# **Summary: Lecture 8**

Summary for the chapters 9.3 and 9.4. [2, 1]

## Undirected graph

An undirected graph G is a pair of sets (V, E) where V is the finite set of nodes and E is a set of unordered pairs in V that are symmetric:

$$\forall i, j \in E, i \neq j : (i, j) \in E \Rightarrow (j, i) \in E$$

# IndependentSet

#### IndependentSet

Input: An undirected Graph G = (V, E) and a number k.

Question: Is there a set  $I \subseteq V$  of k = |I| nodes with no edges in between? (INDEPENDENTSET)

#### 3SAT

Like the SAT problem, 3SAT is determining the satisfiability of a formula in CNF where each clause is limited to at most three literals.

INDEPENDENTSET is NP-complete.

#### Proof idea:

• triangle construction: any independent set can contain at most one node of the triangle

$$(x_1 \lor x_2 \lor x_3) \land (\neg x_1 \lor \neg x_2 \lor \neg x_3) \land (\neg x_1 \lor x_2 \lor x_3)$$

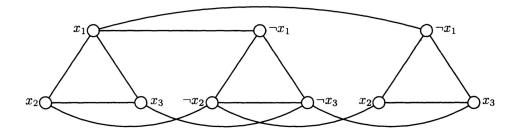


Figure 1: Graph with triangles [2]

- consider only graphs whose nodes can be partitioned in m disjoint triangles  $\rightarrow$  independent set can contain at moast m nodes (one from each triangle)
- reduction from 3SAT to INDEPENDENTSET
- construct graph of formula  $\phi$ :
  - each literal as a node
  - clauses as triangles
  - edges between nodes in different triangles if they correspond to the same literal (negated)
  - -K = m (m clauses)

- given: instance  $\phi$  of 3SAT with m clauses  $C_1, ..., C_m$
- each clause  $C_i = (\alpha_{i1} \vee \alpha_{i2} \vee \alpha_{i3})$  (with  $\alpha$  as boolean variables or negation of those)
- reduction R constructs a graph:  $R(\phi) = (G, K)$  where K = m and G = (V, E)
- nodes  $V = \{v_{ij}: i = 1, ..., m; j = 1, 2, 3\}$  nodes for each of the m clauses (i) for each of the 3 literals (j)
- edges  $E = \{[v_{ij}, v_{ik}] : i = 1, ..., m; j \neq k\} \cup \{[v_{ij}, v_{lk}] : i \neq l, \alpha ij = \neg \alpha_{lk}\}$  edges between the nodes in one clause (triangle edges) edges between nodes with the same corresponding literal, but negated
- there is an independent set I of K nodes in G only if  $\phi$  is satisfiable
- I must contain a node from each triangle
- negated literals are connected: I cannot contain a literal and its negation
- I is a truth assignment of  $\phi$ :
  - true literals: nodes in I
  - one true literal per clause

#### HamiltonPath is NP-complete

#### **HamiltonPath**

A HAMILTON PATH is a path in a graph that visits each node exactly once.

HAMILTON PATH is NP-complete.

#### Proof idea:

- reduction from 3SAT to HAMILTONPATH
- given: formula  $\phi$  in CNF with n variales  $x_1, ..., x_n$  and m clauses  $C_1, ..., C_m$  with each 3 variables
- construct a graph  $R(\phi)$  that has a hamilton path only if  $\phi$  is satisfiable:
- boolean variables:
  - choice between true and false
  - all occurrences of x must have the same value (and  $\neg x$  the opposite)
  - use *choice* gadget (like flip flop)
- XOR:

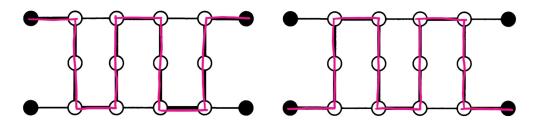


Figure 2: XOR subgraph from the book [2] with the relevant edges marked additionally

- use *consistency* gadget
- because of hamilton path: there are only two ways to traverse through this sub graph (as shown above)
- leads to exclusive or (XOR)

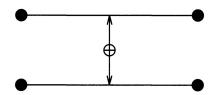


Figure 3: XOR connecting two independent edges (consistency gadget) [2]

#### • clauses:

- triangles for clause construction
- one side for each literal
- if literal is false: hamilton path traveres triangle side
- at least one literal need to be true: else all three edges of triangle will be traversed and this is not a hamilton path
- put everything together as graph G:
  - -G has n copies of the *choice* gadget as a chain (one for each variable)

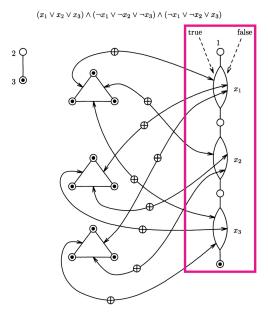


Figure 4: Choice gadgets marked in graph from the book [2]

 $\bullet$  G has m triangles (one for each clause) with edges for each clause in the triangle

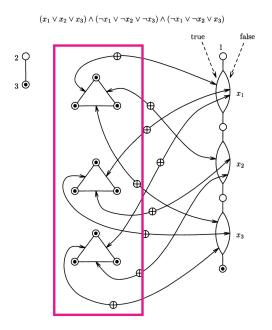


Figure 5: Clauses marked in graph from the book [2]

- finally all 3m nodes of the triangles, the last node of the chain of *choice* gadgets and a new node 3 are connected with all possible edges
- $\bullet\,$  a single node 2 is connectes to the node 3

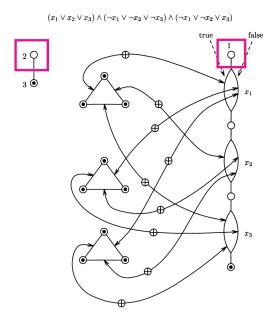


Figure 6: Nodes 1 and 2 marked (start and end node) in graph from the book [2]

- graph has a hamilton path only if  $\phi$  has a satisfying truth assignment
- for hamilton path: start node is node 1 and end node is node 2
- from node 1 it must traverse one of the parallel edges of the *choice* gadget for the first variable
- exclusive ors must be traversed
- whole chain of *choice* gadgets will be traversed
  → in this way a truth assignment T is created

• then the triangles are traversed

#### TODO

Questions:

# TSP(D)

# TSP(D)

TSP(D) is a decision version of TSP.

Input: A  $n \times n$  distance matrix and a bound  $B \in \mathbb{N}$ 

Question: Is there a round tour of length  $\leq B$  that visits all *cities*?

TSP(D) is NP-complete.

## Proof idea:

• budget of nodes is B = |V| + 1

#### TODO

Questions:

## Knapsack

# Knapsack

KNAPSACK is NP-complete.

• filled in in one dimensional array onthe board

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#### TODO

Questions:

# References

- [1] Martin Berglund. Lecture notes in Computational Complexity.
- [2] Christos H. Papadimitriou. Computational Complexity. Addison-Wesley Publishing Company, 1994.