#### **ID2204: Constraint Programming**

# Getting Practical... Modeling Introduction



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# Constraint Programming with Gecode

# Constraint Programming in Practice

- There are two options, use
  - modeling language, for example: MiniZinc
  - constraint system, for example: Gecode
- Modeling language advantages
  - high-level, easy to learn, easy to model
  - models can be tried with different systems
- Key disadvantage for us: you can only model!
  - you will also learn how to implement constraints, ...

# Modeling in Gecode

- Gecode offers two interface layers
  - primitive layer for interfacingChapter 2 in MPG
  - modeling support for making modeling easierChapter 3 in MPG
- Plan for today
  - look at the ugly side first to see the primitives
  - look at the easy side then
- When you model, go with the easy side!
  - always! really, really!

In MPG: Getting Started, Chapter 2

#### PRIMITIVE MODELING

#### Overview

#### Program problem as script

- declare variables
- post constraints (creates propagators)
- define branching

#### Solve script

- basic search strategy: first, all, best solution(s)
- Gist: interactive visual search

# PROGRAM PROBLEM AS SCRIPT

# Script: Overview

- Script is class inheriting from class Space
  - members store variables regarded as solution
- Script constructor
  - initialize variables
  - post propagators for constraints
  - define branching
- Copy constructor and copy function
  - copy a Script object during search
- Exploration takes Script object as input
  - returns object representing solution
- Main function
  - invokes search engine

```
#include <gecode/int.hh>
#include <gecode/search.hh>
using namespace Gecode;
class SendMoreMoney : public Space {
protected:
  IntVarArray 1; // Digits for the letters
public:
  // Constructor for script
  SendMoreMoney(void) ... { ... }
  // Constructor for cloning
  SendMoreMoney(SendMoreMoney& s) ... { ... }
  // Perform copying during cloning
  virtual Space* copy(void) { ... }
  // Print solution
  void print(void) { ... }
};
```

```
#include <gecode/int.hh>
#include <gecode/sear</pre>
                         array of integer variables
                              stores solution
using namespace Ged
class SendMoreMoney : public Space {
protected:
  IntVarArray 1; // Digits for the letters
public:
  // Constructor for script
  SendMoreMoney(void) ... { ... }
  // Constructor for cloning
  SendMoreMoney(SendMoreMoney& s) ... { ... }
  // Perform copying during cloning
  virtual Space* copy(void) { ... }
  // Print solution
  void print(void) { ... }
};
```

```
#include <gecode/int.hh>
#include <gecode/search.hh>
                                constructor: initialize
using namespace Gecode
                                   variables, post
                                 constraints, define
class SendMoreMoney : ph
                                     branching
protected:
                                 the letters
  IntVarArray 1; // Digits f()
public:
  // Constructor for script
  SendMoreMoney(void) ... { ... }
  // Constructor for cloning
  SendMoreMoney(SendMoreMoney& s) ... { ... }
  // Perform copying during cloning
  virtual Space* copy(void) { ... }
  // Print solution
  void print(void) { ... }
};
```

```
#include <gecode/int.hh>
#include <gecode/search.hh>
using namespace Gecode;
class SendMoreMoney : public Space {
protected:
 IntVarArray 1; // Digits for the letters
public:
                                 copy constructor and
 // Constructor for script
 SendMoreMoney(void) ... { ... }
                                    copy function
 // Constructor for cloning
 // Perform copying during cloning
 virtual Space* copy(void) { ... }
 // Print solution
 void print(void) { ... }
};
```

```
SendMoreMoney(void) : 1(*this, 8, 0, 9) {
   IntVar s(1[0]), e(1[1]), n(1[2]), d(1[3]),
        m(1[4]), o(1[5]), r(1[6]), y(1[7]);
   // Post constraints
   ...
   // Post branchings
   ...
}

8 variables
...
```

# Posting Constraints

Defined in namespace Gecode

 Check documentation for available constraints

- Take script reference as first argument
  - where is the propagator for the constraint to be posted!
  - script is a subclass of Space (computation space)

## Linear Equations and Linear Constraints

#### Equations of the form

$$c_1 \cdot x_1 + \ldots + c_n \cdot x_n = d$$

- integer constants:
- integer variables:  $x_i$
- In Gecode specified by arrays
  - integers (IntArgs)  $c_i$
  - variables (IntVarArray, IntVarArgs)  $x_i$
- Not only equations
  - IRT\_EQ, IRT\_NQ, IRT\_LE, IRT\_GR, IRT\_LQ, IRT\_GQ
  - equality, disequality, inequality (less, greater, less or equal, greater or equal)

 $c_i$  and d

```
SendMoreMoney(void) : 1(*this, 8, 0, 9) {
 // The linear equation must hold
 IntArgs c(4+4+5); IntVarArgs x(4+4+5);
 c[0]=1000; c[1]=100; c[2]=10; c[3]=1;
 x[0]=s; x[1]=e; x[2]=n; x[3]=d;
 c[4]=1000; c[5]=100; c[6]=10; c[7]=1;
 x[4]=m; x[5]=o; x[6]=r; x[7]=e;
 c[8]=-10000; c[9]=-1000; c[10]=-100; c[11]=-10; c[12]=-1;
 x[8]=m; x[9]=o; x[10]=n; x[11]=e; x[12]=y;
 linear(*this, c, x, IRT EQ, 0);
 // Branch over the letters
```

```
SendMoreMoney(void) : 1(*this, 8, 0, 9) {
    ...
    // Branch over the letters
    branch(*this, 1, INT_VAR_SIZE_MIN(), INT_VAL_MIN());
}
```

# Branching

#### Which variable to choose

```
given order INT_VAR_NONE()
```

```
smallest size INT_VAR_SIZE_MIN()
```

```
smallest minimum INT_VAR_MIN_MIN()
```

**...** 

#### How to branch: which value to choose

```
try smallest value INT_VAL_MIN()
```

```
split (lower first)
INT_VAL_SPLIT_MIN()
```

**...** 

# Script for SMM: Copying

```
// Constructor for cloning
SendMoreMoney(SendMoreMoney& s) : Space(s) {
    l.update(*this, s.l);
}
// Perform copying during cloning
virtual Space* copy(void) {
    return new SendMoreMoney(*this);
}
```

# Script for SMM: Copying

```
// Constructor for cloning
SendMoreMoney(SendMoreMoney& s) : Space(s) {
    l.update(*this, s.l);
}
// Perform copying during cloning
virtual Space* copy(void) {
    return new SendMoreMoney(*this),
}
update all
variables needed
for solution
}
```

# Script for SMM: Copying

```
// Constructor for cloning
SendMoreMoney(SendMoreMoney& s) : Space(s) {
    l.update(*this, s.l);
}
// Perform copying during cloning
virtual Space* copy(void) {
    return new SendMoreMoney(*this);
}

    create a new copy
    of the space
    during cloning
```

# Copying

- Required during exploration
  - before starting to guess: make copy
  - when guess is wrong: use copy
  - to be discussed later

- Copy constructor and copy function needed
  - copy constructor is specific to script
  - updates (copies) variables in particular

# Copy Constructor And Copy Function

Always same structure

- Important!
  - must update the variables of a script!
  - if you forget: crash, boom, bang, ...

# Script for SMM: Print Function

"
// Print solution
void print(void) {
 std::cout << l << std::endl;
}</pre>

# Summary: Script

- Variables
  - declare as members
  - initialize in constructor
  - update in copy constructor
- Posting constraints
- Create branching
- Provide copy constructor and copy function

In MPG: Getting Started

### **SOLVING SCRIPTS**

# Available Search Engines

- Returning solutions one by one for script
  - DFS depth-first search
  - BAB branch-and-bound
- Interactive, visual search
  - Gist

int main(int argc, char\* argv[]) {
 SendMoreMoney\* m = new SendMoreMoney;
 DFS<SendMoreMoney> e(m);
 delete m;
 if (SendMoreMoney\* s = e.next()) {
 s->print(); delete s;
 }
 return 0;
}

create root space for search

•••

```
int main(int argc, char* argv[]) {
   SendMoreMoney* m = new SendMoreMoney;
   DFS<SendMoreMoney> e(m);
   delete m;
   if (SendMoreMoney* s = e.next()) {
      s->print(); delete s;
   }
   return 0;
}
```

```
create search
engine (takes
clone of m)
int main(int argc, char* argv[])
SendMoreMoney* m = new fendMoreMoney;
DFS<SendMoreMoney> e(m);
delete m;
if (SendMoreMoney* s = e.next()) {
   s->print(); delete s;
}
return 0;
}
```

root space not any longer needed

•••

```
int main(int argc, ch * argv[]) {
    SendMoreMoney* m = new SendMoreMoney;
    DFS<SendMoreMoney> e(m);
    delete m;
    if (SendMoreMoney* s = e.next()) {
        s->print(); delete s;
    }
    return 0;
}
```

#### Main Method: First Solution

#### Main Method: All Solutions

int main(int argc, char\* argv[]) {
 SendMoreMoney\* m = new SendMoreMoney;
 DFS<SendMoreMoney> e(m);
 delete m;
 while (SendMoreMoney\* s = e.next()) {
 s->print(); delete s;
 }
 return 0;
}

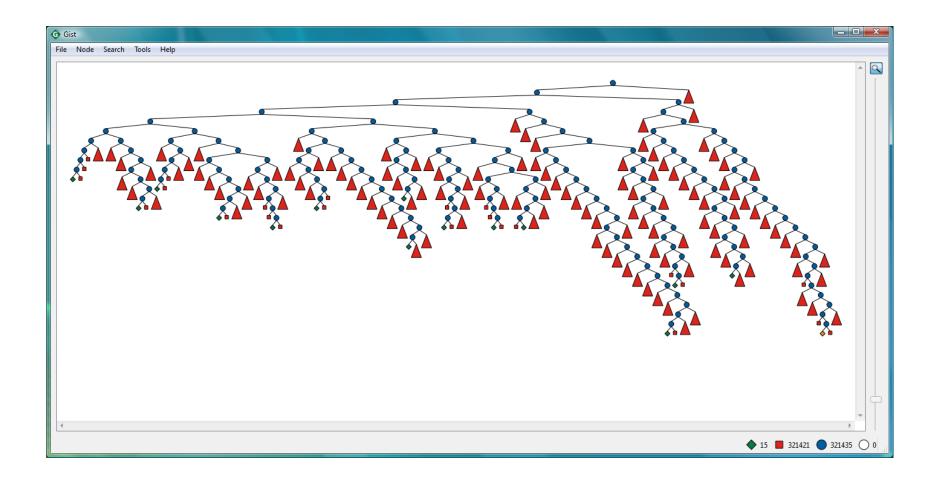
#### Gecode Gist

- A graphical tool for exploring the search tree
  - explore tree step by step
  - tree can be scaled
  - double-clicking node prints information: inspection
  - search for next solution, all solutions
  - **...**
- Best to play a little bit by yourself
  - hide and unhide failed subtrees
  - **...**

#### Main Function: Gist

```
#include <gecode/gist.hh>
int main(int argc, char* argv[]) {
   SendMoreMoney* m = new SendMoreMoney;
   Gist::dfs(m);
   delete m;
   return 0;
}
```

#### Gist Screenshot



# Best Solution Search

#### Reminder: SMM++

Find distinct digits for letters, such that

# Script for SMM++

- Similar, please try it yourself at home
- In the following, referred to by SendMostMoney

# Solving SMM++: Order

- Principle
  - for each solution found, constrain remaining search for better solution
- Implemented as additional method virtual void constrain(const Space& b) { ... }
- Argument b refers to so far best solution
  - only take values from b
  - never mix variables!
- Invoked on object to be constrained

#### Order for SMM++

```
#include <gecode/minimodel.hh>
  virtual void constrain(const Space& b) {
    const SendMostMoney& b =
      static cast<const SendMostMoney&>( b);
    IntVar e(1[1]), n(1[2]), m(1[4]), o(1[5]), y(1[7]);
    IntVar b_e(b.1[1]), b_n(b.1[2]), b_m(b.1[4]),
           b_o(b.1[5]), b_y(b.1[7]);
    int money = (10000*b m.val()+1000*b o.val()+100*b n.val()+
                 10*b e.val()+b y.val());
    rel(*this, 10000*m+1000*o+100*n+10*e+y > money);
  }
```

#### Main Method: All Solutions

int main(int argc, char\* argv[]) {
 SendMostMoney\* m = new SendMostMoney;
 BAB<SendMostMoney> e(m);
 delete m;
 while (SendMostMoney\* s = e.next()) {
 s->print(); delete s;
 }
 return 0;
}

#### Main Function: Gist

```
#include <gecode/gist.hh>
int main(int argc, char* argv[]) {
   SendMostMoney* m = new SendMostMoney;
   Gist::bab(m);
   delete m;
   return 0;
}
```

# Summary: Solving

- Result-only search engines
  - DFS, BAB
- Interactive search engine
  - Gist
- Best solution search uses constrain-method for posting constraint
- Search engine independent of script and constrainmethod

In MPG: Getting Comfortable, Chapter 3

# USING THE GECODE MODELING LAYER

# Modeling Layer and Driver

#### Modeling layer

- provides convenient base-classes for scripts
- supports arithmetic expressions
- supports cost functions
- Chapter 7 in MPG (browse as needed)

#### Driver

- parses command line options used by scripts
- most aspects for search can be controlled from commandline
- Chapter 11 in MPG (browse as needed)

## Predefined Scripts

```
#include <gecode/driver.hh>
#include <gecode/minimodel.hh>
...
class SendMoreMoney : public Script {
    ...
public:
    SendMoreMoney(const Options& opt)
        : Script(opt), ... { ... }
    virtual void print(std::ostream& os) const { ... }
};
```

- Instead of using Space, use Script
- The object opt captures command line options

#### Driver

```
int main(int argc, char* argv[]) {
   Options opt("SEND+MORE=MONEY");
   opt.parse(argc,argv);
   Script::run<SendMoreMoney,DFS,Options>(opt);
   return 0;
}
```

#### Provides

- commandline options
- execution statistics (time, solutions, ...)
- support for different search engines

## Using the Commandline

- Print first solution
  - ./smm.exe
- Print all solutions
  - ./smm.exe -solutions 0
- Use Gist instead
  - ./smm.exe -mode gist
- What else can you do
  - ./smm.exe -help
  - many pre-defined options that can come in handy

#### Arithmetic Expressions

- Function rel overloaded for arithmetic expressions
- Similar function expr returning a variable

#### Use Cost Functions!

```
class SendMostMoney : public IntMaximizeScript {
  IntVar money;
public:
  SendMostMoney(const Options& opt) ... {
    rel(*this, money == 10000*m+1000*o+100*n+10*e+y);
 virtual IntVar cost(void) const {
    return money;
```

Class IntMinimizeScript similar

#### Driver

```
int main(int argc, char* argv[]) {
   Options opt("SEND+MOST=MONEY");
   opt.parse(argc,argv);
   Script::run<SendMostMoney,BAB,Options>(opt);
   return 0;
}
```

#### Provides

- commandline options
- execution statistics (time, solutions, ...)
- support for different search engines

## Getting Started with MPG

- Check the beginning of Part M for reading advice!
- Chapter 2 (Getting started)
  - read all
- Chapter 3 (Getting comfortable)
  - read all
- Chapter 4 (Integer and Boolean variables and constraints)
  - 4.1, 4.2, 4.3: read (maybe a little later)
  - 4.4: browse which constraints are available
- Chapter 7 (Modeling convenience: MiniModel)
  - browse when needed
- Chapter 8 (Branching)
  - 8.1, 8.2: read what you need
- Chapter 9 (Search)
  - 9.3: read what you need
- Chapter 11 (Script Commandline Driver)
  - browse when needed

# Grocery

#### Grocery

Kid goes to store and buys four items

Cashier: that makes \$7.11

Kid: pays, about to leave store

Cashier: hold on, I multiplied!

let me add!

wow, sum is also \$7.11

You: prices of the four items?

#### Model

#### Variables

- for each item A, B, C, D
- take values between {0, ..., 711}
- compute with cents: allows integers

#### Constraints

- A + B + C + D = 711
- A \* B \* C \* D = 711 \* 100 \* 100 \* 100

# Script

```
class Grocery : public Script {
protected:
    IntVarArray abcd;
    const int s = 711;
    const int p = s * 100 * 100 * 100;
public:
    Grocery(...) ... { ... }
```

# Script: Variables

```
Grocery(...) : ..., abcd(*this,4,0,711) {
    ...
}
```

# Script: Sum

```
// Sum of all variables is s
linear(*this, abcd, IRT_EQ, s);
IntVar a(abcd[0]), b(abcd[1]),
        c(abcd[2]), d(abcd[3]);
```

# Script: Product

```
IntVar t1(*this,1,p);
IntVar t2(*this,1,p);
IntVar t3(*this,p,p);

mult(*this, a, b, t1);
mult(*this, c, d, t2);
mult(*this, t1, t2, t3);
```

## Branching

- Bad idea: try values one by one
- Good idea: split variables
  - for variable x
  - with  $m = (\min(x) + \max(x)) / 2$
  - branch x < m or  $x \ge m$
- Typically good for problems involving arithmetic constraints
  - exact reason needs to be explained later

# Script: Branching

#### Search Tree

- 2829 nodes for first solution
- Pretty bad...

#### Better Heuristic?

- Try branches in different order split with larger interval first
  - try: INT\_VAL\_SPLIT\_MAX()
- Search tree: 2999 nodes
  - worse in this case

# Symmetries

- Interested in values for A, B, C, D
- Model admits equivalent solutions
  - interchange values for A, B, C, D
- We can add order A, B, C, D:

$$A \le B \le C \le D$$

Called "symmetry breaking constraint"

# Script: Symmetry Breaking

```
"
rel(*this, a, IRT_LQ, b);
rel(*this, b, IRT_LQ, c);
rel(*this, c, IRT_LQ, d);
...
```

## Effect of Symmetry Breaking

- Search tree size 308 nodes
- Let us try INT\_VAL\_SPLIT\_MAX() again
  - tree size 79 nodes!
  - interaction between branching and symmetry breaking
  - other possibility: A ≥ B ≥ C ≥ D
  - we need to investigate more (later)!

# Any More Symmetries?

- Observe: 711 has prime factor 79
  - that is: 711 = 79 × 9

- Assume: A can be divided by 79
  - add:  $A = 79 \times X$

for some finite domain var X

- remove A ≤ B
- the remaining B, C, D of course can still be ordered

# Any More Symmetries?

In Gecode

```
IntVar x(*this,1,p);
IntVar sn(*this,79,79);
mult(*this, x, sn, a);
```

- Search tree 44 nodes!
  - now we are talking!

## Summary: Grocery

- Branching: consider also
  - how to partition domain
  - in which order to try alternatives
- Symmetry breaking
  - can reduce search space
  - might interact with branching
  - typical: order variables in solutions
- Try to really understand problem!

## Another Observation

Multiplication decomposed as

$$A \cdot B = T_1$$
  $C \cdot D = T_2$   $T_1 \cdot T_2 = P$ 

What if

$$A \cdot B = T_1$$
  $T_1 \cdot C = T_2$   $T_2 \cdot D = P$ 

- propagation changes: 355 nodes
- propagation is not compositional!
- another point to investigate