# STATS607B HW4

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Load some benchmarking tools

```
if (!require(microbenchmark)) {
  install.packages("microbenchmark")
  library(microbenchmark)
}
```

## Loading required package: microbenchmark

#### Initialize data and try R default regression

```
m <- 100
n <- 15
i <- 1:m
j <- 1:n
X <- outer(i, j, function(i,j){((i-1)/(m-1))^(j-1)})
Y = exp(sin(4*(i-1)/(m-1)))/2006.787453080206

lm(Y~X-1)$coefficients[15]
## X15</pre>
```

## X15 ## -0.1958184

R default runs terribly.

#### QR decomposition using standard Gram-Schmitd

```
QRstdGS <- function(){</pre>
  Q <- matrix(0, m, n)
  R <- matrix(0, n, n)</pre>
  for (j in 1:n) {
    \#cat("j = ", j)
    v <- X[,j]
    if (j>1) {
       for (i in 1:(j-1)) {
         \#cat("i = ",i)
         R[i,j] \leftarrow sum(X[,j]*Q[,i])
         v \leftarrow v - R[i,j] *Q[,i]
    }
    R[j,j] \leftarrow sqrt(sum(v^2))
    Q[,j] \leftarrow v/R[j,j]
  # max(abs(Q%*%R-X))
  # solve Rb=Q'Y=y
  b <- numeric(n)</pre>
```

```
y <- t(Q)%*%Y
b[n] <- y[n]/R[n,n]
for (j in (n-1):1) {
  b[j] <- (y[j] - sum(b[(j+1):n]*R[j,(j+1):n]))/R[j,j]
}
(b15QRstdGE <- b[15])
}
QRstdGS()</pre>
```

## [1] 0.0005245056

#### QR decomposition using modified Gram-Schmitd

```
QRmodGS <- function(){</pre>
  Q <- matrix(0, m, n)
  R \leftarrow matrix(0, n, n)
  for (j in 1:n) {
     \#cat("j = ", j)
    v <- X[,j]
    if (j>1) {
       for (i in 1:(j-1)) {
         #cat("i = ",i)
         R[i,j] \leftarrow sum(v*Q[,i])
         v \leftarrow v - R[i,j] *Q[,i]
       }
    }
    R[j,j] \leftarrow sqrt(sum(v^2))
    Q[,j] \leftarrow v/R[j,j]
  # max(abs(Q%*%R-X))
  # solve Rb=Q'Y=y
  b <- numeric(n)</pre>
  y <- t(Q)%*%Y
  b[n] \leftarrow y[n]/R[n,n]
  for (j in (n-1):1) {
    b[j] \leftarrow (y[j] - sum(b[(j+1):n]*R[j,(j+1):n]))/R[j,j]
  (b15QRmodGE \leftarrow b[15])
}
QRmodGS()
```

## [1] 0.9914539

#### QR decomposition using House Holder approach

```
QRHH <- function(){
    R <- X
    y <- Y
    for (j in 1:n) {</pre>
```

```
x <- R[j:m,j]
v <- x + sign(x[1]) * sqrt(sum(x^2)) * c(1,rep(0,m-j))
R[j:m,j:n] <- (diag(m-j+1) - 2*outer(v,v)/sum(v^2)) %*% R[j:m,j:n]
y[j:m] <- (diag(m-j+1) - 2*outer(v,v)/sum(v^2)) %*% y[j:m]
}
# max(Q%*%R - X)
# solve Rb=Q'Y=y
b <- numeric(n)
b[n] <- y[n]/R[n,n]
for (j in (n-1):1) {
  b[j] <- (y[j] - sum(b[(j+1):n]*R[j,(j+1):n]))/R[j,j]
}
(b15QRHouseHolder <- b[15])
}</pre>
QRHH()
```

## [1] 0.999998

#### Cholesky decomposition and solve normal equation

```
XX <- t(X)%*%X
w <- t(X)%*%Y
L <- matrix(0,n,n)
for (j in 1:n) {
    L[j,j] <- sqrt(XX[j,j] - sum(L[j,1:(j-1)]^2))
    for (i in (j+1):n) {
        L[i,j] <- (XX[i,j] - sum(L[j,1:(j-1)]*L[i,1:(j-1)])) / L[j,j]
    }
}
max(abs(L%*%t(L)-XX),na.rm = T)</pre>
```

The Cholesky decomposition breaks down due to rounding in R! Last entry cannot be computed, although LL' is close to X'X.

Perhaps I should do it in MATLAB

#### Compare speed and accuracy

```
microbenchmark(list = c(QRstdGS(), QRmodGS(), QRHH()),times = 1e6)
## Unit: nanoseconds
##
                   expr min lq
                                  mean median uq
                                                   max neval
##
  0.000524505634284717 3 5 8.384768
                                            8 10 12668 1e+06
##
      0.991453927119202
                        3 5 8.347794
                                            8 10 12534 1e+06
##
      0.999999830007055
                        3 5 8.580755
                                            8 10 15648 1e+06
```

Householder decomposition is most accurate in terms of finding the regression coefficient for  $b_15$ .

The three methods have comparable speed, which is expected given that the computational cost is identical from the analysis of the algorithms.

#### Question 2

Standard GS

```
QRstdGS <- function(X){
    Q <- matrix(0, n, n)
    R <- matrix(0, n, n)
for (j in 1:n) {
    v <- X[,j]
    if (j>1) {
        for (i in 1:(j-1)) {
            #cat("i = ",i)
            R[i,j] <- sum(X[,j]*Q[,i])
            v <- v - R[i,j]*Q[,i]
        }
    }
    R[j,j] <- sqrt(sum(v^2))
    Q[,j] <- v/R[j,j]
}
</pre>
```

Modified GS

We compare Standard Gram-Schmitd and modified version under 2 setting considered by John R. Rice.<sup>1</sup>

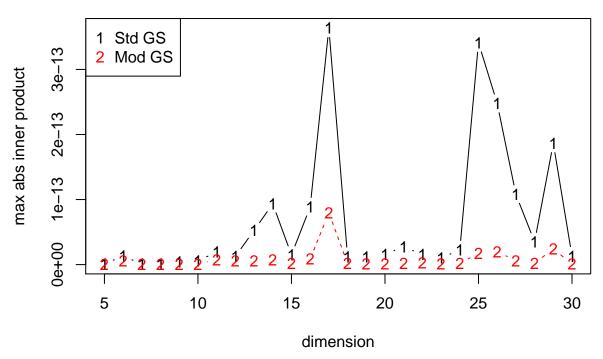
- 1. First is for randomly generated matrices, sized ranging from 5x5 to 30x30
- 2. Then matrices generated by functions that induce colinearity among columns

Evaluation of the accuracies will be based on the maximum absolute value of the inner products among the orthogonalized matrix Q

```
evaluate_Q <- function(Q) {
  max_inner_prod <- 0
  for (i in 1:(n-1)) {
    for (j in (i+1):n) {
      max_inner_prod <- max(abs(sum(Q[,i]*Q[,j])), max_inner_prod)
    }
}</pre>
```

<sup>&</sup>lt;sup>1</sup>Rice, John R. "Experiments on gram-schmidt orthogonalization." Mathematics of Computation 20.94 (1966): 325-328.

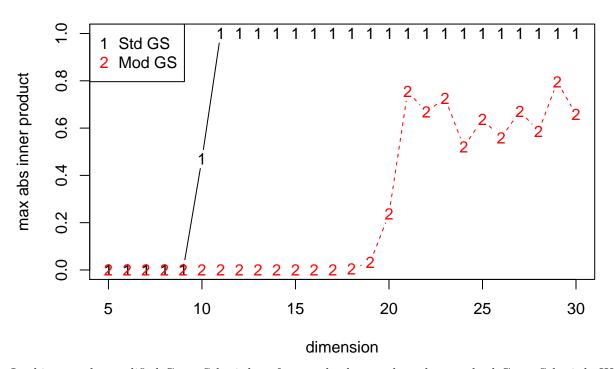
## Error when decomposing random matrices



Although the modified Gram-Schmitd performs consistently better than the standard Gram-Schmitd, the error is tiny  $(\sim 10^{-13})$  for both algorithms.

```
# Case 2: polynomials
dimension <- 5:30
result_stdGS <- numeric(length(dimension))
result_modGS <- numeric(length(dimension))
for (i in 1:length(dimension)) {
   n <- dimension[i]
   #X <- matrix(runif(n^2),n,n)</pre>
```

### Error when decomposing multicolinear matrices



In this case the modified Gram-Schmitd performs a lot better than the standard Gram-Schmitd. When dimension is large, the columns of X are highly dependent and multicolinear, the standard GS almost always produce identical columns. While the modified GS, although also performs poorly, is more stable.

Section 3 of John's paper gave a reasonable explanation of this phenomena.

In the standard Gram-Schmitd the errors in taking the inner products can accumulate. When the independent element in the vector is small compared to the errors accumulated, the remainder will be a linear combination of the previous vectors still. This error is further blown up by the normalization step.

In the modified Gram-Schmitd, the latest vector is at least orthogonal to the immediate preceding one within machine accuracy, thus preserving orthogonality better. (Although I believe this is no guarantee that the latest vector is orthogonal to even earlier ones, hence the errors are still large for vectors further apart.)