```
function [v,a]= radar_config(t,r,A)

[~,n]= size(t);
v= zeros(n, 2);
a= zeros(n, 2);
h = t(2)-t(1);
for i= 2: n-1
    dot_r = (r(i+1)-r(i-1))/h;
    dot_r2 = (r(i+1)-2*r(i)+r(i-1))/h^2;

    dot_A = (A(i+1)-r(i-1))/h;
    dot_A2 = (A(i+1)-2*A(i)+A(i-1))/h^2;

    v(i,1) = dot_r;
    v(i,2)= r(i)*dot_A2;
    a(i,1)= dot_r2-r(i)*dot_A^2;
    a(i,2)=r(i)*dot_A2 + 2*dot_r*dot_A;
end
```

Not enough input arguments.

```
Error in radar_config (line 3)
[~,n]= size(t);
```

Published with MATLAB® R2021b