

# Recursive Methods

## Lecture 2: Analyzing the Bellman Equation

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## Fixed point formulation

We have shown that (under some transversality conditions) the original (SP) objective has a recursive formulation.

Why is this progress?

- Breaks down original problem into series of 2-period problems whose optimality conditions are intuitive and economically meaningful.
- Fixed point analysis allows us to prove existence, uniqueness and to establish properties of optimal policy.
- Recursive problem is "easy" to solve with numerical methods.



# Fixed point formulation

Think of the LHS of

$$(FE) : V(x) = \max_{x' \in \Gamma(x)} \{F(x, x') + \beta V(x')\}.$$

as a **functional**  $T : \mathcal{C}(X) \rightarrow \mathcal{C}(X)$  where  $\mathcal{C}(X)$  is the space of **bounded** continuous function  $f : X \rightarrow \mathbb{R}$ .

Then (FE) is equivalent to

 
$$Tv(x) = \max_{x' \in \Gamma(x)} \{F(x, x') + \beta v(x')\}.$$
 

Our problem therefore boils down to finding a **fixed-point** of  $T$ .

## Example

**Exercise 2.1:** Consider the estate planning problem

$$\max_{\{c_t\}_{t=0}^{\infty}} \sum_{t=0}^T \beta^t U(c_t)$$

s.t.  $a_{t+1} = (1 + r)a_t - c_t$ . Assume that  $U(c) = \log(c)$ . Write the associated-fixed point problem. Then show that the value function is of the form  $V(a) = K + D \log(a)$  with  $D = 1/(1 - \beta)$ .



We are now going to prove this result in a convoluted manner which outlines the general approach to problems that cannot be solved analytically.

## Example

1. **Contraction:** Define the function  $T(D) = 1 + \beta D$ . Then use the fact that,  $|T(D'') - T(D')| = \beta|D'' - D'|$ , to show that if  $T$  has a fixed-point, it is unique.
2. **Convergence:** Define the sequence  $D_n = 1 + \beta D_{n-1}$ . Show that  $D_n$  is a Cauchy sequence, so that  $\lim_{n \rightarrow \infty} D_n$  exists.
3. **Fixed-point:** Show that if  $D = \lim_{n \rightarrow \infty} D_n$ ,  $D$  is a fixed-point of  $T$ .

Steps 1 and 2 establish uniqueness and existence. Step 3 provides a way to compute the fixed-point.

We now generalize this approach.

# Metric Spaces

A **norm**  $\|\cdot\|$  is a real-valued function on  $\mathcal{C}$  which captures the notion of distance between functions. It satisfies the following properties

1. Positive definite  $\|y\| > 0$  if  $y \neq 0$ ,
2. Homogeneous  $\|\lambda y\| = |\lambda| \cdot \|y\|$  for all  $\lambda \in \mathbb{R}, y \in V$ ,
3. Triangle Inequality  $\|y + z\| \leq \|y\| + \|z\|$ .

The norm allows us to define a **metric**  $d(y, z) \equiv \|y - z\|$ .

On the space  $\mathcal{C}(X)$ , the most common norm is

$$\|y\| \equiv \max_{\{x \in X\}} |y(x)|,$$

where  $|\cdot|$  is the standard Euclidean norm on  $\mathbb{R}^n$ .

# Complete Metric Spaces

**Definition 2.1:** A sequence  $\{x_n\}_{n=0}^{\infty}$  in a vector space  $S$  converges to  $x \in S$ , if for each  $\varepsilon > 0$ , there exists  $N_{\varepsilon}$  such that  $\|x_n - x\| < \varepsilon$  for all  $n \geq N_{\varepsilon}$ .

**Definition 2.2:** A sequence  $\{x_n\}_{n=0}^{\infty}$  in  $S$  is a **Cauchy sequence** if for each  $\varepsilon > 0$ , there exists  $N_{\varepsilon}$  such that  $\|x_n - x_m\| < \varepsilon$  for all  $n, m \geq N_{\varepsilon}$ .

**Definition 2.3:** A metric space  $(S, \|\cdot\|)$  is **complete** if every Cauchy sequence in  $S$  converges to an element in  $S$ .

**Exercise 2.2:** Prove that the set  $\mathcal{C}(X)$  of bounded continuous functions  $f : X \rightarrow \mathbb{R}$  equipped with the sup norm  $\|y\| \equiv \max_{\{x \in X\}} |y(x)|$  is a complete normed vector space.

# Contraction Mapping

**Definition 2.4:** Let  $(S, \|\cdot\|)$  be a metric space and  $T : S \rightarrow S$  be a function mapping  $S$  into itself.  $T$  is a **contraction mapping** if for some  $\beta \in (0, 1)$ ,  $\|Tx - Ty\| \leq \beta\|x - y\|$ , for all  $x, y \in S$ .

## Theorem 2.1. (Contraction Mapping Theorem)

If  $(S, \|\cdot\|)$  is a **complete** metric space and  $T : S \rightarrow S$  is a contraction mapping, then  $T$  has exactly one fixed point  $v$  in  $S$ . Furthermore, for any  $v_0 \in S$ ,  $\|T^n v_0 - v\| \leq \beta^n \|v_0 - v\|$  where  $T^{n+1}(v) = T(T^n(v))$  and  $n = 0, 1, 2, \dots$





# Proof of Contraction Mapping Theorem

**PROOF of Theorem 2.1. (Contraction Mapping Theorem):**

**Step 1.** Take any  $v_0 \in S$  and let  $v_{n+1} \equiv Tv_n$ . Then

$$||v_{n+1} - v_n|| = ||Tv_n - Tv_{n-1}|| \leq \beta ||v_n - v_{n-1}|| \leq \beta^n ||v_1 - v_0||$$

and so, for  $m > n$ ,

$$\begin{aligned} ||v_m - v_n|| &\leq ||v_m - v_{m-1}|| + ||v_{m-1} - v_{m-2}|| + \dots + ||v_{n+1} - v_n|| \\ &\leq (\beta^{m-1} + \beta^{m-2} + \dots + \beta^n) ||v_1 - v_0|| \\ &\leq \beta^n (\beta^{m-n-1} + \beta^{m-n-2} + \dots + 1) ||v_1 - v_0|| \leq \frac{\beta^n}{1 - \beta} ||v_1 - v_0||. \end{aligned}$$

Thus  $\{v_n\}$  is a Cauchy sequence and  $v_n \rightarrow v$ .

**Step 2.** To show that  $v = Tv$  notice that

$$||Tv - v|| \leq ||Tv - v_n|| + ||v_n - v|| \leq \beta ||v - v_{n-1}|| + ||v_n - v|| \rightarrow 0.$$

**Step 3.** Finally, we proceed by contradiction to prove that  $v$  is unique. Assume that there are two fixed points  $v^1$  and  $v^2$ . Then

$$0 \leq a = ||v^1 - v^2|| = ||Tv^1 - Tv^2|| \leq \beta ||v^1 - v^2|| = \beta a,$$

which is only possible if  $a = 0$ , i.e., if  $v^1 = v^2$ .



# Contraction Mapping

## Theorem 2.2. (Blackwell's Sufficient Condition)

Let  $X \subseteq \mathbb{R}^n$ ,  $T : \mathcal{C}(X) \rightarrow \mathbb{D}$  is a contraction mapping if it satisfies:



1. **Monotonicity:**  $f(x) \leq g(x)$  for all  $x \in X$  and  $f, g \in \mathcal{C}(X)$ , implies  $Tf(x) \leq Tg(x)$ , for all  $x \in X$ .
2. **Discounting:** There exists some  $\beta \in (0, 1)$  such that  $T(f + a)(x) \leq Tf(x) + \beta a$  for all  $f \in \mathcal{C}(X)$ ,  $a \geq 0$ ,  $x \in X$ .

**PROOF:** See theorem 3.3 in SLP. ■

# Contraction Mapping

We now apply the contraction mapping theorem to our functional equation

$$Tv(x) = \max_{x' \in \Gamma(x)} \{F(x, x') + \beta v(x')\}.$$

We need to show that:

1.  $T$  maps the set of continuous and bounded functions into itself.
2.  $T$  is a contraction.

We first prove 2 assuming 1, and then establish 1.

# Contraction Mapping

## Theorem 2.3.

Let  $Tv(x) = \max_{x' \in \Gamma(x)} \{F(x, x') + \beta v(x')\}$ .  $T$  satisfies Balckwell's sufficient conditions.  $\Rightarrow T$  is a contraction mapping

PROOF:

1. **Monotonicity:** For  $f \geq v$

$$\begin{aligned} Tv(x) &= \max_{x' \in \Gamma(x)} \{F(x, x') + \beta v(x')\} \\ &\leq F(x, g(x)) + \beta f(g(x)) \leq \max_{x' \in \Gamma(x)} \{F(x, x') + \beta f(x')\} = Tf(x). \end{aligned}$$

2. **Discounting:** For  $a > 0$

$$\begin{aligned} T(v + a)(x) &= \max_{x' \in \Gamma(x)} \{F(x, x') + \beta(v(x') + a)\} \\ &= \max_{x' \in \Gamma(x)} \{F(x, x') + \beta v(x')\} + \beta a = Tv(x) + \beta a. \end{aligned}$$



## Theorem of the Maximum

We still have to identify the restrictions on the correspondence  $\Gamma$  and on the return function  $F$  under which  $T$  maps the set of continuous and bounded functions into itself.

Our optimization problem is of the form

$$h(x) = \max_{x' \in \Gamma(x)} f(x, x'). \quad (1)$$

The max is attained when  $f(x, \cdot)$  is continuous in  $x'$  and  $\Gamma(x)$  is nonempty and compact. Then the function  $h(x)$  is well defined as is the policy correspondence

$$G(x) = \{x' \in \Gamma(x) : f(x, x') = h(x)\}. \quad (2)$$

# Theorem of the Maximum

## Theorem 2.4. (Theorem of the Maximum)

Let  $X \subseteq \mathbb{R}^n$  and  $f : X \times X \rightarrow \mathbb{R}$  be a continuous function, and let  $\Gamma : X \rightarrow X$  be a compact valued and continuous correspondence. Then the function  $h$  defined in (1) is continuous, and the correspondence  $G$  defined in (2) is nonempty, compact valued and upper hemi-continuous.

**PROOF:** See theorem 3.6 in SLP. ■

**Corollary 2.1.:** If  $\Gamma$  is convex-valued and  $f$  is strictly concave in  $y$ , then the policy correspondence  $G$  is single-valued and continuous.

## Summary

We are now in a position to study our original problem. If we assume that:

**Assumption 2.1.**  $X$  is a convex subset of  $\mathbb{R}^n$ , and  $\Gamma$  is a non-empty, continuous and compact-valued correspondence.

**Assumption 2.2.**  $F : X \times X \rightarrow \mathbb{R}$  is continuous and bounded.

Then we can combine the theorems above to study (FE) in a similar way as the basic estate planning problem:

1. Theorem of the maximum shows that  $T$  maps  $\mathcal{C}(X)$  into itself;
2. Then Blackwell's Sufficient Conditions shows that  $T$  is a contraction;
3. Contraction Mapping Theorem shows that, for any initial guess  $v_0$ ,  $T$  generates a Cauchy sequence of functions  $v_n$ ;
4. Since  $\mathcal{C}(X)$  is a complete metric space,  $v_n$  converges to the unique value function  $v$ .



## Additional Assumptions

To further characterize the value and policy functions, we have to impose more stringent assumptions on the fundamentals.

**Assumption 2.3.**  $F$  is strictly concave and, for each  $x'$ ,  $F(\cdot, x')$  is strictly increasing in each of its first arguments.

**Assumption 2.4.**  $\Gamma$  is convex and monotone in the sense that  $x \leq y$  implies  $\Gamma(x) \subseteq \Gamma(y)$ .





# Concavity of Value Function

## Theorem 2.5.



When assumptions 2.1-2.4 hold, the value function  $v$  is strictly increasing.

**PROOF:** We prove a stronger version, namely  $Tf$  is increasing if  $f$  is non-decreasing. Pick  $x_1, x_2 \in X$  with  $x_2 > x_1$ . The optimal policy  $g(x_1) \in \Gamma(x_2)$  by monotonicity of  $\Gamma$ , so

$$Tf(x_2) = \max_{x' \in \Gamma(x_2)} \{F(x_2, x') + \beta f(x')\} \geq F(x_2, g(x_1)) + \beta f(g(x_1)) > F(x_1, g(x_1)) + \beta f(g(x_1)) = Tf(x_1),$$

where the last inequality holds because  $F$  is increasing. Since  $v$  is the limit of  $T^n f_0$ , and the space of non-decreasing function is the closure of the space of increasing functions,  $v$  must be non-decreasing. Furthermore, since  $v = Tv$ , the equation above implies that  $v$  is actually increasing.



**Exercise 2.3:** Use an inductive argument similar to the one in the proof of Theorem 2.5. to establish that, when assumptions 2.1-2.4 hold,  $v$  is concave.

## Differentiability of Value Function



It is often insightful to look at the FOC of the problem, in our case

$$F_{x'}(x, x') + \beta V'(x') = 0.$$



To do so, however, we first need to establish that the value function is indeed differentiable.

**Example of non differentiable value function:** Two period problem

$$v(x) = \max_{y \in [0,1]} y^2 - xy.$$

Then  $v(x) = 1 - \min(x, 1)$  and the value function is not differentiable at 1.

This example suggests that non-differentiability is likely to originate from non-concavity.

# Differentiability of Value Function

The approach used to prove concavity does not work because the space of differentiable functions is not closed.

We use instead the notion of subgradient:

1. If a function  $f : X \rightarrow \mathbb{R}$  is concave, with  $X$  a convex subset of  $\mathbb{R}^n$ , it admits a subgradient  $p \in \mathbb{R}^n$  so that

$$f(x) - f(x_0) \leq p \cdot (x - x_0), \text{ for all } x \in X.$$

2. If  $f$  is differentiable, then  $p$  is unique and is the gradient of  $f$  at  $x_0$ .
3. The converse of 2 holds, that is if  $f$  is concave with a **unique** subgradient, it is differentiable (See Rockafellar, 1970, Th.25.1 for a proof).

# Differentiability of Value Function

## Theorem 2.5. (Benveniste and Sheinkman)

Suppose that  $F$  is differentiable in  $x$  and that assumptions 2.1-2.4 hold. If  $x_0 \in \text{int } X$  and  $g(x_0) \in \text{int } \Gamma(x_0)$ , then  $v$  is differentiable at  $x_0$  and  $\nabla v(x_0) = \nabla F_x(x_0, g(x_0))$ .

**PROOF:** Consider the following lower approximation of  $v$  in the neighborhood of  $x_0$

$$w(x) = F(x, g(x_0)) + \beta v(g(x_0)).$$

Since  $F$  is differentiable so is  $w$ . Given continuity of  $\Gamma$  and the fact that  $g(x_0) \in \text{int} \Gamma(x_0)$ , there exists a neighborhood  $D$  of  $x_0$  such that  $g(x_0) \in \Gamma(x)$  for all  $x \in D$ . By definition of  $v$ , we have

$$w(x) \leq v(x) \text{ for all } x \in D.$$

Since  $v$  is concave, it has a subgradient  $p$  and so

$$w(x) - w(x_0) \leq v(x) - v(x_0) \leq p \cdot (x - x_0) \text{ for all } x \in D.$$

But remember that  $w$  is differentiable. Hence  $p = \nabla w(x_0)$  and the subgradient is unique, which by point 3 in the previous slide, proves that  $v$  is differentiable.



# Conclusion

To summarize, we have identified in this lecture the conditions under which

1. The Functional Equation is the unique solution of a fixed point problem;
2. The value function can be approximated by an iterative procedure;
3. The value function is concave and differentiable.