

Introduction to Model Checking

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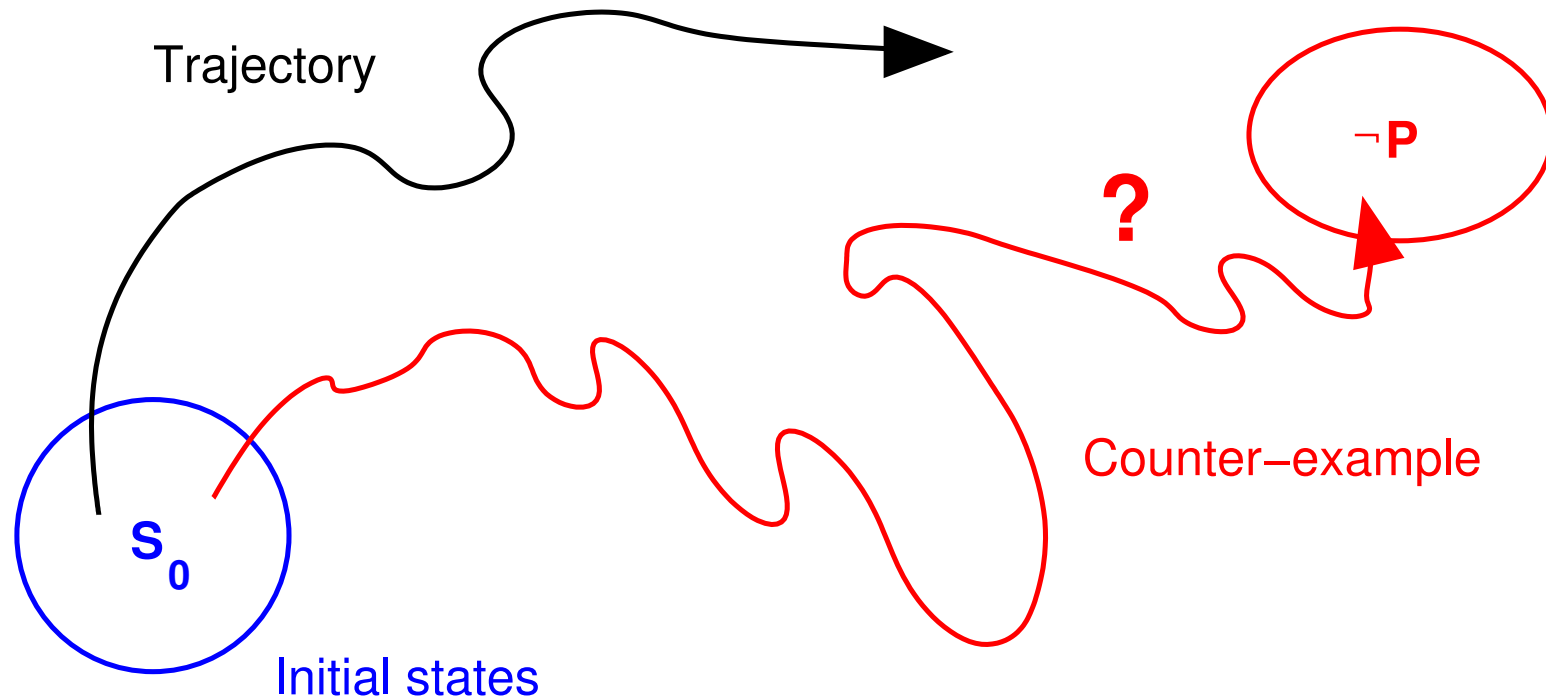
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Goal: Compute all possible system behaviors

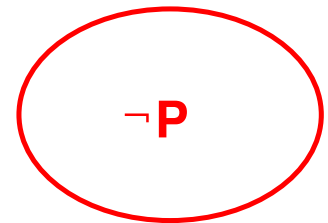
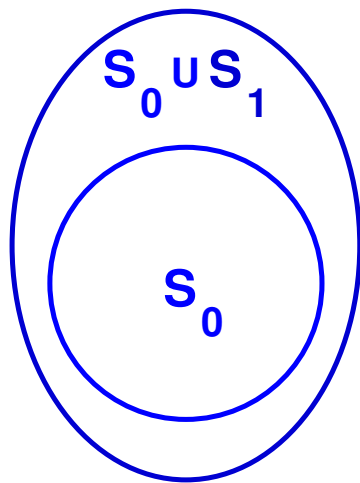
- ◆ **Question:** All possible outcomes of a program execution.
No matter what the inputs/parameters are.
- ◆ **Answer:** Enumerate all possibilities! → Model Checking.
- ◆ Alternative: Reason about all outcomes (theorem proving).

Model Checking = state space search

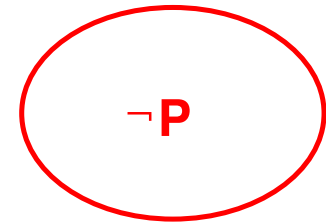
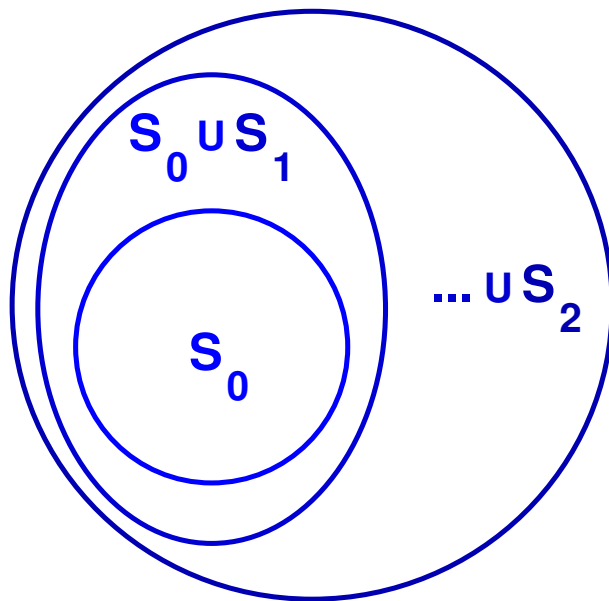


- ◆ Traditionally applied to specifications, protocols, algorithms.
- ◆ Certain types of software (embedded) can be mapped to such model checkers.

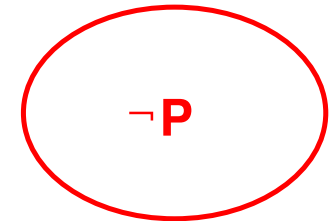
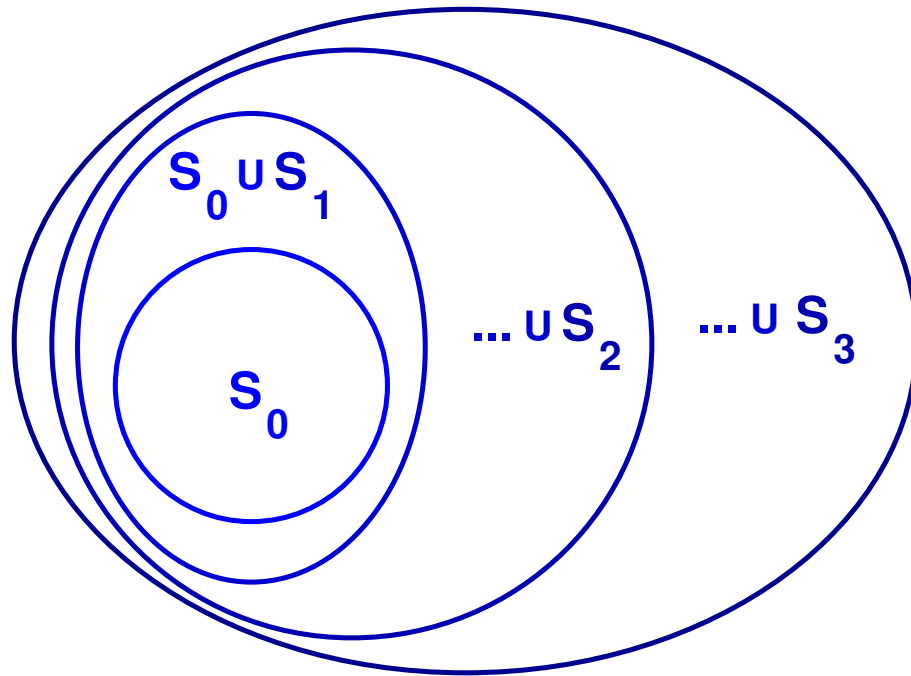
State space search



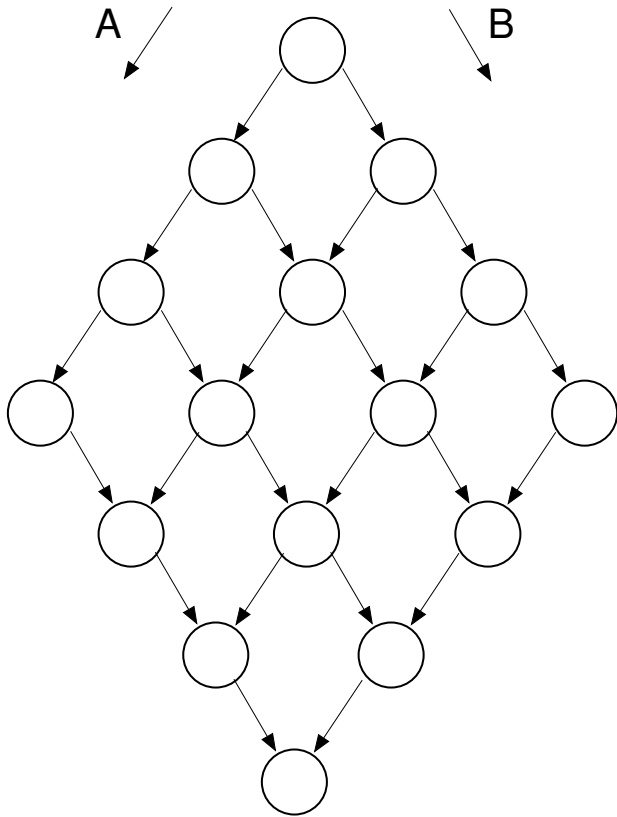
State space search — 2



State space search — 3



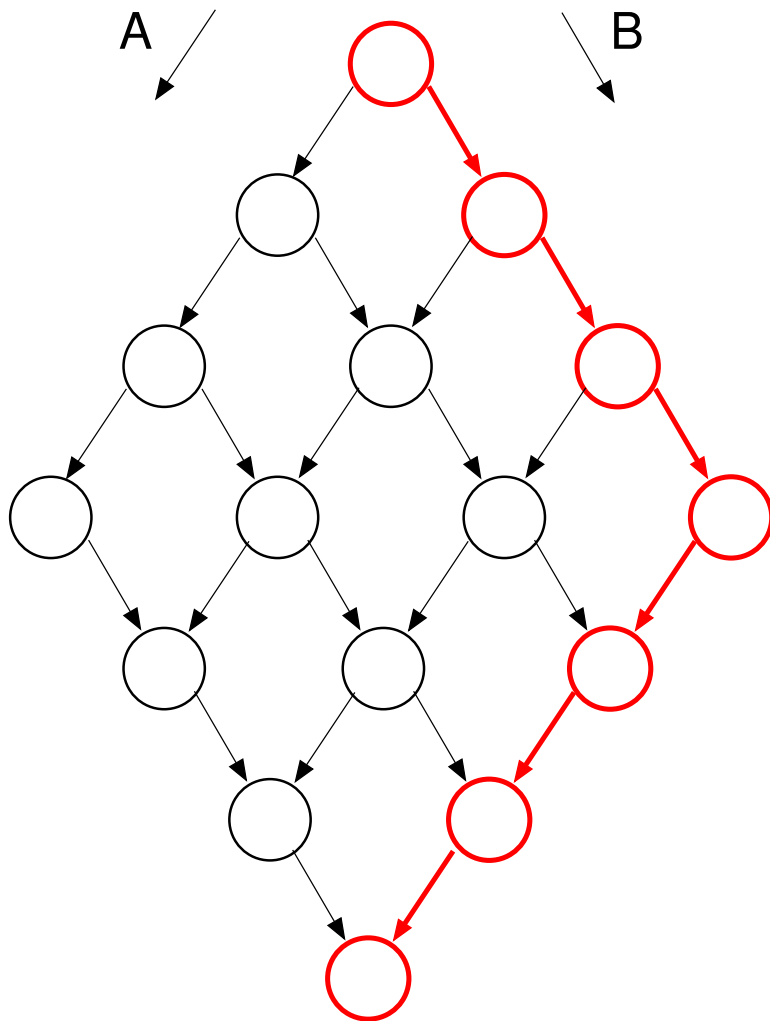
Problem: State space explosion!



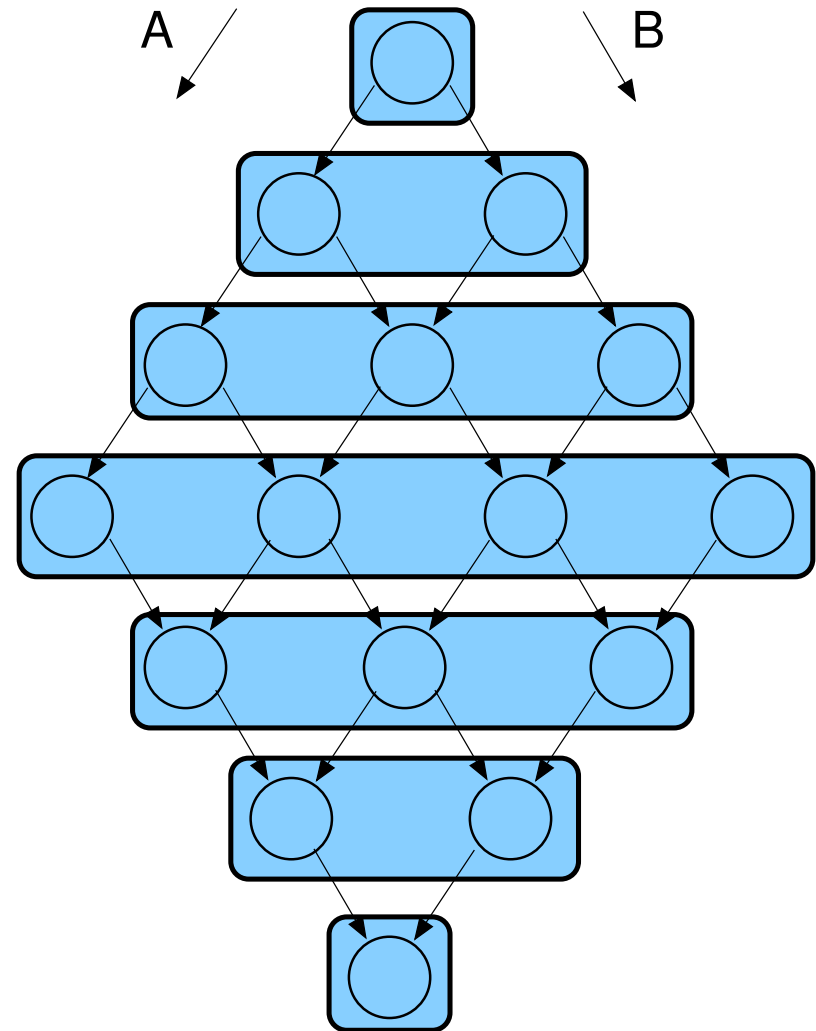
- ◆ Process state space exponential in the size of the state.
- ◆ Cross-product of processes.

Remedies

Partial-order reduction



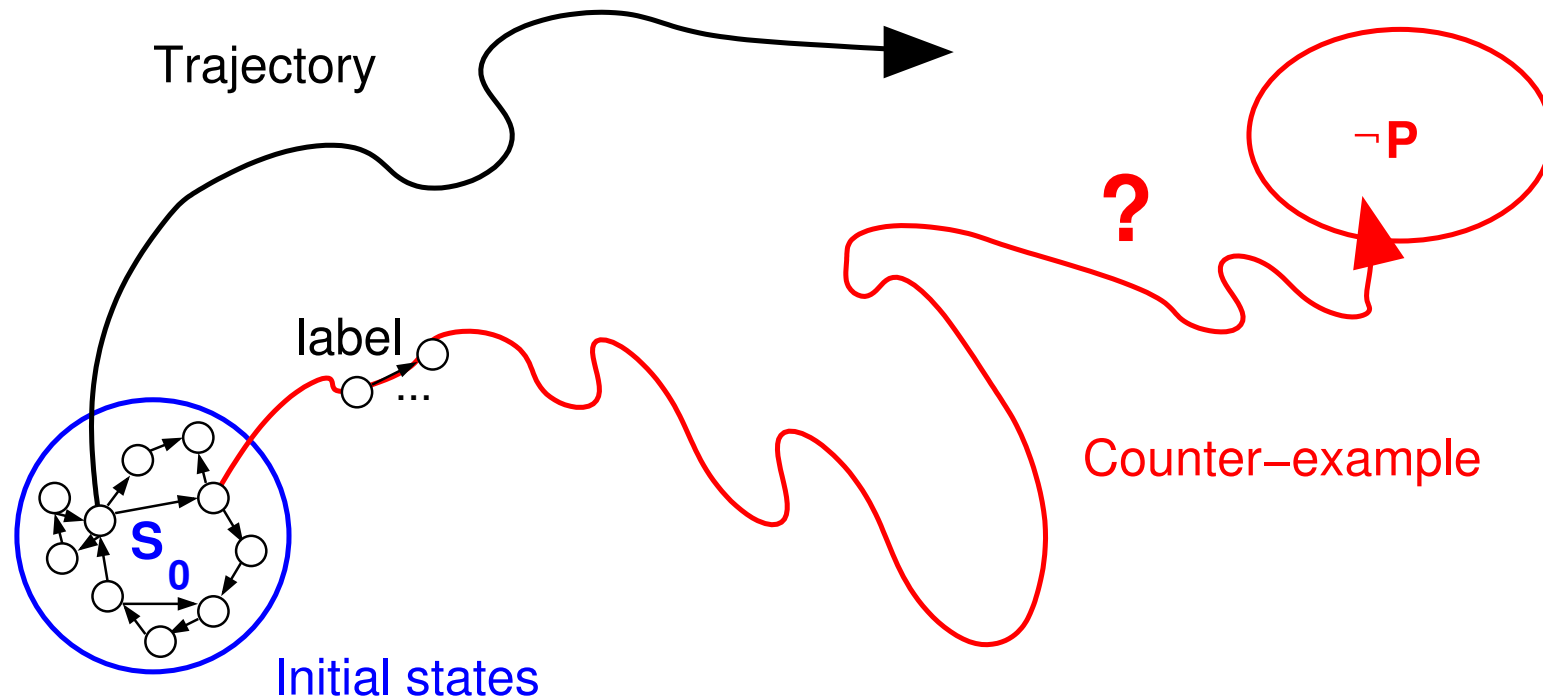
System abstraction



Outline

1. The structure of common models: Kripke structures.
2. How to write (temporal) properties:
 - (a) Linear Temporal Logic (LTL).
 - (b) Computation Tree Logic (CTL).
3. How to implement a model checker (key ideas):
 - (a) Explicit-state model checking (SPIN).
 - (b) Binary Decision Diagrams (BDDs).
 - (c) Symbolic model checking/NuSMV.

How to define models: Kripke structures



State transition system $M = (S, S_0, R, L)$.

Each transition affects AP : atomic properties.

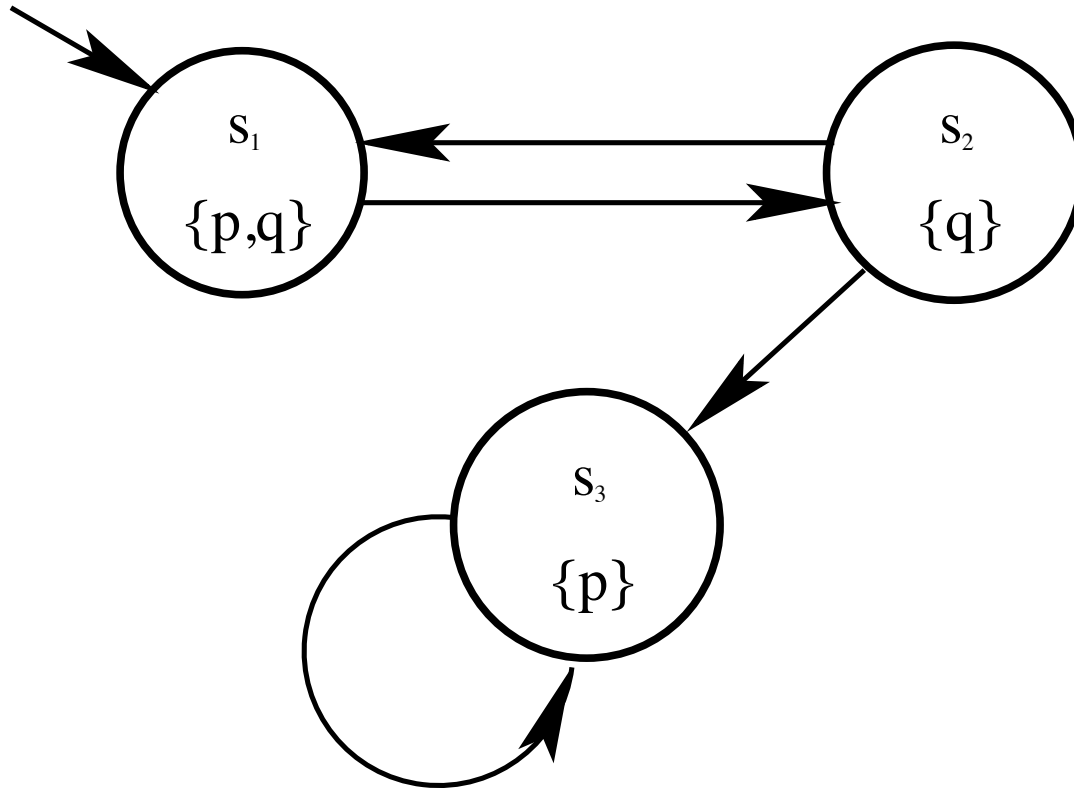
S : set of states

$R : S \times S$: transition relation

S_0 (or I): set of initial states L : set of (action) labels: $S \rightarrow 2^{AP}$

2^{AP} : power set: each atomic property is true or false at given state.

Example (by Ashutosh Gupta)



$$S = \{s_1, s_2, s_3\}$$

$$I = \{ \quad \}$$

$$R = \{(s_1, s_2), (s_2, s_1),$$
$$\quad \}$$

$$L = \{(s_1, \{p, q\}),$$
$$\quad \}$$

Fill in the gaps

Give some example paths that this system can generate!

Words generated by transition systems

- ◆ Example: $\{p, q\}, \{q\}, \{p, q\}, \{q\}, \{p\}, \dots$
- ◆ Words can be infinitely long.
- ◆ We need to reason about words (sequence of atomic properties).

How model is designed

- ◆ We typically think of a „state” as certain (state) variables having certain values.
- ◆ State transitions have preconditions and actions (more in next lecture).
- ◆ Model checker translates this into (simpler but larger) Kripke structure.
- ◆ Efficient algorithms to check reachability (more on that soon).
- ◆ We could just label „bad” states but that’s not convenient.

How to describe properties?

Linear Temporal Logic (LTL)

1. **Propositions:** $p, \neg p, p \wedge q, p \vee q$ (also for subformulas)

2. **Temporal operators**

X next \bigcirc

U until

F finally \Diamond

G globally \Box

Other operators exists but they are not used quite as frequently, and can be derived from the ones above.

Semantics: defined on *paths*

1. **Propositions:** $p, \neg p, p \wedge q, p \vee q$ (also for subformulas)

Formula p is true if p holds in first state: $w \models p$ if $p \in w(0)$

Negation: $w \models \neg p$ if $w \not\models p$; conjunct: $w \models p \wedge q$ if $w \models p$ and $w \models q$

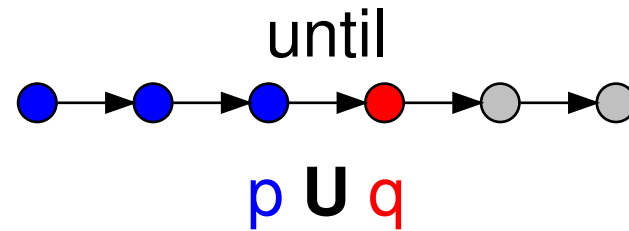
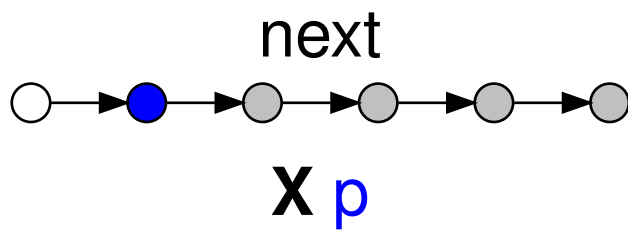
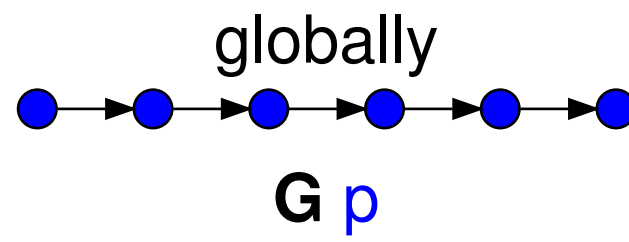
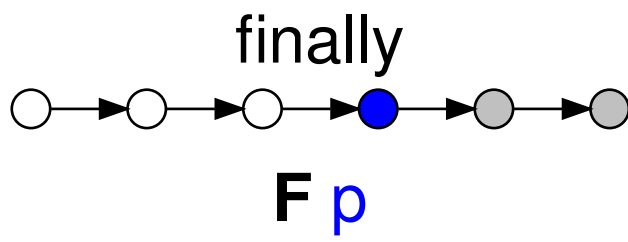
2. **Temporal operators**

$\mathbf{X} p$	next	$\bigcirc p$	$w \models \mathbf{X} p$ if $w_1 \models p$
$p \mathbf{U} q$	until		$\exists j \geq 0, w_j \models q \wedge \forall i, 0 \leq i < j, w_i \models p$
$\mathbf{F} p$	finally	$\Diamond p$	$\text{true U } p$, equivalent to $\exists j \geq 0, w_j \models p$
$\mathbf{G} p$	globally	$\Box p$	$\neg \mathbf{F} \neg p$, equivalent to $\forall j \geq 0, w_j \models p$

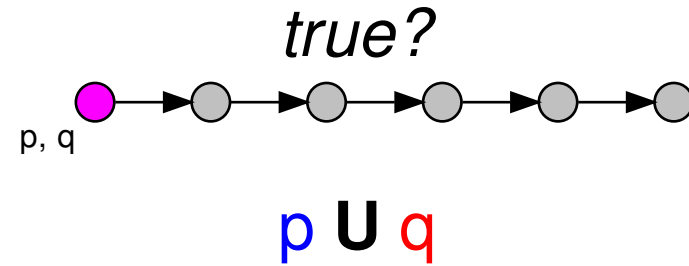
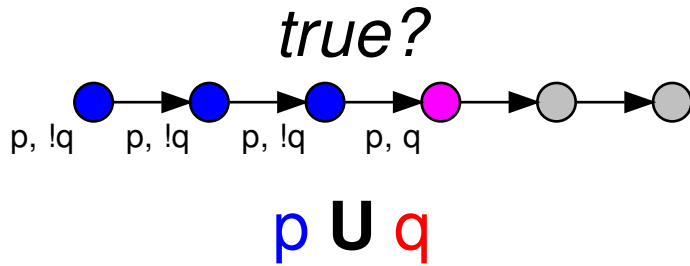
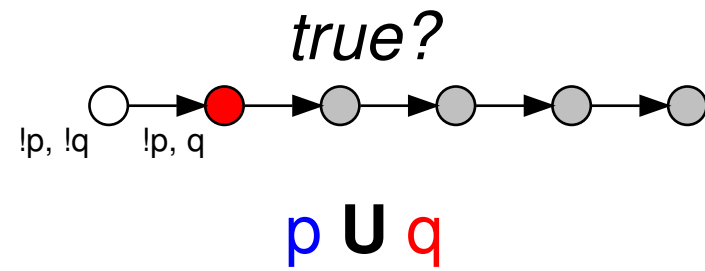
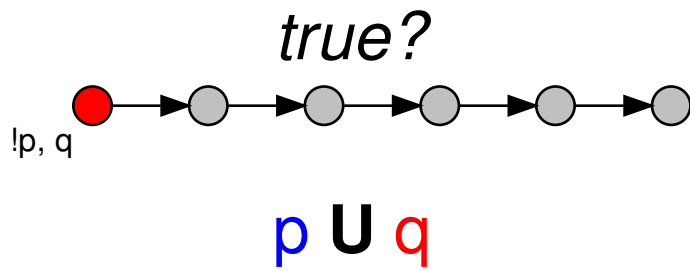
3. **Temporal operators can be nested.**

Furthermore, instead of just atomic propositions for p and q , we can also use other temporal formulas as subexpressions.

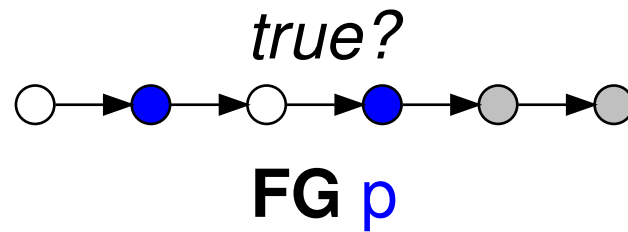
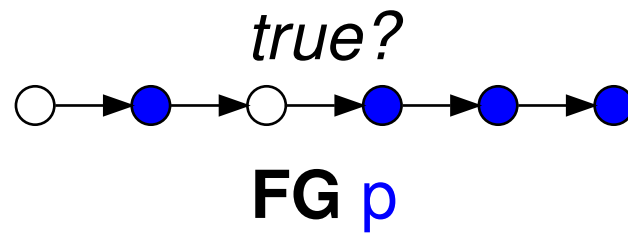
Examples



Until



Nesting

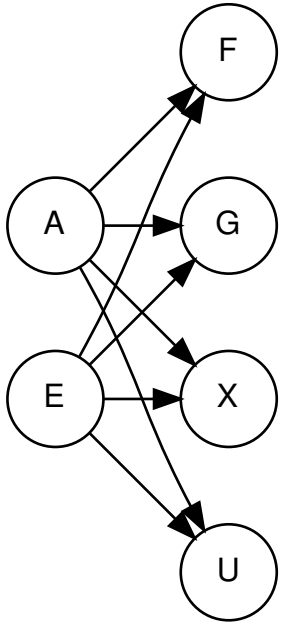


How about infinite traces?

Computation Tree Logic

1. Propositions

2. Path quantifiers + temporal operators



AF p : For all paths, p is eventually true.

AG p : For all paths, p is always true.

AX p : For all paths, p is true in the next state.

A $[p \textbf{U} q]$: For all paths, p holds until q holds.

E: There exists a path...

3. Temporal operators always follow path quantifier

Semantics: Defined on *transition systems*

1. **Propositions:** same as above

2. **Temporal operators** for model $M(S, \rightarrow, L)$

$$\mathbf{AX} \ p \quad ((M, s) \models \mathbf{AX} p) \Leftrightarrow (\forall \langle s \rightarrow s_1 \rangle ((M, s_1) \models p))$$

$$\mathbf{AG} \ p \quad ((M, s) \models \mathbf{AG} p) \Leftrightarrow (\forall \langle s_1 \rightarrow s_2 \rightarrow \dots \rangle (s = s_1) \forall i ((M, s_i) \models p))$$

$$\mathbf{AF} \ p \quad ((M, s) \models \mathbf{AF} p) \Leftrightarrow (\forall \langle s_1 \rightarrow s_2 \rightarrow \dots \rangle (s = s_1) \exists i ((M, s_i) \models p))$$

$$\mathbf{A} [p \ \mathbf{U} \ q] \quad ((M, s) \models \mathbf{A} [p \ \mathbf{U} \ q]) \Leftrightarrow \forall (\langle s_1 \rightarrow s_2 \rightarrow \dots \rangle (s = s_1) \exists j \\ ((M, s_j) \models q) \wedge (\forall (i < j) (M, s_i) \models p))$$

E... defined analogously with existential path quantifier.

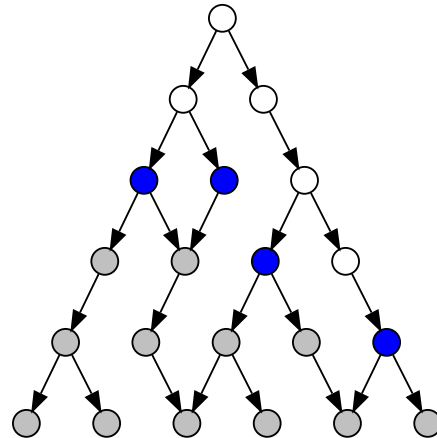
3. **Temporal operators canNOT be directly nested.**

However, instead of just atomic propositions for p and q , we can also use other temporal formulas as subexpressions.

Computation Tree Logic (CTL): finally, globally

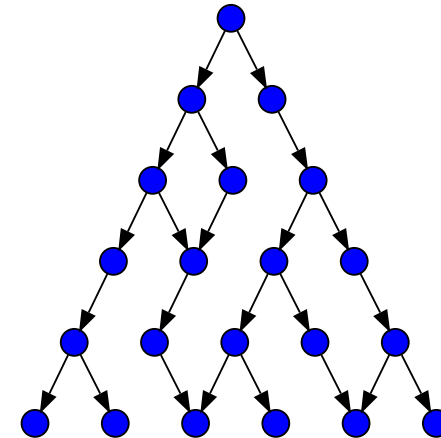
for
all
paths

finally



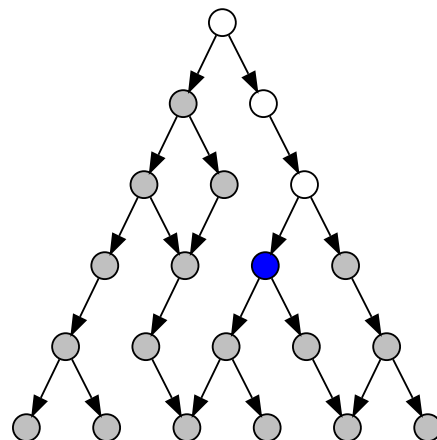
AF p

globally

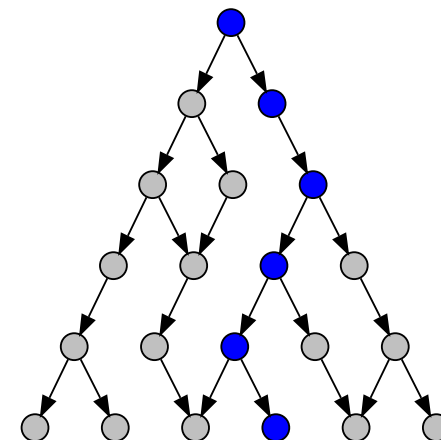


AG p

there
exists
a path



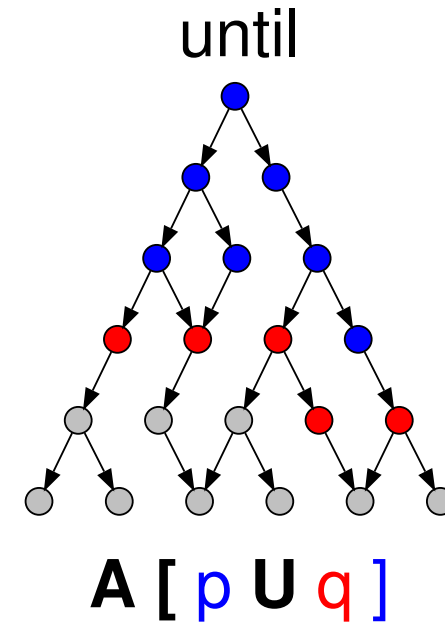
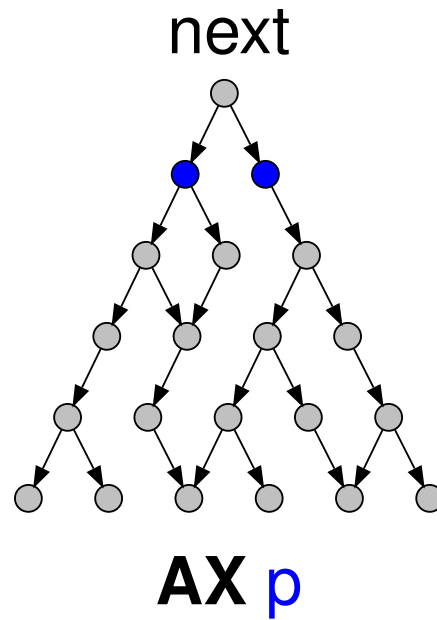
EF p



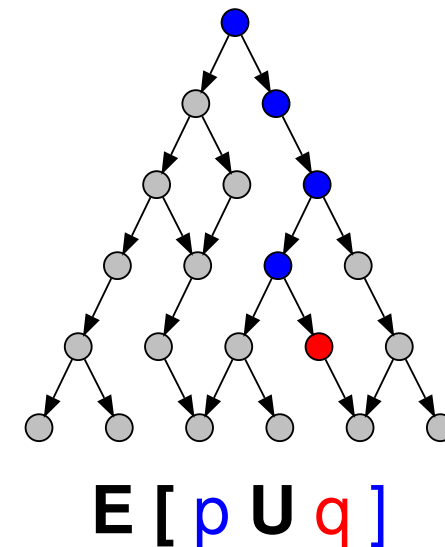
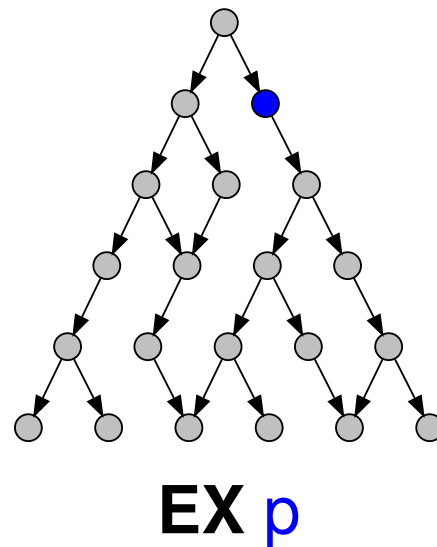
EG p

Computation Tree Logic (CTL): next, until

for
all
paths



there
exists
a path



LTL \neq CTL

1. **FG**(p)

2. **EX**(p)

- ◆ *Which logic can express the formulas above?*
- ◆ *What is the semantics of each formula?*
- ◆ *Where does the counterpart fail to express it?*

CTL* : Combines LTL and CTL.

Safety vs. Liveness

Safety: Something bad will never happen.

Ensures absence of defects and hazards.

Liveness: Something good eventually happens.

Ensures progress.

Which temporal logic operators are suitable for which type of property?

Summary

Temporal logics

Linear temporal logic (LTL):

- ◆ No branching.
- ◆ Defined on paths.

Computational tree logic (CTL):

- ◆ Branching.
- ◆ Defined on transition systems.

Model checking

Enumerate all reachable states.

- ◆ Check if „bad” state reachable.
- ◆ Active research, many optimizations (such as BDDs).

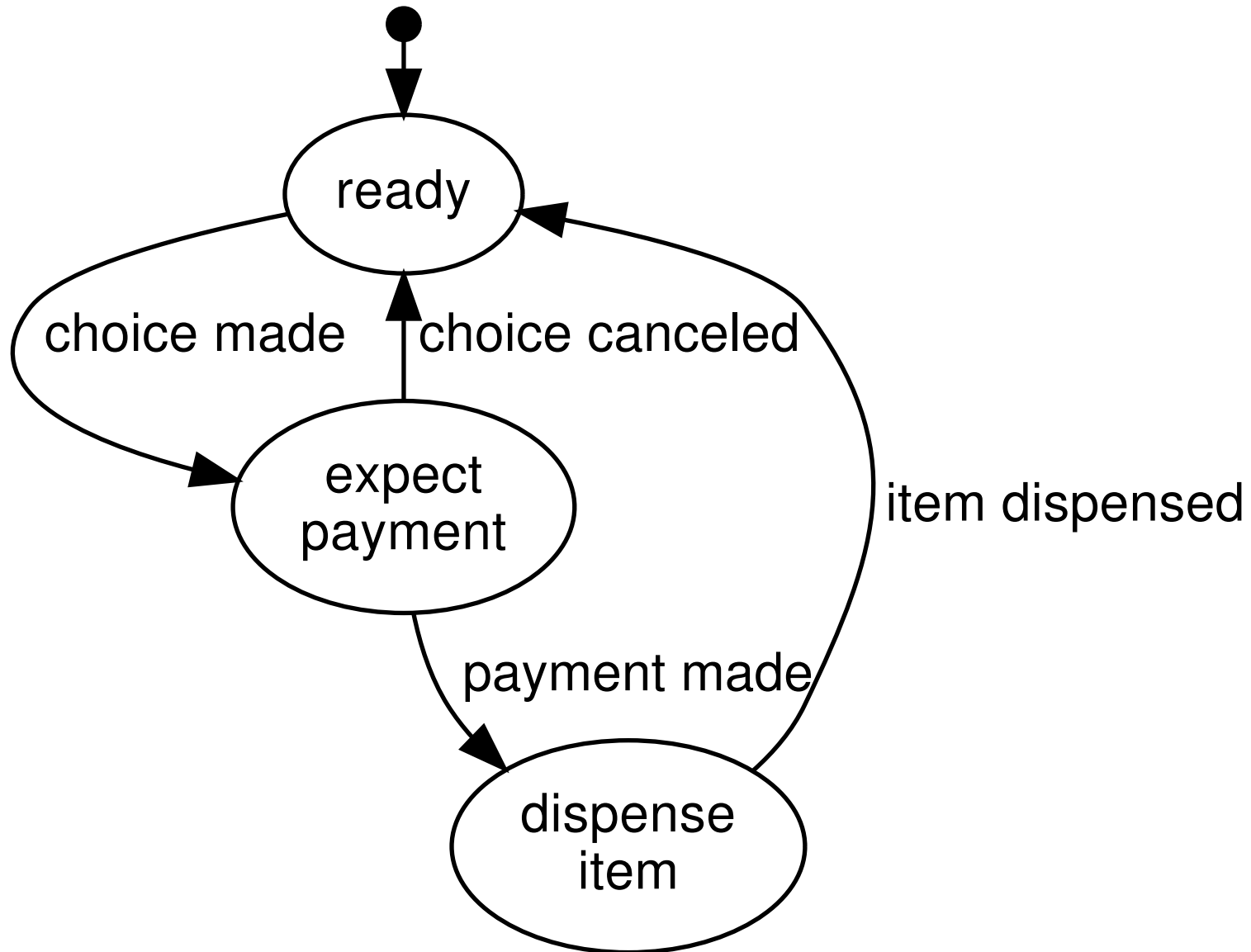
SMV and NuSMV

- ◆ Symbolic Model Verifier (SMV):
First practical symbolic model checker by Ken McMillan/CMU.
- ◆ Re-implementation NuSMV (open source) at IRST Trento, Italy.
- ◆ NuSMV is still being maintained and developed.
- ◆ Current version is 2.6.0 (used in this course).

NuSMV

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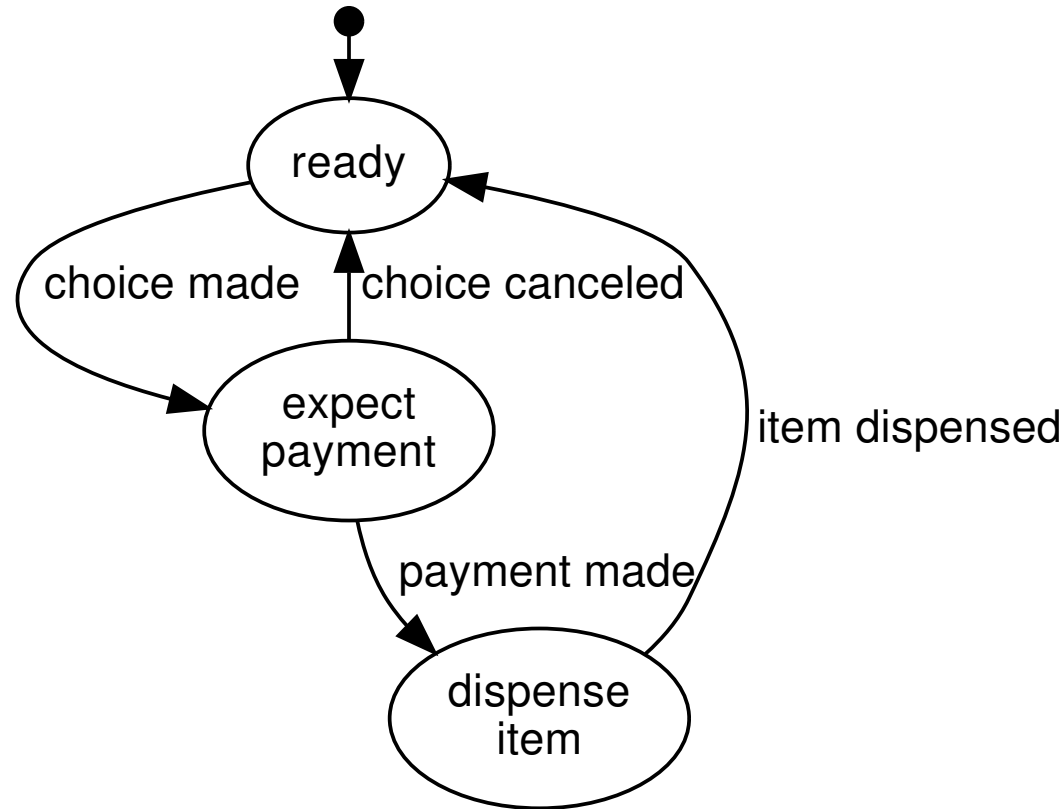
Example: Vending machine



Details not modeled

- ◆ How choice is made (how many choices) and canceled.
→ Button, timeout, both?
- ◆ How payment is handled/accepted; price of goods.
- ◆ Item dispenser mechanism, time taken to dispense item.

Example: Vending machine—2



- ◆ Three states: ready, expect_payment, dispense_item.
- ◆ Two user inputs (non-deterministic):
 1. Choice (of item); can be cancelled.
 2. Payment (requires choice to be made first).

Vending machine in NuSMV

```
MODULE main
VAR
  choice, payment:  boolean;
  state:  { ready, expect_payment, dispense_item };
ASSIGN
  init (state) := ready;
  next (state) := case
    state = ready          & choice:  expect_payment;
    state = expect_payment & payment: dispense_item;
    state = expect_payment & !choice: ready;
    state = dispense_item:  ready;
  esac;
```

NuSMV syntax

- ◆ Module, variables, assignments.
- ◆ case (follows order of declaration); can have multiple outcomes.

Error message

```
file vending.smv: line 3: at token ",": syntax error  
file vending.smv: line 3: Parser error  
NuSMV terminated by a signal
```

- ◆ Cannot declare more than one variable per line!
- ◆ Try again...

Another error message

file vending.smv: line 14: case conditions are not exhaustive

◆ Recall the **case** block:

```
state = ready          & choice: expect_payment;  
state = expect_payment & payment: dispense_item;  
state = expect_payment & !choice: ready;  
state = dispense_item: ready;
```

◆ State should remain the same by default: specify!

Complete case block

ASSIGN

```
init (state) := ready;
next (state) := case
    state = ready          & choice: expect_payment;
    state = expect_payment & payment: dispense_item;
    state = expect_payment & !choice: ready;
    state = dispense_item:  ready;
    TRUE:                  state;
esac;
```

- ◆ Transitions from ready and expect_payment depend on user choice.
- ◆ Cancellation is modeled as **choice** reverting to **false**.
- ◆ Transition from dispense_item back to ready is automatic.

Run NuSMV

- ◆ Nothing happens!
- ◆ We need properties...

LTLSPEC

`G(choice -> F state = dispense_item);`

- ◆ „Every time I choose something, I eventually get it”.

Nice try!

```
-- specification
  G (choice -> F state = dispense_item)  is false
-- as demonstrated by the following execution sequence
Trace Description: LTL Counterexample
Trace Type: Counterexample
  -- Loop starts here
-> State: 1.1 <-
    choice = TRUE
    payment = FALSE
    state = ready
-> State: 1.2 <-
    choice = FALSE
    state = expect_payment
-> State: 1.3 <-
    choice = TRUE
    state = ready
```

OK, I'll pay...

LTLSPEC

```
G(payment -> F state = dispense_item);  
-- specification  
G (payment -> F state = dispense_item) is false  
-- as demonstrated by the following execution sequence  
Trace Description: LTL Counterexample  
Trace Type: Counterexample  
-- Loop starts here  
-> State: 1.1 <-  
    choice = FALSE  
    payment = TRUE  
    state = ready  
-> State: 1.2 <-
```

◆ State 1.2: no progress.

◆ Payment is accepted even when no choice has been made!

Accept payment only when choice is made

```
MODULE main
```

```
VAR
```

```
    choice:  boolean;
```

```
    payment: boolean;
```

```
    acc_payment: boolean;
```

```
    state:    { ready, expect_payment, dispense_item };
```

```
ASSIGN
```

```
    init (state) := ready;
```

```
    next (state) := case
```

```
        state = ready           & choice:  expect_payment;
```

```
        state = expect_payment & acc_payment: dispense_item;
```

```
        state = expect_payment & !choice: ready;
```

```
        state = dispense_item:    ready;
```

```
        TRUE:                      state;
```

```
    esac;
```

```
    init (acc_payment) := FALSE;
```

```
    next (acc_payment) := (state = expect_payment & payment);
```

Another problem?!

G (acc_payment -> F state = dispense_item) is false

```
-> State: 1.1 <-  
  choice = FALSE  
  payment = FALSE  
  acc_payment = FALSE  
  state = ready  
-> State: 1.2 <-  
  choice = TRUE  
-> State: 1.3 <-  
  choice = FALSE  
  payment = TRUE  
  state = expect_payment  
-> State: 1.4 <-  
  payment = FALSE  
  acc_payment = TRUE  
  state = ready  
-- Loop starts here  
-> State: 1.5 <-  
  acc_payment = FALSE  
-> State: 1.6 <-
```

State 1.3: Choice is made,
next state = accept payment

State 1.4: accepting payment,
but choice is canceled just now!

- ◆ Need a way to prevent this transition back to *ready*.
- ◆ Use stricter **case** condition!
- ◆ Lab exercise 1.

Extension of the vending machine

- ◆ Limited capacity of n items.
- ◆ Payment should not be accepted when no items available.
- ◆ Counting down items:

```
next(n_items) := case
  ...: n_items - 1;
  TRUE: n_items;
esac;
```

- ◆ Fails!

```
file vending3.smv: line 16:
  cannot assign value -1 to variable n_items
```

Counting without over- or underflow

- ◆ NuSMV recognized possible over- or underflow at compile time.

```
next(n_items) := case
    ... & n_items > 0: n_items - 1;
    TRUE: n_items;
esac;
```

- ◆ Underflow needs to be prevented in code.

Additional properties

1. Number of items should always be ≥ 0 .
2. Payment should only be accepted if number of items > 0 .
3. If an item is dispensed, the counter of items is always reduced by 1.

First lab exercise (part of assignment 1): Summary

1. Use NuSMV on `vending1.smv`.
 - (a) Study error trace.
 - (b) Refine transition (**case** condition).
2. Counting remaining items.
 - (a) Add a counter `n_items` (see above).
 - (b) Write LTL or CTL properties for the three properties above.
 - (c) Ensure your model fulfills all properties.

Assignment: Install NuSMV

1. Download NuSMV from

`http://nusmv.fbk.eu/NuSMV/download/getting-v2.html`

2. Install a binary or download the source:

(a) `cd /tmp`

(b) `tar -xzf ~/Downloads/NuSMV-2.6.0.tar.gz`

(c) `cd NuSMV-2.6.0/NuSMV`

(d) `mkdir build`

(e) `cd build`

(f) `cmake .. -DCMAKE_INSTALL_PREFIX=/path/to/binary`

(g) `make`

(h) `make install`

(i) include `/path/to/binary` in `PATH` if needed