

Ito Integration and Calculus, Concept and Didactical Simulations

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1 Concept

Ito calculus is a major topic in the field of stochastic calculus, which is a particular area of mathematics that deals with stochastic differential equations (SDEs).

When we talk about Ito integration we have to keep in mind the following key concepts:

- **Stochastic integral:** The Ito integral extends the classical integral, which is based on the idea of summing up infinitesimally small quantities, to include terms involving the Brownian motion or other stochastic processes.
- **Stochastic differential equations (SDEs):** This is where Ito integration comes in, as it is often used to solve SDEs, which describe the evolution of a stochastic process.
- **Ito process:** We obtain an Ito process, which is a stochastic process itself, by integrating a generic stochastic process with respect to a Brownian motion. Mathematically, if $X(t)$ is an Ito process, the Ito integral of a function $f(t, X(t))$ with respect to $X(t)$ is written as

$$\int_0^t f(s, X(s))dX(s)$$

Talking about Ito's calculus instead, we need to consider these two fundamental properties:

1. **Ito's Lemma:** It's the analogous of the chain rule in classical calculus, allowing us to differentiate functions of stochastic processes. The lemma's statement is the following:

$$df(t, X(t)) = \left(\frac{\partial f}{\partial t} + \frac{\partial f}{\partial x} \mu(t, X(t)) + \frac{1}{2} \frac{\partial^2 f}{\partial x^2} \sigma^2(t, X(t)) \right) dt + \frac{\partial f}{\partial x} \sigma(t, X(t)) dW(t)$$

Where $W(t)$ is a Brownian motion, $\mu(t, X(t))$ is the drift coefficient and $\sigma(t, X(t))$ is the diffusion coefficient.

2. **Ito Isomery:** The Ito isometry is a result that relates the expectation of the square of an Ito integral to the time parameter and the integrand's properties. It is a crucial tool in the analysis of stochastic processes.

2 Simulations

I arranged a simulation in Python to compute the Ito's integral of t^3 . I create a function to generate some random numbers from a normal distribution and scale them with the square root, then I generate the Brownian motion increments by using the previously mentioned function. After defining the integrand I compute the Ito's integral with the partial sums. I then plot the values of the Ito's integral with respect to the time interval. Of course, because of the randomness brought by the Brownian motion, the graphs are different each time. Note that the number of steps n determines how finely the Ito's integral is approximated.

```
1 import streamlit as st
2 import numpy as np
3 import matplotlib.pyplot as plt
4
5 # Function to generate Brownian increments
6 def brownian_step(num_steps, dt):
7     return np.sqrt(dt) *
8         np.random.normal(size=num_steps)
9
10 # Function to simulate Ito integral
11 def simulate_ito_integral(num_steps, dt):
12     t_values = np.linspace(0, num_steps * dt,
13                             num_steps + 1)
14     brownian_increments = brownian_step(num_steps, dt)
15     integrand_values = t_values**3 # Integrand
16     function: t^3
17     ito_integral_values =
18         np.cumsum(integrand_values[:-1] *
19                 brownian_increments)
20     return t_values[:-1], ito_integral_values
21
22 # Streamlit app
23 def main():
24     st.title("Ito Integration Simulation")
25
26     # User input
27     num_steps = st.slider("Number of Steps",
28                             min_value=10, max_value=1000, value=100,
29                             step=10)
30
31     # Simulation
```

```

25 dt = 1.0 / num_steps
26 t_values, ito_integral_values =
    simulate_ito_integral(num_steps, dt)
27
28 # Plotting
29 fig, ax = plt.subplots()
30 ax.plot(t_values, ito_integral_values, label="Ito
    Integral")
31 ax.set_xlabel("Time")
32 ax.set_ylabel("Value")
33 ax.legend()
34
35 # Display the plot using Streamlit
36 st.pyplot(fig)
37
38 if __name__ == "__main__":
39     main()

```

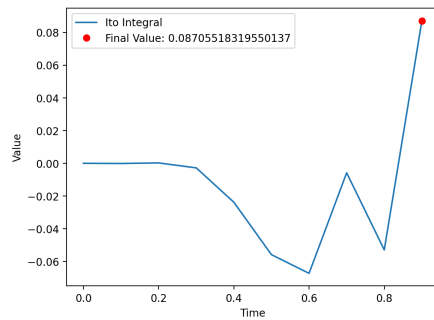


Figure 1: Simulation run with $n = 10$.

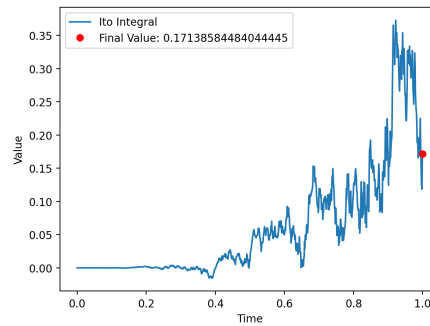


Figure 2: Simulation run with $n = 1000$.