Rates of convergence in Bayesian meta-learning

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Riou, C., Alquier, P. and Chérief-Abdellatif, B.-E. (2023). Bayes meets Bernstein at the Meta Level: an Analysis of Fast Rates in Meta-Learning with PAC-Bayes. Preprint arXiv:2302.11709. Introduction : Bayesian learning and meta-learning Overview of our results More detailed view of our results

Introduction : Bayesian learning and meta-learning

Overview of our results

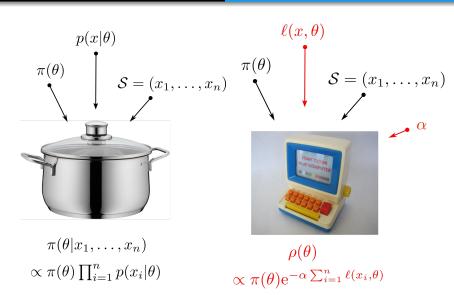
More detailed view of our results

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1 Introduction: Bayesian learning and meta-learning

Overview of our results

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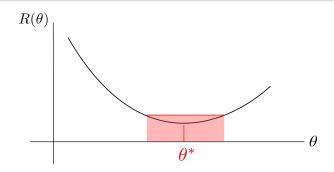
To keep the results as simple as possible :

- $S = (X_1, \dots, X_n)$ i.i.d. from P,
- $\ell(x, \theta)$ bounded by 1.
- Generalization risk : $R(\theta) = \mathbb{E}_{X \sim P}[\ell(X, \theta)].$
- Objective : $\theta^* = \arg\min_{\theta \in \Theta} R(\theta)$.
- Risk of the "Bayes" procedure $\rho : \mathbb{E}_{\theta \sim \rho}[R(\theta)]$.

Theorem (stated informally)

$$\mathbb{E}_{\mathcal{S}}\Big\{\mathbb{E}_{ heta\sim
ho}[R(heta)]\Big\} \leq R(heta^*) + c\sqrt{rac{d\log(n)}{n}}$$

where $d = d(P, \pi)$ defined in the next slide, for α well chosen.



$$N(\theta^*, s) := \{ \theta \in \Theta : R(\theta) - R(\theta^*) \le s \}.$$

 $d=d(P,\pi)$ is the smallest number such that, for any s small enough :

$$\pi(N(\theta^*,s)) \geq s^d$$
.

How do we prove the theorem?

$$\begin{split} \rho(\theta) &\propto \pi(\theta) \mathrm{e}^{-\alpha \sum_{i=1}^n \ell(x_i, \theta)} \\ &= \underset{p \in \mathcal{P}rob(\Theta)}{\mathsf{min}} \left\{ \mathbb{E}_{\theta \sim p} \left[\frac{1}{n} \sum_{i=1}^n \ell(x_i, \theta) \right] + \frac{\mathit{KL}(p, \pi)}{\alpha n} \right\}. \end{split}$$

PAC-Bayes / Information bounds

$$\mathbb{E}_{\mathcal{S}}\Big\{\mathbb{E}_{\theta \sim \rho}[R(\theta)]\Big\} \leq \inf_{\rho} \left\{\mathbb{E}_{\theta \sim \rho}[R(\theta)] + \alpha + \frac{\mathsf{KL}(\rho, \pi)}{\alpha n}\right\}.$$

In particular, for p as the restriction of π to $N(\theta^*, s)$,

$$\mathbb{E}_{\mathcal{S}}\Big\{\mathbb{E}_{\theta \sim \rho}[R(\theta)]\Big\} \leq \inf_{s>0} \left\{R(\theta^*) + s + \alpha + \frac{d \log \frac{1}{s}}{\alpha n}\right\}.$$

• Old result : in a "noiseless setting", when there is a θ such that $\ell(x,\theta)=0$ almost surely for $x\sim P$,

$$\mathbb{E}_{\mathcal{S}}\Big\{\mathbb{E}_{\theta \sim \rho}[R(\theta)]\Big\} \leq \underbrace{R(\theta^*)}_{=0} + c\frac{d\log(n)}{n}.$$

- Similar fast rates obtained in classification under Mammen and Tsybakov margin assumption (1999).
- Also with Lipschitz and strongly convex losses $\ell(x,\cdot)$ by Bartlett and Mendelson (2006).

All these assumptions turned out to be a special case of :

Bernstein condition

$$\mathbb{E}_{x \sim P} \left\{ \left[\ell(x, \theta) - \ell(x, \theta^*) \right]^2 \right\} \le C \left[R(\theta) - R(\theta^*) \right].$$

What about variational Bayes?

Let W be a subset of $Prob(\Theta)$, and put :

$$\rho^{\mathcal{W}}(\theta) = \operatorname*{arg\,min}_{p \in \operatorname{\textit{Prob}}(\mathbf{G})\mathcal{W}} \left\{ \mathbb{E}_{\theta \sim p} \left[\frac{1}{n} \sum_{i=1}^n \ell(\mathbf{x}_i, \theta) \right] + \frac{\mathit{KL}(p, \pi)}{\alpha n} \right\}.$$



P. Alquier, J. Ridgway , N. Chopin (2016). On the Properties of Variational Approximations of Gibbs Posteriors. JMLR.

provides minimal assumptions on ${\mathcal W}$ ensuring

$$\mathbb{E}_{\mathcal{S}}\Big\{\mathbb{E}_{\theta \sim \rho^{\mathcal{W}}}[R(\theta)]\Big\} \leq R(\theta^*) + c\left(\frac{d(P,\pi)\log(n)}{n}\right)^{\beta}$$

where $\beta=1$ under Bernstein condition, $\beta=1/2$ otherwise.

Recap

$$\rho(\theta) \propto \pi(\theta) e^{-\alpha \sum_{i=1}^{n} \ell(x_i, \theta)}$$
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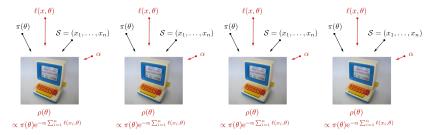
We have :

$$\mathbb{E}_{\mathcal{S}}\Big\{\mathbb{E}_{ heta\sim
ho}[R(heta)]\Big\} \leq R(heta^*) + c\left(rac{d\log(n)}{n}
ight)^eta$$

where $\beta = 1$ under Bernstein condition, $\beta = 1/2$ otherwise.

- The generalization error is driven by $d = d(P, \pi)$ that depends on π .
- Tempting to learn a better π , but π is not allowed to depend on the data...

Idea of Bayesian meta-learning :



- We solve many related tasks (say T) using Bayesian learning.
- By related, we mean that the same prior could be used in all tasks.
- ullet Based on past tasks, can we define a π that would work better for future tasks?

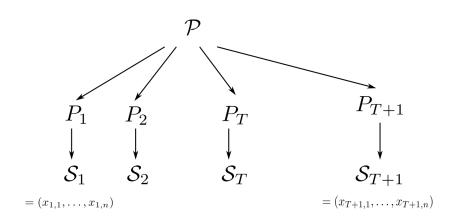
Notations:

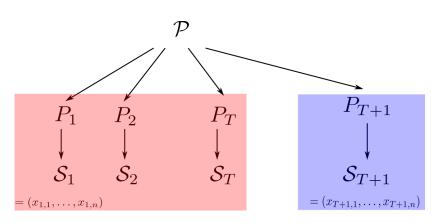
- Tasks : t = 1, ..., T.
- P_1, \ldots, P_T are i.i.d from \mathcal{P} .
- Task $t: \mathcal{S}_t = (x_{t,1}, \dots, x_{t,n})$ i.i.d from P_t .
- Generalization error in task $t: R_t(\theta) = \mathbb{E}_{x \sim P_t}[\ell(x, \theta)]$.
- Best error in task $t : R_t(\theta_t^*) = \min_{\theta} R_t(\theta)$.
- $\rho_t(\pi, \alpha)(\theta) \propto \pi(\theta) \exp[-\alpha \sum_{i=1}^n \ell(\theta, x_{t,i})].$

Objective

- Learn $\hat{\pi} = \hat{\pi}(\mathcal{S}_1, \dots, \mathcal{S}_T)$.
- For a new task $P_{T+1} \sim \mathcal{P}$, $S_{T+1} = (x_{T+1,1}, \dots, x_{T+1,n})$ i.i.d. from P_{T+1} , we want :

$$\mathbb{E}_{\theta \sim \rho_{T+1}(\hat{\pi}, \alpha)} \left[R_{T+1}(\theta) \right] \leq \mathbb{E}_{\theta \sim \rho_{T+1}(\pi, \alpha)} \left[R_{T+1}(\theta) \right].$$





- Past tasks, used to learn a better prior. Expectation with respect to $P_1, \ldots, P_T, S_1, \ldots, S_T$ denoted by \mathbb{E}_{data} .
- New task. Expectation with respect to P_{T+1} and S_{T+1} will be denoted by \mathbb{E}_{new} .

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Ultimate (non-achievable) performance :

$$\mathcal{E}^* = \mathbb{E}_{\text{new}}[R_{T+1}(\theta_{T+1}^*)] = \mathbb{E}_{P_{T+1} \sim \mathcal{P}}[R_{T+1}(\theta_{T+1}^*)].$$

With a fixed prior:

$$\mathcal{E}(\pi) = \mathbb{E}_{\text{new}} \left\{ \mathbb{E}_{\theta \sim \rho_{T+1}(\pi,\alpha)}[R_{T+1}(\theta)] \right\}$$

$$\leq \mathcal{E}^* + c \, \mathbb{E}_{P_{T+1} \sim \mathcal{P}} \left[\left(\frac{d(P_{T+1},\pi) \log(n)}{n} \right)^{\beta} \right].$$

To give an overview of our results, let us consider first an easy situation : we want to find the best of K priors, say

$$\pi_1,\ldots,\pi_K$$

Recall:

$$\rho_t(\pi,\alpha) = \arg\min_{p} \left\{ \underbrace{\mathbb{E}_{\theta \sim p} \left[\frac{1}{n} \sum_{i=1}^{n} \ell(x_{t,i},\theta) \right] + \frac{\mathit{KL}(p,\pi)}{\alpha n}}_{\hat{\mathcal{R}}_t(p,\pi)} \right\}.$$

In this case, our procedure boils down to:

$$\hat{\pi} = \operatorname*{arg\,min}_{\pi \in \{\pi_1, \dots, \pi_K\}} \left\{ \frac{1}{T} \sum_{t=1}^T \hat{\mathcal{R}}_t \Big[\rho_t(\pi, \alpha), \pi \Big] \right\}.$$

Theorem

$$\begin{split} & \mathbb{E}_{\text{data}}[\mathcal{E}(\hat{\pi})] \\ & \leq \min_{k=1,\dots,K} \mathcal{E}(\pi_k) + \frac{\log K}{T} \\ & \leq \mathcal{E}^* + c \min_{k=1,\dots,K} \mathbb{E}_{P_{T+1} \sim \mathcal{P}} \left[\left(\frac{d(P_{T+1}, \pi_k) \log(n)}{n} \right)^{\beta} \right] + \frac{\log K}{T}. \end{split}$$

Important observations:

- gain expected only if $T \gg n$.
- the rate for learning the prior is in 1/T regardless or the rate within tasks ($\beta = 1$ or $\beta = 1/2$).

- More generally, we can learn the best prior in an infinite set Q (for example, all Gaussian priors, etc).
- The definition of $\hat{\pi}$ gets a little more convoluted.
- We will recover similar results

$$\mathbb{E}_{\text{data}}[\mathcal{E}(\hat{\pi})] \leq \min_{\pi \in \mathcal{Q}} \mathcal{E}(\pi) + \frac{\mathcal{C}(\mathcal{Q})}{T}$$

where C(Q) is a complexity measure of Q.

Example 1 : Gaussian priors.

- $\theta \in \mathbb{R}^p$.
- $Q = \{ \mathcal{N}(\mu, \Sigma), \mu \in \mathbb{R}^p, \Sigma \in \mathcal{S}_+^p \}.$
- fix some m and put $V = \mathbb{E}_{\text{new}} \left[\|\theta_{T+1}^* m\|^2 \right]$.

Very approximatevely,

$$\mathbb{E}_{\mathrm{data}}[\mathcal{E}(\hat{\pi})] \leq \mathcal{E}^* + rac{p}{T} + \left\{egin{array}{ll} rac{V + p \log n}{n} & ext{if } V > rac{n}{T} \ 0 & ext{otherwise} \end{array}
ight..$$

Example 2: mixture of Gaussian priors.

- $\theta \in \mathbb{R}^p$.
- $Q = \left\{ \sum_{k=1}^{K} p_k \mathcal{N}(\mu_k, \Sigma_k) \right\}.$
- fix m_1, \ldots, m_K and put $V = \mathbb{E}_{\text{new}} \left[\min_k \|\theta_{T+1}^* m_k\|^2 \right]$.

$$\mathbb{E}_{\text{data}}[\mathcal{E}(\hat{\pi})] \leq \mathcal{E}^* + \frac{pK}{T} + \frac{\log K}{n} + \begin{cases} \frac{V + p \log n}{n} & \text{if } V > \frac{n}{T} \\ 0 & \text{otherwise} \end{cases}.$$

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The general procedure $\hat{\pi} = \hat{\pi}(S_1, \dots, S_T)$ is a little more convoluted, it is actually a Bayesian procedure :

- fix a prior Π on the set of priors $\mathcal{Q}: \Pi \in \mathcal{P}rob(\mathcal{Q})$,
- define :

$$\hat{\Lambda} = \underset{\Lambda \in \mathcal{P} \textit{rob}(\mathcal{Q})}{\arg \min} \left\{ \mathbb{E}_{\pi \sim \Lambda} \left[\frac{1}{T} \sum_{t=1}^{T} \hat{\mathcal{R}}_t \Big(\rho_t(\pi, \alpha), \pi \Big) \right] + \frac{\textit{KL}(\Lambda, \Pi)}{\gamma T} \right\},$$

• draw $\hat{\pi} \sim \hat{\Lambda}$.

Define

$$\pi^* = \arg\min_{\pi} \mathbb{E}_{\text{new}} \left[\hat{\mathcal{R}}_{T+1} \Big(\rho_{T+1}(\pi, \alpha), \pi \Big) \right].$$

Lemma – Bernstein condition at the meta-level

For any $\pi \in \mathcal{Q}$,

$$\mathbb{E}_{\text{new}}\left[\left(\hat{\mathcal{R}}_{T+1}\left(\rho_{T+1}(\pi,\alpha),\pi\right)-\hat{\mathcal{R}}_{T+1}\left(\rho_{T+1}(\pi^*,\alpha),\pi^*\right)\right)^{2}\right]$$

$$\leq C\,\mathbb{E}_{\text{new}}\left[\hat{\mathcal{R}}_{T+1}\left(\rho_{T+1}(\pi,\alpha),\pi\right)-\hat{\mathcal{R}}_{T+1}\left(\rho_{T+1}(\pi^*,\alpha),\pi^*\right)\right].$$

Theorem

$$\begin{split} \mathbb{E}_{\text{data}} \Big\{ \mathbb{E}_{\hat{\pi} \sim \hat{\Lambda}} [\mathcal{E}(\hat{\pi})] \Big\} &\leq \mathcal{E}^* \\ &+ \min_{\Lambda \in \mathcal{P} rob(\mathcal{Q})} \mathbb{E}_{\pi \sim \Lambda} \Big\{ \mathbb{E}_{P_{T+1} \sim \mathcal{P}} \left[\left(\frac{d(P_{T+1}, \pi) \log(n)}{n} \right)^{\beta} \right] \\ &+ \frac{\mathcal{K}(\Lambda, \Pi)}{\gamma T} \Big\}. \end{split}$$

The aforementioned examples are obtained by specification of Π , and taking an explicit Λ above.

Remark:

$$\hat{\Lambda} = \underset{\Lambda \in \mathcal{P} \textit{rob}(\mathcal{Q})}{\arg \min} \left\{ \mathbb{E}_{\pi \sim \Lambda} \left[\frac{1}{T} \sum_{t=1}^{T} \hat{\mathcal{R}}_t \Big(\rho_t(\pi, \alpha), \pi \Big) \right] + \frac{\textit{KL}(\Lambda, \Pi)}{\gamma \, T} \right\}.$$

What happens if we minimize over a smaller set $V \subset Prob(Q)$?

$$\hat{\Lambda}_{\mathcal{V}} = \operatorname*{arg\,min}_{\Lambda \in \mathcal{V}} \left\{ \mathbb{E}_{\pi \sim \Lambda} \left[\frac{1}{T} \sum_{t=1}^{T} \hat{\mathcal{R}}_{t} \Big(\rho_{t}(\pi, \alpha), \pi \Big) \right] + \frac{\mathit{KL}(\Lambda, \Pi)}{\gamma \, \mathit{T}} \right\}.$$

Note : can be seen as a variational Bayes version of $\hat{\Lambda}$.

Theorem

$$\begin{split} \mathbb{E}_{\text{data}} \Big\{ \mathbb{E}_{\hat{\pi} \sim \hat{\Lambda}_{\mathcal{V}}} [\mathcal{E}(\hat{\pi})] \Big\} &\leq \mathcal{E}^* \\ &+ \min_{\Lambda \in \mathcal{V}} \mathbb{E}_{\pi \sim \Lambda} \Big\{ \mathbb{E}_{P_{T+1} \sim \mathcal{P}} \left[\left(\frac{d(P_{T+1}, \pi) \log(n)}{n} \right)^{\beta} \right] \\ &+ \frac{\mathcal{K}(\Lambda, \Pi)}{\gamma T} \Big\}. \end{split}$$

For example, in the case $Q = \{\pi_1, \dots, \pi_K\}$, taking \mathcal{V} as the set of Dirac masses allows to define $\hat{\pi}$ by a minimization rather than by randomisation.

Note however that our result require to use "exact" Bayes within tasks.

Lemma – Bernstein condition at the meta-level

For any $\pi \in \mathcal{Q}$,

$$\mathbb{E}_{\text{new}} \left[\left(\hat{\mathcal{R}}_{T+1} \Big(\rho_{T+1}(\pi, \alpha), \pi \Big) - \hat{\mathcal{R}}_{T+1} \Big(\rho_{T+1}(\pi^*, \alpha), \pi^* \Big) \right)^2 \right]$$

$$\leq C \, \mathbb{E}_{\text{new}} \left[\hat{\mathcal{R}}_{T+1} \Big(\rho_{T+1}(\pi, \alpha), \pi \Big) - \hat{\mathcal{R}}_{T+1} \Big(\rho_{T+1}(\pi^*, \alpha), \pi^* \Big) \right].$$

We don't know how to extend this lemma if we replace $\rho_{T+1}(\pi, \alpha)$ by a variational approximation.

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Some important open questions:

- extending the Lemma to allow variational approximations.
- lower bounds.