	layer network, but would become impractical as we move to bigger models. Ideally we want to build networks using a more modular design so that we can implement different layer types in isolation and then snap them together into models with different architectures.  In this exercise we will implement fully-connected networks using a more modular approach. For each layer we will implement a
	<pre>forward and a backward function. The forward function will receive inputs, weights, and other parameters and will return both an output and a cache object storing data needed for the backward pass, like this:  def layer_forward(x, w):     """ Receive inputs x and weights w """     # Do some computations     z = # some intermediate value     # Do some more computations</pre>
	<pre>out = # the output  cache = (x, w, z, out) # Values we need to compute gradients  return out, cache  The backward pass will receive upstream derivatives and the cache object, and will return gradients with respect to the inputs and weights, like this:  def layer_backward(dout, cache):</pre>
	Receive dout (derivative of loss with respect to outputs) and cache, and compute derivative with respect to inputs.  # Unpack cache values x, w, z, out = cache  # Use values in cache to compute derivatives
	<pre>dx = # Derivative of Loss with respect to x dw = # Derivative of Loss with respect to w  return dx, dw  After implementing a bunch of layers this way, we will be able to easily combine them to build classifiers with different architectures.  In addition to implementing fully-connected networks of arbitrary depth, we will also explore different update rules for optimization, and introduce Dropout as a regularizer and Batch/Layer Normalization as a tool to more efficiently optimize deep networks.</pre>
in [1]:	Acknowledgement: This exercise is adapted from Stanford CS231n.  # As usual, a bit of setup fromfuture import print_function import time import numpy as np import matplotlib.pyplot as plt
	<pre>from libs.classifiers.fc_net import * from libs.data_utils import get_CIFAR10_data from libs.gradient_check import eval_numerical_gradient, eval_numerical_gradient_array from libs.solver import Solver  %matplotlib inline plt.rcParams['figure.figsize'] = (10.0, 8.0) # set default size of plots plt.rcParams['image.interpolation'] = 'nearest' plt.rcParams['image.cmap'] = 'gray'  # for auto-reloading external modules # see http://stackoverflow.com/questions/1907993/autoreload-of-modules-in-ipython %load_ext autoreload %autoreload 2</pre>
in [2]:	<pre>def rel_error(x, y):     """ returns relative error """     return np.max(np.abs(x - y) / (np.maximum(1e-8, np.abs(x) + np.abs(y))))  # Load the (preprocessed) CIFAR10 data.  data = get_CIFAR10_data()     for k, v in list(data.items()):         print(('%s: ' % k, v.shape))</pre>
	('X_train: ', (49000, 3, 32, 32)) ('y_train: ', (49000,)) ('X_val: ', (1000, 3, 32, 32)) ('y_val: ', (1000,)) ('X_test: ', (1000, 3, 32, 32)) ('y_test: ', (1000,))
în [3]:	Affine layer: foward  Open the file libs/layers.py and implement the affine_forward function.  Once you are done you can test your implementaion by running the following:  # Test the affine_forward function
	<pre>num_inputs = 2 input_shape = (4, 5, 6) output_dim = 3  input_size = num_inputs * np.prod(input_shape) weight_size = output_dim * np.prod(input_shape)  x = np.linspace(-0.1, 0.5, num=input_size).reshape(num_inputs, *input_shape) w = np.linspace(-0.2, 0.3, num=weight_size).reshape(np.prod(input_shape), output_dim) b = np.linspace(-0.3, 0.1, num=output_dim)  out, _ = affine_forward(x, w, b) correct_out = np.array([[ 1.49834967,  1.70660132,  1.91485297],</pre>
	<pre>print('Testing affine_forward function:') print('difference: ', rel_error(out, correct_out))  Testing affine_forward function: difference: 9.769849468192957e-10</pre> Affine layer: backward
in [4]:	Now implement the affine_backward function and test your implementation using numeric gradient checking.  # Test the affine_backward function np.random.seed(231) x = np.random.randn(10, 2, 3) w = np.random.randn(6, 5) b = np.random.randn(5) dout = np.random.randn(10, 5)  dx_num = eval_numerical_gradient_array(lambda x: affine_forward(x, w, b)[0], x, dout) dw_num = eval_numerical_gradient_array(lambda w: affine_forward(x, w, b)[0], w, dout)
	<pre>db_num = eval_numerical_gradient_array(lambda b: affine_forward(x, w, b)[0], b, dout) _, cache = affine_forward(x, w, b) dx, dw, db = affine_backward(dout, cache)  # The error should be around e-10 or less print('Testing affine_backward function:') print('dx error: ', rel_error(dx_num, dx)) print('dw error: ', rel_error(dw_num, dw)) print('db error: ', rel_error(db_num, db))  Testing affine_backward function: dx error: 5.399100368651805e-11</pre>
	dw error: 9.904211865398145e-11 db error: 2.4122867568119087e-11  ReLU activation: forward  Implement the forward pass for the ReLU activation function in the relu_forward function and test your implementation using the following:
n [5]:	<pre># Test the relu_forward function  x = np.linspace(-0.5, 0.5, num=12).reshape(3, 4)  out, _ = relu_forward(x) correct_out = np.array([[ 0.,</pre>
	print ('difference: ', rel_error(out, correct_out))  Testing relu_forward function: difference: 4.999999798022158e-08  ReLU activation: backward  Now implement the backward pass for the ReLU activation function in the relu_backward function and test your implementation usin numeric gradient checking:
n [6]:	<pre>np.random.seed(231) x = np.random.randn(10, 10) dout = np.random.randn(*x.shape)  dx_num = eval_numerical_gradient_array(lambda x: relu_forward(x)[0], x, dout)  _, cache = relu_forward(x) dx = relu_backward(dout, cache)  # The error should be on the order of e-12  print(lambda x: relu_backward(lambda x: relu_forward(x)[0], x, dout)</pre>
	print('Testing relu_backward function:') print('dx error: ', rel_error(dx_num, dx))  Testing relu_backward function: dx error: 3.2756349136310288e-12  "Sandwich" layers  There are some common patterns of layers that are frequently used in neural nets. For example, affine layers are frequently followed by a ReLU nonlinearity. To make these common patterns easy, we define several convenience layers in the file libs/layer_utils.py.
In [7]:	For now take a look at the affine_relu_forward and affine_relu_backward functions, and run the following to numerically gradient check the backward pass:  from libs.layer_utils import affine_relu_forward, affine_relu_backward np.random.seed(231)  x = np.random.randn(2, 3, 4)  w = np.random.randn(12, 10)  b = np.random.randn(10)  dout = np.random.randn(2, 10)  out, cache = affine_relu_forward(x, w, b)  dx, dw, db = affine_relu_backward(dout, cache)
	<pre>dx_num = eval_numerical_gradient_array(lambda x: affine_relu_forward(x, w, b)[0], x, dout) dw_num = eval_numerical_gradient_array(lambda w: affine_relu_forward(x, w, b)[0], w, dout) db_num = eval_numerical_gradient_array(lambda b: affine_relu_forward(x, w, b)[0], b, dout)  # Relative error should be around e-10 or less print('Testing affine_relu_forward and affine_relu_backward:') print('dx error: ', rel_error(dx_num, dx)) print('dw error: ', rel_error(dw_num, dw)) print('db error: ', rel_error(db_num, db))  Testing affine_relu_forward and affine_relu_backward: dx error: 2.299579177309368e-11</pre>
în [8]:	dw error: 8.162011105764925e-11 db error: 7.826724021458994e-12  Loss layers: Softmax  You implemented these loss functions in the last assignment, so we'll give them to you for free here. You should still make sure you understand how they work by looking at the implementations in libs/layers.py  You can make sure that the implementations are correct by running the following:  np.random.seed(231)
	<pre>num_classes, num_inputs = 10, 50 x = 0.001 * np.random.randn(num_inputs, num_classes) y = np.random.randint(num_classes, size=num_inputs)  dx_num = eval_numerical_gradient(lambda x: softmax_loss(x, y)[0], x, verbose=False) loss, dx = softmax_loss(x, y)  # Test softmax_loss function. Loss should be close to 2.3 and dx error should be around e-8 print('\nTesting softmax_loss:') print('loss: ', loss) print('dx error: ', rel_error(dx_num, dx))</pre> Testing softmax_loss:
	Two-layer network  In the previous assignment you implemented a two-layer neural network in a single monolithic class. Now that you have implemented modular versions of the necessary layers, you will reimplement the two layer network using these modular implementations.  Open the file libs/classifiers/fc_net.py and complete the implementation of the TwoLayerNet class. This class will serve as a modular transfer you will implement in this assignment, so read through it to make our you understand the ARI You can record the relation of the TwoLayerNet class.
[10]:	model for the other networks you will implement in this assignment, so read through it to make sure you understand the API. You can ru the cell below to test your implementation.  np.random.seed(231) N, D, H, C = 3, 5, 50, 7 X = np.random.randn(N, D) y = np.random.randint(C, size=N)  std = 1e-3 model = TwoLayerNet(input_dim=D, hidden_dim=H, num_classes=C, weight_scale=std)
	<pre>print('Testing initialization ') W1_std = abs(model.params['W1'].std() - std) b1 = model.params['b1'] W2_std = abs(model.params['W2'].std() - std) b2 = model.params['b2'] assert W1_std &lt; std / 10, 'First layer weights do not seem right' assert np.all(b1 == 0), 'First layer biases do not seem right' assert W2_std &lt; std / 10, 'Second layer weights do not seem right'</pre>
	<pre>assert np.all(b2 == 0), 'Second layer biases do not seem right'  print('Testing test-time forward pass ') model.params['W1'] = np.linspace(-0.7, 0.3, num=D*H).reshape(D, H) model.params['b1'] = np.linspace(-0.1, 0.9, num=H) model.params['W2'] = np.linspace(-0.3, 0.4, num=H*C).reshape(H, C) model.params['b2'] = np.linspace(-0.9, 0.1, num=C) X = np.linspace(-5.5, 4.5, num=N*D).reshape(D, N).T scores = model.loss(X)</pre>
	<pre>correct_scores = np.asarray(    [[11.53165108, 12.2917344, 13.05181771, 13.81190102, 14.57198434, 15.33206765, 16.09215096],    [12.05769098, 12.74614105, 13.43459113, 14.1230412, 14.81149128, 15.49994135, 16.18839143],    [12.58373087, 13.20054771, 13.81736455, 14.43418138, 15.05099822, 15.66781506, 16.2846319 ]]) scores_diff = np.abs(scores - correct_scores).sum() assert scores_diff &lt; 1e-6, 'Problem with test-time forward pass'  print('Testing training loss (no regularization)')</pre>
	y = np.asarray([0, 5, 1])  loss, grads = model.loss(X, y)  correct_loss = 3.4702243556  assert abs(loss - correct_loss) < 1e-10, 'Problem with training-time loss'  model.reg = 1.0  loss, grads = model.loss(X, y)  correct loss = 26.5948426952
	<pre>assert abs(loss - correct_loss) &lt; 1e-10, 'Problem with regularization loss'  # Errors should be around e-7 or less for reg in [0.0, 0.7]:     print('Running numeric gradient check with reg = ', reg)     model.reg = reg     loss, grads = model.loss(X, y)</pre>
	<pre>for name in sorted(grads):     f = lambda _: model.loss(X, y)[0]     grad_num = eval_numerical_gradient(f, model.params[name], verbose=False)     print('%s relative error: %.2e' % (name, rel_error(grad_num, grads[name])))  Testing initialization Testing test-time forward pass Testing training loss (no regularization) Running numeric gradient check with reg = 0.0</pre>
	W1 relative error: 1.83e-08 W2 relative error: 3.12e-10
	b1 relative error: 9.83e-09 b2 relative error: 4.33e-10 Running numeric gradient check with reg = 0.7 W1 relative error: 2.53e-07 W2 relative error: 2.85e-08 b1 relative error: 1.56e-08 b2 relative error: 7.76e-10
	b1 relative error: 9.83e-09 b2 relative error: 4.33e-10 Running numeric gradient check with reg = 0.7 W1 relative error: 2.53e-07 W2 relative error: 2.85e-08 b1 relative error: 1.56e-08 b2 relative error: 7.76e-10  Solver  In the previous assignment, the logic for training models was coupled to the models themselves. Following a more modular design, for this assignment we have split the logic for training models into a separate class.
[26]:	b1 relative error: 9.83e-09 b2 relative error: 4.33e-10 Running numeric gradient check with reg = 0.7 W1 relative error: 2.53e-07 W2 relative error: 2.85e-08 b1 relative error: 1.56e-08 b2 relative error: 7.76e-10  Solver  In the previous assignment, the logic for training models was coupled to the models themselves. Following a more modular design, for this assignment we have split the logic for training models into a separate class.
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1 [26]:	bl relative error: 9.83e-19 b2 relative error: 1.33e-10 Running numeric gradient check with reg = 0.7 b2 relative error: 2.81e-08 b1 relative error: 1.56e-08 b2 relative error: 1.56e-08 b3 relative error: 1.56e-08 b3 relative error: 1.76e-10  Solver  In the previous assignment, the logic for training models was coupled to the models themselves. Following a more modular design, for this assignment we have split the logic for training models into a separate class.  Open the file libs/solver.py and read through it to familiarize yourself with the API. After doing so, use a Solver instance to train TwoLayerNet that achieves at least 50% accuracy on the validation set.  # X val: (1000, 3, 32, 32) # X train: (49000, 3, 32, 32) # X train: (49000, 3, 32, 32) # Y val: (1000, 3, 32, 32) # Y val: (1000, 3) # Y train: (49000) # y train: (49000) # y train: (49000) # y train: (49000) # wodel = TwoLayerNet() # solver = None  ###################################
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