# Parametric estimation via MMD optimization: robustness to outliers and to dependence

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## RIKEN AIP: ABI team



Approximate Bayesian Inference team (ABI), lead by Emtiyaz Khan



#### Please visit the team website

https://emtiyaz.github.io/

## Co-authors



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ENSAE Paris

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#### Statistical inference:

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Letting  $p_{\theta}$  denote the density of  $P_{\theta}$ , then

$$\hat{ heta}_n^{MLE} = rgmax_{ heta \in \Theta} L( heta)$$
, where  $L( heta) = \prod_{i=1}^n p_{ heta}(X_i)$ .

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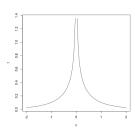
Example :  $P_{(m,\sigma)} = \mathcal{N}(m,\sigma^2)$  then

$$\hat{m} = \frac{1}{n} \sum_{i=1}^{n} X_i \text{ and } \hat{\sigma}^2 = \frac{1}{n} \sum_{i=1}^{n} (X_i - \hat{m})^2.$$

# MLE not unique / not consistent

#### Example:

$$p_{\theta}(x) = \frac{\exp(-|x-\theta|)}{2\sqrt{\pi|x-\theta|}},$$



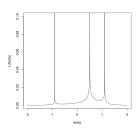
# MLE not unique / not consistent

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$$L(\theta) = \frac{\exp\left(-\sum_{i=1}^{n} |X_i - \theta|\right)}{(2\sqrt{\pi})^n \prod_{i=1}^{n} \sqrt{|X_i - \theta|}}.$$





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Huber proposed the contamination model : with probability  $\varepsilon$ ,  $X_i$  is not drawn from  $P_{\theta_0}$  but from Q that can be anything :

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In the case of the following contamination, the MLE is extremely far from the truth :

$$P_0 = (1 - \varepsilon).Unif[0, 1] + \varepsilon.\mathcal{N}(10^{10}, 1)...$$

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The MLE does not satisfy these requirements.

## Some examples

Yatracos' skeleton estimate  $\hat{\theta}_n^Y$ :

$$\mathbb{E}\left[d_{TV}(P_{\hat{\theta}_n^Y}, P_0)\right] \leq 3d_{TV}(P_0, P_{\theta_0}) + C.\sqrt{\frac{\dim(\Theta)}{n}}$$

where

$$d_{TV}(P,Q) = \sup_{E} |P(E) - Q(E)|.$$



Yatracos, Y. G. (1985). Rates of convergence of minimum distance estimators and Kolmogorov's entropy. *Annals of Statistics*.

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#### More recent work with the Hellinger distance :



Baraud, Y., Birgé, L., & Sart, M. (2017). A new method for estimation and model selection :  $\rho$ -estimation. *Inventiones mathematicae*.

Estimation via MMD optimization Robustness to outliers Robustness to dependence

## But...

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Additional requirement : an estimator must be computable!!!

## Overview of the talk

- Estimation via MMD optimization
  - Definition of the estimator
  - Basic properties
  - References and further works
- 2 Robustness to outliers
  - Application to Huber contamination model
  - Example : estimation of the mean of a Gaussian
  - Numerical experiments
- Robustness to dependence
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## Reminder: kernels

Let  $\mathcal{H}$  be a Hilbert space and any continuous function  $\Phi: \mathcal{X} \to \mathcal{H}$ . The function

$$K(x,y) = \langle \Phi(x), \Phi(y) \rangle_{\mathcal{H}}$$

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is called a kernel. Conversely:

#### Mercer's theorem

Let K(x, y) be a continuous function such that for any  $(x_1, \ldots, x_n) \in \mathcal{X}^n$  and  $(c_1, \ldots, c_n) \neq (0, \ldots, 0) \in \mathbb{R}^n$ ,

$$\sum_{i=1}^{n} \sum_{j=1}^{n} c_i c_j K(x_i, x_j) > 0,$$

then there is  $\mathcal{H}$  and  $\Phi$  such that  $K(x,y) = \langle \Phi(x), \Phi(y) \rangle_{\mathcal{H}}$ .

Assume that the kernel is bounded :  $0 \le K(x, y) \le 1$ .

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Consider, for any probability distribution P on  $\mathcal{X}$ ,

$$\mu_{K}(P) = \mathbb{E}_{X \sim P} \left[ \Phi(x) \right].$$

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#### $\mathsf{Theorem}$

$$K(x,y) = \exp(-\frac{\|x-y\|^2}{\gamma^2})$$
 and  $\exp(-\frac{\|x-y\|}{\gamma})$  are char. kernels.

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#### Definition: the MMD distance

$$\mathbb{D}_K(P,Q) = \|\mu_K(P) - \mu_K(Q)\|_{\mathcal{U}}.$$

## MMD-based estimator

#### Reminder of the context:

 $lackbox{1}{} X_1, \ldots, X_n$  be i.i.d in  $\mathcal{X}$  from a probability distribution  $P_0$ ,

② model  $(P_{\theta}, \theta \in \Theta)$ .

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- **2** model  $(P_{\theta}, \theta \in \Theta)$ .

#### Definition - MMD based estimator

$$\hat{\theta}_n^{MMD} = \operatorname*{arg\,min}_{\theta \in \Theta} \mathbb{D}_K \left( P_{\theta}, \hat{P}_n \right) \ \ \text{where} \ \ \hat{P}_n = rac{1}{n} \sum_{i=1}^n \delta_{X_i}.$$

## A preliminary lemma

#### Lemma

For any  $P_0$ , when  $X_1, \ldots, X_n$  are i.i.d from  $P_0$ ,

$$\mathbb{E}\left[\mathbb{D}_{K}\left(\hat{P}_{n},P^{0}\right)\right]\leq\frac{1}{\sqrt{n}}.$$

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$$\mathbb{E}\left[\mathbb{D}_{K}\left(\hat{P}_{n},P^{0}\right)\right]\leq\frac{1}{\sqrt{n}}.$$

$$\left\{ \mathbb{E} \left[ \mathbb{D}_{K} \left( \hat{P}_{n}, P^{0} \right) \right] \right\}^{2} \leq \mathbb{E} \left[ \mathbb{D}_{K}^{2} \left( \hat{P}_{n}, P^{0} \right) \right] \\
= \mathbb{E} \left[ \left\| (1/n) \sum_{i} (\mu(\delta_{X_{i}}) - \mu(P_{0})) \right\|_{\mathcal{H}}^{2} \right] \\
= (1/n) \mathbb{E} \left[ \left\| \mu(\delta_{X_{1}}) - \mu(P_{0}) \right\|_{\mathcal{H}}^{2} \right] \\
\leq 1/n.$$

### A bound in expectation

$$\forall \theta, \, \mathbb{D}_{K}\left(P_{\hat{\theta}_{n}^{MMD}}, P^{0}\right) \leq \mathbb{D}_{K}\left(P_{\hat{\theta}_{n}^{MMD}}, \hat{P}_{n}\right) + \mathbb{D}_{K}\left(\hat{P}_{n}, P^{0}\right)$$

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#### Theorem

For any  $P_0$ , when  $X_1, \ldots, X_n$  are i.i.d from  $P_0$ ,

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## A bound in probability

We can replace the control on the expectation of  $\mathbb{D}_K\left(\hat{P}_n,P^0\right)$  by a bound that holds with large probability, thanks to McDiarmid's inequality.

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#### $\mathsf{Theorem}$

For any  $P_0$ , when  $X_1, \ldots, X_n$  are i.i.d from  $P_0$ , with probability at least  $1 - \delta$ ,

$$\mathbb{D}_{\mathcal{K}}\left(P_{\hat{\theta}_n}, P^0\right) \leq \inf_{\theta \in \Theta} \mathbb{D}_{\mathcal{K}}\left(P_{\theta}, P^0\right) + \frac{2 + 2\sqrt{2\log\left(\frac{1}{\delta}\right)}}{\sqrt{n}}.$$

# How to compute $\hat{\theta}_n^{MMD}$ ?

We actually have

$$\begin{split} \mathbb{D}_{K}^{2}(P_{\theta},\hat{P}_{n}) &= \mathbb{E}_{X,X'\sim P_{\theta}}[K(X,X')] - \frac{2}{n}\sum_{i=1}^{n}\mathbb{E}_{X\sim P_{\theta}}[K(X_{i},X)] \\ &+ \frac{1}{n^{2}}\sum_{1\leq i,j\leq n}K(X_{i},X_{j}) \end{split}$$

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 and so

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abla_{ extit{K}} \mathbb{D}_{K}^{2}(P_{ heta}, \hat{P}_{n}) \ &= 2\mathbb{E}_{X,X'\sim P_{ heta}} \left\{ \left[ K(X,X') - rac{1}{n} \sum_{i=1}^{n} K(X_{i},X) 
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that can be approximated by sampling from  $P_{\theta}$ .



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define the estimator and used it to train GANs.



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provided the first theoretical study: asymptotic distribution.

#### Estimation via MMD optimization Robustness to outliers Robustness to dependence

Definition of the estimator Basic properties References and further works



Chérief-Abdellatif, B.-E. and Alquier, P. (2019). Finite Sample Properties of Parametric MMD Estimation: Robustness to Misspecification and Dependence. *Preprint arxiv*:1912.05737.



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application to the estimation of copulas.

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#### Reminder

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$$\mathbb{D}_{\kappa}(P_{\theta_0}, P_0) = \|P_{\theta_0} - [(1 - \varepsilon)P_{\theta_0} + \varepsilon Q]\|_{\mathcal{H}}$$

$$\leq \varepsilon \|P_{\theta_0}\|_{\mathcal{H}} + \varepsilon \|Q\|_{\mathcal{H}}$$

$$= 2\varepsilon.$$

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Huber contamination model :  $P_0 = (1 - \varepsilon)P_{\theta_0} + \varepsilon Q$ .

$$\mathbb{D}_{K}(P_{\theta_{0}}, P_{0}) \leq 2\varepsilon.$$

#### Corollary

When  $X_1, \ldots, X_n$  are i.i.d from  $(1 - \varepsilon)P_{\theta_0} + \varepsilon Q$ ,

$$\mathbb{E}\left[\mathbb{D}_{K}\left(P_{\hat{\theta}_{n}^{MMD}},P_{\theta_{0}}\right)\right]\leq4\varepsilon+\frac{2}{\sqrt{n}}.$$

Example: the model is given by  $p_{\theta} = \mathcal{N}(\theta, \sigma^2 I)$  for  $\theta \in \mathbb{R}^d$ .

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Using a Gaussian kernel  $K(x,y) = \exp(-\|x-y^2\|/\gamma^2)$ , from the previous theorem and from the equality

$$\mathbb{D}_{K}^{2}\left(P_{\theta}, P_{\theta'}\right) = 2\left(\frac{\gamma^{2}}{4\sigma^{2} + \gamma^{2}}\right)^{\frac{d}{2}}\left[1 - \exp\left(-\frac{\|\theta - \theta'\|^{2}}{4\sigma^{2} + \gamma^{2}}\right)\right]$$

we obtain

$$\begin{split} \mathbb{E}\left[\|\hat{\theta}_{n}^{MMD} - \theta_{0}\|^{2}\right] \\ &\leq -(4\sigma^{2} + \gamma^{2})\log\left[1 - 4\left(\frac{1}{n} + \varepsilon^{2}\right)\left(\frac{4\sigma^{2} + \gamma^{2}}{\gamma^{2}}\right)^{\frac{d}{2}}\right]. \end{split}$$

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$$\begin{split} \mathbb{E}\left[\|\hat{\theta}_n^{MMD} - \theta_0\|^2\right] \ \ \text{take} \ \gamma &= 2d\sigma^2 \\ &\leq -(4\sigma^2 + \gamma^2)\log\left[1 - 4\left(\frac{1}{n} + \varepsilon^2\right)\left(\frac{4\sigma^2 + \gamma^2}{\gamma^2}\right)^{\frac{d}{2}}\right]. \end{split}$$

Example: the model is given by  $p_{\theta} = \mathcal{N}(\theta, \sigma^2 I)$  for  $\theta \in \mathbb{R}^d$ .

Using a Gaussian kernel  $K(x,y) = \exp(-\|x-y^2\|/\gamma^2)$ , from the previous theorem and from the equality

$$\mathbb{D}_{K}^{2}\left(P_{\theta}, P_{\theta'}\right) = 2\left(\frac{\gamma^{2}}{4\sigma^{2} + \gamma^{2}}\right)^{\frac{d}{2}}\left[1 - \exp\left(-\frac{\|\theta - \theta'\|^{2}}{4\sigma^{2} + \gamma^{2}}\right)\right]$$

we obtain

$$\mathbb{E}\left[\|\hat{ heta}_n^{MMD} - heta_0\|^2
ight] \lesssim d\sigma^2\left(rac{1}{n} + arepsilon^2
ight).$$

### Example: Gaussian mean estimation, simulations

Model :  $\mathcal{N}(\theta, 1)$ , and  $X_1, \ldots, X_n$  i.i.d  $\mathcal{N}(\theta_0, 1)$ , n = 100 and we repeat the experiment 200 times.

	$\hat{\theta}_n^{MLE}$	$\hat{\theta}_n^{MMD}$
mean absolute error	0.0722	0.0838

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Now,  $\varepsilon = 1\%$  are replaced by 1,000.

mean absolute error 10.018 0.0903

- Estimation via MMD optimization
  - Definition of the estimator
  - Basic properties
  - References and further works
- 2 Robustness to outliers
  - Application to Huber contamination model
  - Example : estimation of the mean of a Gaussian
  - Numerical experiments
- Robustness to dependence
  - Extension to non-independent observations
  - A (new?) dependence coefficient
  - Example : auto-regressive observations

### And now, non-independent observations

#### Lemma

When  $X_1, \ldots, X_n$  are identically distributed from  $P_0$ ,

$$\mathbb{E}\left[\mathbb{D}_{K}\left(\hat{P}_{n},P^{0}\right)\right]\leq ?$$

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$$\mathbb{E}\left[\mathbb{D}_{K}^{2}\left(\hat{P}_{n}, P^{0}\right)\right]$$

$$= \mathbb{E}\left[\left\|\left(1/n\right)\sum_{1\leq i\leq n}\left(\mu(\delta_{X_{i}}) - \mu(P_{0})\right)\right\|_{\mathcal{H}}^{2}\right]$$

$$= \frac{1}{n} + \frac{2}{n^{2}}\sum_{1\leq i\leq n}\mathbb{E}\left\langle\mu(\delta_{X_{i}}) - \mu(P_{0}), \mu(\delta_{X_{j}}) - \mu(P_{0})\right\rangle_{\mathcal{H}}$$

#### Definition

When  $(X_1, \ldots, X_n, \ldots)$  is a stationary process with marginal distribution  $P_0$ , we put :

$$\varrho_h = \left| \mathbb{E} \left\langle \mu(\delta_{X_{t+h}}) - \mu(P_0), \mu(\delta_{X_t}) - \mu(P_0) \right\rangle_{\mathcal{H}} \right|.$$

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#### Lemma - dependent case

When  $X_1, \ldots, X_n$  are identically distributed from  $P_0$ ,

$$\mathbb{E}\left[\mathbb{D}_{K}\left(\hat{P}_{n}, P^{0}\right)\right] \leq \frac{1}{n}\left[1 + \sum_{h=1}^{n} \varrho_{h}\right]$$

#### Theorem - dependent case

When  $(X_1, \ldots, X_n, \ldots)$  is a stationary process with marginal distribution  $P_0$ 

$$\mathbb{E}\left[\mathbb{D}_{K}\left(P_{\hat{\theta}_{n}^{MMD}}, P_{0}\right)\right] \leq \inf_{\theta \in \Theta} \mathbb{D}_{K}(P_{\theta}, P_{0}) + \frac{2 + 2\sum_{h=1}^{n} \varrho_{h}}{\sqrt{n}}.$$

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**1** assume that  $\sum_{h=1}^{\infty} \varrho_h = \Sigma < +\infty$  then

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we also have a bound in probability, based on Rio's version of Hoeffding's inequality; it requires more assumptions.

### An example : auto-regressive processes

#### Proposition

Assume that  $X_t$  takes values in  $\mathbb{R}^d$  and that  $K(x,y) = F(\|x-y\|)$  where F is an L-Lipschitz function. Assume that

$$X_{t+1} = AX_t + \varepsilon_{t+1}$$

where the  $(\varepsilon_t)$  are i.i.d with  $\mathbb{E}\|\varepsilon_0\| < \infty$ , and A is a matrix with  $\|A\| = \sup_{\|x\|=1} \|Ax\| < 1$ .

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$$\varrho_t \leq \|A\|^t \frac{2L\mathbb{E}\|\varepsilon_0\|}{1-\|A\|} \text{ and } \Sigma = \sum_{t=1}^\infty \varrho_t = \frac{2\|A\|L\mathbb{E}\|\varepsilon_0\|}{(1-\|A\|)^2}.$$

Example : consider  $X_0 \sim \mathcal{U}([0,1])$ ,  $\eta_t$  i.i.d  $\mathcal{B}e(1/2)$  and

$$X_{t+1}=\frac{X_t+\eta_{t+1}}{2}.$$

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Note however that this process is known to be non-mixing.

More generally, we prove the following result:

#### Proposition

Under some (non-restrictive) assumption on the kernel K,

$$\rho_t < c_K . \beta_t$$
 (the  $\beta$ -mixing coef.)

Estimation via MMD optimization Robustness to outliers Robustness to dependence Extension to non-independent observations A (new?) dependence coefficient Example: auto-regressive observations

Thank you!