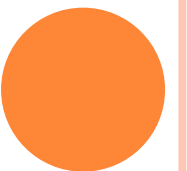


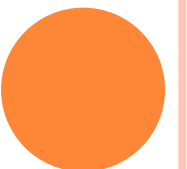
Priority Queues

Computing 2 COMP1927 13s2



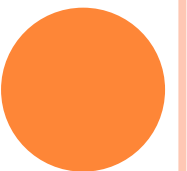
PRIORITY

- Some applications of queues require items processed in order of "key" or priority
- rather than in order of entry (FIFO)
- Priority Queues (PQueues or PQs) provide this via:
 - insert item into PQ
 - leave: remove item with highest priority key
 - Highest priority key may be one with smallest or largest value depending on the application
- Plus generic ADT operations: new, drop, empty, ...



PRIORITY QUEUES

- Characteristic priority queue (PQ) operations:
 - insert item
 - delete item with highest priority key
 - Highest priority key may be the smallest or largest key depending on the application
- Along with generic ADT operations, such as:
 - create new queue
 - test if queue is empty
 - destroy existing queue (reclaim memory)



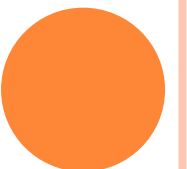
PRIORITY QUEUE INTERFACE

```
typedef struct priQ * PriQ;

//We assume we have a more complex Item type that has
//a key and a value, where the key is the priority and the
//value is the data being stored

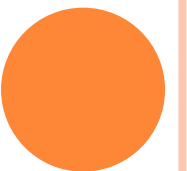
// Core operations
PriQ initPriQ(void);
void insert(PriQ q, Item i);
//retrieve and delete Item with highest priority
Item delete(PriQ q);

// Useful operations
int sizePriQ(PriQ q);
void changePriority(PriQ q, Key k, Item i);
void deleteKey(PriQ q, Key k);
int maxSize(PriQ q);
```



HEAP SORT : SORTING BY PQS

- PQs do partial sorting. Can we use them for full-sorting?
- Two-stage process:
 - put all elements from array into priority queue
 - one-at-a-time, delete maximum and add to sorted array
- Since each PQ operation (when implemented via a heap) is $\log_2 n$
 - overall cost is $O(n \log_2 n)$



COMPARISON OF POSSIBLE IMPLEMENTATIONS

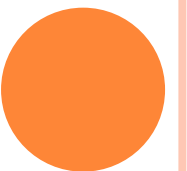
Implementation	insert	delete
ordered array/list	$O(N)$	$O(1)$
unordered array/list	$O(1)$	$O(N)$

- Can we implement BOTH operations efficiently?
 - Heap
 - $O(\log N)$ for insert and delete



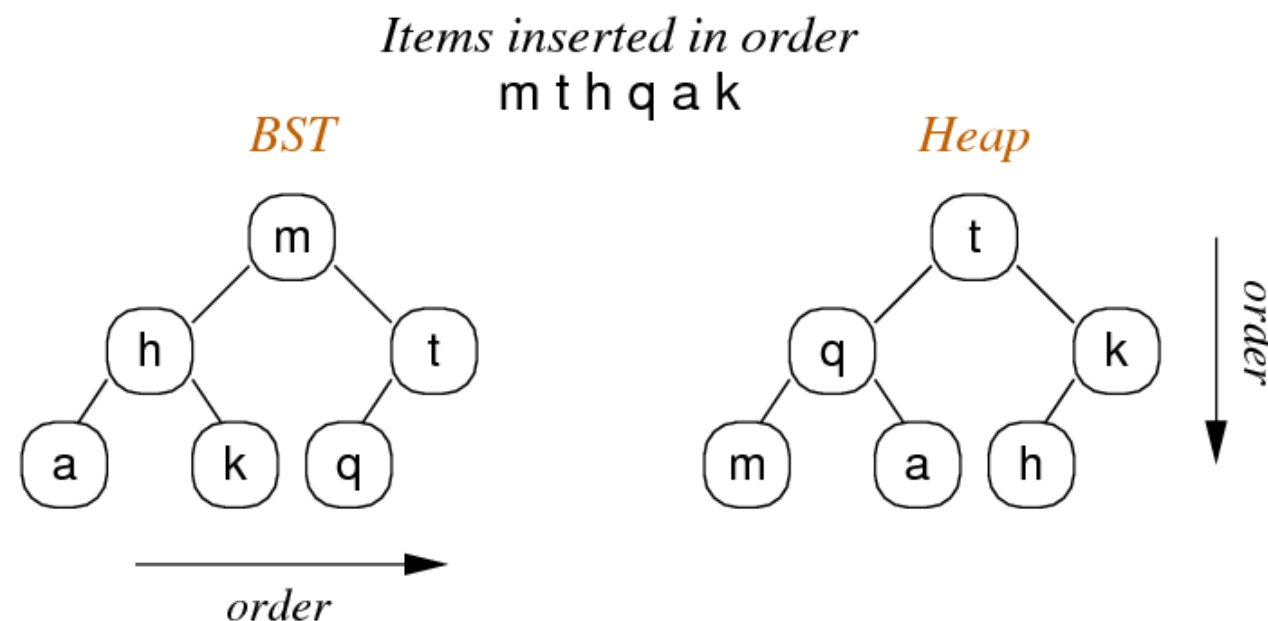
PRIORITY QUEUE SORT ALGORITHM

```
void pqSort(Item a[], int lo, int hi) {  
    int i;  
    PriQ q = initPriQ();  
    // put items into PQ  
    for (i = lo; i <= hi; i++) {  
        insert(q, a[i]);  
    }  
    // remove items from PQ  
    for (i = hi; i >= lo; i--) {  
        a[i] = delete(q);  
    }  
}
```



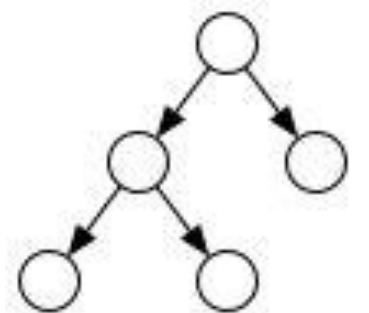
HEAPS

- Heaps can be viewed as trees with top-to-bottom ordering
 - Heap-ordered trees
 - for all keys both subtrees are \leq root
 - property applies to all nodes in tree (i.e. root contains largest value in that subtree)

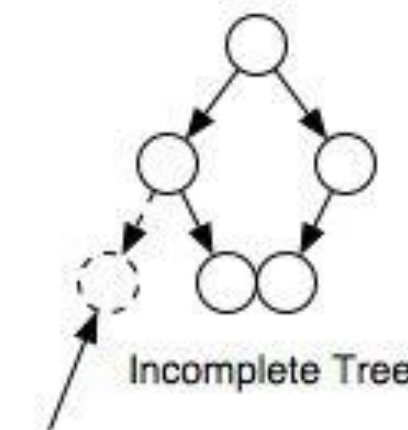


COMPLETE TREE PROPERTY

- Heaps are "complete trees"
 - every level is filled in before adding a node to the next level
 - the nodes in a given level are filled in from left to right, with no breaks.

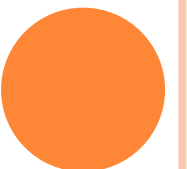


Complete Tree



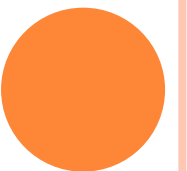
Incomplete Tree

Missing Node Here



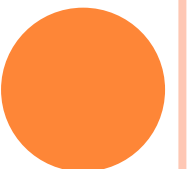
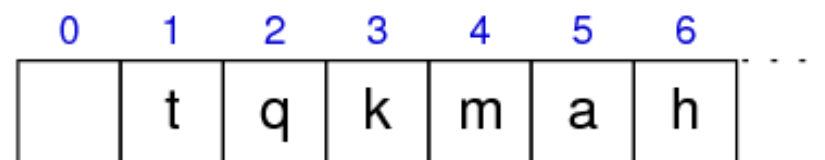
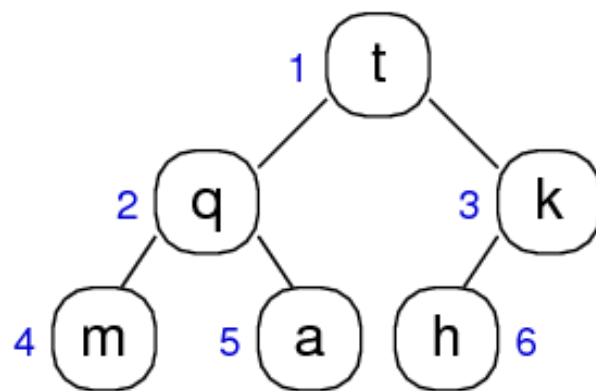
HEAP IMPLEMENTATIONS

- BSTs are typically implemented as linked data structures
- Heaps CAN be implemented as linked data structures
 - Heaps are TYPICALLY implemented via arrays.
 - The property of being **complete** makes array implementations suitable



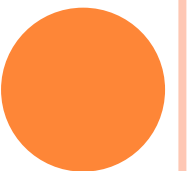
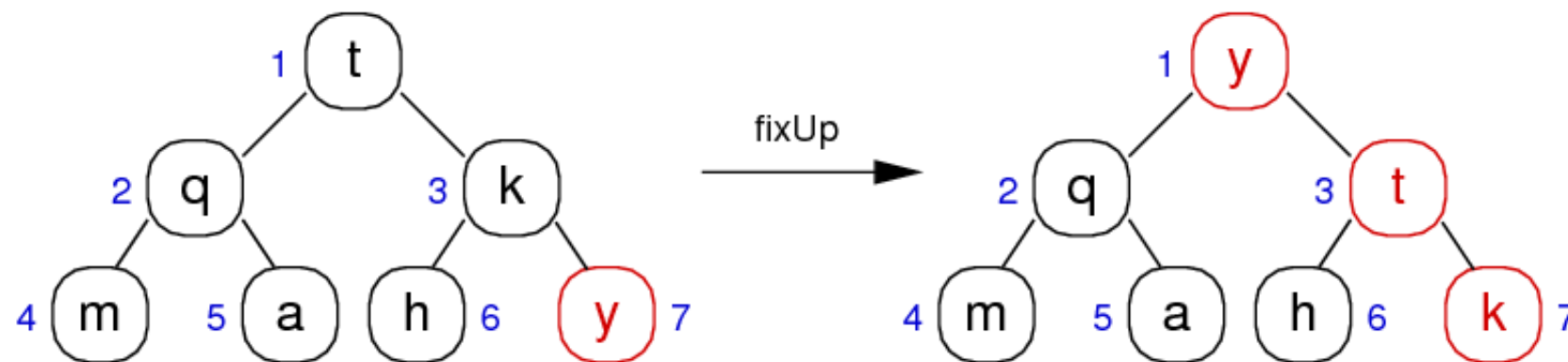
ARRAY BASED HEAP IMPLEMENTATION

- Simple index calculations allow navigation through the tree:
 - left child of node at index i is located at $2i$
 - right child of node at index i is located at $2i+1$
 - parent of node at index i is located at $i/2$



HEAP INSERTION

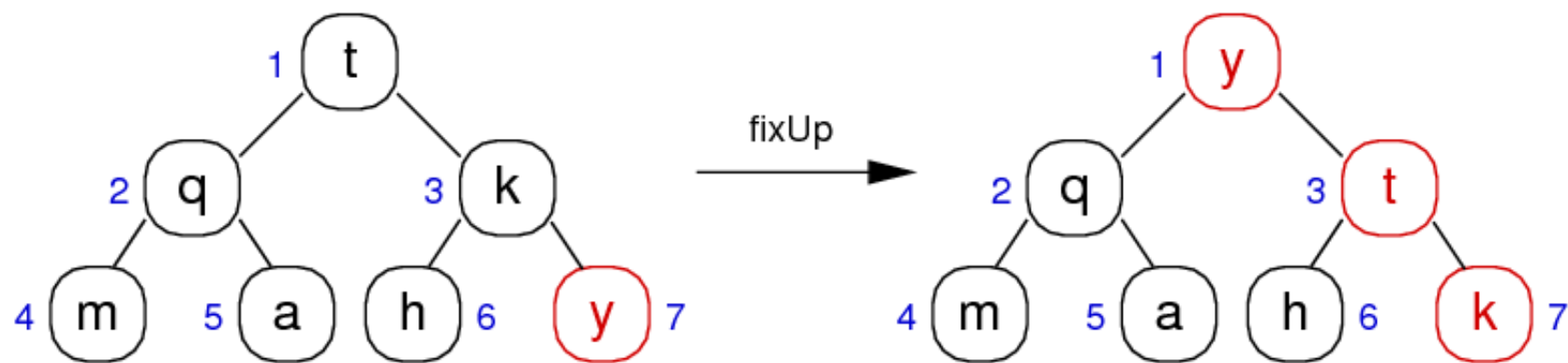
- Insertion is a two-step process
 - add new element at bottom-most, rightmost position
 - reorganise values along path to root to restore heap property



HEAP INSERTION FIX-UP CODE

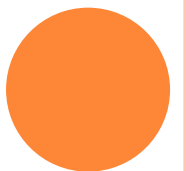
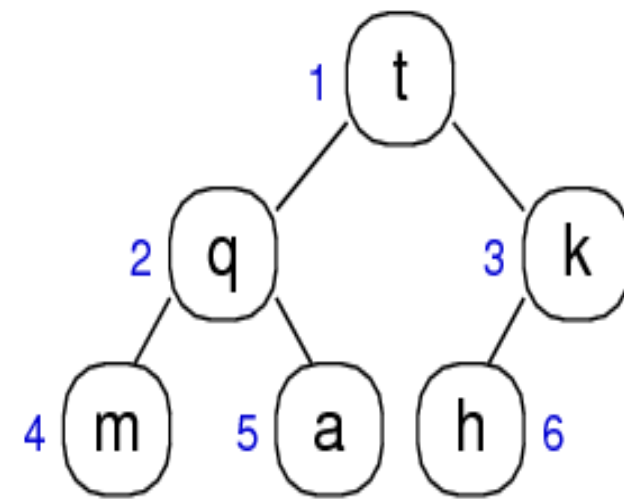
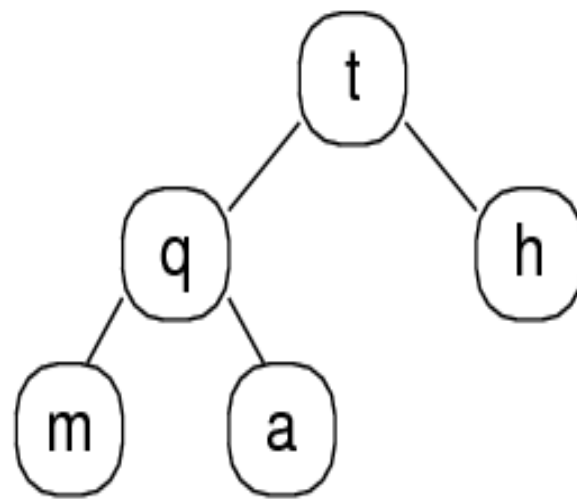
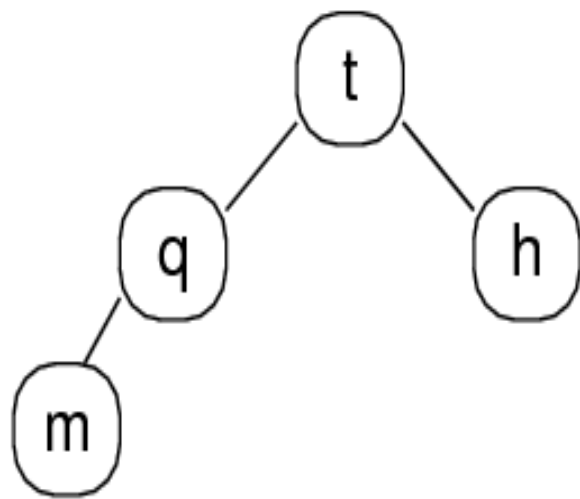
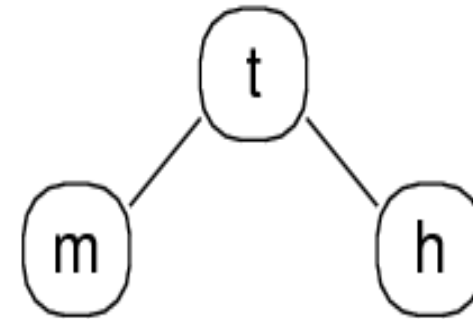
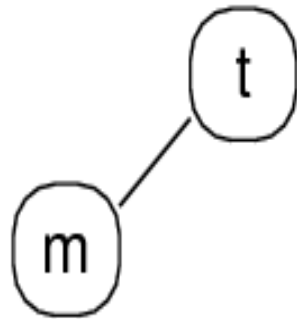
- Bottom-up heapify:

```
// force value at a[k] into correct position
void fixUp(Item a[], int k) {
    while (k > 1 && less(a[k/2], a[k])) {
        swap(a, k, k/2);
        k = k/2; // integer division
    }
}
```



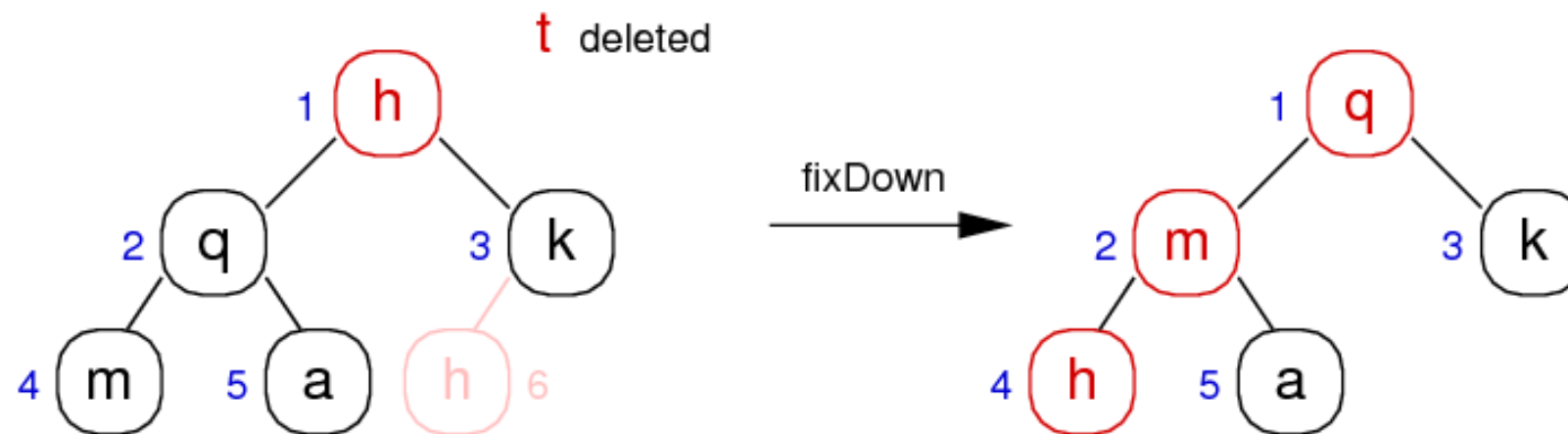
HEAP INSERTION

Items inserted in order m t h q a k



DELETION WITH HEAPS

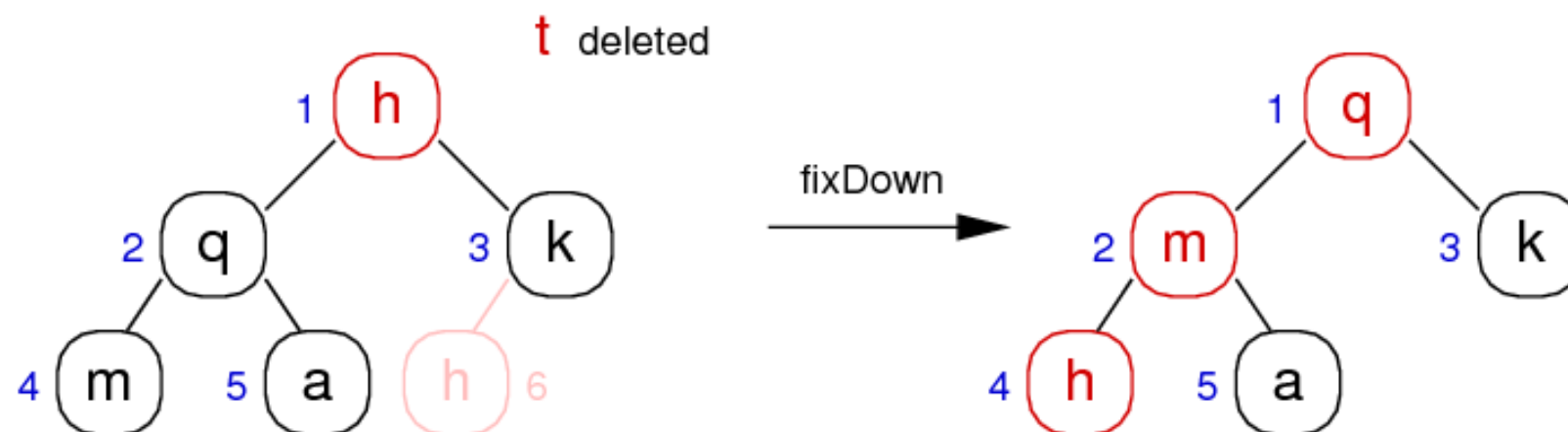
- Deletion is a three-step process
 - replace root value by bottom-most, rightmost value
 - remove bottom-most, rightmost value
 - reorganise values along path from root to restore heap



HEAP DELETION FIX-DOWN CODE

- Top-down heapify:

```
void fixDown(Item a[], int k) {  
    int done = 0;  
    while (2*k <= N && !done) {  
        int j = 2*k; //choose larger of two children  
        if (j < N && less(a[j], a[j+1])) {  
            j++;  
        }  
        if (!less(a[k], a[j])) {  
            done = 1;  
        } else {  
            swap(a, k, j);  
            k = j;  
        }  
    }  
}
```



EXERCISE:

- Show the construction of the heap produced by inserting
 - H E A P S F U N
- Show the heap after an item is deleted.
- Show the heap after another item is deleted.

