

Assignment 1

Neurorobotics 2024/2025

Objective:

Students are tasked with analyzing data collected during a 3-day Motor Imagery (MI) Brain-Computer Interface (BCI) experiment involving 8 healthy participants.

Data description:

The data was recorded using a 16-channel EEG amplifier (g.USBamp, g.Tec) at a sampling rate of 512 Hz. Electrodes were positioned according to the 10-20 international system. The placement and order of electrodes are illustrated in Figure 1A. Each participant completed at least two recording days:

- **Day 1:** 3 "offline" runs (calibration, without real feedback) and 2 "online" runs (with real feedback).
- **Day 2 and Day 3:** 2 "online" runs per day.

Data Link: [Access the dataset](#)

The task and the visual paradigm:

Participants performed two motor imagery tasks—imagining movements of **both hands** or **both feet**—and a **rest** task. The training visual paradigm is shown in Figure 1B. The color of the cue indicated which motor imagery task to perform (e.g., both hands, both feet, or rest).

- During the **calibration runs**, feedback associated with the cue automatically moved in the correct direction.
- During the **online runs**, feedback movement was determined by the output of the classifier.

Assignments:

Students are required to analyze the data using techniques covered in class. The following analyses must be performed:

1. Grand average analyses on the whole population and on representative subjects
 - a. Process the data using appropriate methods.
 - b. Identify and extract the most relevant features.
 - c. Report the achieved results
2. Analyses on BMI decoding on each subject
 - a. Calibration phase:
 - Consider only the offline runs
 - Process the data, compute the features, select the most discriminant features
 - Create a classifier based on those features
 - b. Evaluation phase:
 - Consider only the online runs
 - Process the data, compute the features, and extract those already selected during the calibration phase
 - Use this data to evaluate the classifier created during the calibration phase
 - Implement and apply an evidence accumulation framework on the posterior probabilities
 - c. Report and discuss the achieved results in terms of (but not limited to): single sample accuracy (offline/online), trial accuracy (offline/online), average time to deliver a command.

Reference:

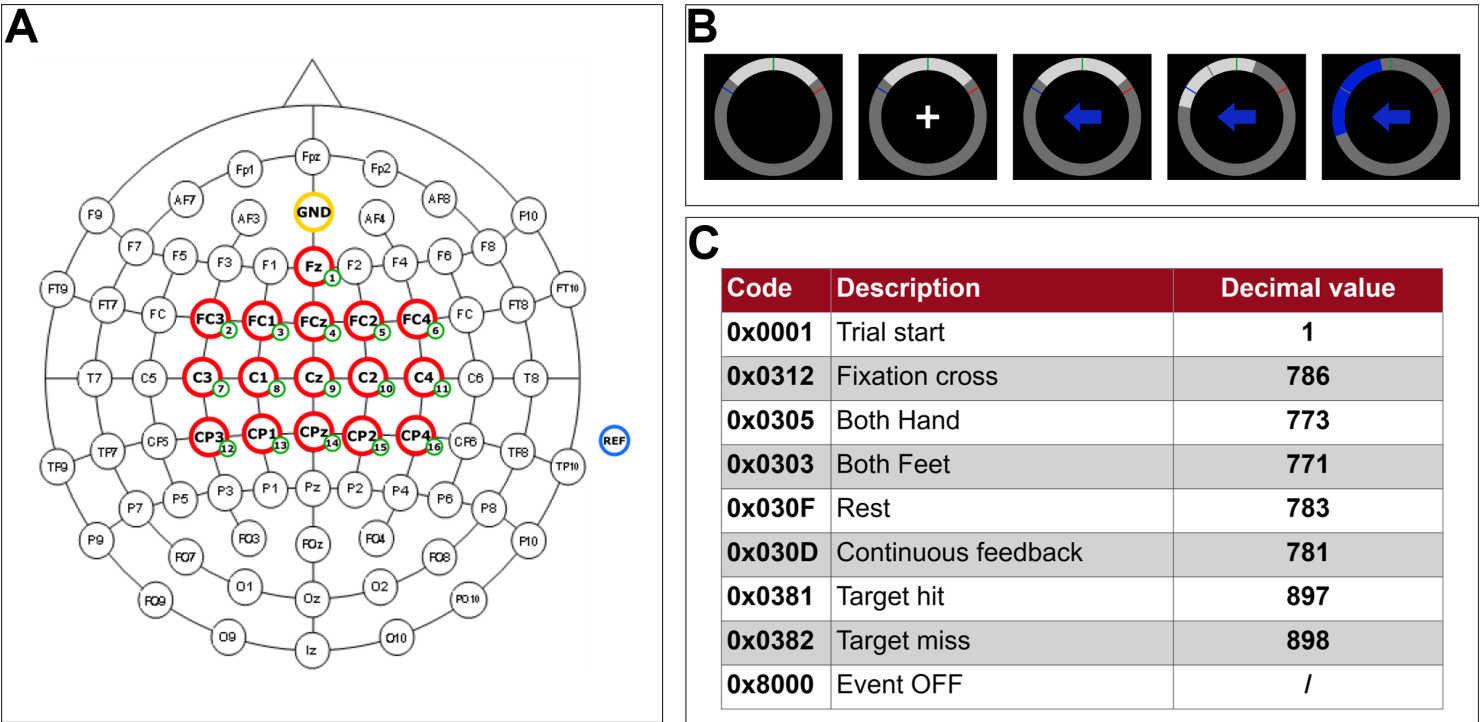
Tonin L et al. The role of the control framework for continuous tele-operation of a BMI driven mobile robot. IEEE Transactions on Robotics, 36(1):78-91, 2020. doi: 10.1109/TRO.2019.2943072

Pfurtscheller G et al. Motor imagery and direct brain-computer communication. Proceedings of the IEEE, 89(7):1123-34, 2001. doi: 10.1109/5.939829

Wolpaw JR et al. Control of a two-dimensional movement signal by a noninvasive brain-computer interface in humans. Proc Natl Acad Sci USA, 101(51):17849-54, 2004. doi: 10.1073/pnas.0403504101

Leeb R et al. Transferring brain-computer interfaces beyond the laboratory: Successful application control for motor-disabled users. Artificial Intelligence in Medicine, 59(2):121-32, 2013. doi: 10.1016/j.artmed.2013.08.004

Perdikis S et al. The Cybathlon BCI race: Successful longitudinal mutual learning with two tetraplegic users. PLOS Biology 16(5):e2003787, 2018. doi: 10.1371/journal.pbio.2003787



Guidelines for the report

1. Format:

- The report must be submitted in **PDF format**
- The report must be accompanied by all MATLAB scripts used to compute the results
- The report must be accompanied by a README file to run the scripts
- Each group member's contribution must be clearly specified in the README file

2. Data:

- **Do not include** raw EEG data or processed data in the submission.

3. Length and Layout:

- Maximum length: **12 pages**, double-column format
- Margins:
 - Top: **1.5 cm**
 - Bottom: **1.3 cm**
 - Inner: **1.5 cm**
 - Outer: **1.5 cm**

4. Content Requirements:

- **Methods:** Provide a clear justification for all methods used.
- **Results:** Present results clearly and comprehensively.

5. Plagiarism Check:

- A plagiarism check will be conducted on both the report and the submitted MATLAB code.