

Embedded System Design with MCU and FPGA

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Goal

Let us know more about GPIO, Timer, and Clock.

Problems

1. Describe at least two methods that you used to blink the LED.

- There are three methods which could be used to blink the LED.

① **Waiting**

- Use `delay()` function, such as Fig 1., to blink the LED. ([Here is the link of the experiment.](#))
- `delay()` is a blocking function.

```
1 void setup() {
2     DDRB |= (1 << 5);
3 }
4
5 void loop() {
6     PORTB |= (1 << 5);
7     delay(1000);
8     PORTB &= ~(1 << 5);
9     delay(1000);
10 }
```

Fig 1. using `delay()` to blink LED

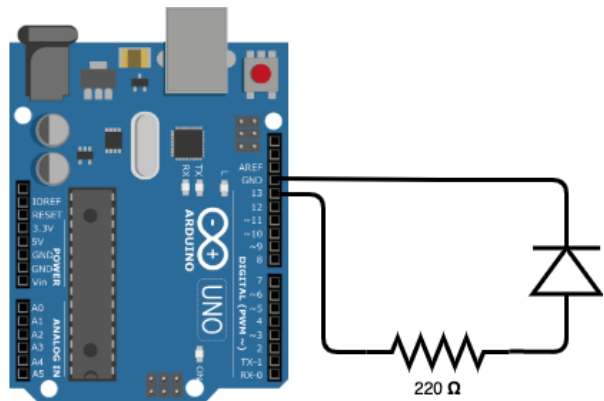


Fig 2. circuit diagram of blink LED

- Use `millis()` function, such as Fig 3., to blink the LED.

② **Interrupt**

- Use a **timer**, such as Fig 4., to blink the LED. ([Here is the link of the experiment.](#))

```
1 const int ledPin = 13;
2 void setup() {
3     pinMode(ledPin, OUTPUT);
4     TCCR1A = 0x00;
5     TCCR1B |= _BV(CS12);
6     TCCR1B &= ~_BV(CS11);
7     TCCR1B |= _BV(CS10);
8     TCNT1 = 0;
9 }
10
11 void loop() {
12     digitalWrite(ledPin, HIGH);
13     delay1s();
14     digitalWrite(ledPin, LOW);
15     delay1s();
16 }
17
18 void delay1s() {
19     while (TCNT1 < 15625/2)
20     ;
21     TCNT1 = 0;
22 }
```

Fig 4. using timer to blink the LED

```
1 const int ledPin = 13;
2 int ledState = LOW;
3 unsigned long previousMillis = 0;
4 const int interval = 1000;
5
6 void setup() {
7     pinMode(ledPin, OUTPUT);
8 }
9
10 void loop() {
11     unsigned long currentMillis = millis();
12     if (currentMillis - previousMillis > interval) {
13         previousMillis = currentMillis;
14         ledState = !ledState;
15         digitalWrite(ledPin, ledState);
16     }
17 }
```

Fig 3. using `millis()` to blink the LED

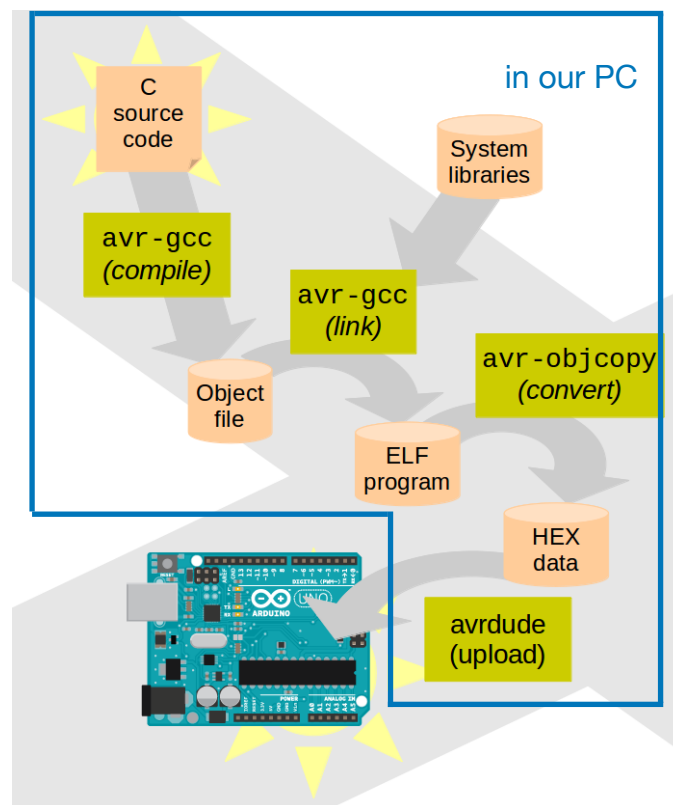
- Use an **external interrupt wired** to an external source that toggles a logic state each second. (Any clock should be a good source.)
- ③ **Polling**
 - Use a **library** like TimedAction, EventFuse, Scheduler or simply 'Blink without delay'

2. How many timer in ATmega 328p? What is the usage of timer0 in Arduino world.

- There are **three timer registers** in ATmega 328p. [3]
 - two 8-bit timers which are **timer0** and **timer2**
 - one 16-bit timers which is **timer1**
 - The most important difference between 8-bit and 16-bit timer is the timer resolution. 8bits means 256 values where 16bit means 65536 values.
- In the Arduino world, the usage of each timer:
 - timer0 is been used for the **timer functions, like delay(), millis() and micros()**
 - timer1 is been used in the Servo library
 - timer2 is been used in the tone() function

3. Explain why we should use the cross-compiler.

- A cross compiler is for cross-platform software development of machine code. [1]
- In the Arduino, direct compilation is infeasible, because it **doesn't contain operating system**. We could use the cross-compiler to compile the code on our computer, and generate the executable machine code for Arduino.



4. Explain your plan of de-bouncing the push button.

- Use **millis() function** to de-bounce the push button. ([Here is the link of the experiment.](#))
- In Fig 6., it is the flow chart I used to de-bounce the push button.

```

1  const int buttonPin = 2;
2  const int ledPin = 13;
3  int ledState = HIGH;
4  int buttonState;
5  int lastButtonState = LOW;
6
7  unsigned long lastDebounceTime = 0;
8  unsigned long debounceDelay = 50;
9
10 void setup() {
11   pinMode(buttonPin, INPUT);
12   pinMode(ledPin, OUTPUT);
13   digitalWrite(ledPin, ledState);
14 }
15
16 void loop() {
17   int reading = digitalRead(buttonPin);
18   if (reading != lastButtonState) {
19     lastDebounceTime = millis();
20   }
21   if ((millis() - lastDebounceTime) > debounceDelay) {
22     if (reading != buttonState) {
23       buttonState = reading;
24       if (buttonState == HIGH) {
25         ledState = !ledState;
26       }
27     }
28   }
29   digitalWrite(ledPin, ledState);
30   lastButtonState = reading;
31 }

```

Fig 5. using millis() to de-bounce the push

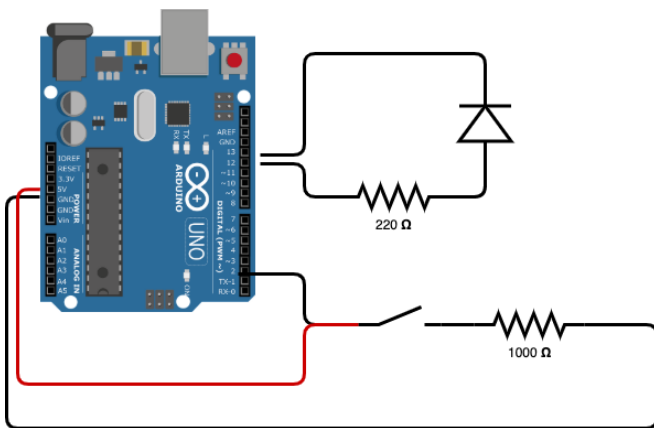


Fig 7. circuit diagram of de-bouncing the

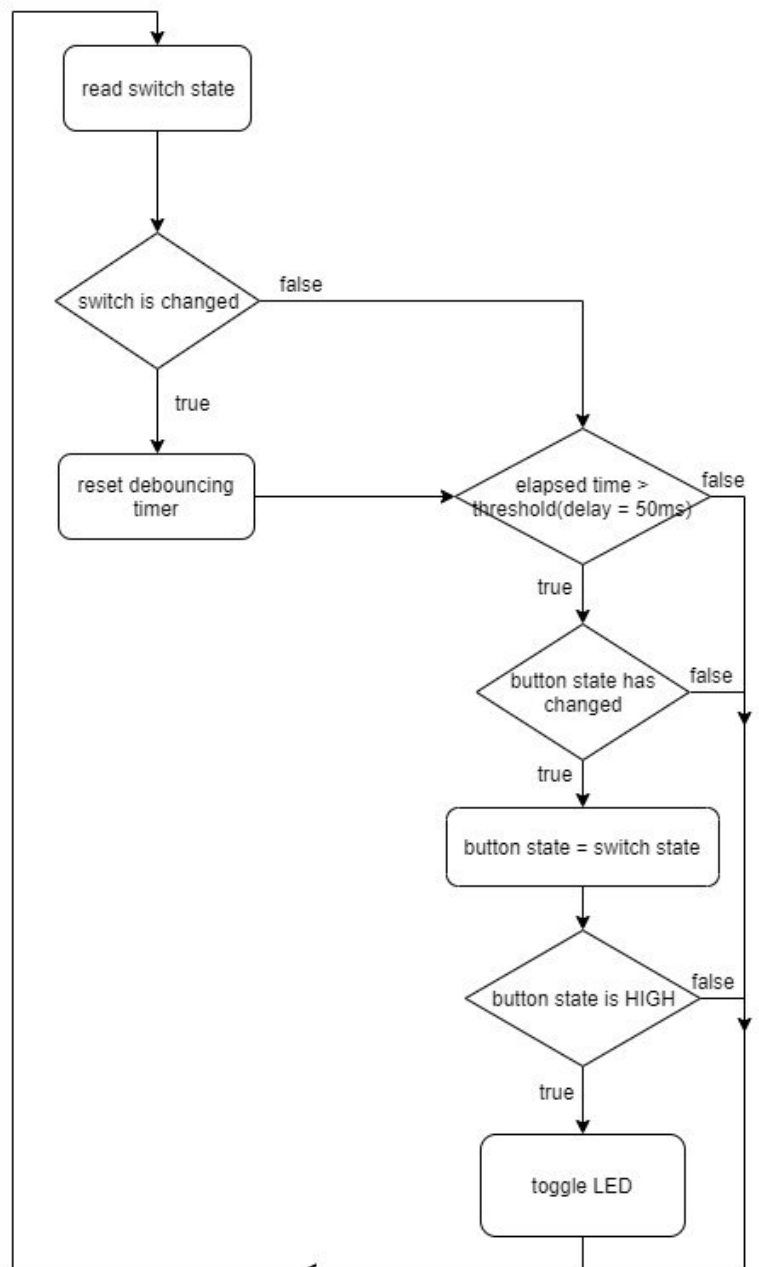


Fig 6. flow chart of de-bouncing the push button

Reference

- [1] https://en.wikipedia.org/wiki/Cross_compiler
- [2] <http://www.avrbeginners.net/architecture/timers/timers.html>
- [3] <https://www.arnabkumardas.com/online-courses/avr-timer-counter-programming-tutorial-atmega328p-avr-8-bit-arduino-uno/>

* Note: The LAB exercises and answers in this report are discussed with another student 吳承霖(0858615).