STATS 406 Fall 2015 Final Review

December 8, 2015

Random number generation

- Inversion method: If CDF F(x) is known, we can sample $X \stackrel{\text{CDF}}{\sim} F$ by $F^{-1}(U)$, where $U \sim \text{Uniform}(0,1)$.
- **Question 1.(a):** Sample standard Cauchy: $F(x) = \frac{1}{\pi} \arctan(x) + \frac{1}{2}$.
- **Answer:** First figure out the inverse function F^{-1} :

$$y = \frac{1}{\pi}\arctan(x) + \frac{1}{2}$$

which gives $x = \tan\left(\pi\left(y - \frac{1}{2}\right)\right)$, that is $F^{-1}(t) = \tan\left(\pi\left(t - \frac{1}{2}\right)\right)$. We can sample X by $X := \tan\left(\pi\left(U - \frac{1}{2}\right)\right)$.

Random number generation

- Inversion method: If CDF F(x) is known, we can sample $X \stackrel{\text{CDF}}{\sim} F$ by $F^{-1}(U)$, where $U \sim \text{Uniform}(0,1)$.
- Question 1.(b): Sample Geometric(p):

$$\mathbb{E}(X=k)=p(1-p)^{k-1}$$

- Answer: The discrete version of the inversion method is a stick breaking algorithm:
 - **1** Sample $U \sim \text{Uniform}(0,1)$. Set k=1, v=p.
 - 2 while(U > v){ k = k + 1; $v = v + p*(1-p)^(k-1)$; }
 - Return k.

Random number generation

- Rejection sampling: Want to sample from PDF f(x), know: 1. how to sample from PDF g(x); 2. for a constant M, $f(x) \le Mg(x)$ for all x.
 - M doesn't have to be its optimal choice.
 - The domination of Mg over f must hold for all x.
- **Question 1.(c):** Given CDF $F(x) = \sin(\pi x)$ on $\left[0, \frac{1}{2}\right]$, sample from F.
- **Answer:** First derive the corresponding PDF: $f(x) = F'(x) = \pi \cos(\pi x)$. f(x) ranges from π to 0 on $\left[0,\frac{1}{2}\right]$. So we can use the uniform distribution on $\left[0,\frac{1}{2}\right]$ to dominate f(x) with the choice of $M=\frac{\pi}{2}$.

Algorithm:

- I Sample $U \sim \text{Uniform}(0, \frac{1}{2})$.

 2 Accept U with probability $\frac{\pi \cos(\pi U)}{\frac{\pi}{2} \cdot 2} = \cos(\pi U)$.

All Monte-Carlo integration techniques start with the common insight:

$$I = \int f(x) dx = \int \frac{f(x)}{\pi(x)} \pi(x) dx = \mathbb{E}\left[\frac{f(X)}{\pi(X)}\right]$$

where $X \stackrel{\mathrm{PDF}}{\sim} \pi(x)$.

They only differ in choices of $\pi(x)$ and/or ways to compute $\mathbb{E}\left[\frac{f(X)}{\pi(X)}\right]$.

- Plain Monte-Carlo: Use a uniform distribution as $\pi(x)$.
- Question 2.(a): Use Uniform(1,3).

Algorithm:

- **I** Sample $X_1, \ldots, X_n \sim \mathsf{Uniform}(1,3)$.
- 2 Estimate I by

$$\hat{I} = \frac{2}{n} \sum_{i=1}^{n} \frac{1}{X_i^2}$$

Where does the factor 2 come from?

- Importance sampling: To improve efficiency, choose $\pi(x)$ that mimics the shape of f(x).
- **Question 2.(b):** Compute $\mathbb{E}[Y]$, where $Y = X^3 \mathbb{1}[X > 0]$, $X \sim N(0, 1)$.
- Answer: First write the expectation in integration form:

$$I = \int_0^{+\infty} x^3 \cdot \frac{1}{\sqrt{2\pi}} e^{-\frac{x^2}{2}} dx = \int_0^{+\infty} \frac{x^3 \cdot \frac{1}{\sqrt{2\pi}} e^{-\frac{x^2}{2}}}{\pi(x)} \pi(x) dx = \mathbb{E}\left[\frac{X^3 \cdot \frac{1}{\sqrt{2\pi}} e^{-\frac{X^2}{2}}}{\pi(X)}\right]$$

for $X \stackrel{\text{PDF}}{\sim} \pi(x)$. As required by the question, choose $\pi(x)$ to be the PDF of the standard exponential distribution, that is, $\pi(x) = e^{-x}$ for x > 0.

Algorithm:

- **I** Sample X_1, \ldots, X_n from standard exponential distribution.
- 2 Estimate I by

$$\hat{I} = \frac{1}{n} \sum_{i=1}^{n} \left\{ \frac{X_i^3 \cdot \frac{1}{\sqrt{2\pi}} e^{-\frac{X_i^2}{2}}}{e^{-X_i}} \right\}$$

- Importance sampling (self-normalized): Ordinary importance sampling requires knowing f(x) exactly. When f(x) is only known up to a constant, the self-normalized version of importance sampling should be used.
- **Question 2.(c):** Compute $\mathbb{E}[X]$, where $X \stackrel{\mathrm{PDF}}{\sim} f(x) \propto e^{-x^{3/2}}$.
- **Answer:** Recall the derivation of the self-normalized importance sampling:

$$I = \mathbb{E}[X] = \int x f(x) dx = \int \frac{x f(x)}{\pi(x)} \pi(x) dx = \mathbb{E}\left[\frac{X f(X)}{\pi(X)}\right] = \frac{\mathbb{E}\left[\frac{X f(X)}{\pi(X)}\right]}{\mathbb{E}\left[\frac{f(X)}{\pi(X)}\right]}$$

where $X \stackrel{\mathrm{PDF}}{\sim} \pi(x)$. With X_1, \ldots, X_n generated from PDF $\pi(x)$, we use the self-normalized importance sampling:

$$\hat{I} = \frac{\frac{1}{n} \sum_{i=1}^{n} \frac{X_{i} f(X_{i}) \pi(X_{i})}{\pi(X_{i})}}{\frac{1}{n} \sum_{i=1}^{n} \frac{f(X_{i})}{\pi(X_{i})}} = \frac{\sum_{i=1}^{n} \frac{X_{i} f_{0}(X_{i}) \pi(X_{i})}{\pi(X_{i})}}{\sum_{i=1}^{n} \frac{f_{0}(X_{i})}{\pi(X_{i})}}$$

where $f_0(x) := e^{-x^{3/2}} \propto f(x)$ with unknown constant. Blue part: the ordinary importance sampling estimator if f(x) is fully known.

- Definition of mean-squared error(MSE).
- Question 3.(a) answer: $MSE(\widehat{\mu^2}) = \mathbb{E}\left[\left(\widehat{\mu^2} \mu^2\right)^2\right]$.

- Monte-Carlo performance evaluation: if we know the true values of the parameter, we can generate simulated data from the population. Draw many samples to evaluate the accuracy of an estimator.
- **Question 3.(b):** Consider $N(\mu, 1)$ and the estimator $\widehat{\mu}^2 = (\bar{X})^2$. If μ is known how to compute $MSE(\widehat{\mu}^2)$?
- **Answer:** Very straightforward:
 - **I** Generate many samples $X^{(1)}, \ldots, X^{(m)}$, each of size n.
 - **2** Compute the square of each sample mean: $\widehat{\mu^2}^{(i)} = (\operatorname{mean}(X^{(i)}))^2$.
 - **Solution** Estimate the MSE: $\widehat{\mathrm{MSE}}(\widehat{\mu^2}) = \frac{1}{m} \sum_{i=1}^m \left(\left(\bar{X}^{(i)} \right)^2 \mu^2 \right)^2$
- **Remark:** Rigorously speaking, the MSE here depends on the sample size. We should have stated that $\widehat{\mu^2}$ is estimating the MSE at sample size n.

Bootstrap: When the true parameter value is unknown, the population distribution becomes unknown, too. We carry out the evaluation procedures referring to the replacement chart as follows:

Monte-Carlo evaluation	Bootstrap
population distribution	sample distribution
true parameter value	estimated parameter value
generated samples	resamples
sample statistic	sample statistics of resamples

- Bootstrap:
- **Question 3.(c):** Consider $N(\mu,1)$ and the estimator $\widehat{\mu}^2 = (\bar{X})^2$. If μ is unknown how to estimate $MSE(\widehat{\mu}^2)$?
- Answer: Following the replacement chart to derive the algorithm:
 - \blacksquare Use the estimated parameter in place of the true parameter: $\widehat{\mu^2} = \left(\bar{X}\right)^2$
 - 2 Draw resamples $X^{*(1)}, \ldots, X^{*(m)}$, each of size n.
 - Compute the square of each sample mean: $\widehat{\mu^2}^{*(i)} = (\text{mean}(X^{*(i)}))^2$.
 - 4 Estimate the MSE: $\widehat{\mathrm{MSE}}^*(\widehat{\mu^2}) = \frac{1}{m} \sum_{i=1}^m \left(\left(\bar{X}^{*(i)} \right)^2 \widehat{\mu^2} \right)^2$.

- Recall the order in which we read an SQL script. This is also the order in which we write an SQL script.
 - FROM (including INNER JOIN)
 - 2 WHERE
 - GROUP BY
 - 4 HAVING
 - 5 SELECT
 - 6 ORDER BY

- Question 4.(a): Query all pianists from Soviet. Only report pianist and country.
- Answer:

SELECT Pianist, Country FROM Pianists WHERE Country="Soviet"

- Question 4.(b): Query the table Works and summarize the number of works performed by pianist. Only report pianist and the number of works performed.
- Answer: SELECT Pianists, Count(Title) as NumberOfWorksPerformed FROM Works GROUP BY Pianists

Question 4.(c): Combine tables Works and Pianists and query works played by European(including Soviet) pianists. Only report title, composer and pianist.

Answer:

SELECT Title, Composer, Pianists.Pianist AS Pianist FROM
Works INNER JOIN Pianists
ON Works.Pianist = Pianists.Pianist
WHERE Pianists.Pianist = "Soviet" OR Pianists.Pianist = "Germany"
OR Pianists Pianist = "Austria"

- Question 4.(d): Combine all three tables and query works composed by Germany composers and performed by Soviet pianists. Only report title, composer and pianist.
- Answer:

First combine the first two tables:

SELECT Composers.Composer AS Composer, Era, Works.Pianist AS Pianist FROM Composers INNER JOIN Works ON Composers.Composer = Works.Composer WHERE Composers.Country = "Germany"

- Question 4.(d): Combine all three tables and query works composed by Germany composers and performed by Soviet pianists. Only report title, composer and pianist.
- Answer:

Then combine this table (in blue) with the third table:

```
SELECT Title, T1.Composer AS Composer, T1.Pianist AS Pianist
FROM
SELECT Composers. Composer AS Composer, Era, Works. Pianist AS
Pianist
FROM Composers INNER JOIN Works
ON Composers.Composer = Works.Composer
WHERE Composers.Country = "Germany"
) AS T1
INNER JOIN
Pianists
ON T1 Pianist = Pianists Pianist
WHERE Pianists.Country = "Soviet"
```

XML

• Question 5: Rewrite the following entry, transforming the attributes into children:

```
Author="Thomas Hardy" PublishedYear="1878" />
Consider the rewritten version: write an R command (assume the package "XML" is loaded and root points to the book tag) to query the content of the PublishedYear tag. The returned value must be numeric.
```

Answer: Rewrite the entry:

```
<book>
<Title>The Return of The Native</Title>
<Author>Thomas Hardy</Author>
<PublishedYear>1878</PublishedYear>
</book>
```

<book Title="The Return of The Native"</pre>

Notice: 1. no quote marks needed; 2. remember to close each tag; 3. XML is case-sensitive.

Query the Author tag:

```
as.numeric(xmlValue(root[["PublishedYear"]]))
```

Optimization

- Use the illustration in Lab_11.pdf to help you memorize the formulations of gradient methods and Newton's method.
- Those illustrations are univariate, but once you have the formulation, it's easy to extend it to the multivariate case.

Optimization

- **Question 6.(a):** Optimize $f(x, y) = x^2 + 4(y 1)^2$, starting at $(x_0, y_0) = (2, 3)$. Use gradient method and Newton's method.
- **Answer:** First compute the gradient: $\nabla f(x,y) = (2x,8(y-1))^T$.

Gradient method: minimization \Rightarrow gradient descend.

$$(x_1, y_1) = (x_0, y_0) - \text{StepSize} \cdot \nabla f(x_0, y_0)$$

$$= (2, 3) - 0.1 \cdot (4, 16) = (1.6, 1.4)$$

$$(x_2, y_2) = (x_1, y_1) - \text{StepSize} \cdot \nabla f(x_1, y_1)$$

$$= (1.6, 1.4) - 0.1 \cdot (3.2, 3.2) = (1.28, 1.08)$$

Newton's method: calculate Hessian: $\frac{\partial^2 f}{\partial x^2} = 2$, $\frac{\partial^2 f}{\partial x \partial y} = 0$ and $\frac{\partial^2 f}{\partial y^2} = 8$, so

$$\begin{pmatrix} x_{t+1} \\ y_{t+1} \end{pmatrix} = \begin{pmatrix} x_t \\ y_t \end{pmatrix} - H^{-1}(x_t, y_t) \cdot \nabla f(x_t, y_t) = \begin{pmatrix} x_t \\ y_t \end{pmatrix} - \begin{pmatrix} \frac{1}{2} & 0 \\ 0 & \frac{1}{8} \end{pmatrix} \begin{pmatrix} 2x_t \\ 8(y_t - 1) \end{pmatrix}$$

$$= \begin{pmatrix} x_t \\ y_t \end{pmatrix} - \begin{pmatrix} x_t \\ y_t - 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

Newton's method converges to the optimum after only one iteration, and will stay there forever.

Optimization

- **Question 6.(b):** Poisson mixture: 3 Poisson distributions with λ_k and mixing probabilities π_k , k = 1, 2, 3. Observe X_1, \ldots, X_n . Write down and maximize the incomplete log-likelihood.
- Answer: By total probability theorem, we have the likelihood:

$$\mathbb{P}(X_i = k) = \sum_{j=1}^{3} \mathbb{P}(X_i = k | Z_i = j) \mathbb{P}(Z_i = j) = \sum_{j=1}^{3} \frac{\lambda_j^k}{k!} e^{-\lambda_j} \pi_j$$

Therefore, the log-likelihood function is:

$$I(\Theta|X) = \sum_{i=1}^{n} \log \left(\sum_{j=1}^{3} \frac{\lambda_{j}^{k}}{k!} e^{-\lambda_{j}} \pi_{j} \right)$$

The gradient method we should use here is a gradient ascend as follows:

$$\Theta_{t+1} = \Theta_t + \operatorname{StepSize} \cdot \nabla I(\Theta_t | X)$$

- **Question 7:** Poisson mixture: 3 Poisson distributions with λ_k and mixing probabilities π_k , k = 1, 2, 3. Observe X_1, \ldots, X_n . Write down and maximize the incomplete log-likelihood.
- Answer: The question is not yet completely ready to apply EM algorithm upon. We need to first finish modeling by introducing latent random variables.

Set $Z_i \in \{1,2,3\}$ to be a categorical random variable that indicates which Poisson distribution generates X_i . The *i*th term in the complete likelihood function is:

$$\mathbb{P}(X_i = k, Z_i = j) = \frac{\lambda_j^k}{k!} e^{-\lambda_j} \cdot \pi_j$$

Employing the indicator function $\mathbb{1}[Z_i = j]$, the log-likelihood function is:

$$\begin{split} I_c(\Theta; X, Z) &= \sum_{i=1}^n \left\{ \sum_{j=1}^3 \mathbb{1}[Z_i = j] \log \left(\frac{\lambda_j^{X_i}}{X_i!} e^{-\lambda_j} \cdot \pi_j \right) \right\} \\ &= \sum_{i=1}^n \left\{ \sum_{j=1}^3 \mathbb{1}[Z_i = j] \left(X_i \log \lambda_j - \lambda_j + \log \pi_j \right) \right\} + \text{constant} \end{split}$$

Answer(continued): The complete log-likelihood:

$$I_c(\Theta; X, Z) = \sum_{i=1}^n \left\{ \sum_{j=1}^3 \mathbb{1}[Z_i = j] \left(X_i \log \lambda_j - \lambda_j + \log \pi_j \right) \right\} + \text{constant}$$

■ E-step: calculate $\mathbb{E}[I_c(\Theta; X, Z)|\Theta_t, X]$.

Notice that here I is linear in $\mathbb{1}[Z_i = j]$, which only depends on X_i , it suffices to evaluate $\mathbb{E}[\mathbb{1}[Z_i = j] | \Theta_t, X_i]$. By Bayes formula:

$$\begin{split} \langle \mathbb{1}[Z_i = j] \rangle &:= \mathbb{E}\left[\mathbb{1}[Z_i = j] | \Theta_t, X_i \right] = \mathbb{P}\left(Z_i = j | \Theta_t, X_i \right) \\ &= \frac{\mathbb{P}\left(X = X_i | Z_i = j, \Theta_t \right) \mathbb{P}\left(Z_i = j | \Theta_t \right)}{\sum_{\tilde{j}=1}^{3} \mathbb{P}\left(X = X_i | Z_i = \tilde{j}, \Theta_t \right) \mathbb{P}\left(Z_i = \tilde{j} | \Theta_t \right)} \\ &= \frac{\left(\lambda_j^{(t)}\right)^{X_i} e^{-\lambda_j^{(t)}}}{X_i!} \cdot \pi_j^{(t)}}{\sum_{\tilde{j}=1}^{3} \left\{ \frac{\left(\lambda_{\tilde{j}}^{(t)}\right)^{X_i} e^{-\lambda_{\tilde{j}}^{(t)}}}{X_i!} \cdot \pi_{\tilde{j}}^{(t)} \right\}} \end{split}$$

- Answer(continued):
- M-step: replacing all $\mathbb{1}[Z_i = j]$ in the complete log-likelihood by $\langle \mathbb{1}[Z_i = j] \rangle$, we have

$$\mathbb{E}\left[l_c(\Theta; X, Z) | \Theta_t, X\right] = \sum_{i=1}^n \left\{ \sum_{j=1}^3 \langle \mathbb{1}[Z_i = j] \rangle \left(X_i \log \lambda_j - \lambda_j + \log \pi_j \right) \right\} + \text{constant}$$

By taking the derivative of $\mathbb{E}[I_c(\Theta; X, Z)|\Theta_t, X]$ over each λ_j respectively and setting it to zero, we immediately have:

$$\lambda_j^{(t+1)} = \frac{\sum_{i=1}^n \langle \mathbb{1}[Z_i = j] \rangle X_i}{\sum_{i=1}^n \langle \mathbb{1}[Z_i = j] \rangle}$$

for i = 1, 2, 3.

- Answer(continued):
- M-step(continued): recall that

$$\mathbb{E}\left[\mathit{I}_{c}(\Theta;X,Z)|\Theta_{t},X\right] = \sum_{i=1}^{n} \left\{\sum_{j=1}^{3} \langle \mathbb{1}[Z_{i}=j]\rangle \left(X_{i}\log\lambda_{j} - \lambda_{j} + \log\pi_{j}\right)\right\} + \text{constant}$$

Obtaining the update for π_i 's is slightly harder due to the constraint $\sum_{j=1}^{3} \pi_j =$. We consider the corresponding terms plus the Langrangian multiplier:

$$\sum_{i=1}^n \left\{ \sum_{j=1}^3 \left(\mathbb{1}[Z_i = j] \log \pi_j \right) \right\} - \alpha \left(\pi_1 + \pi_2 + \pi_3 - 1 \right)$$

and set its derivative to zero. We have

$$\alpha = \frac{\sum_{i=1}^{n} \mathbb{1}[Z_i = 1]}{\pi_1} = \frac{\sum_{i=1}^{n} \mathbb{1}[Z_i = 2]}{\pi_2} = \frac{\sum_{i=1}^{n} \mathbb{1}[Z_i = 3]}{\pi_3}$$

Therefore

$$\pi_j^{(t+1)} = \frac{\sum_{i=1}^n \mathbb{1}[Z_i = j]}{n}$$