimal(TX_p), \ldots, minimal(TX_t),
                   minimal(U_1), \ldots, minimal(U_{n-1}),
                   r(U_1,e),\ldots,r(U_{p-1},e),
                   r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                   I_{t+1}=e,
                   compose(TY_t, I_{t+1}, I_t), \ldots, compose(TY_p, I_{p+1}, I_p),
                   process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                   compose(e, I_{p-1}, I_{p-2}), \ldots, compose(e, I_1, I_0),
                   HY = I_0
                   compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \ldots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                   compose(A, K_{p-2}, NA), compose(NA, HY, NNA),
                   r \perp t d_1(TXs, Y, NNA)
```

By introducing new, i.e. existentially quantified, variables  $YU_1, \ldots, YU_{p-1}$  in place of some occurrences of e:

```
 \begin{array}{l} {\it clause} \ 25: \ r! d_1(Xs,Y,A) \leftarrow \\ Xs = [X|TXs], \\ nonMinimal(X), decompose(X,HX,TX_1,\ldots,TX_t), \\ (nonMinimal(TX_1);\ldots;nonMinimal(TX_{p-1})), \\ minimal(TX_p),\ldots,minimal(TX_t), \\ minimal(U_1),\ldots,minimal(U_{p-1}), \\ r(U_1,YU_1),\ldots,r(U_{p-1},YU_{p-1}), \\ r(TX_1,TY_1),\ldots,r(TX_t,TY_t), \\ I_{t+1} = e, \\ compose(TY_t,I_{t+1},I_t),\ldots,compose(TY_p,I_{p+1},I_p), \\ process(HX,HHY),compose(HHY,I_p,I_{p-1}), \\ compose(YU_{p-1},I_{p-1},I_{p-2}),\ldots,compose(YU_1,I_1,I_0), \\ HY = I_0, \\ compose(TY_1,TY_2,K_1),compose(K_1,TY_3,K_2),\ldots,compose(K_{p-3},TY_{p-1},K_{p-2}), \\ compose(A,K_{p-2},NA),compose(NA,HY,NNA), \\ r! d_1(TXs,Y,NNA) \end{array}
```

By introducing nonMinimal(N) and  $decompose(N, HX, U_1, ..., U_{p-1}, TX_p, ..., TX_t)$ , since

```
\exists N: \mathcal{X}.nonMinimal(N) \land decompose(N, HX, U_1, \ldots, U_{p-1}, TX_p, \ldots, TX_t)
```

always holds (because N is existentially quantified):

```
clause 26: r \perp td_1(Xs, Y, A) \leftarrow
                   Xs = [X|TXs],
                   nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                   (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                   minimal(TX_p), \ldots, minimal(TX_t),
                   minimal(U_1), \ldots, minimal(U_{p-1}),
                   r(U_1, YU_1), \ldots, r(U_{p-1}, YU_{p-1}),
                   nonMinimal(N), decompose(N, HX, U_1, \dots, U_{p-1}, TX_p, \dots, TX_t),
                   r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                   I_{t+1} = e,
                   compose(TY_t, I_{t+1}, I_t), \ldots, compose(TY_p, I_{p+1}, I_p),
                   process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                   compose(YU_{p-1}, I_{p-1}, I_{p-2}), \ldots, compose(YU_1, I_1, I_0),
                   HY = I_0,
                   compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \dots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                   compose(A, K_{p-2}, NA), compose(NA, HY, NNA),
                   r \perp td_1(TXs, Y, NNA)
```

By duplicating goal  $decompose(N, HX, U_1, \ldots, U_{p-1}, TX_p, \ldots, TX_t)$ :

```
clause 27: r \perp d_1(Xs, Y, A) \leftarrow
                    Xs = [X|TXs]
                    nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                    (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                    minimal(TX_p), \ldots, minimal(TX_t),
                    minimal(U_1), \ldots, minimal(U_{p-1}),
                    r(U_1, YU_1), \ldots, r(U_{p-1}, YU_{p-1}),
                    nonMinimal(N), decompose(N, HX, U_1, \dots, U_{p-1}, TX_p, \dots, TX_t),
                    decompose(N, HX, U_1, \ldots, U_{p-1}, TX_p, \ldots, TX_t),
                    r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                    I_{t+1} = e,
                    compose(TY_t, I_{t+1}, I_t), \ldots, compose(TY_p, I_{p+1}, I_p),
                    process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                    compose(YU_{p-1}, I_{p-1}, I_{p-2}), \ldots, compose(YU_1, I_1, I_0),
                    HY = I_0,
                    compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \dots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                    compose(A, K_{p-2}, NA), compose(NA, HY, NNA),
                    r \perp td_1(TXs, Y, NNA)
By folding clause 27 using DCRL:
 clause 28: r \pm d_1(Xs, Y, A) \leftarrow
                    Xs = [X|TXs]
                    nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                    (nonMinimal(TX_1); \dots; nonMinimal(TX_{p-1})),
                    minimal(TX_p), \ldots, minimal(TX_t),
                    minimal(U_1), \ldots, minimal(U_{p-1}),
                    decompose(N, HX, U_1, \ldots, U_{p-1}, TX_p, \ldots, TX_t),
                    r(TX_1, TY_1), \ldots, r(TX_{p-1}, TY_{p-1}), r(N, HY),
                    compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \dots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                    compose(A, K_{p-2}, NA), compose(NA, HY, NNA),
                    r \perp td_1(TXs, Y, NNA)
By folding clause 28 using clauses 1 and 2:
 clause 29: r \pm d_1(Xs, Y, A) \leftarrow
                    Xs = [X|TXs],
                    nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                    (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                    minimal(TX_p), \ldots, minimal(TX_t),
                    minimal(U_1), \ldots, minimal(U_{p-1}),
                    decompose(N, HX, U_1, \ldots, U_{p-1}, TX_p, \ldots, TX_t),
                    r(TX_1, TY_1), \ldots, r(TX_{p-1}, TY_{p-1}),
                    compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \ldots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                    compose(A, K_{p-2}, NA),
                    r \perp td_1([N|TXs], Y, NA)
By p-1 times folding clause 29 using clauses 1 and 2:
 clause 30 : r t d_1(Xs, Y, A) \leftarrow
                    Xs = [X|TXs],
                    nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                    (nonMinimal(TX_1); \dots; nonMinimal(TX_{p-1})),
                    minimal(TX_p), \ldots, minimal(TX_t),
                    minimal(U_1), \ldots, minimal(U_{p-1}),
                    decompose(N, HX, U_1, \ldots, U_{p-1}, TX_p, \ldots, TX_t),
                    r \pm d_1([TX_1, \dots, TX_{p-1}, N|TXs], Y, A)
```

By introducing atoms  $minimal(U_1), \ldots, minimal(U_t)$  (with new, i.e. existentially quantified, variables  $U_1, \ldots, U_t$ ) in clause 8:

```
clause 31: r \perp d_1(Xs, Y, A) \leftarrow
                    Xs = [X|TXs]
                    nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                    (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                    (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                    minimal(U_1), \ldots, minimal(U_t),
                    r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                    I_{t+1} = e,
                    compose(TY_t, I_{t+1}, I_t), \ldots, compose(TY_p, I_{p+1}, I_p),
                    process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                    compose(TY_{p-1}, I_{p-1}, I_{p-2}), \ldots, compose(TY_1, I_1, I_0),
                    HY = I_0,
                    compose(A, HY, NA), r\_td_1(TXs, Y, NA)
By using applicability condition (3):
 clause 32: r \not = d_1(Xs, Y, A) \leftarrow
                    Xs = [X|TXs]
                    nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                    (nonMinimal(TX_1); \dots; nonMinimal(TX_{p-1})),
                    (nonMinimal(TX_p); \dots; nonMinimal(TX_t)),
                    minimal(U_1), \ldots, minimal(U_t),
                    r(U_1,e),\ldots,r(U_t,e),
                    r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                    I_{t+1} = e,
                    compose(TY_t, I_{t+1}, I_t), \ldots, compose(TY_p, I_{p+1}, I_p),
                    process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                    compose(TY_{p-1}, I_{p-1}, I_{p-2}), \ldots, compose(TY_1, I_1, I_0),
                    HY = I_0,
                    compose(A, HY, NA), r \perp td_1(TXs, Y, NA)
By using applicability condition (2):
 clause 33: r t d_1(Xs, Y, A) \leftarrow
                    Xs = [X|TXs].
                    nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                    (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                    (nonMinimal(TX_p); \dots; nonMinimal(TX_t)),
                    minimal(U_1), \ldots, minimal(U_t),
                    r(U_1,e),\ldots,r(U_t,e),
                    r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                    I_{t+1} = e
                    compose(TY_t, I_{t+1}, I_t), \ldots, compose(TY_p, I_{p+1}, I_p),
                    compose(e, I_p, K_{t+1}),
                    compose(e, K_{t+1}, K_t), \ldots, compose(e, K_{p+1}, K_p),
                    process(HX, HHY), compose(HHY, K_p, K_{p-1}),
                    compose(e, K_{p-1}, K_{p-2}), \ldots, compose(e, K_1, K_0),
                    compose(e, K_0, I_{p-1}),
                    compose(TY_{p-1}, I_{p-1}, I_{p-2}), \ldots, compose(TY_1, I_1, I_0),
                    HY = I_0,
                    compose(A, HY, NA), r t d_1(TXs, Y, NA)
```

By using applicability conditions (1) and (2):

```
clause 34: r \perp d_1(Xs, Y, A) \leftarrow
                        Xs = [X|TXs]
                        nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                        (nonMinimal(TX_1); ...; nonMinimal(TX_{p-1})),
                        (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                        minimal(U_1), \ldots, minimal(U_t),
                        r(U_1,e),\ldots,r(U_t,e),
                        r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                        compose(e, I_{t+1}, I_t), \ldots, compose(e, I_{p+1}, I_p),
                        process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                        compose(e, I_{p-1}, I_{p-2}), \ldots, compose(e, I_1, I_0),
                        NHY = I_0,
                        compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \ldots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                        compose(TY_p, TY_{p+1}, K_p), compose(K_p, TY_{p+2}, K_{p+1}), \ldots, compose(K_{t-2}, TY_t, K_{t-1}),
                        compose(A, K_{p-2}, NA_1), compose(NA_1, NHY, NA_2),
                        compose(NA_2, K_{t-1}, NA), r t d_1(TXs, Y, NA)
   By introducing new, i.e. existentially quantified, variables YU_1, \ldots, YU_t in place of some occurrences
of e:
     clause 35: r \perp td_1(Xs, Y, A) \leftarrow
                        Xs = [X|TXs]
                        nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                        (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                        (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                        minimal(U_1), \ldots, minimal(U_t),
                        r(U_1, YU_1), \ldots, r(U_t, YU_t),
                        r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                        I_{t+1} = e,
                        compose(Y U_t, I_{t+1}, I_t), \ldots, compose(Y U_p, I_{p+1}, I_p),
                        process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                        compose(YU_{p-1}, I_{p-1}, I_{p-2}), \ldots, compose(YU_1, I_1, I_0),
                        compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \ldots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                        compose(TY_p, TY_{p+1}, K_p), compose(K_p, TY_{p+2}, K_{p+1}), \ldots, compose(K_{t-2}, TY_t, K_{t-1}),
                        compose(A, K_{p-2}, NA_1), compose(NA_1, NHY, NA_2),
                        compose(NA_2, K_{t-1}, NA), r \not\perp td_1(TXs, Y, NA)
   By introducing nonMinimal(N) and decompose(N, HX, U_1, \ldots, U_t), since
                         \exists N: \mathcal{X}.nonMinimal(N) \land decompose(N, HX, U_1, \ldots, U_t)
always holds (because N is existentially quantified):
     clause 36: r \pm d_1(Xs, Y, A) \leftarrow
                        Xs = [X|TXs]
                        nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                        (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                        (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                        minimal(U_1), \ldots, minimal(U_t),
                        r(U_1, YU_1), \ldots, r(U_t, YU_t),
                        nonMinimal(N), decompose(N, HX, U_1, \ldots, U_t),
                        r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                        I_{t+1} = e,
                        compose(YU_t, I_{t+1}, I_t), \ldots, compose(YU_p, I_{p+1}, I_p),
                        process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                        compose(Y U_{p-1}, I_{p-1}, I_{p-2}), \ldots, compose(Y U_1, I_1, I_0),
                        NHY = I_0,
                        compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \ldots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                        compose(TY_p, TY_{p+1}, K_p), compose(K_p, TY_{p+2}, K_{p+1}), \ldots, compose(K_{t-2}, TY_t, K_{t-1}),
                        compose(A, K_{p-2}, NA_1), compose(NA_1, NHY, NA_2),
```

 $compose(NA_2, K_{t-1}, NA), r td_1(TXs, Y, NA)$ 

```
By duplicating goal decompose(N, HX, U_1, \ldots, U_t):
 clause 37: r \pm d_1(Xs, Y, A) \leftarrow
                    Xs = [X|TXs],
                    nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                    (nonMinimal(TX_1); ...; nonMinimal(TX_{p-1})),
                    (nonMinimal(TX_p); \dots; nonMinimal(TX_t)),
                    minimal(U_1), \ldots, minimal(U_t),
                    r(U_1, YU_1), \ldots, r(U_t, YU_t),
                    nonMinimal(N), decompose(N, HX, U_1, \ldots, U_t),
                    decompose(N, HX, U_1, \ldots, U_t),
                    r(TX_1, TY_1), \ldots, r(TX_t, TY_t),
                    I_{t+1} = e,
                    compose(Y U_t, I_{t+1}, I_t), \ldots, compose(Y U_p, I_{p+1}, I_p),
                    process(HX, HHY), compose(HHY, I_p, I_{p-1}),
                    compose(YU_{p-1}, I_{p-1}, I_{p-2}), \ldots, compose(YU_1, I_1, I_0),
                    NHY = I_0,
                    compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \dots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                    compose(TY_p, TY_{p+1}, K_p), compose(K_p, TY_{p+2}, K_{p+1}), \ldots, compose(K_{t-2}, TY_t, K_{t-1}),
                    compose(A, K_{p-2}, NA_1), compose(NA_1, NHY, NA_2),
                    compose(NA_2, K_{t-1}, NA), r \perp td_1(TXs, Y, NA)
By folding clause 37 using DCRL:
 clause 38: r t d_1(Xs, Y, A) \leftarrow
                    Xs = [X|TXs],
                    nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                    (nonMinimal(TX_1); \dots; nonMinimal(TX_{p-1})),
                    (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                    minimal(U_1), \ldots, minimal(U_t),
                    decompose(N, HX, U_1, \ldots, U_t),
                    r(TX_1, TY_1), \ldots, r(TX_t, TY_t), r(N, NHY),
                    compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \ldots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                    compose(TY_p, TY_{p+1}, K_p), compose(K_p, TY_{p+2}, K_{p+1}), \ldots, compose(K_{t-2}, TY_t, K_{t-1}),
                    compose(A, K_{p-2}, NA_1), compose(NA_1, NHY, NA_2),
                    compose(NA_2, K_{t-1}, NA), r \pm d_1(TXs, Y, NA)
By t - p + 1 times folding clause 38 using clauses 1 and 2:
 clause 39: r \perp td_1(Xs, Y, A) \leftarrow
                    Xs = [X|TXs]
                    nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                    (nonMinimal(TX_1); ...; nonMinimal(TX_{p-1})),
                    (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                    minimal(U_1), \ldots, minimal(U_t),
                    decompose(N, HX, U_1, \ldots, U_t),
                    r(TX_1, TY_1), \ldots, r(TX_{p-1}, TY_{p-1}), r(N, NHY),
                    compose(TY_1, TY_2, K_1), compose(K_1, TY_3, K_2), \dots, compose(K_{p-3}, TY_{p-1}, K_{p-2}),
                    compose(A, K_{p-2}, NA_1), compose(NA_1, NHY, NA_2),
                    r \not\perp d_1([TX_p, \ldots, TX_t|TXs], Y, NA_2)
```

By folding clause 39 using clauses 1 and 2:

```
clause 40: r \sharp d_1(Xs,Y,A) \leftarrow Xs = [X|TXs],

nonMinimal(X), decompose(X,HX,TX_1,\ldots,TX_t),

(nonMinimal(TX_1);\ldots;nonMinimal(TX_{p-1})),

(nonMinimal(TX_p);\ldots;nonMinimal(TX_t)),

minimal(U_1),\ldots,minimal(U_t),

decompose(N,HX,U_1,\ldots,U_t),

r(TX_1,TY_1),\ldots,r(TX_{p-1},TY_{p-1}),

compose(TY_1,TY_2,K_1),compose(K_1,TY_3,K_2),\ldots,compose(K_{p-3},TY_{p-1},K_{p-2}),

compose(A,K_{p-2},NA_1),

r \sharp d_1([N,TX_p,\ldots,TX_t|TXs],Y,NA_1)
```

By p-1 times folding clause 40 using clauses 1 and 2:

```
clause \ 41: \ r \sharp d_1(Xs,Y,A) \leftarrow \\ Xs = [X|TXs], \\ nonMinimal(X), decompose(X,HX,TX_1,\ldots,TX_t), \\ (nonMinimal(TX_1);\ldots;nonMinimal(TX_{p-1})), \\ (nonMinimal(TX_p);\ldots;nonMinimal(TX_t)), \\ minimal(U_1),\ldots,minimal(U_t), \\ decompose(N,HX,U_1,\ldots,U_t), \\ r \sharp d_1([TX_1,\ldots,TX_{p-1},N,TX_p,\ldots,TX_t|TXs],Y,A)
```

Clauses 1, 3, 13, 20, 30 and 41 are the clauses of  $P_{r_{-}td_1}$ . Therefore  $P_{r_{-}td_1}$  is steadfast wrt  $S_{r_{-}td_1}$  in S.

To prove that  $P_r$  is steadfast wrt  $S_r$  in  $\{S_{r\_td_1}\}$ , we do a backward proof that we begin with  $P_r$  in TDGLR and from which we try to obtain  $S_r$ .

The procedure  $P_r$  for r in TDGLR is:

$$r(X,Y) \leftarrow r t d_1([X],Y,e)$$

By taking the 'completion':

$$\forall X: \mathcal{X}, \forall Y: \mathcal{Y}. \ \mathcal{I}_r(X) \Rightarrow [r(X,Y) \Leftrightarrow r \bot td_1([X],Y,e)]$$

By unfolding the 'completion' above wrt  $r \perp td_1([X], Y, e)$  using  $S_{r \perp td_1}$ :

$$\forall X: \mathcal{X}, \forall Y: \mathcal{Y}. \quad \mathcal{I}_r(X) \Rightarrow [r(X,Y) \Leftrightarrow \exists Y_1, I_1: \mathcal{Y}. \quad \mathcal{O}_r(X,Y_1) \land I_1 = Y_1 \land \mathcal{O}_c(e,I_1,Y)]$$

By using applicability condition (2):

$$\forall X: \mathcal{X}, \forall Y: \mathcal{Y}. \quad \mathcal{I}_r(X) \Rightarrow [r(X,Y) \Leftrightarrow \exists Y_1, I_1: \mathcal{Y}. \quad \mathcal{O}_r(X,Y_1) \land I_1 = Y_1 \land Y = I_1]$$

By simplification:

$$\forall X : \mathcal{X}, \forall Y : \mathcal{Y}. \ \mathcal{I}_r(X)) \Rightarrow [r(X,Y) \Leftrightarrow \mathcal{O}_r(X,Y)]$$

We obtain  $S_r$ , so  $P_r$  is steadfast wrt  $S_r$  in  $\{S_{r\_td_1}\}$ . Therefore, TDGLR is also steadfast wrt  $S_r$  in S.

## 5 Proofs of the Duality Schemas

**Theorem 11** The duality schema  $D_{dc}$ , which is given below, is correct.

```
\begin{array}{l} D_{dc}: \langle \ DCLR, \ DCRL, \ A_{ddc}, \ O_{ddc12}, \ O_{ddc21} \rangle \ \ \text{where} \\ A_{ddc}: (1) \ compose \ \text{is associative} \\ (2) \ compose \ \text{has} \ e \ \text{as} \ \text{the left and right identity element}, \\ \text{where} \ e \ \text{appears in} \ DCLR \ \text{and} \ DCRL \\ O_{ddc12}: \ \text{-partial evaluation of the conjunction} \\ process(HX, HY), compose(HY, I_p, I_{p-1}) \\ \text{results in the introduction of a non-recursive relation} \\ O_{ddc21}: \ \text{-partial evaluation of the conjunction} \\ process(HX, HY), compose(I_{p-1}, HY, I_p) \\ \text{results in the introduction of a non-recursive relation} \end{array}
```

where the template DCLR is Logic Program Template 1 in Section 2 and the template DCRL is Logic Program Template 3 in Section 3.

The specification  $S_r$  of both a DCLR program and a DCRL program for relation r is:

$$\forall X : \mathcal{X} . \ \forall Y : \mathcal{Y} . \ \mathcal{I}_r(X) \Rightarrow [r(X,Y) \Leftrightarrow \mathcal{O}_r(X,Y)]$$

**Proof 11** To prove the correctness of the duality schema  $D_{dc}$ , by Definition 10, we have to prove that templates DCLR and DCRL are equivalent wrt  $S_r$  under the applicability conditions  $A_{ddc}$ . By Definition 5, the templates DCLR and DCRL are equivalent wrt  $S_r$  under the applicability conditions  $A_{ddc}$  iff DCLR is equivalent to DCRL wrt the specification  $S_r$  provided that the conditions in  $A_{ddc}$  hold. By Definition 4, DCLR is equivalent to DCRL wrt the specification  $S_r$  iff the following two conditions hold:

- (a) DCLR is steadfast wrt  $S_r$  in  $S = \{S_{minimal}, S_{nonMinimal}, S_{solve}, S_{decompose}, S_{process}, S_{compose}\}$ , where  $S_{minimal}, S_{nonMinimal}, S_{solve}, S_{process}, S_{decompose}, S_{compose}$  are the specifications of minimal, nonMinimal, solve, decompose, process, compose, which are all the undefined relation names appearing in DCLR.
- (b) DCRL is also steadfast wrt  $S_r$  in S.

Note that the sets  $\{S_1, \ldots, S_m\}$  and  $\{S'_1, \ldots, S'_t\}$  in Definition 4 are equal to  $\mathcal{S}$  when Q is obtained by duality transformation of P.

In program transformation, we assume that the input program, here template DCLR, is steadfast wrt  $S_r$  in S, so condition (a) always holds.

To prove equivalence, we have to prove condition (b). We will use Definition 3: DCRL is steadfast wrt  $S_r$  in  $\mathcal{S}$  iff  $DCRL \cup P_S$  is correct wrt  $S_r$ , where  $P_S$  is any closed program such that  $P_S$  is correct wrt each specification in  $\mathcal{S}$  and  $P_S$  contains no occurrences of the relation r.

To prove that DCRL is steadfast wrt  $S_r$  in S, we do a constructive forward proof that we begin with  $S_r$  and from which we try to obtain the open program DCRL.

By taking the 'decompletion' of  $S_r$ :

```
clause 1: r(X,Y) \leftarrow r(X,Y)
```

By unfolding clause 1 wrt the atom r(X,Y) on the right-hand side of  $\leftarrow$  using DCLR, and using the assumption that DCLR is steadfast wrt  $S_r$  in S:

```
 \begin{array}{ll} clause \ 2: & r(X,Y) \leftarrow \\ & minimal(X), \\ & solve(X,Y) \end{array} \\ clause \ 3: & r(X,Y) \leftarrow \\ & nonMinimal(X), decompose(X,HX,TX_1,\ldots,TX_t), \\ & r(TX_1,TY_1),\ldots,r(TX_t,TY_t), \\ & I_0 = e, \\ & compose(I_0,TY_1,I_1),\ldots,compose(I_{p-2},TY_{p-1},I_{p-1}), \\ & process(HX,HY),compose(I_{p-1},HY,I_p), \\ & compose(I_p,TY_p,I_{p+1}),\ldots,compose(I_t,TY_t,I_{t+1}), \\ & Y = I_{t+1} \end{array}
```

By using applicability condition (1) on clause 3:

```
clause 4: r(X,Y) \leftarrow nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t), \\ r(TX_1, TY_1), ..., r(TX_t, TY_t), \\ compose(TY_{t-1}, TY_t, A_{t-1}), \\ compose(TY_{t-2}, A_{t-1}, A_{t-2}), ..., compose(TY_p, A_{p+1}, A_p), \\ process(HX, HY), compose(HY, A_p, A_{p-1}), \\ compose(TY_{p-1}, A_{p-1}, A_{p-2}), ..., compose(TY_1, A_1, A_0), \\ compose(e, A_0, Y)
```

By using applicability conditions (1) and (2) on clause 4:

```
clause \ 5: \ r(X,Y) \leftarrow \\ nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t), \\ r(TX_1, TY_1), \ldots, r(TX_t, TY_t), \\ compose(TY_t, e, A_t), \\ compose(TY_{t-1}, A_t, A_{t-1}), \ldots, compose(TY_p, A_{p+1}, A_p), \\ process(HX, HY), compose(HY, A_p, A_{p-1}), \\ compose(TY_{p-1}, A_{p-1}, A_{p-2}), \ldots, compose(TY_1, A_1, A_0), \\ Y = A_0
```

By introducing a new, i.e. existentially quantified, variable  $A_{t+1}$ :

```
clause 6: r(X,Y) \leftarrow nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t), \\ r(TX_1, TY_1), ..., r(TX_t, TY_t), \\ A_{t+1} = e, \\ compose(TY_t, A_{t+1}, A_t), ..., compose(TY_p, A_{p+1}, A_p), \\ process(HX, HY), compose(HY, A_p, A_{p-1}), \\ compose(TY_{p-1}, A_{p-1}, A_{p-2}), ..., compose(TY_1, A_1, A_0), \\ Y = A_0
```

Clauses 2 and 6 are the clauses of DCRL.

Therefore DCRL is steadfast wrt  $S_r$  in  $\mathcal{S}$ .

**Theorem 12** The duality schema  $D_{dg}$ , which is given below, is correct.

```
\begin{array}{l} D_{dg}: \left\langle \right. DGLR, DGRL, A_{ddg}, O_{ddg12}, O_{ddg21} \right\rangle \text{ where} \\ A_{ddg}: \left(1\right) \ compose \ \text{is associative} \\ \left(2\right) \ compose \ \text{has } e \ \text{as the left and right identity element,} \\ O_{ddg12}: -\mathcal{I}_r(X) \wedge minimal(X) \Rightarrow \mathcal{O}_r(X,e) \\ - \ \text{partial evaluation of the conjunction} \\ process(HX, HY), compose(HY, A_p, A_{p-1}) \\ \text{results in the introduction of a non-recursive relation} \\ O_{ddg21}: -\mathcal{I}_r(X) \wedge minimal(X) \Rightarrow \mathcal{O}_r(X,e) \\ - \ \text{partial evaluation of the conjunction} \\ process(HX, HY), compose(A_{p-1}, HY, A_p) \\ \text{results in the introduction of a non-recursive relation} \end{array}
```

and the templates DGLR and DGRL are Logic Program Templates 4 and 5 in Section 3. The specification  $S_r$  of both a DGLR program and a DGRL program for relation r is:

$$\forall X : \mathcal{X} : \forall Y : \mathcal{Y} : \mathcal{I}_r(X) \Rightarrow [r(X,Y) \Leftrightarrow \mathcal{O}_r(X,Y)]$$

The specification  $S_{r\_des\,cen\,din\,g_1}$  of relation  $r\_des\,cen\,din\,g_1$  is:

$$\forall X: \mathcal{X}. \ \forall Y, A: \mathcal{Y}. \ \mathcal{I}_r(X) \Rightarrow [r \_descending_1(X,Y,A) \ \Leftrightarrow \ \exists S: \mathcal{Y}. \ \mathcal{O}_r(X,S) \land \mathcal{O}_c(A,S,Y)]$$

The specification  $S_{r\_des\,cendin\,g_2}$  of relation  $r\_des\,cendin\,g_2$  is:

$$\forall X: \mathcal{X}. \ \forall Y, A: \mathcal{Y}. \ \mathcal{I}_r(X) \Rightarrow [r\_descending_2(X,Y,A) \Leftrightarrow \exists S: \mathcal{Y}. \ \mathcal{O}_r(X,S) \land \mathcal{O}_c(S,A,Y)]$$

**Proof 12** To prove the correctness of the duality schema  $D_{dg}$ , by Definition 10, we have to prove that templates DGLR and DGRL are equivalent wrt  $S_r$  under the applicability conditions  $A_{ddg}$ . By Definition 5, the templates DGLR and DGRL are equivalent wrt  $S_r$  under the applicability conditions  $A_{ddg}$  iff DGLR is equivalent to DGRL wrt the specification  $S_r$  provided that the conditions in  $A_{ddg}$  hold. By Definition 4, DGLR is equivalent to DGRL wrt the specification  $S_r$  iff the following two conditions hold:

- (a) DGLR is steadfast wrt  $S_r$  in  $\mathcal{S} = \{S_{minimal}, S_{nonMinimal}, S_{solve}, S_{decompose}, S_{process}, S_{compose}\}$ , where  $S_{minimal}, S_{nonMinimal}, S_{solve}, S_{process}, S_{decompose}, S_{compose}$  are the specifications of minimal, nonMinimal, solve, decompose, process, compose, which are all the undefined relation names appearing in DGLR.
- (b) DGRL is also steadfast wrt  $S_r$  in S.

Note that the sets  $\{S_1, \ldots, S_m\}$  and  $\{S'_1, \ldots, S'_t\}$  in Definition 4 are equal to  $\mathcal{S}$  when Q is obtained by duality transformation of P.

In program transformation, we assume that the input program, here template DGLR, is steadfast wrt  $S_r$  in S, so condition (a) always holds.

To prove equivalence, we have to prove condition (b). We will use the following property of stead-fastness: DGRL is steadfast wrt  $S_r$  in S if  $P_{r\_descending_2}$  is steadfast wrt  $S_{r\_descending_2}$  in S, where  $P_{r\_descending_2}$  is the procedure for  $r\_descending_2$ , and  $P_r$  is steadfast wrt  $S_r$  in  $\{S_{r\_descending_2}\}$ , where  $P_r$  is the procedure for r.

To prove that  $P_{r\_descending_2}$  is steadfast wrt  $S_{r\_descending_2}$  in  $\mathcal{S}$ , we do a constructive forward proof that we begin with  $S_{r\_descending_2}$  and from which we try to obtain  $P_{r\_descending_2}$ .

By taking the 'decompletion' of  $S_{r\_descending_2}$ :

```
clause 1: r\_descending_2(X, Y, A) \leftarrow r(X, S), compose(S, A, Y)
```

By unfolding clause 1 wrt r(X, S) using DGLR, and using the assumption that DGLR is steadfast wrt  $S_r$  in S:

```
clause 2: r\_descending_2(X, Y, A) \leftarrow r\_descending_1(X, S, e), compose(S, A, Y)
```

By unfolding clause 2 wrt r\_descending<sub>1</sub>(X, S, e) using DGLR, and using the assumption that  $P_{r\_descending_1}$  is steadfast wrt  $S_{r\_descending_1}$  in S, since  $P_{r\_descending_1}$  must be steadfast wrt  $S_{r\_descending_1}$  in S for DGLR to be steadfast wrt  $S_r$  in S:

```
\begin{array}{ll} clause \ 3: & r.descending_2(X,Y,A) \leftarrow \\ & minimal(X), \\ & solve(X,S'), compose(e,S',S), compose(S,A,Y) \\ clause \ 4: & r.descending_2(X,Y,A) \leftarrow \\ & nonMinimal(X), decompose(X,HX,TX_1,\ldots,TX_t), \\ & compose(e,e,A_0), \\ & r.descending_1(TX_1,A_1,A_0),\ldots,r.descending_1(TX_{p-1},A_{p-1},A_{p-2}), \\ & process(HX,HS), compose(A_{p-1},HS,A_p), \\ & r.descending_1(TX_p,A_{p+1},A_p),\ldots,r.descending_1(TX_t,A_{t+1},A_t), \\ & S = A_{t+1}, compose(S,A,Y) \end{array}
```

By using applicability condition (2) on clause 3:

```
clause 5: r 	ext{\_descending}_2(X, Y, A) \leftarrow minimal(X),

solve(X, S'), S = S, compose(S, A, Y)
```

By simplification:

```
clause 6: r\_descending_2(X, Y, A) \leftarrow minimal(X), \\ solve(X, S), compose(S, A, Y)
```

By t times unfolding clause 4 wrt the atoms

```
r\_descending_1(TX_1, A_1, A_0), \ldots, r\_descending_1(TX_{p-1}, A_{p-1}, A_{p-2}),

r\_descending_1(TX_p, A_{p+1}, A_p), \ldots, r\_descending_1(TX_t, A_{t+1}, A_t)

using the 'decompletion' of S_{r\_descending_1} (refer to Proofs 3 and 6):
```

```
clause 7: r \cdot descending_2(X, Y, A) \leftarrow nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t), compose(e, e, A_0), r(TX_1, TS_1), ..., r(TX_{p-1}, TS_{p-1}), compose(A_0, TS_1, A_1), ..., compose(A_{p-2}, TS_{p-1}, A_{p-1}), process(HX, HS), compose(A_{p-1}, HS, A_p), r(TX_p, TS_p), ..., r(TX_t, TS_t), compose(A_p, TS_p, A_{p+1}), ..., compose(A_t, TS_t, A_{t+1}), S = A_{t+1}, compose(S, A, Y)
```

By using applicability condition (1) on clause 7:

```
clause 8: r \cdot descending_2(X, Y, A) \leftarrow nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t), \\ compose(e, I, Y), compose(e, A_0, I), \\ r(TX_1, TS_1), ..., r(TX_{p-1}, TS_{p-1}), \\ compose(TS_1, A_1, A_0), ..., compose(TS_{p-1}, A_{p-1}, A_{p-2}), \\ process(HX, HS), compose(HS, A_p, A_{p-1}), \\ r(TX_p, TS_p), ..., r(TX_t, TS_t), \\ compose(TS_p, A_{p+1}, A_p), ..., compose(TS_t, A, A_t)
```

By using applicability condition (2):

```
clause 9: r \cdot descending_2(X, Y, A) \leftarrow nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),

Y = A_0,

r(TX_1, TS_1), ..., r(TX_{p-1}, TS_{p-1}),

compose(TS_1, A_1, A_0), ..., compose(TS_{p-1}, A_{p-1}, A_{p-2}),

process(HX, HS), compose(HS, A_p, A_{p-1}),

r(TX_p, TS_p), ..., r(TX_t, TS_t),

compose(TS_p, A_{p+1}, A_p), ..., compose(TS_t, A_{t+1}, A_t),

compose(e, A, A_{t+1})
```

By t times folding clause 9 using clause 1:

```
 \begin{array}{ll} clause \ 10: & r.descending_2(X,Y,A) \leftarrow \\ & nonMinimal(X), decompose(X,HX,TX_1,\ldots,TX_t), \\ & compose(e,A,A_{t+1}), \\ & r.descending_2(TX_t,A_t,A_{t+1}),\ldots,r.descending_2(TX_p,A_p,A_{p+1}), \\ & process(HX,HY), compose(HY,A_p,A_{p-1}), \\ & r.descending_2(TX_{p-1},A_{p-2},A_{p-1}),\ldots,r.descending_2(TX_1,A_0,A_1), \\ & Y = A_0 \end{array}
```

Clauses 2 and 10 are the clauses of  $P_{r\_descending_2}$ . Therefore  $P_{r\_descending_2}$  is steadfast wrt  $S_{r\_descending_2}$  in S.

To prove that  $P_r$  is steadfast wrt  $S_r$  in  $\{S_{r\_descending_2}\}$ , we do a backward proof that we begin with  $P_r$  in DGRL and from which we try to obtain  $S_r$ .

The procedure  $P_r$  for r in DGRL is:

$$r(X,Y) \leftarrow r\_descending_2(X,Y,e)$$

By taking the 'completion':

$$\forall X: \mathcal{X}, \forall Y: \mathcal{Y}. \ \mathcal{I}_r(X) \Rightarrow [r(X,Y) \Leftrightarrow r\_descending_2(X,Y,e)]$$

By unfolding the 'completion' above wrt  $r\_descending_2(X,Y,e)$  using  $S_{r\_descending_2}$ :

$$\forall X : \mathcal{X}, \forall Y : \mathcal{Y}. \quad \mathcal{I}_r(X) \Rightarrow [r(X,Y) \Leftrightarrow \exists S : \mathcal{Y}. \quad \mathcal{O}_r(X,S) \land \mathcal{O}_c(S,e,Y)]$$

By using applicability condition (2):

$$\forall X : \mathcal{X}, \forall Y : \mathcal{Y}. \ \mathcal{I}_r(X) \Rightarrow [r(X,Y) \Leftrightarrow \exists S : \mathcal{Y}. \ \mathcal{O}_r(X,S) \land S = Y]$$

By simplification:

$$\forall X : \mathcal{X}, \forall Y : \mathcal{Y}. \ \mathcal{I}_r(X) \Rightarrow [r(X,Y) \Leftrightarrow \mathcal{O}_r(X,Y)]$$

We obtain  $S_r$ , so  $P_r$  is steadfast wrt  $S_r$  in  $\{S_{r\_descending_2}\}$ . Therefore, DGRL is also steadfast wrt  $S_r$  in S.

**Theorem 13** The duality schema  $D_{tdq}$ , which is given below, is correct.

$$D_{tdg}: \langle TDGLR, TDGRL, A_{dtdg}, O_{dtdg12}, O_{dtdg21} \rangle$$
 where  $A_{dtdg}: (1)$  compose is associative

(2) compose has e as the left and right identity element,

where e appears in TDGLR and TDGRL  $O_{dtdg12}$ : -  $\forall X: \mathcal{X}: \mathcal{I}_r(X) \land minimal(X) \Rightarrow \mathcal{O}_r(X,e)$  - partial evaluation of the conjunction process(HX,HY), compose(HY,NewA,F) results in the introduction of a non-recursive relation  $O_{dtdg21}$ : -  $\forall X: \mathcal{X}: \mathcal{I}_r(X) \land minimal(X) \Rightarrow \mathcal{O}_r(X,e)$  - partial evaluation of the conjunction process(HX,HY), compose(A,HY,NewA) results in the introduction of a non-recursive relation

where the templates TDGLR and TDGRL are Logic Program Templates 6 and 7 in Section 4.

The specification  $S_r$  of relation r is:

$$\forall X : \mathcal{X}, \forall Y : \mathcal{Y}. \ \mathcal{I}_r(X) \Rightarrow [r(X,Y) \Leftrightarrow \mathcal{O}_r(X,Y)]$$

The specification of  $r \perp td_1$ , namely  $S_{r \perp td_1}$ , is:

$$\forall Xs: list \ of \ \mathcal{X}, \forall Y, A: \mathcal{Y}. \quad (\forall X: \mathcal{X}. \ X \in Xs \Rightarrow \mathcal{I}_r(X)) \Rightarrow [r \mathcal{J}d_1(Xs, Y, A) \Leftrightarrow (Xs = [] \land Y = A) \\ \lor (Xs = [X_1, X_2, \dots, X_q] \land \bigwedge_{i=1}^q \mathcal{O}_r(X_i, Y_i) \quad \land I_1 = Y_1 \land \bigwedge_{i=2}^q \mathcal{O}_c(I_{i-1}, Y_i, I_i) \\ \land \mathcal{O}_c(A, I_q, I_{q+1}) \land Y = I_{q+1})]$$

The specification of  $r\_td_2$ , namely  $S_{r\_td_2}$ , is:

$$\forall Xs : list \ of \ \mathcal{X}, \forall Y, A : \mathcal{Y}. \ (\forall X : \mathcal{X} : X \in Xs \Rightarrow \mathcal{I}_r(X)) \Rightarrow [r \perp td_2(Xs, Y, A) \Leftrightarrow (Xs = [] \land Y = A) \\ \lor (Xs = [X_1, X_2, \dots, X_q] \land \bigwedge_{i=1}^q \mathcal{O}_r(X_i, Y_i) \ \land I_1 = Y_1 \land \bigwedge_{i=2}^q \mathcal{O}_c(I_{i-1}, Y_i, I_i) \\ \land \mathcal{O}_c(I_q, A, I_{q+1}) \land Y = I_{q+1})]$$

**Proof 13** To prove the correctness of the duality schema  $D_{tdg}$ , by Definition 10, we have to prove that templates TDGLR and TDGRL are equivalent wrt  $S_r$  under the applicability conditions  $A_{dtdg}$ . By Definition 5, the templates TDGLR and TDGRL are equivalent wrt  $S_r$  under the applicability conditions  $A_{dtdg}$  iff TDGLR is equivalent to TDGRL wrt the specification  $S_r$  provided that the conditions in  $A_{dtdg}$  hold. By Definition 4, TDGLR is equivalent to TDGRL wrt the specification  $S_r$  iff the following two conditions hold:

- (a) TDGLR is steadfast wrt  $S_r$  in  $\mathcal{S} = \{S_{minimal}, S_{nonMinimal}, S_{solve}, S_{decompose}, S_{process}, S_{compose}\}$ , where  $S_{minimal}, S_{nonMinimal}, S_{solve}, S_{process}, S_{decompose}, S_{compose}$  are the specifications of minimal, nonMinimal, solve, decompose, process, compose, which are all the undefined relation names appearing in TDGLR.
- (b) TDGRL is also steadfast wrt  $S_r$  in S.

Note that the sets  $\{S_1, \ldots, S_m\}$  and  $\{S'_1, \ldots, S'_t\}$  in Definition 4 are equal to S when Q is obtained by duality transformation of P.

In program transformation, we assume that the input program, here template TDGLR, is steadfast wrt  $S_r$  in S, so condition (a) always holds.

To prove equivalence, we have to prove condition (b). We will use the following property of steadfastness: TDGRL is steadfast wrt  $S_r$  in  $\mathcal{S}$  if  $P_{r-td_2}$  is steadfast wrt  $S_{r-td_2}$  in  $\mathcal{S}$ , where  $P_{r-td_2}$  is the procedure for  $r \perp td_2$ , and  $P_r$  is steadfast wrt  $S_r$  in  $\{S_{r-td_2}\}$ , where  $P_r$  is the procedure for r.

To prove that  $P_{r\_td_2}$  is steadfast wrt  $S_{r\_td_2}$  in S, we do a constructive forward proof that we begin with  $S_{r\_td_2}$  and from which we try to obtain  $P_{r\_td_2}$ .

If we separate the cases of  $q \ge 1$  by  $q = 1 \lor q \ge 2$ , then  $S_{r\_td_2}$  becomes:

```
\forall Xs: list \ of \ \mathcal{X}, \forall Y: \mathcal{Y}. \ (\forall X: \mathcal{X}. \ X \in Xs \Rightarrow \mathcal{I}_r(X)) \Rightarrow [r \mathcal{I} d_2(Xs, Y, A) \Leftrightarrow (Xs = [] \land Y = A) \\ \lor (Xs = [X_1] \land \mathcal{O}_r(X_1, Y_1) \land Y_1 = I_1 \land \mathcal{O}_c(I_1, A, I_2) \land Y = I_2) \\ \lor (Xs = [X_1, X_2, \dots, X_q] \land \ \bigwedge_{i=1}^q \mathcal{O}_r(X_i, Y_i) \ \land I_1 = Y_1 \land \ \bigwedge_{i=2}^q \mathcal{O}_c(I_{i-1}, Y_i, I_i) \ \land \mathcal{O}_c(I_q, A, I_{q+1}) \land Y = I_{q+1})]
where q \geq 2.
```

By using applicability conditions (1) and (2):

```
\forall Xs: list \ of \ \mathcal{X}, \forall Y: \mathcal{Y}: \ (\forall X: \mathcal{X}. \ X \in Xs \Rightarrow \mathcal{I}_r(X)) \Rightarrow [r \, \mathcal{I}d_2(Xs, Y, A) \Leftrightarrow (Xs = [] \land Y = A) \\ \lor (Xs = [X_1 | TXs] \land TXs = [] \land \mathcal{O}_r(X_1, Y_1) \land Y_1 = I_1 \land TY = A \land \mathcal{O}_c(TY, A, NA) \land \mathcal{O}_c(I_1, NA, Y)) \\ \lor (Xs = [X_1 | TXs] \land TXs = [X_2, \dots, X_q] \land \ \bigwedge_{i=1}^q \mathcal{O}_r(X_i, Y_i) \ \land Y_1 = I_1 \land Y_2 = I_2 \land A \land \mathcal{O}_c(I_{i-1}, Y_i, I_i) \ \land TY = I_q \land \mathcal{O}_c(TY, A, NA) \land \mathcal{O}_c(I_1, NA, Y))]
```

where  $q \geq 2$ .

By folding using  $S_{r_{-}td_2}$ , and renaming:

```
\forall Xs : list \ of \ \mathcal{X}, \forall Y : \mathcal{Y}. \ (\forall X : \mathcal{X}. \ X \in Xs \Rightarrow \mathcal{I}_r(X)) \Rightarrow [r \pm d_2(Xs, Y, A) \Leftrightarrow (Xs = [] \land Y = A) \\ \lor (Xs = [X|TXs] \land \mathcal{O}_r(X, HY) \land r \pm d_2(TXs, NA, A) \land \mathcal{O}_c(HY, NA, Y))]
```

By taking the 'decompletion':

```
\begin{array}{ll} clause \ 1: & r \not \pm d_2(Xs,Y,A) \leftarrow \\ & Xs = [],Y = A \\ clause \ 2: & r \not \pm d_2(Xs,Y,A) \leftarrow \\ & Xs = [X|TXs],r(X,HY), \\ & r \not \pm d_2(TXs,NA,A),compose(HY,NA,Y) \end{array}
```

By unfolding clause 2 wrt r(X, HY) using TDGLR, and using the assumption that DCLR is steadfast wrt  $S_r$  in S:

```
clause 3: r \pm d_2(Xs, Y, A) \leftarrow Xs = [X|TXs], r \pm d1([X], HY, e), r \pm d_2(TXs, NA, A), compose(HY, NA, Y)
```

By unfolding clause 3 wrt  $r_{-t}d_1([X], HY, e)$  using TDGLR, and using the assumption that  $P_{r_{-t}d_1}$  is steadfast wrt  $S_{r_{-t}d_1}$  in S, since  $P_{r_{-t}d_1}$  must be steadfast wrt  $S_{r_{-t}d_1}$  in S for TDGLR to be steadfast wrt  $S_r$  in S:

```
clause 4: r td_2(Xs, Y, A) \leftarrow
                Xs = [X|TXs]
                Xs' = [X|TXs'], TXs' = [],
                minimal(X), solve(X, HY'),
                compose(e, HY', NA'), r \pm d1(TXs', HY, NA'),
                r \perp td_2(TXs, NA, A), compose(HY, NA, Y)
clause 5: r \pm d_2(Xs, Y, A) \leftarrow
                Xs = [X|TXs],
                Xs' = [X|TXs'], TXs' = [],
                nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                minimal(TX_1), \ldots, minimal(TX_t),
                process(HX, HY'), compose(e, HY', NA'),
                r \perp td_1(TXs', HY, NA'),
                r \perp td_2(TXs, NA, A), compose(HY, NA, Y)
clause 6: r \pm d_2(Xs, Y, A) \leftarrow
                Xs = [X|TXs],
                Xs' = [X|TXs'], TXs' = [],
                nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                minimal(TX_1), \ldots, minimal(TX_{p-1}),
                (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                process(HX, HY'), compose(e, HY', NA'),
                r \perp td_1([TX_p, \ldots, TX_t|TXs'], HY, NA'),
                r \perp td_2(TXs, NA, A), compose(HY, NA, Y)
```

```
clause 7: r td_2(Xs, Y, A) \leftarrow
                 Xs = [X|TXs]
                 Xs' = [X|TXs'], TXs' = [],
                 nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                 (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                 minimal(TX_p), \ldots, minimal(TX_t),
                 minimal(U_1), \ldots, minimal(U_{p-1}),
                 decompose(N, HX, U_1, \ldots, U_{p-1}, TX_p, \ldots, TX_t),
                 r_{t}td_{1}([TX_{1},\ldots,TX_{p-1},N|TXs'],H\dot{Y},e),
                 r\_td_2(TXs, NA, A), compose(HY, NA, Y)
clause 8: r \pm d_2(Xs, Y, A) \leftarrow
                 Xs = [X|TXs]
                 Xs' = [X|TXs'], TXs' = [],
                 nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
                 (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                 (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                 minimal(U_1), \ldots, minimal(U_t),
                 decompose(N, HX, U_1, \ldots, U_t),
                 r \perp td_1([TX_1, \ldots, TX_{p-1}, N, TX_p, \ldots, TX_t | TXs'], HY, e),
                 r \perp td_2(TXs, NA, A), compose(HY, NA, Y)
```

By unfolding clause 4 wrt  $r \pm td_1(TXs', HY, NA')$  using TDGLR, and using the assumption that  $P_{r \pm td_1}$  is steadfast wrt  $S_{r \pm td_1}$  in S:

```
clause 9: r \sharp d_2(Xs, Y, A) \leftarrow Xs = [X|TXs],

Xs' = [X|TXs'], TXs' = [],

minimal(X), solve(X, HY'),

compose(e, HY', NA'),

TXs' = [], HY = NA',

r \sharp d_2(TXs, NA, A), compose(HY, NA, Y)
```

By using applicability condition (2):

```
clause 10: r \pm d_2(Xs, Y, A) \leftarrow Xs = [X|TXs],

Xs' = [X|TXs'], TXs' = [],

minimal(X), solve(X, HY'),

HY' = NA',

TXs' = [], HY = NA',

r \pm d_2(TXs, NA, A), compose(HY, NA, Y)
```

By simplification:

```
clause 11: r \sharp d_2(Xs, Y, A) \leftarrow Xs = [X|TXs],

minimal(X), solve(X, HY),

r \sharp d_2(TXs, NA, A), compose(HY, NA, Y)
```

By unfolding clause 5 wrt  $r \pm d_1(TXs', HY, NA')$  using TDGLR, and using the assumption that  $P_{r \pm td_1}$  is steadfast wrt  $S_{r \pm td_1}$  in S:

```
clause 12: r \sharp d_2(Xs, Y, A) \leftarrow Xs = [X|TXs],

Xs' = [X|TXs'], TXs' = [],

nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),

minimal(TX_1), ..., minimal(TX_t),

process(HX, HY'), compose(e, HY', NA'),

TXs' = [], HY = NA',

r \sharp d_2(TXs, NA, A), compose(HY, NA, Y)
```

By using applicability condition (2):

```
clause 13: r \not = d_2(Xs, Y, A) \leftarrow Xs = [X|TXs],

Xs' = [X|TXs'], TXs' = [],

nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),

minimal(TX_1), ..., minimal(TX_t),

process(HX, HY'), HY' = NA',

TXs' = [], HY = NA',

r \not = d_2(TXs, NA, A), compose(HY, NA, Y)

By simplification:

clause 14: r \not = d_2(Xs, Y, A) \leftarrow Xs = [X|TXs],

nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),
```

 $minimal(TX_1), \ldots, minimal(TX_t),$ 

process(HX, HY), compose(HY, NA, Y)

 $r \perp td_2(TXs, NA, A),$ 

By t times unfolding clause 6 wrt

$$r \perp t d_1([TX_p, \ldots, TX_t | TXs'], HY, NA'), \ldots, r \perp t d_1([TX_t | TXs'], HY, NA_{t-1})$$

using the "decompletion" of  $S_{r_{-}td_{1}}$  in Section 4:

```
clause 15: r \cdot \mathcal{I}d_2(Xs, Y, A) \leftarrow Xs = [X|TXs],

Xs' = [X|TXs'], TXs' = [],

non Minimal(X), decompose(X, HX, TX_1, ..., TX_t),

minimal(TX_1), ..., minimal(TX_{p-1}),

(non Minimal(TX_p); ...; non Minimal(TX_t)),

process(HX, HY'), compose(e, HY', NA'),

r(TX_p, TY_p), ..., r(TX_t, TY_t),

compose(NA', TY_p, NA_p), ..., compose(NA_{t-1}, TY_t, NA_t),

r \cdot \mathcal{I}d_1(TXs', HY, NA_t),

r \cdot \mathcal{I}d_2(TXs, NA, A), compose(HY, NA, Y)
```

By unfolding clause 15 wrt  $r \pm t d_1(TXs', HY, NA_t)$  using TDGLR, and using the assumption that  $P_{r \pm t d_1}$  is steadfast wrt  $S_{r \pm t d_1}$  in S:

```
clause 16: r \pm d_2(Xs, Y, A) \leftarrow Xs = [X|TXs],

Xs' = [X|TXs'], TXs' = [],

nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),

minimal(TX_1), ..., minimal(TX_{p-1}),

(nonMinimal(TX_p); ...; nonMinimal(TX_t)),

process(HX, HY'), compose(e, HY', NA'),

r(TX_p, TY_p), ..., r(TX_t, TY_t),

compose(NA', TY_p, NA_p), ..., compose(NA_{t-1}, TY_t, NA_t),

TXs' = [], HY = NA_t,

r \pm d_2(TXs, NA, A), compose(HY, NA, Y)
```

By using applicability conditions (1) and (2), and simplification:

```
clause 17: r \not \exists d_2(Xs, Y, A) \leftarrow Xs = [X|TXs],

nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),

minimal(TX_1), ..., minimal(TX_{p-1}),

(nonMinimal(TX_p); ...; nonMinimal(TX_t)),

process(HX, HY), compose(HY, I_p, Y),

r(TX_p, TY_p), ..., r(TX_t, TY_t),

compose(TY_p, I_{p+1}, I_p), ..., compose(TY_t, NA, I_t),

r \not\exists d_2(TXs, NA, A)
```

By t times folding clause 17 using clauses 1 and 2:

```
\begin{aligned} \textit{clause } 18: \quad r \not\exists d_2(Xs, Y, A) \leftarrow \\ Xs &= [X|TXs], \\ &\quad nonMinimal(X), decompose(X, HX, TX_1, \dots, TX_t), \\ &\quad minimal(TX_1), \dots, minimal(TX_{p-1}), \\ &\quad (nonMinimal(TX_p); \dots; nonMinimal(TX_t)), \\ &\quad r \not\exists d_2([TX_p, \dots, TX_t|TXs], NA, A), \\ &\quad process(HX, HY), compose(HY, NA, Y) \end{aligned} By p times unfolding clause 7 wrt
```

 $r \perp td_1([TX_1, \dots, TX_{n-1}, N|TXs'], HY, NA'), \dots, r \perp td_1([N|TXs'], HY, NA_{n-1})$ 

using the "decompletion" of  $S_{r-td}$ , in Section 4:

```
 clause \ 19: \ r \sharp d_2(Xs,Y,A) \leftarrow \\ Xs = [X|TXs], \\ Xs' = [X|TXs'], TXs' = [], \\ nonMinimal(X), decompose(X,HX,TX_1,...,TX_t), \\ (nonMinimal(TX_1);...;nonMinimal(TX_{p-1})), \\ minimal(TX_p),...,minimal(TX_t), \\ minimal(U_1),...,minimal(U_{p-1}), \\ decompose(N,HX,U_1,...,U_{p-1},TX_p,...,TX_t), \\ r(TX_1,TY_1),...,r(TX_{p-1},TY_{p-1}),r(N,YN), \\ compose(e,TY_1,NA_1), \\ compose(NA_1,TY_2,NA_2),...,compose(NA_{p-2},TY_{p-1},NA_{p-1}), \\ compose(NA_{p-1},YN,NA_p), \\ r \sharp d_1(TXs',HY,NA_p), \\ r \sharp d_2(TXs,NA,A),compose(HY,NA,Y)
```

By unfolding clause 19 wrt  $r \pm d_1(TXs', HY, NA_p)$  using TDGLR, and using the assumption that  $P_{r \pm td_1}$  is steadfast wrt  $S_{r \pm td_1}$  in S:

```
clause \ 20: \ r t d_2(Xs,Y,A) \leftarrow \\ Xs = [X|TXs], \\ Xs' = [X|TXs'], TXs' = [], \\ non Minimal(X), decompose(X, HX, TX_1, ..., TX_t), \\ (non Minimal(TX_1); ...; non Minimal(TX_{p-1})), \\ minimal(TX_p), ..., minimal(TX_t), \\ minimal(U_1), ..., minimal(U_{p-1}), \\ decompose(N, HX, U_1, ..., U_{p-1}, TX_p, ..., TX_t), \\ r(TX_1, TY_1), ..., r(TX_{p-1}, TY_{p-1}), r(N, YN), \\ compose(e, TY_1, NA_1), \\ compose(NA_1, TY_2, NA_2), ..., compose(NA_{p-2}, TY_{p-1}, NA_{p-1}), \\ compose(NA_{p-1}, YN, NA_p), \\ TXs' = [], HY = NA_p, \\ r t d_2(TXs, NA, A), compose(HY, NA, Y)
```

By using applicability conditions (1) and (2), and simplification:

```
clause 21: r \sharp d_2(Xs,Y,A) \leftarrow Xs = [X|TXs],
	nonMinimal(X), decompose(X,HX,TX_1,\ldots,TX_t),
	(nonMinimal(TX_1);\ldots;nonMinimal(TX_{p-1})),
	minimal(TX_p),\ldots,minimal(TX_t),
	minimal(U_1),\ldots,minimal(U_{p-1}),
	decompose(N,HX,U_1,\ldots,U_{p-1},TX_p,\ldots,TX_t),
	r(TX_1,TY_1),\ldots,r(TX_{p-1},TY_{p-1}),r(N,YN),
	compose(TY_1,I_1,Y),
	compose(TY_2,I_2,I_1),\ldots,compose(TY_{p-1},I_p,I_{p-1}),
	compose(YN,NA,I_p),
	r \sharp d_2(TXs,NA,A)
```

By p times folding clause 21 using clauses 1 and 2:

```
clause 22: r \perp d_2(Xs, Y, A) \leftarrow
                        Xs = [X|TXs]
                        nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                        (nonMinimal(TX_1); \ldots; nonMinimal(TX_{p-1})),
                        minimal(TX_p), \ldots, minimal(TX_t),
                        minimal(U_1), \ldots, minimal(U_{p-1}),
                        decompose(N, HX, U_1, \ldots, U_{p-1}, TX_p, \ldots, TX_t),
                        r \not = d_2([TX_1, \dots, TX_{p-1}, N|TX_s], Y, A)
   By t+1 times unfolding clause 8 wrt
      r \pm d_1([TX_1, \dots, TX_{p-1}, N, TX_p, \dots, TX_t | TXs'], HY, NA'), \dots, r \pm d_1([TX_t | TXs'], HY, NA_t)
using the "decompletion" of S_{r_{-td_1}} in Section 4:
     clause 23: r \pm d_2(Xs, Y, A) \leftarrow
                        Xs = [X|TXs]
                        Xs' = [X|TXs'], TXs' = [],
                        nonMinimal(X), decompose(X, HX, TX_1, \ldots, TX_t),
                        (nonMinimal(TX_1); ...; nonMinimal(TX_{p-1})),
                        (nonMinimal(TX_p); \ldots; nonMinimal(TX_t)),
                        minimal(U_1), \ldots, minimal(U_t),
                        decompose(N, HX, U_1, \ldots, U_t),
                        r(TX_1, TY_1), \ldots, r(TX_t, TY_t), r(N, YN),
                        compose(e, TY_1, NA_1),
                        compose(NA_1, TY_2, NA_2), \ldots, compose(NA_{p-2}, TY_{p-1}, NA_{p-1}),
                        compose(NA_{p-1}, YN, NA_p),
```

By unfolding clause 23 wrt  $r_{\star}td_1(TXs', HY, NA_{t+1})$  using TDGLR, and using the assumption that  $P_{r_{\star}td_1}$  is steadfast wrt  $S_{r_{\star}td_1}$  in S:

 $compose(NA_p, TY_p, NA_{p+1}), \ldots, compose(NA_t, TY_t, NA_{t+1}),$ 

```
clause 24: r \sharp d_2(Xs,Y,A) \leftarrow Xs = [X|TXs],

Xs' = [X|TXs'], TXs' = [],

nonMinimal(X), decompose(X, HX, TX_1, ..., TX_t),

(nonMinimal(TX_1); ...; nonMinimal(TX_{p-1})),

(nonMinimal(TX_p); ...; nonMinimal(TX_t)),

minimal(U_1), ..., minimal(U_t),

decompose(N, HX, U_1, ..., U_t),

r(TX_1, TY_1), ..., r(TX_t, TY_t), r(N, YN),

compose(NA_1, TY_2, NA_2), ..., compose(NA_{p-2}, TY_{p-1}, NA_{p-1}),

compose(NA_{p-1}, YN, NA_p),

compose(NA_p, TY_p, NA_{p+1}), ..., compose(NA_t, TY_t, NA_{t+1}),

TXs' = [], HY = NA_{t+1},

r \sharp d_2(TXs, NA, A), compose(HY, NA, Y)
```

 $r \perp td_2(TXs, NA, A), compose(HY, NA, Y)$ 

By using applicability conditions (1) and (2), and simplification:

 $r \perp td_1(TXs', HY, NA_{t+1}),$ 

```
clause \ 25: \ r \sharp d_2(Xs,Y,A) \leftarrow \\ Xs = [X|TXs], \\ nonMinimal(X), decompose(X,HX,TX_1,\ldots,TX_t), \\ (nonMinimal(TX_1);\ldots;nonMinimal(TX_{p-1})), \\ (nonMinimal(TX_p);\ldots;nonMinimal(TX_t)), \\ minimal(U_1),\ldots,minimal(U_t), \\ decompose(N,HX,U_1,\ldots,U_t), \\ r(TX_1,TY_1),\ldots,r(TX_t,TY_t),r(N,YN), \\ compose(TY_1,I_1,Y), \\ compose(TY_2,I_2,I_1),\ldots,compose(TY_{p-1},I_p,I_{p-1}), \\ compose(YN,I_{p+1},I_p), \\ compose(YN,I_{p+1},I_p), \\ compose(TY_t,NA,I_{t+1}), \\ r \sharp d_2(TXs,NA,A)
```

By t + 1 times folding clause 25 using clauses 1 and 2:

```
 clause \ 26: \ r \sharp d_2(Xs,Y,A) \leftarrow \\ Xs = [X|TXs], \\ nonMinimal(X), decompose(X,HX,TX_1,\ldots,TX_t), \\ (nonMinimal(TX_1);\ldots;nonMinimal(TX_{p-1})), \\ (nonMinimal(TX_p);\ldots;nonMinimal(TX_t)), \\ minimal(U_1),\ldots,minimal(U_t), \\ decompose(N,HX,U_1,\ldots,U_t), \\ r \sharp d_2([TX_1,\ldots,TX_{p-1},N,TX_p,\ldots,TX_t|TXs],Y,A)
```

Clauses 1, 11, 14, 18, 22 and 26 are the clauses of  $P_{r\_td_2}$ . Therefore  $P_{r\_td_2}$  is steadfast wrt  $S_{r\_td_2}$  in S.

To prove that  $P_r$  is steadfast wrt  $S_r$  in  $\{S_{r-td_2}\}$ , we do a backward proof that we begin with  $P_r$  in TDGRL and from which we try to obtain  $S_r$ .

The procedure  $P_r$  for r in TDGRL is:

$$r(X,Y) \leftarrow r\_td_2([X],Y,e)$$

By taking the 'completion':

$$\forall X: \mathcal{X}, \forall Y: \mathcal{Y}. \ \mathcal{I}_r(X) \Rightarrow [r(X,Y) \Leftrightarrow r \bot d_2([X],Y,e)]$$

By unfolding the 'completion' above wrt  $r \perp d_2([X], Y, e)$  using  $S_{r \perp td_2}$ :

$$\forall X: \mathcal{X}, \forall Y: \mathcal{Y}. \quad \mathcal{I}_r(X) \Rightarrow [r(X,Y) \Leftrightarrow \exists Y_1, I_1: \mathcal{Y}. \quad \mathcal{O}_r(X,Y_1) \land I_1 = Y_1 \land \mathcal{O}_c(I_1,e,Y)]$$

By using applicability condition (2):

$$\forall X: \mathcal{X}, \forall Y: \mathcal{Y}. \ \mathcal{I}_r(X) \Rightarrow [r(X,Y) \Leftrightarrow \exists Y_1, I_1: \mathcal{Y}. \ \mathcal{O}_r(X,Y_1) \land I_1 = Y_1 \land Y = I_1]$$

By simplification:

$$\forall X : \mathcal{X}, \forall Y : \mathcal{Y}. \ \mathcal{I}_r(X)) \Rightarrow [r(X,Y) \Leftrightarrow \mathcal{O}_r(X,Y)]$$

We obtain  $S_r$ , so  $P_r$  is steadfast wrt  $S_r$  in  $\{S_{r\_td_2}\}$ . Therefore, TDGRL is also steadfast wrt  $S_r$  in S.

## 6 Conclusion

In this report, we have proven the correctness of the 13 transformation schemas in [3]. The transformation schemas and their schema patterns can be given as the graph in Figure 1 below, where the schema patterns are the nodes of the graph, and the transformation schemas are the edges. The arrow indicates in what way the transformation schema is proved (i.e., the arrow is printed from the assumed input program

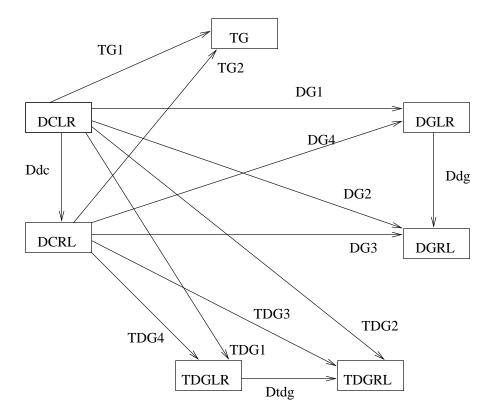


Figure 1: A Graph to Represent the Correctness Proofs of Transformation Schemas

schema pattern to the output program schema pattern in the proof of the corresponding transformation schema). Each of these transformation schemas can of course be proven in the other direction, since these transformation schemas are applicable in both directions.

Therefore, the transformation schemas proved in this report are a successful pre-compilation of the corresponding transformation techniques.

## References

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