

Coordination in complex environments

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Coordination and complexity

Coordination motives and uncertainty are common in innovative contexts.

Examples:

1. Interoperability of Electronic Medical Record Systems (Lin '23),
2. Co-op advertising (Jørgensen-Zaccour '14),
3. Technological innovation.

This paper introduces a model of **coordination** in an **informationally complex** environment.

Overview

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- (1) A model of coordination in complex environments;
- (2) New **conformity** phenomenon;
- (3) Source of conformity: **correlation** between the outcomes of the decisions of **different players**.
- (4) Applications:
 1. Oligopoly pricing;
 2. Multi-division organization.

Model

n players.

$x_i \in \mathbf{R}$ is player i 's **outcome**.

Payoff to player i from the profile of outcomes \mathbf{x} is:

$$\pi_i(\mathbf{x}) = - \left[\underbrace{(1 - \alpha)\delta_i + \alpha \sum_{j \neq i} \gamma^{ij} x_j}_{i\text{'s target}} - x_i \right]^2,$$

in which

$\alpha \geq 0$ captures coordination motives,

$\delta_i \in \mathbf{R}$ is i 's favorite outcome,

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[Ballaster *et al.* '06]

Model | Complexity

Players simultaneously choose **policies** from $[\underline{p}, \bar{p}] \subset \mathbf{R}$.

The **outcome function** χ maps every policy p_i to the corresponding outcome $\chi(p_i)$,

$$\chi: \mathbf{R} \rightarrow \mathbf{R}.$$

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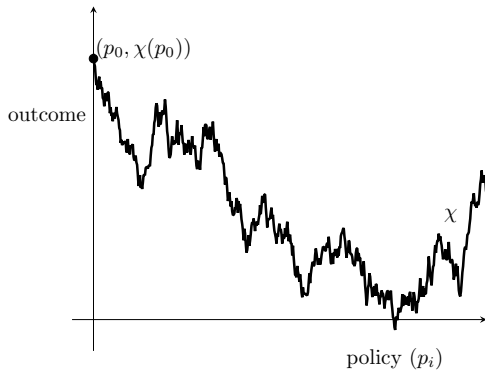
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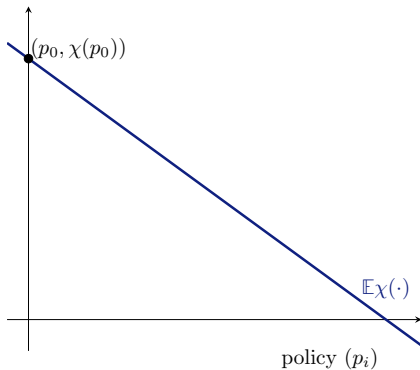
χ is the realization of a Brownian motion with known:

- ▶ Drift $\mu < 0$,
- ▶ Variance σ^2 ,
- ▶ Initial point $(p_0, \chi(p_0))$.

Model | Complexity



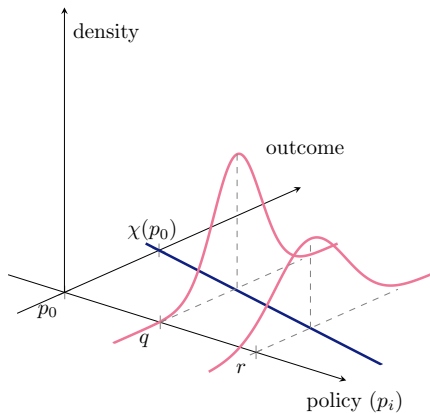
Model | Complexity



Status quo:

$(p_0, \chi(p_0)).$

Model | Complexity



Complexity:

$$k = \frac{\sigma^2}{2|\mu|}.$$

► Details

Equilibrium

1. Players simultaneously choose policies p_1, \dots, p_n .
2. Player i gets the payoff from the profile of corresponding outcomes:

$$\pi_i(\chi(p_1), \dots, \chi(p_n)).$$

Equilibrium

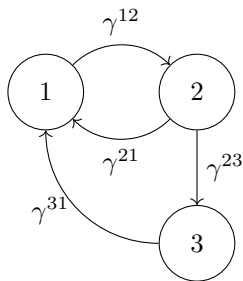
1. Players simultaneously choose policies p_1, \dots, p_n .
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The policy profile \mathbf{p} is an **equilibrium** if, for every player i :

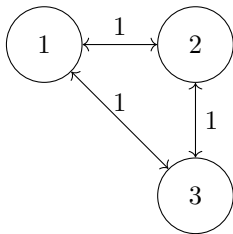
$$\mathbb{E}\pi_i(\chi(\mathbf{p})) \geq \mathbb{E}\pi_i(\chi(q_i), \chi(\mathbf{p}_{-i})) \text{ for all policies } q_i.$$

Network



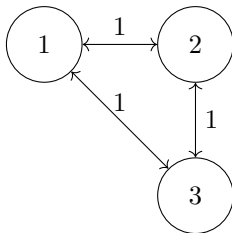
$$\mathbf{\Gamma} = (\gamma^{ij}) = \begin{pmatrix} 0 & \gamma^{12} & 0 \\ \gamma^{21} & 0 & \gamma^{23} \\ \gamma^{31} & 0 & 0 \end{pmatrix}$$

Network



$$\mathbf{\Gamma} = \begin{pmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{pmatrix}$$

Network



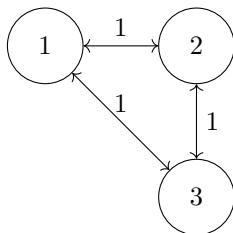
$$\mathbf{\Gamma} = \begin{pmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{pmatrix}$$

Upper bound on strength of coordination motives:

$$\alpha\lambda(\mathbf{\Gamma}) < 1,$$

in which $\lambda(\mathbf{\Gamma})$ is the largest eigenvalue of the adjacency matrix.

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For this talk: $\gamma^{ij} = \gamma^{ji}$, and:

1. $\underline{p} = p_0$,
2. \bar{p} and $\chi(p_0)$ are sufficiently large.

No complexity

The *centrality of player i* is the i th entry of:

$$\beta = (1 - \alpha)(\mathbf{I} - \alpha\mathbf{\Gamma})^{-1}\delta.$$

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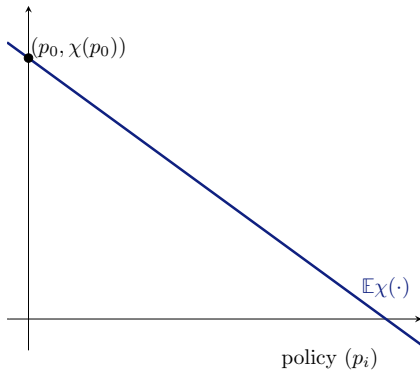
β_i counts all ‘ α -discounted’ walks from i and weighs walks to j by $(1 - \alpha)\delta_j$, so:

$$\beta \propto \delta + \alpha\mathbf{\Gamma}\delta + \alpha^2\mathbf{\Gamma}^2\delta + \dots$$

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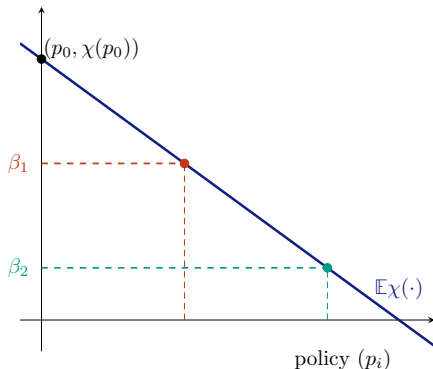
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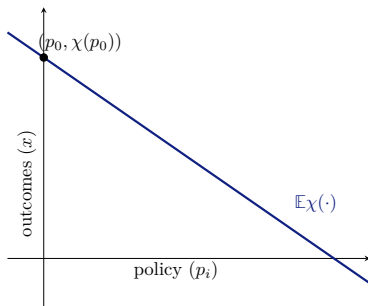


Fact A. (Ballester *et al.* '06)

If $k = 0$, in the unique equilibrium:

$$\mathbb{E}\chi(\mathbf{p}) = \beta.$$

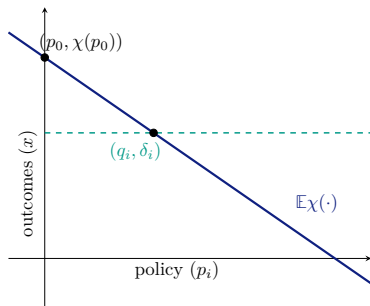
Single player



Fact B. (Callander '11a)
If $\alpha = 0$, player i has a unique optimal policy p_i :

$$\mathbb{E}\chi(p_i) = \delta_i + k.$$

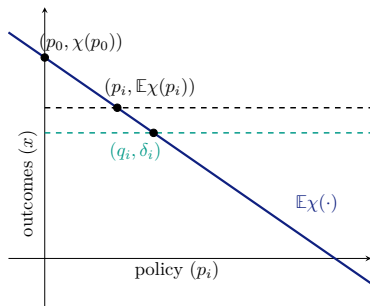
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Fact B. (Callander '11a)
If $\alpha = 0$, player i has a unique optimal policy p_i :

$$\mathbb{E}\chi(p_i) = \delta_i + \underbrace{k}_{\text{status quo bias}}.$$

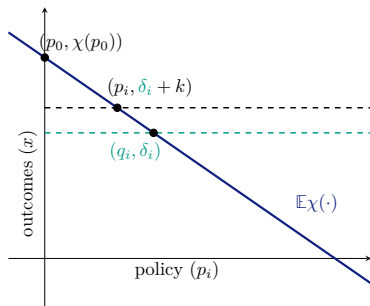
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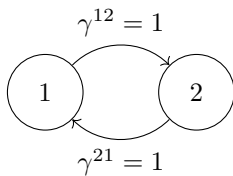
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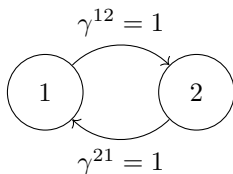
Two players



$$\mathbf{\Gamma} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

And: $\delta_1 > \delta_2$

Two players



$$\mathbf{\Gamma} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

And: $\delta_1 > \delta_2 \xRightarrow{\text{no complexity}} p_1 < p_2$.

Disentangling **pure noise** and **correlation** of players' outcomes.

Two players | Independent outcomes

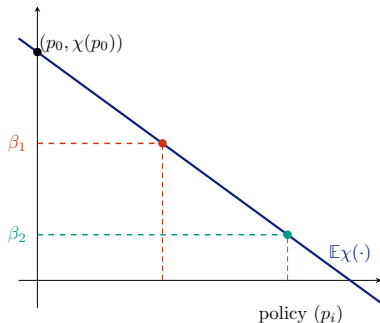
Player i 's outcome of policy p_i is:

$$\chi^i(p_i) = \chi(p_0) + \mu p_i + \sigma W^i(p_i), \quad \text{for independent standard } W^1, W^2.$$

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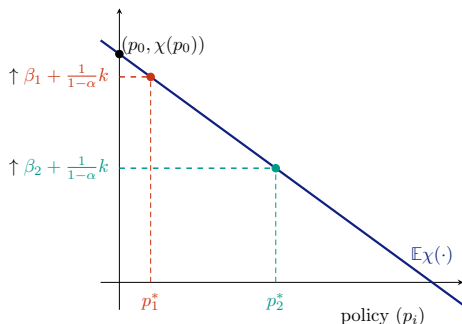
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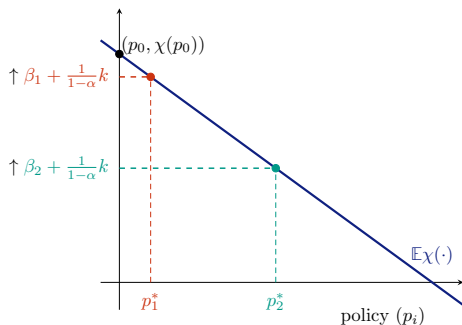
In the unique equilibrium:

$$\mathbb{E}\chi^i(p_i^*) = \beta_i + \underbrace{\frac{1}{1-\alpha}}_{\substack{\text{amplified} \\ \text{s.q. bias}}} k.$$

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Conformity? $\mathbb{E}\chi^i(p_i^*) - \mathbb{E}\chi^j(p_j^*) = \beta_i - \beta_j.$

Two players | Correlated outcomes

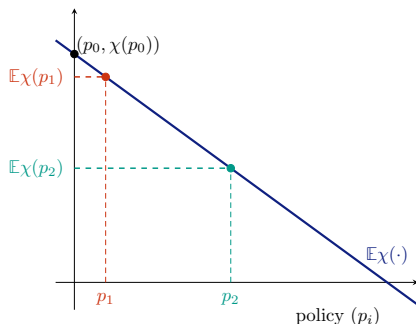
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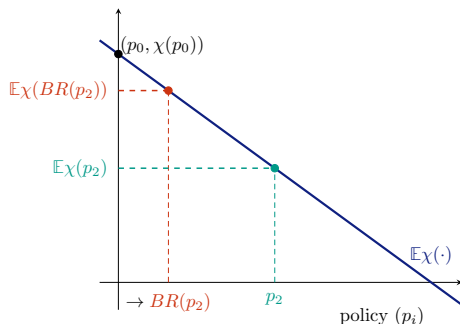
2 is the **Leader** and 1 is the **Follower**,

$$\text{Cov}(\chi(p_1), \chi(p_2)) = \text{Var } \chi(p_1).$$

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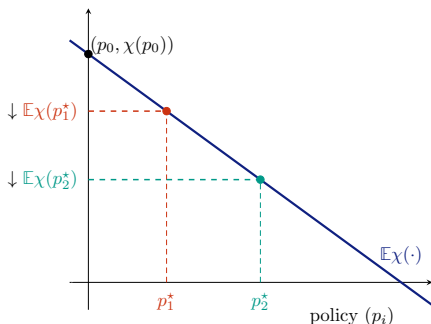
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\Rightarrow **Extra Exploration Motive for 1.**

Two players | Correlated outcomes

Player i 's outcome of policy p_i is:

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In the unique equilibrium:

$$\mathbb{E}\chi^1(p_1^*) = \beta_i + k + \frac{1}{1+\alpha}k,$$

$$\mathbb{E}\chi^2(p_2^*) = \beta_2 + k - \frac{1}{1+\alpha}k,$$

$$\text{if: } \delta_1 - \delta_2 > 2k \frac{\alpha}{1-\alpha}.$$

Conformity: $\mathbb{E}\chi(p_1^*) - \mathbb{E}\chi(p_2^*) - (\beta_1 - \beta_2) = -2 \underbrace{\frac{\alpha}{1+\alpha}k}_{< 0}.$

Two players | Imperfect correlation

Outcomes are given, for $\rho \in [0, 1]$, by:

$$\chi^1(p_1) = \chi(p_0) + \mu p_1 + \sigma W^1(p_1)$$

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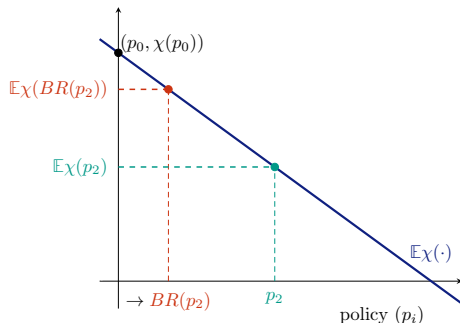
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\Rightarrow ρ -Weighted **Extra Exploration Motive for 1.**

Two players | Imperfect correlation

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In equilibrium:

$$\mathbb{E}\chi^1(p_1) - \mathbb{E}\chi^2(p_2) - (\beta_1 - \beta_2) = \rho \underbrace{\left(-2\frac{\alpha}{1+\alpha}k\right)}_{\substack{< 0 \\ \text{(perfect correlation)}}}.$$

Strategic complementarities

Lemma 1 (Strategic complementarities)

The expected payoff $\mathbb{E}\pi_i(\chi(\mathbf{p}))$ exhibits increasing differences in (p_i, \mathbf{p}_{-i}) , for every player i .

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- ▶ Complementarities in outcomes.
- ▶ Covariance structure $(\text{Cov}(\chi(p_1), \chi(p_2)) = \text{Var } \chi(p_1))$. [▶ More](#)

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Theorem 1 (Existence)

There exist a greatest and least equilibrium.

- ▶ Tarski's fixed point theorem.
(Milgrom-Shannon '90, Vives '90.)

Equilibrium decomposition

Proposition 1 (Decomposition)

The profile of policies $\mathbf{p} \in (p_0, \bar{p})^n$ is an equilibrium if and only if:

$$\mathbb{E}\chi(\mathbf{p}) = \beta + k\mathbf{1} + \alpha(\mathbf{I} - \alpha\mathbf{\Gamma})^{-1}(\mathbf{\Gamma} \odot \mathbf{A})\mathbf{1}k,$$

for a matrix $\mathbf{A} = (a_{ij})$ such that $a_{ij} \in [-1, 1]$ and

$$a_{ij} = \begin{cases} 1 & \text{if } p_i > p_j, \\ -1 & \text{if } p_i < p_j. \end{cases}$$

(\odot is element-wise product.)

Equilibrium decomposition

Proposition 1 (Decomposition)

Without complexity, $\mathbf{p} \in (p_0, \bar{p})^n$ is an equilibrium iff:

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(\odot is element-wise product.)

Equilibrium decomposition

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Without coordination, $\mathbf{p} \in (p_0, \bar{p})^n$ is an equilibrium iff:

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for a matrix $\mathbf{A} = (a_{ij})$ such that $a_{ij} \in [-1, 1]$ and

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Player i 's **conformity effect** weighs each walk to j by $w_j := \sum_{\ell} \alpha k \gamma^{j\ell} a_{j\ell}$:

$$\mathbf{w} + \alpha\Gamma\mathbf{w} + \alpha^2\Gamma^2\mathbf{w} + \dots = \alpha(\mathbf{I} - \alpha\Gamma)^{-1}(\Gamma \odot \mathbf{A})\mathbf{1}k.$$

(\odot is element-wise product.)

Conformity

Suppose the network is complete.

Lemma 2 (Pairwise conformity)

If $\mathbf{p} \in (p_0, \bar{p})^n$ is an equilibrium:

$$\text{If } p_i < p_j, \text{ then: } \mathbb{E}\chi(p_i) - \mathbb{E}\chi(p_j) < \beta_i - \beta_j.$$

Conformity

Suppose the network is complete.

Lemma 2 (Conformity in ordered equilibria)

Let $\mathbf{p} \in (p_0, \bar{p})^n$ be an equilibrium. If $p_1 < \dots < p_n$, then:

$$\mathbb{E}\chi(p_i) - \mathbb{E}\chi(p_{i+1}) - (\beta_i - \beta_{i+1}) = \underbrace{-2\frac{\alpha}{1+\alpha}k}_{\downarrow \text{ in } \alpha \text{ \& } k}.$$

1. If $\uparrow k$, matching a leader's outcome is a more cost effective way of dealing with uncertainty

Conformity

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1. If $\uparrow k$, matching a leader's outcome is a more cost effective way of dealing with uncertainty + Conformity 'feeds back' through the network.

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1. If $\uparrow k$, matching a leader's outcome is a more cost effective way of dealing with uncertainty + Conformity 'feeds back' through the network.
2. "Yielding is far greater on **difficult** items than on easy ones."
(Asch '51; difficulty elicited as "certainty of judgement".)

Extra slides

Literature

Complexity à la Callander '11a

- ▶ Decision problems, players interacting over time: Jovanovic-Rob '90, Callander-Hummel '14, Garfagnini-Strulovici '16, Callander-Matouschek '19.
- ▶ Competitive elections: Callander '11b.
- ▶ Principal-Agent models: Callander '08, Callander *et al.* '21, Aybas-Callander '23.

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Gaussian processes Bardhi '24, Bardhi-Bobkova '23, Cetemen *et al.* '23, Ilut-Valchev '20, Anderson *et al.* '60.

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Coordination games with quadratic payoffs

- ▶ Complete information: Ballester *et al.* '06, Bramoullé *et al.* '14, Galeotti *et al.* '20, oligopoly (Amir *et al.* '17), ...
- ▶ Incomplete information: Radner '62, Vives '84, Morris-Shin '02, Angeletos-Pavan '07, Galeotti *et al.* '10, Lambert *et al.* '18, decentralization (Dessein-Santos '06), ...

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- ▶ Decision problems, players interacting over time: Jovanovic-Rob '90, Callander-Hummel '14, Garfagnini-Strulovici '16, Callander-Matouschek '19.
- ▶ Competitive elections: Callander '11b.
- ▶ Principal-Agent models: Callander '08, Callander *et al.* '21, Aybas-Callander '23.

Gaussian processes Bardhi '24, Bardhi-Bobkova '23, Cetemen *et al.* '23, Ilut-Valchev '20, Anderson *et al.* '60.

Coordination games with quadratic payoffs

- ▶ Complete information: Ballester *et al.* '06, Bramoullé *et al.* '14, Galeotti *et al.* '20, oligopoly (Amir *et al.* '17), ...
- ▶ Incomplete information: Radner '62, Vives '84, Morris-Shin '02, Angeletos-Pavan '07, Galeotti *et al.* '10, Lambert *et al.* '18, decentralization (Dessein-Santos '06), ...

Team & potential games Radner '62, Monderer-Shapley '96, ...

Order structure of the equilibrium set

Let $n = 2$ and $\delta_1 = \delta_2 = 0$.

Every equilibrium \mathbf{p} is symmetric: $p_1 = p_2$.

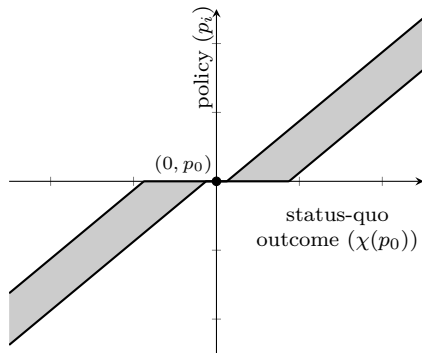


Figure: The equilibrium set, represented by player i 's policy, for every status-quo outcome.

Extensions

(1) The outcome of policy p to player i is:

$$\chi^i(p) = \chi(p_0) + \mu p + \sigma W^i(p),$$

with $dW^i(p)dW^j(p) = \rho c_{ij}dt$.

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In equilibrium, if Γ is irreducible:

$$\mathbb{E}\chi^i(p_i) = \beta_i + \overbrace{a_i k}^{\text{amplified s.q. bias}} + \overbrace{\rho b_i k}^{\text{exploration motive}},$$

$\underbrace{\hspace{1.5cm}}_{>1} \qquad \underbrace{\hspace{1.5cm}}_{\leq 0}$

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- (2) Player i believes that the initial point is:

$$(p_0^i, \underbrace{\chi(p_0^i)}_{\text{private information}}).$$

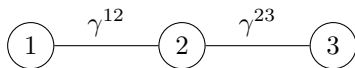
Single Crossing.

The expected payoff

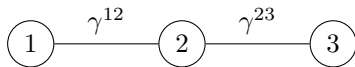
$\mathbb{E}^i \pi_i(\chi(p_i), \chi(\sigma_{-i}))$ has strictly increasing differences in $(p_i, \chi(p_0^i))$, if strategies in σ_{-i} are nondecreasing.

◀ More

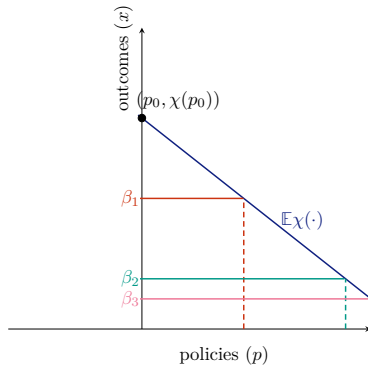
Counterformity



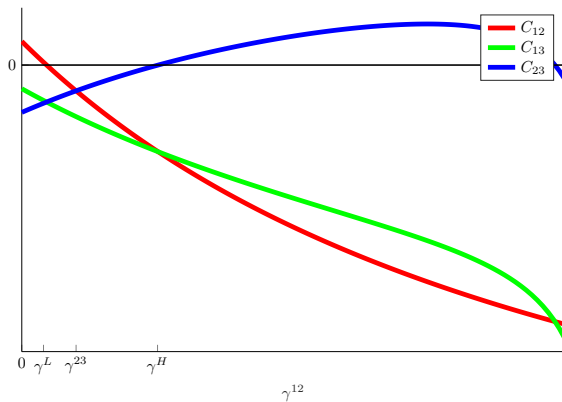
Counterformity



Without complexity:



Counterformity



$$C_{ij} = \mathbb{E}\chi(p_i^*) - \mathbb{E}\chi(p_j^*) - \beta_i + \beta_j.$$

Distribution

For $p_0 < p < q$:

$$\mathbb{E}\chi(p) = \chi(p_0) + \mu(p - p_0)$$

$$\text{Var } \chi(p) = (p - p_0)\sigma^2$$

$$\begin{aligned}\text{Cov}(\chi(p), \chi(q)) &= \text{Var } \chi(p). \\ &= \min\{p - p_0, q - p_0\}\sigma^2\end{aligned}$$

► Back

Coordination and complexity

If $\omega > 0$ and $\alpha > 0$, ‘kinked’ mean-variance decomposition.

Coordination and complexity

With $n = 2$ and $\delta_1 = \delta_2 = 0$, player i 's loss given $p_i \geq p_j \geq p_0$ is

$$\mathbb{E}(\chi(p_i) - \alpha\chi(p_j))^2 = (\mathbb{E}\chi(p_i) - \alpha\mathbb{E}\chi(p_j))^2 + \mathbb{V}\chi(p_i) \\ \underbrace{- 2\alpha\mathbb{C}(\chi(p_i), \chi(p_j))}_{k > 0 \ \& \ \alpha > 0} + \cdots ,$$

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in which:

$$\mathbb{C}(\chi(p_i), \chi(p_j)) = \mathbb{C}(\chi(p_j) + \underbrace{\chi(p_i) - \chi(p_j)}_{\text{increment from } \chi(p_j)}, \chi(p_j)) \\ = \min\{\mathbb{V}\chi(p_i), \mathbb{V}\chi(p_j)\}.$$

(Independent increments = ‘maximum ignorance’, Jovanovic-Rob ’90.)

Endogenous location of the kink: p_j .

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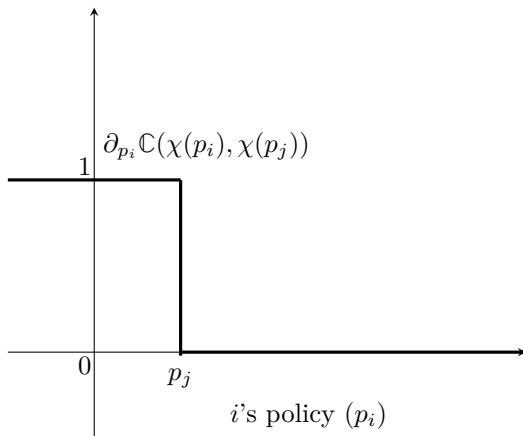
$$\mathbb{C}(\chi(p_i), \chi(p_j)) = \mathbb{C}(\chi(p_j) + \underbrace{\chi(p_i) - \chi(p_j)}_{\text{increment from } \chi(p_j)}, \chi(p_j)) \\ = \min\{\mathbb{V}\chi(p_i), \mathbb{V}\chi(p_j)\}.$$

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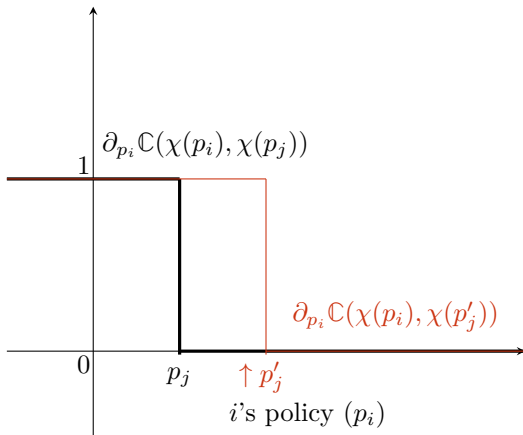
Coordination and complexity

Covariance ($\min\{\mathbb{V}\chi(p_i), \mathbb{V}\chi(p_j)\}$) is supermodular in (p_i, p_j) .



Coordination and complexity

Covariance ($\min\{\mathbb{V}\chi(p_i), \mathbb{V}\chi(p_j)\}$) is supermodular in (p_i, p_j) .



Covariance

$f(p_1, p_2)$ has ***strictly increasing differences*** in p_1 and p_2 if:

$$p'_1 > p_1 \text{ and } p'_2 > p_2 \implies f(p'_1, p'_2) - f(p_1, p'_2) > f(p'_1, p_2) - f(p_1, p_2).$$

Covariance

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$\text{Cov}(\chi(p), \chi(p'))$, for $p_0 = 0$ and $p, p' > 0$, can be:

► Brownian:

$$\min\{p, p'\}\sigma^2; \quad \checkmark$$

► Ornstein-Uhlenbeck:

$$e^{-\frac{|p-p'|}{\ell}}, \ell > 0; \quad \times$$

► Squared exponential:

$$e^{-\left(\frac{p-p'}{\ell}\right)^2}, \ell > 0. \quad \times$$

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