

Numerical Methods Comparison

Pietro Colaguori 1936709

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1 Euler-Maruyama

The Euler-Maruyama method for the stochastic differential equation

$$dX(t) = a(X(t), t) dt + b(X(t), t) dW(t)$$

with initial condition $X(0) = X_0$ is given by the update rule

$$X_{n+1} = X_n + a(X_n, t_n)\Delta t + b(X_n, t_n)\sqrt{\Delta t}Z_n$$

where X_n is the approximation of $X(t_n)$ at time step n , $t_n = n\Delta t$, $\Delta t = \frac{T}{N}$ is the time step size, and Z_n is a standard normal random variable.

2 Milstein

The Milstein method for the stochastic differential equation

$$dX(t) = a(X(t), t) dt + b(X(t), t) dW(t)$$

with initial condition $X(0) = X_0$ is given by the update rule

$$X_{n+1} = X_n + a(X_n, t_n)\Delta t + b(X_n, t_n)\Delta W_n + \frac{1}{2}b(X_n, t_n)\frac{\partial b(X_n, t_n)}{\partial x}(\Delta W_n^2 - \Delta t),$$

where X_n is the approximation of $X(t_n)$ at time step n , $t_n = n\Delta t$, $\Delta t = \frac{T}{N}$ is the time step size, ΔW_n is the increment of a Wiener process at time step n , and $\frac{\partial b(X_n, t_n)}{\partial x}$ is the partial derivative of $b(X, t)$ with respect to X .

3 Runge Kutta

The Runge-Kutta method for the stochastic differential equation

$$dX(t) = a(X(t), t) dt + b(X(t), t) dW(t)$$

with initial condition $X(0) = X_0$ is given by the update rule

$$\begin{aligned} k_1 &= a(X_n, t_n)\Delta t + b(X_n, t_n)\sqrt{\Delta t}Z_{n,1}, \\ k_2 &= a(X_n + \frac{k_1}{2}, t_n + \frac{\Delta t}{2})\Delta t + b(X_n + \frac{k_1}{2}, t_n + \frac{\Delta t}{2})\sqrt{\Delta t}Z_{n,2}, \\ k_3 &= a(X_n + \frac{k_2}{2}, t_n + \frac{\Delta t}{2})\Delta t + b(X_n + \frac{k_2}{2}, t_n + \frac{\Delta t}{2})\sqrt{\Delta t}Z_{n,3}, \\ k_4 &= a(X_n + k_3, t_n + \Delta t)\Delta t + b(X_n + k_3, t_n + \Delta t)\sqrt{\Delta t}Z_{n,4}, \\ X_{n+1} &= X_n + \frac{1}{6}(k_1 + 2k_2 + 2k_3 + k_4). \end{aligned}$$

where X_n is the approximation of $X(t_n)$ at time step n , $t_n = n\Delta t$, $\Delta t = \frac{T}{N}$ is the time step size, and $Z_{n,i}$ are independent standard normal random variables.

4 Heun

The Heun method for the stochastic differential equation

$$dX(t) = a(X(t), t) dt + b(X(t), t) dW(t)$$

with initial condition $X(0) = X_0$ is given by the update rule

$$\begin{aligned} Y_{n+1} &= X_n + a(X_n, t_n)\Delta t + b(X_n, t_n)\sqrt{\Delta t}Z_n, \\ X_{n+1} &= X_n + \frac{1}{2} [a(X_n, t_n) + a(Y_{n+1}, t_{n+1})] \Delta t + \frac{1}{2} [b(X_n, t_n) + b(Y_{n+1}, t_{n+1})] \sqrt{\Delta t}Z_{n+1}, \end{aligned}$$

where X_n is the approximation of $X(t_n)$ at time step n , $t_n = n\Delta t$, $\Delta t = \frac{T}{N}$ is the time step size, Z_n is a standard normal random variable, and Y_{n+1} is an intermediate approximation.