# Calc III Notes

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# 1 Multivariable calc goals

- vectors and geometry of R"
- functions of serval variables diff and int
- higher dimensional versions of FTC
- fund them for line integrals
- greens them
- $\boldsymbol{\mathsf{-}}$  stokes them
- divergence them

# 12 Chapter 12: vectors and geo of space

## 12.1

R = line

dist(x,y) = |y - x|

 $R^2 = Plane$ 

Orders pairs of (x,y) of real numbers

 $R^3 = space$ 

ordered triples of (x,y,z) of real numbers

right-hand rule: point fingers toward pos x-axis and curl towards pos y-axis, thumb should point to positive z

 $R^n = \text{n-tuples } (x_1, x_2, ... x_n) \text{ n-dim space}$ 

Distance D from (0,0) to (x,y)

$$D^2 = x^2 + y^2$$

Distance D from (0,0,0) to (x,y,z)

$$D = \sqrt{x^2 + yy^2 + z^2}$$

Sphere with center  $X_0, Y_0, Z_0$  and radius R has equation:

$$(X - X_0)^2 + (y - y_0)^2 + (z - z_0)^2 = r^2$$

Find equation of the set of points equidistant from the points a 1,4,2, and b 3,3,3

$$AX = \sqrt{(x-1)^2 + (y-4)^2 + (z-2)^2}$$

$$BX = \sqrt{(x-3)^2 + (y-3)^2 + (z-3)^2}$$

 $\mathrm{set}\ \mathrm{AX} = \mathrm{BX}$ 

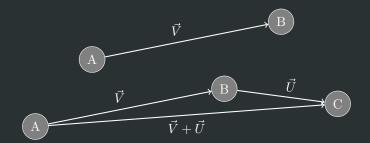
Result is a plane

# 12.2 vectors and geo of space

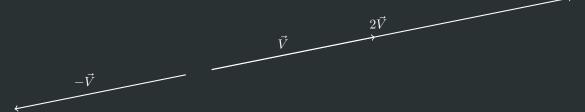
 $scaler = magnitude \le 0$ 

vector = magnitude + direction

$$\vec{u} = <5, 3>, \vec{u} = 5\hat{i} + 3\hat{j}$$



## 12.2.1 Scaler multiple



Changes the length of the vectors, ie, stretches them in a direction. Length of  $k\vec{v} = |K| * |V|$  direction of  $k\vec{V} = sameas\vec{V}ifk > 0$  real numbers work like scaling factors

Points = 
$$(a,b)$$
  
Vector =  $\langle a, b \rangle$ 

#### 12.2.2 Vectors in $\mathbb{R}^3$

Extra cords for points and extra comps for vectors

$$point = (a,b,c)$$
$$vector = \langle a,b,c \rangle$$

$$if\vec{V} = P_1\vec{P}_2, then|\vec{V}| = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2}$$

$$P(4,-1,-3)$$
  
 $Q(8,0,-5)$ 

$$R(0, -2, -1)$$

$$\vec{PQ} = <8-4, 0--1, -5--3>$$

$$\vec{u} = <3, 1, 3>$$

$$\vec{v}=<1,3,7>$$

$$\vec{v} + \vec{v} = <3+1, 1+3, 3+7>$$

$$5 * \vec{v} = < 1 * 5, 3 * 5, 7 * 5 >$$

#### 12.2.3 notation

$$V_n$$

set of all n-dim vectors  $< V_1, V_2, ..., V_n > V_3$  set of all vectors  $< v_1, v_2, v_3 > \hat{i} = <1,0,0>$ 

$$\hat{j} = <0, 1, 0 >$$
  
 $\hat{k} = <0, 0, 1 >$ 

unit vector = vector of length 1  $\hat{i}, \hat{j}, \hat{k}$  are unit vectors

find the unit vector that has the same direction as  $\vec{b} = 4\hat{i} - 2\hat{j} + 3\hat{k}$ 

$$\sqrt{4^{2}(-2)^{2} + 3^{2}}$$

$$\sqrt{16 + 4 + 9}$$

$$\sqrt{29}$$

$$\frac{\vec{b}}{|\vec{b}|} = \frac{1}{\sqrt{29}}(4\hat{i} - 2\hat{j} + 3\hat{k})$$

#### 12.2.4 dot product

 $\begin{array}{l} \text{dot product} \rightarrow 2 \text{ vectors} \rightarrow 1 \text{ scaler} \\ \text{cross product} \rightarrow 2 \text{ vectors} \rightarrow 1 \text{ vector} \end{array}$ 

$$\vec{a} \cdot \vec{b} = a_1 b_1 + a_2 b_2 + a_3 b_3$$

#### **Properties**

$$\vec{a} \cdot \vec{a} = \vec{a}^2$$

if  $\theta$  is the angle between the vectors  $\vec{a}$  and  $\vec{b}$ , then  $\vec{a} \cdot \vec{b} = |\vec{a}| |\vec{b}| \cos(\theta)$ 

follows from the law of cosines

 $\vec{a}$  and  $\vec{b}$  are orthogonal (or perp) if te angle between them is  $\theta=\frac{\pi}{2}$ 

the zero vector  $\vec{0}$  is considered orthogonal to all vectors

 $\vec{a} \cdot \vec{b} = 0 \ll \vec{a} \perp \vec{b}$ , orthogonal, form 90deg angle

accute

 $\vec{a} \cdot \vec{b} > 0$ 

obtuse

$$\vec{a} \cdot \vec{b} > 0$$

find angle  $\theta$  between a=<1,1,5> and b=<0,3,4>

$$a = \sqrt{1^2 + 1^2 + 5^2}$$

$$b = \sqrt{0^2 + 3^2 + 4^2}$$

$$\cos \theta = \frac{\vec{a}\vec{b}}{|\vec{a}|\vec{b}|}$$

$$\cos \theta = \frac{23}{3\sqrt{3} \times 5}$$

$$\theta = \arccos(\frac{23}{15\sqrt{3}})$$

# 12.3 Projections

 $proj_{\vec{a}}(\vec{b}) = \text{vector projection of } \vec{b} \text{ onto } \vec{a}$ Vector = A scaler-multiple of  $\vec{a}$ 

 $comp_{\vec{a}}(\vec{a}) = \text{Scaler projection of } \vec{b} \text{ onto } \vec{a}$  Scaler = Signed magnitude of the vector projection $= |\vec{b}cos\theta|$ 

## dot product

- valid in any dim
- result is a scaler
- application:work

#### cross product

- valid in only  $r^3$
- result is a vector
- application: torque

$$\hat{i} \times \hat{j} = \hat{k}$$

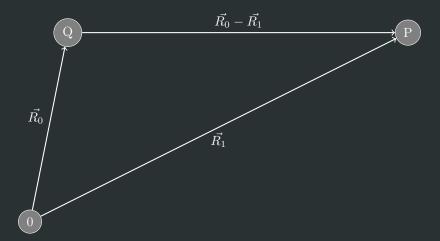
$$\vec{a} \times \vec{b} = -\vec{b} \times \vec{a}$$

## 12.4

# 12.5 Equations of lines and planes

line segment from  $\vec{r_0}$  to  $\vec{r_1}$ 

$$\vec{r} = \vec{0} + t(\vec{r_1} - \vec{r_0}), 0 \le t \le 1$$



EX: Find parametric eq for the line seg from P(1,-3,5) to Q(4,-7,2)

## **12.5.1** Planes in $R^3$

How to specify plane?

- specify a point  $P_0 \approx (x_0, y_0, z_0) on plane$
- and a normal vector  $\vec{n}=< a,b,c> \neq \vec{0}$  which is perp to the plane

Then P (x,y,z) is in plane : $\Leftrightarrow \vec{n}$  and  $\vec{p_0}\vec{p}$  are orth

$$\vec{n} \cdot \vec{p_0 P} = 0$$

eqn of a plane 
$$a(x-x_0) + b(y-y_0) + c(z-z_0) = 0$$
 or 
$$ax + by + cz + d = 0, \text{ where } d = -(ax_0 + by_0 + cz_0)$$

Ex. Find an eqn of the plane through points

$$P_{1}(0,1,4)$$

$$P_{2}(2,4,1)$$

$$P_{3}(3,-1,5)$$

$$\vec{V} = P_{1}\vec{P}_{2} = \langle 2,3,-3 \rangle = P_{2} - P - 1$$

$$\vec{W} = P_{1}\vec{P}_{3} = \langle 3,-2,1 \rangle = P_{3} - P - 1$$

$$\vec{N} = \vec{V} \times \vec{W} = \begin{bmatrix} \hat{i} & \hat{j} & \hat{k} \\ 2 & 3 & -3 \\ 3 & -2 & 1 \end{bmatrix} = -3\hat{i} - 11\hat{j} - 13\hat{k}$$

PLANE: 
$$P_1(0, 1, 4), \vec{n} = < -3, -11, -13 >$$

$$-3(x - 0) + -11(y - 1) + -13(z - 1) = 0$$

$$+3(x - 0) + 11(y - 1) + 13(z - 1) = 0$$

$$+3(x) + 11y + 13z - 63 = 0$$

EX: Find an eqn of a plane that is parallel to the plane \*x - y - 3z + 3 = 0 and goes through the point (5,6,7)

$$8(x-5) - 1(y-6) - 3(z-7) = 0$$

Angle between two planes = Angle b<br/>tween their normal vectors use  $\cos\theta = \frac{\vec{n_1}\cdot\vec{n_2}}{|\vec{n_1}||\vec{n_2}|}$ 

Sketching a plane 3 noncollinear points determine a plane find interactions with x,y,z axes then draw plane between them

#### 12.5.2 Intersections

ex: line and plane

$$X = 2 - 3t$$

$$y = 1 + 4t$$

$$z = -1 + 2t$$

## Plane =

$$8x - y - 3z + 3 = 0$$

$$8(2+3t) - (1+4t) - 3(-1+2t) + 3 = 0$$
$$21 + 14t = 0$$
$$t = -\frac{3}{2}$$

ex: plane and plane

$$plane1 = 8x - y - 3z + 3 = 0$$

$$plane2 = -4x + y + 2z + 5 = 0$$

First method: introduce a parameter. z=t

$$plane1 = 8x - y - 3t + 3 = 0$$

$$plane2 = -4x + y + 2t + 5 = 0$$

$$P_1 + P_2 = 4x - t + 8 = 0$$

$$x = \frac{1}{4}t - 2$$

$$8(\frac{1}{4}t - 2) - y - 3t + 3 = 0$$

$$-t-13=y$$

$$x = 2 + 1/4t$$

$$y - 13 - t$$

$$z = t$$

- 13 Chapter 13: vector functions
- 14 Chapter 14: partial derivate
- 15 Chapter 15: multiple integrals
- 16 Chapter 16: vector calculus