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# Python POD API

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**CONTENTS:**

<b>1</b>	<b>API_Modules</b>	<b>1</b>
1.1	BasicPodProtocol module . . . . .	1
1.2	GetUserInput module . . . . .	5
1.3	PodCommands module . . . . .	9
1.4	PodDevice_8206HR module . . . . .	13
1.5	PodDevice_8401HR module . . . . .	14
1.6	PodPacketHandling module . . . . .	17
1.7	SerialCommunication module . . . . .	20
1.8	Setup_8206HR module . . . . .	22
1.9	Setup_8401HR module . . . . .	23
1.10	Setup_PodDevices module . . . . .	24
1.11	Setup_PodInterface module . . . . .	25
<b>2</b>	<b>Indices and tables</b>	<b>29</b>
	<b>Python Module Index</b>	<b>31</b>
	<b>Index</b>	<b>33</b>



## API\_MODULES

### 1.1 BasicPodProtocol module

**class** BasicPodProtocol.POD\_Basics(*port: str | int, baudrate: int = 9600*)

Bases: object

POD\_Basics handles basic communication with a generic POD device, including reading and writing packets and packet interpretation.

**\_\_numPod**

Class-level integer counting the number of POD\_Basics instances

**Type**  
int

**\_\_MINSTANDARDLENGTH**

Class-level integer representing the minimum length of a standard POD command packet.

**Type**  
int

**\_\_MINBINARYLENGTH**

Class-level integer representing the minimum length of a binary POD command packet.

**Type**  
int

**\_port**

Instance-level COM\_io object, which handles the COM port

**Type**  
*COM\_io*

**\_commands**

Instance-level POD\_Commands object, which stores information about the commands available to this POD device.

**Type**  
*POD\_Commands*

**GetDeviceCommands()** → dict[int, list[str | tuple[int] | bool]]

Gets the dictionary containing the class instance's available POD commands.

**Returns**

Dictionary containing the available commands and their information. Formatted as

key(command number) : value([command name, number of argument ASCII bytes, number of return bytes, binary flag ])

**Return type**

dict[int, list[str|tuple[int]|bool]]

**static GetNumberOfPODDevices()** → int

Gets the POD device counter (\_\_numPod).

**Returns**

Number of POD\_Basics instances.

**Return type**

int

**GetPODpacket**(*cmd: str | int, payload: int | bytes | tuple[int | bytes] | None = None*) → bytes

Builds a POD packet and writes it to a POD device via COM port. If an integer payload is give, the method will convert it into a bytes string of the length expected by the command. If a bytes payload is given, it must be the correct length.

**Parameters**

- **cmd** (*str | int*) – Command number.
- **payload** (*int | bytes | tuple[int | bytes], optional*) – None when there is no payload. If there is a payload, set to an integer value, bytes string, or tuple. Defaults to None.

**Raises**

- **Exception** – POD command does not exist.
- **Exception** – POD command requires a payload.

**Returns**

Bytes string of the POD packet.

**Return type**

bytes

**ReadPODpacket**(*validateChecksum: bool = True*) → bytes

Reads a complete POD packet, either in standard or binary format, beginning with STX and ending with ETX. Reads first STX and then starts recursion.

**Parameters**

**validateChecksum** (*bool, optional*) – Set to True to validate the checksum. Set to False to skip validation. Defaults to True.

**Returns**

Bytes string containing a POD packet beginning with STX and ending with ETX. This may be a standard packet, binary packet, or an unformatted packet (STX+something+ETX).

**Return type**

bytes

**SetBaudrateOfDevice**(*baudrate: int*) → bool

If the port is open, it will change the baud rate to the parameter's value.

**Parameters**

**baudrate** (*int*) – Baud rate to set for the open serial port.

**Returns**

True if successful at setting the baud rate, false otherwise.

**Return type**

bool

**TranslatePODpacket**(*msg: bytes*) → dict[str, int | bytes]

Determines if the packet is standard or binary, and translates accordingly.

**Parameters****msg** (*bytes*) – Bytes string containing either a standard or binary packet.**Returns**

A dictionary containing the unpacked message in numbers.

**Return type**

dict[str,int|bytes]

**static TranslatePODpacket\_Binary**(*msg: bytes*) → dict[str, int | bytes]

Unpacks the variable-length binary POD packet and converts the values of the ASCII-encoded bytes into integer values and leaves the binary-encoded bytes as is.

**Parameters****msg** (*bytes*) – Bytes message containing a variable-length POD packet.**Returns**

A dictionary containing the ‘Command Number’ and ‘Binary Packet Length’ in integers, and ‘Binary Data’ in bytes.

**Return type**

dict[str,int|bytes]

**TranslatePODpacket\_Standard**(*msg: bytes*) → dict[str, int]

Unpacks the standard POD packet and converts the ASCII-encoded bytes values into integer values.

**Parameters****msg** (*bytes*) – Bytes message containing a standard POD packet**Returns**

A dictionary containing the POD packet’s ‘Command Number’ and ‘Payload’ (if applicable) in integers.

**Return type**

dict[str,int]

**UnpackPODpacket**(*msg: bytes*) → dict[str, bytes]

Determines if the packet is standard or binary, and unpacks accordingly.

**Parameters****msg** (*bytes*) – Bytes string containing either a standard or binary packet**Returns**

A dictionary containing the unpacked message in bytes

**Return type**

dict[str,bytes]

**static UnpackPODpacket\_Binary**(*msg: bytes*) → dict[str, bytes]

Converts a variable-length binary packet into a dictionary containing the command number, binary packet length, and binary data in bytes.

**Parameters****msg** (*bytes*) – Bytes message containing a variable-length POD packet

**Returns**

A dictionary containing 'Command Number', 'Binary Packet Length', and 'Binary Data' keys with bytes values.

**Return type**

dict[str,bytes]

**Raises****Exception –**

- (1) The msg does not have the minimum number of bytes in a standard pod packet,(2) does not begin with STX, (3) does not end with ETX, and (4) does not have an ETX after standard packet.

**static UnpackPODpacket\_Standard**(msg: bytes) → dict[str, bytes]

Converts a standard POD packet into a dictionary containing the command number and payload (if applicable) in bytes.

**Parameters**

**msg** (bytes) – Bytes message containing a standard POD packet.

**Returns**

A dictionary containing the POD packet's 'Command Number' and 'Payload' (if applicable) in bytes.

**Return type**

dict[str,bytes]

**Raises****Exception –**

- (1) The msg does not have the minimum number of bytes in a standard pod packet, (2) does not begin with STX, and (3) does not end with ETX.

**WritePacket**(cmd: str | int, payload: int | bytes | tuple[int | bytes] | None = None) → bytes

Builds a POD packet and writes it to the POD device.

**Parameters**

- **cmd** (str | int) – Command number.
- **payload** (int | bytes | tuple[int | bytes], optional) – None when there is no payload. If there is a payload, set to an integer value, bytes string, or tuple. Defaults to None.

**Returns**

Bytes string that was written to the POD device.

**Return type**

bytes

**WriteRead**(cmd: str | int, payload: int | bytes | tuple[int | bytes] | None = None, validateChecksum: bool = True) → bytes

Writes a command with optional payload to POD device, then reads (once) the device response.

**Parameters**

- **cmd** (str | int) – Command number.
- **payload** (int | bytes | tuple[int|bytes], optional) – None when there is no payload. If there is a payload, set to an integer value or a bytes string. Defaults to None.



- **validateChecksum** (*bool, optional*) – Set to True to validate the checksum. Set to False to skip validation. Defaults to True.

**Returns**

Bytes string containing a POD packet beginning with STX and ending with ETX. This may be a standard packet, binary packet, or an unformatted packet (STX+something+ETX).

**Return type**

bytes

## 1.2 GetUserInput module

### **class** GetUserInput.UserInput

Bases: object

UserInput contains several methods for getting user input for POD device setup.

**static AskForFloat** (*prompt: str*) → float

Asks user for float type input.

**Parameters**

**prompt** (*str*) – Statement requesting input from the user.

**Returns**

Float type input from user.

**Return type**

float

**static AskForFloatInList** (*prompt: str, goodInputs: list, badInputMessage: str | None = None*) → float

Asks the user for a float that exists in the list of valid options.

**Parameters**

- **prompt** (*str*) – Statement requesting input from the user.
- **goodInputs** (*list*) – List of valid input options.
- **badInputMessage** (*str | None, optional*) – Error message to be printed if invalid input is given. Defaults to None.

**Returns**

User's choice from the options list as a float.

**Return type**

float

**static AskForFloatInRange** (*prompt: str, minimum: float, maximum: float, thisIs: str = 'Input', unit: str = ''*) → float

Asks the user for an float value that falls in a given range.

**Parameters**

- **prompt** (*str*) – Statement requesting input from the user.
- **minimum** (*float*) – Minimum value of range.
- **maximum** (*float*) – Maximum value of range.
- **thisIs** (*str, optional*) – Description of the input/what is being asked for. Used when printing the error message. Defaults to 'Input'.

- **unit** (*str*, *optional*) – Unit of the requested value. Use when printing the error message. Defaults to ‘.’.

**Returns**

Float value given by the user that falls in the given range.

**Return type**

float

**static AskForInput**(*prompt: str*, *append: str = ': '*) → *str*

Asks user for input given a prompt. Will append a colon ‘:’ to the end of prompt by default

**Parameters**

- **prompt** (*str*) – Statement requesting input from the user
- **append** (*str*, *optional*) – Appended to the end of the prompt. Defaults to ‘: ’.

**Returns**

String of the user input

**Return type**

str

**static AskForInt**(*prompt: str*) → *int*

Asks user for int type input.

**Parameters**

**prompt** (*str*) – Statement requesting input from the user.

**Returns**

integer type input from user.

**Return type**

int

**static AskForIntInList**(*prompt: str*, *goodInputs: list*, *badInputMessage: str | None = None*) → *int*

Asks the user for an integer that exists in the list of valid options.

**Parameters**

- **prompt** (*str*) – Statement requesting input from the user
- **goodInputs** (*list*) – List of valid input options.
- **badInputMessage** (*str | None*, *optional*) – Error message to be printed if invalid input is given. Defaults to None.

**Returns**

User’s choice from the options list as an integer.

**Return type**

int

**static AskForIntInRange**(*prompt: str*, *minimum: int*, *maximum: int*, *thisIs: str = 'Input'*, *unit: str = ''*) → *int*

Asks the user for an integer value that falls in a given range.

**Parameters**

- **prompt** (*str*) – Statement requesting input from the user.
- **minimum** (*int*) – Minimum value of range.
- **maximum** (*int*) – Maximum value of range.

- **thisIs** (*str*, *optional*) – Description of the input/what is being asked for. Used when printing the error message. Defaults to ‘Input’.
- **unit** (*str*, *optional*) – Unit of the requested value. Use when printing the error message. Defaults to ‘’.

**Returns**

Integer value given by the user that falls in the given range.

**Return type**

int

**static AskForStrInList** (*prompt: str*, *goodInputs: list*, *badInputMessage: str | None = None*) → str

Asks the user for a string that exists in the list of valid options.

**Parameters**

- **prompt** (*str*) – Statement requesting input from the user.
- **goodInputs** (*list*) – List of valid input options
- **badInputMessage** (*str | None*, *optional*) – Error message to be printed if invalid input is given. Defaults to None.

**Returns**

User’s choice from the options list as a string.

**Return type**

str

**static AskForType** (*typecast: function*, *prompt: str*) → int | float | str

Ask user for input of a specific data type. If invalid input is given, an error message will print and the user will be prompted again.

**Parameters**

- **typecast** (*function*) – Datatype to cast the user input (ex. `_CastInt`, `_CastFloat`, `_CastStr`)
- **prompt** (*str*) – Statement requesting input from the user

**Returns**

Input from user as the requested type.

**Return type**

int|float|str

**static AskForTypeInList** (*typecast: function*, *prompt: str*, *goodInputs: list*, *badInputMessage: str | None = None*) → int | float | str

Asks the user for a value of a given type that exists in the list of valid options. If invalid input is given, an error message will print and the user will be prompted again.

**Parameters**

- **typecast** (*function*) – Datatype to cast the user input (ex. `_CastInt`, `_CastFloat`, `_CastStr`).
- **prompt** (*str*) – Statement requesting input from the user.
- **goodInputs** (*list*) – List of valid input options.
- **badInputMessage** (*str | None*, *optional*) – Error message to be printed if invalid input is given. Defaults to None.

**Returns**

User's choice from the goodInputs list as the given datatype.

**Return type**

int|float|str

**static AskForTypeInRange**(*typecast: function, prompt: str, minimum: int | float, maximum: int | float, thisIs: str = 'Input', unit: str = ''*) → int | float

Asks user for a numerical value that falls between two numbers. If invalid input is given, an error message will print and the user will be prompted again.

**Parameters**

- **typecast** (*function*) – Datatype to cast the user input (ex. `_CastInt`, `_CastFloat`, `_CastStr`).
- **prompt** (*str*) – Statement requesting input from the user.
- **minimum** (*int | float*) – Minimum value of range.
- **maximum** (*int | float*) – Maximum value of range.
- **thisIs** (*str, optional*) – Description of the input/what is being asked for. Used when printing the error message. Defaults to 'Input'.
- **unit** (*str, optional*) – Unit of the requested value. Use when printing the error message. Defaults to ''.

**Returns**

Numerical value given by the user that falls in the given range.

**Return type**

int|float

**static AskYN**(*question: str, append: str = '(y/n): '*) → bool

Asks the user a yes or no question. If invalid input is given, an error message will print and the user will be prompted again.

**Parameters**

- **question** (*str*) – Statement requesting input from the user.
- **append** (*str, optional*) – Appended to the end of the question. Defaults to '(y/n): '.

**Returns**

True for yes, false for no.

**Return type**

bool

**static CastFloat**(*value*) → float

Casts the argument as an float.

**Parameters**

**value** – Value to type casted.

**Returns**

Value type casted as a float.

**Return type**

float

**static** **CastInt**(*value*) → int

Casts the argument as an integer.

**Parameters**

**value** – Value to type casted.

**Returns**

Value type casted as an integer.

**Return type**

int

**static** **CastStr**(*value*) → str

Casts the argument as a string.

**Parameters**

**value** – Value to type casted.

**Returns**

Value type casted as a string.

**Return type**

str

## 1.3 PodCommands module

**class** PodCommands.**POD\_Commands**

Bases: object

POD\_Commands manages a dictionary containing available commands for a POD device.

**\_\_NAME**

Class-level integer representing the index key for the command name for \_\_commands list values.

**Type**

int

**\_\_ARGUMENTS**

Class-level integer representing the index key for the number of bytes in an argument for \_\_commands list values.

**Type**

int

**\_\_RETURNS**

Class-level integer representing the index key for the number of bytes in the return for \_\_commands list values.

**Type**

int

**\_\_BINARY**

Class-level integer representing the index key for the binary flag for \_\_commands list values.

**Type**

int

**\_\_NOVALUE**

Class-level integer used to mark when a list item in `__commands` means ‘no value’ or is undefined.

**Type**  
int

**\_\_U8**

Class-level integer representing the number of hexadecimal characters for an unsigned 8-bit value.

**Type**  
int

**\_\_U16**

Class-level integer representing the number of hexadecimal characters for an unsigned 16-bit value.

**Type**  
int

**\_\_commands**

Dictionary containing the available commands for a POD device. Each entry is formatted as { key(command number) : value([command name, number of argument ASCII bytes, number of return bytes, binary flag ) }.

**Type**  
dict[int,list[str|tuple[int]]|bool]]

**AddCommand**(*commandNumber: int, commandName: str, argumentBytes: tuple[int], returnBytes: tuple[int], isBinary: bool*) → bool

Adds a command entry to the current commands dictionary (`__commands`) if the command does not exist.

**Parameters**

- **commandNumber** (*int*) – Integer of the command number.
- **commandName** (*str*) – String of the command’s name.
- **argumentBytes** (*tuple[int]*) – Integer of the number of bytes in the argument.
- **returnBytes** (*tuple[int]*) – Integer of the number of bytes in the return.
- **isBinary** (*bool*) – Boolean flag to mark if the command is binary (True) or standard (False).

**Returns**

True if the command was successfully added, False if the command could not be added because it already exists.

**Return type**  
bool

**ArgumentHexChar**(*cmd: int | str*) → tuple[int] | None

Gets the tuple for the number of hex characters in the argument for a given command.

**Parameters**

**cmd** (*int | str*) – integer command number or string command name.

**Returns**

Tuple representing the number of bytes in the argument for cmd. If the command could not be found, return None.

**Return type**  
tuple[int]|None

**CommandNumberFromName**(*name: str*) → int | None

Gets the command number from the command dictionary using the command's name.

**Parameters**

**name** (*str*) – string of the command's name.

**Returns**

Integer representing the command number. If the command could not be found, return None.

**Return type**

int|None

**DoesCommandExist**(*cmd: int | str*) → bool

Checks if a command exists in the \_\_commands dictionary.

**Parameters**

**cmd** (*int | str*) – integer command number or string command name.

**Returns**

True if the command exists, false otherwise.

**Return type**

bool

**static GetBasicCommands**() → dict[int, list[str | tuple[int] | bool]]

Creates a dictionary containing the basic POD command set (0,1,2,3,4,5,6,7,8,9,10,11,12).

**Returns**

Dictionary containing the available commands for this POD device. Each entry is formatted as { key(command number) : value([command name, number of argument ASCII bytes, number of return bytes, binary flag ) }.

**Return type**

dict[int,list[str|tuple[int]|bool]]

**GetCommands**() → dict[int, list[str | tuple[int] | bool]]

Gets the contents of the current command dictionary (\_\_commands).

**Returns**

Dictionary containing the available commands for a POD device. Each entry is formatted as { key(command number) : value([command name, number of argument ASCII bytes, number of return bytes, binary flag ) }.

**Return type**

dict[int, list[str|tuple[int]|bool]]

**IsCommandBinary**(*cmd: int | str*) → bool | None

Gets the binary flag for a given command.

**Parameters**

**cmd** (*int | str*) – integer command number or string command name.

**Returns**

Boolean flag that is True if the command is binary and False if standard. If the command could not be found, return None.

**Return type**

bool|None

**static NoValue**() → int

Gets value of \_\_NOVALUE.

**Returns**

Value of \_\_NOVALUE.

**Return type**

int

**RemoveCommand**(*cmd: int | str*) → bool

Removes the entry for a given command in \_\_commands dictionary.

**Parameters**

**cmd** (*int* / *str*) – integer command number or string command name.

**Returns**

True if the command was successfully removed, False if the command does not exist.

**Return type**

bool

**RestoreBasicCommands**() → None

Sets the current commands (\_\_commands) to the basic POD command set.

**ReturnHexChar**(*cmd: int | str*) → tuple[int] | None

Gets the tuple for the number of hex characters in the return for a given command.

**Parameters**

**cmd** (*int* / *str*) – integer command number or string command name.

**Returns**

Tuple representing the number of hex characters in the return for cmd. If the command could not be found, return None.

**Return type**

tuple[int]|None

**static U16**() → int

Gets value of \_\_U16.

**Returns**

Value of \_\_U16.

**Return type**

int

**static U8**() → int

Gets value of \_\_U8.

**Returns**

Value of \_\_U8.

**Return type**

int



## 1.4 PodDevice\_8206HR module

**class** PodDevice\_8206HR.POD\_8206HR(*port: str | int, preampGain: int, baudrate: int = 9600*)

Bases: [POD\\_Basics](#)

POD\_8206HR handles communication using an 8206HR POD device.

**\_\_B4LENGTH**

Class-level integer representing the number of bytes for a Binary 4 packet.

**Type**

int

**\_\_B4BINARYLENGTH**

Class-level integer representing the number of binary bytes for a Binary 4 packet.

**Type**

int

**\_preampGain**

Instance-level integer (10 or 100) preamplifier gain.

**Type**

int

**TranslatePODpacket**(*msg: bytes*) → dict[str, int | dict[str, int]]

Overwrites the parent's method. Determines if the packet is standard or binary, and translates accordingly. Adds a check for the 'GET TTL PORT' command.

**Parameters**

**msg** (*bytes*) – Bytes string containing either a standard or binary packet.

**Returns**

A dictionary containing the unpacked message in numbers.

**Return type**

dict[str,int|dict[str,int]]

**TranslatePODpacket\_Binary**(*msg: bytes*) → dict[str, int | float | dict[str, int]]

Overwrites the parent's method. Unpacks the binary4 POD packet and converts the values of the ASCII-encoded bytes into integer values and the values of binary-encoded bytes into integers. Channel values are given in Volts.

**Parameters**

**msg** (*bytes*) – Bytes string containing a complete binary4 Pod packet: STX (1 byte) + command (4 bytes) + packet number (1 bytes) + TTL (1 byte) + ch0 (2 bytes) + ch1 (2 bytes) + ch2 (2 bytes) + checksum (2 bytes) + ETX (1 byte).

**Returns**

A dictionary containing 'Command Number', 'Packet #', 'TTL', 'Ch0', 'Ch1', and 'Ch2' as numbers.

**Return type**

dict[str,int|float|dict[str,int]]

**static UnpackPODpacket\_Binary**(*msg: bytes*) → dict[str, bytes]

Overwrites the parent's method. Separates the components of a binary4 packet into a dictionary.

**Parameters**

**msg** (*bytes*) – Bytes string containing a complete binary4 Pod packet: STX (1 byte) + command (4 bytes) + packet number (1 bytes) + TTL (1 byte) + ch0 (2 bytes) + ch1 (2 bytes) + ch2 (2 bytes) + checksum (2 bytes) + ETX (1 byte).

**Raises**

**Exception** –

- (1) the packet does not have the minimum number of bytes, (2) does not begin with STX, or (3) does not end with ETX.

**Returns**

A dictionary containing ‘Command Number’, ‘Packet #’, ‘TTL’, ‘Ch0’, ‘Ch1’, and ‘Ch2’ in bytes.

**Return type**

dict[str,bytes]

## 1.5 PodDevice\_8401HR module

```
class PodDevice_8401HR.POD_8401HR(port: str | int, ssGain: dict[str, int | None] = {'A': None, 'B': None, 'C': None, 'D': None}, preampGain: dict[str, int | None] = {'A': None, 'B': None, 'C': None, 'D': None}, baudrate: int = 9600)
```

Bases: [POD\\_Basics](#)

POD\_8401HR handles communication using an 8401-HR POD device.

**\_\_B5LENGTH**

Class-level integer representing the number of bytes for a Binary 5 packet.

**Type**

int

**\_\_B5BINARYLENGTH**

Class-level integer representing the number of binary bytes for a Binary 5 packet.

**Type**

int

**\_\_CHANNELMAPALL**

Class-level dictionary containing the channel map for all preamplifier devices.

**Type**

dict[str,dict[str,str]]

**\_ssGain**

Instance-level dictionary storing the second-stage gain for all four channels.

**Type**

dict[str,int|None]

**\_preampGain**

Instance-level dictionary storing the pramplifier gain for all four channels.

**Type**

dict[str,int|None]

**static CalculateBiasDAC\_GetDACValue**(*vout: int | float*) → int

Calculates the DAC value given the output voltage. Used for ‘GET/SET BIAS’ commands.

**Parameters**

**vout** (*int | float*) – Output voltage (+/- 2.048 V).

**Returns**

Integer of the DAC value (16 bit 2’s complement).

**Return type**

int

**static CalculateBiasDAC\_GetVout**(*value: int*) → float

Calculates the output voltage given the DAC value. Used for ‘GET/SET BIAS’ commands.

**Parameters**

**value** (*int*) – DAC value (16 bit 2’s complement).

**Returns**

Float of the output bias voltage [V].

**Return type**

float

**static GetChannelMapForPreampDevice**(*preampName: str*) → dict[str, str] | None

Get the channel mapping (channel labels for A,B,C,D) for a given device.

**Parameters**

**preampName** (*str*) – String for the device/sensor name.

**Returns**

Dictionary with keys A,B,C,D with values of the channel names. Returns None if the device name does not exist.

**Return type**

dict[str,str]|None

**static GetSSConfigBitmask\_int**(*gain: int, highpass: float*) → int

Gets a bitmask, represented by an unsigned integer, used for ‘SET SS CONFIG’ command.

**Parameters**

- **gain** (*int*) – 1 for 1x gain. else for 5x gain.
- **highpass** (*float*) – 0 for DC highpass, else for 0.5Hz highpass.

**Returns**

Integer representing a bitmask.

**Return type**

int

**static GetSupportedPreampDevices**() → list[str]

Gets a list of device/sensor names used for channel mapping.

**Returns**

List of string names of all supported sensors.

**Return type**

list[str]

**static GetTTLbitmask\_Int**(*ext0: bool = 0, ext1: bool = 0, ttl4: bool = 0, ttl3: bool = 0, ttl2: bool = 0, ttl1: bool = 0*) → int

Builds an integer, which represents a binary mask, that can be used for TTL command arguments.

**Parameters**

- **ext0** (*bool, optional*) – boolean bit for ext0. Defaults to 0.
- **ext1** (*bool, optional*) – boolean bit for ext1. Defaults to 0.
- **ttl4** (*bool, optional*) – boolean bit for ttl4. Defaults to 0.
- **ttl3** (*bool, optional*) – boolean bit for ttl3. Defaults to 0.
- **ttl2** (*bool, optional*) – boolean bit for ttl2. Defaults to 0.
- **ttl1** (*bool, optional*) – boolean bit for ttl1. Defaults to 0.

**Returns**

Integer number to be used as a bit mask.

**Return type**

int

**static IsPreampDeviceSupported**(*name: str*) → bool

Checks if the argument exists in channel map for all preamp sensors.

**Parameters**

**name** (*str*) – name of the device

**Returns**

True if the name exists in \_\_CHANNELMAPALL, false otherwise.

**Return type**

bool

**TranslatePODpacket**(*msg: bytes*) → dict[str, int | dict[str, int]]

Overwrites the parent's method. Unpacks the binary5 POD packet and converts the values of the ASCII-encoded bytes into integer values and the values of binary-encoded bytes into integers. The channels and analogs are converted to volts (V).

**Parameters**

**msg** (*bytes*) – Bytes string containing a complete binary 5 Pod packet: STX (1 byte) + command (4) + packet number (1) + status (1) + channels (9) + analog inputs (12) + checksum (2) + ETX (1).

**Returns**

A dictionary containing 'Command Number', 'Packet #', 'Status', 'D', 'C', 'B', 'A', 'Analog EXT0', 'Analog EXT1', 'Analog TTL1', 'Analog TTL2', 'Analog TTL3', 'Analog TTL4', as numbers.

**Return type**

dict[str,int|dict[str,int]]

**TranslatePODpacket\_Binary**(*msg: bytes*) → dict[str, int | float]

Unpacks the variable-length binary POD packet and converts the values of the ASCII-encoded bytes into integer values and leaves the binary-encoded bytes as is.

**Parameters**

**msg** (*bytes*) – Bytes message containing a variable-length POD packet.

**Returns**

A dictionary containing the 'Command Number' and 'Binary Packet Length' in integers, and 'Binary Data' in bytes.

**Return type**

dict[str,int|bytes]

**static UnpackPODpacket\_Binary**(*msg: bytes*) → dict[str, bytes]

Overwrites the parent's method. Separates the components of a binary5 packet into a dictionary.

**Parameters**

**msg** (*bytes*) – Bytes string containing a complete binary5 Pod packet: STX (1 byte) + command (4) + packet number (1) + status (1) + channels (9) + analog inputs (12) + checksum (2) + ETX (1)

**Raises****Exception –**

- (1) The packet does not have the minimum number of bytes, (2) does not begin with STX, or (3) does not end with ETX.

**Returns**

A dictionary containing 'Command Number', 'Packet #', 'Status', 'Channels', 'Analog EXT0', 'Analog EXT1', 'Analog TTL1', 'Analog TTL2', 'Analog TTL3', 'Analog TTL4', in bytes.

**Return type**

dict[str,bytes]

## 1.6 PodPacketHandling module

**class PodPacketHandling.POD\_Packets**

Bases: object

POD\_Packets is a collection of methods for creating and interpreting POD packets.

**static ASCIIbytesToInt\_Split**(*msg: bytes, keepTopBits: int, cutBottomBits: int*) → int

Converts a specific bit range in an ASCII-encoded bytes object to an integer.

**Parameters**

- **msg** (*bytes*) – Bytes message holding binary information to be converted into an integer.
- **keepTopBits** (*int*) – Integer position of the msb of desired bit range.
- **cutBottomBits** (*int*) – Integer number of lsb to remove.

**Returns**

Integer result from the ASCII-encoded bytes message in a given bit range.

**Return type**

int

**static AsciiBytesToInt**(*msg\_b: bytes, signed: bool = False*) → int

Converts a ASCII-encoded bytes message into an integer. It does this using a base-16 conversion. If the message is signed and the msb is '1', the integer will be converted to it's negative 2's complement.

**Parameters**

- **msg\_b** (*bytes*) – Bytes message to be converted to an integer. The bytes must be base-16 or the conversion will fail.

- **signed** (*bool*, *optional*) – True if the message is signed, false if unsigned. Defaults to False.

**Returns**

Integer result from the ASCII-encoded byte conversion.

**Return type**

int

**static BinaryBytesToInt** (*msg: bytes, byteorder: str = 'big', signed: bool = False*) → int

Converts binary-encoded bytes into an integer.

**Parameters**

- **msg** (*bytes*) – Bytes message holding binary information to be converted into an integer.
- **byteorder** (*str*, *optional*) – Ordering of bytes. ‘big’ for big endian and ‘little’ for little endian. Defaults to ‘big’.
- **signed** (*bool*, *optional*) – Boolean flag to mark if the msg is signed (True) or unsigned (False). Defaults to False.

**Returns**

Integer result from the binary-encoded bytes message.

**Return type**

int

**static BinaryBytesToInt\_Split** (*msg: bytes, keepTopBits: int, cutBottomBits: int, byteorder: str = 'big', signed: bool = False*) → int

Converts a specific bit range in a binary-encoded bytes object to an integer.

**Parameters**

- **msg** (*bytes*) – Bytes message holding binary information to be converted into an integer.
- **keepTopBits** (*int*) – Integer position of the msb of desired bit range.
- **cutBottomBits** (*int*) – Integer number of lsb to remove.
- **byteorder** (*str*, *optional*) – Ordering of bytes. ‘big’ for big endian and ‘little’ for little endian. Defaults to ‘big’.
- **signed** (*bool*, *optional*) – Boolean flag to mark if the msg is signed (True) or unsigned (False). Defaults to False.

**Returns**

Integer result from the binary-encoded bytes message in a given bit range.

**Return type**

int

**static BuildPODpacket\_Standard** (*commandNumber: int, payload: bytes | None = None*) → bytes

Builds a standard POD packet as bytes: STX (1 byte) + command number (4 bytes) + optional packet (? bytes) + checksum (2 bytes)+ ETX (1 bytes).

**Parameters**

- **commandNumber** (*int*) – Integer representing the command number. This will be converted into a 4 byte long ASCII-encoded bytes string.
- **payload** (*bytes | None, optional*) – bytes string containing the payload. Defaults to None.

**Returns**

Bytes string of a complete standard POD packet.

**Return type**

bytes

**static Checksum**(*bytesIn: bytes*) → bytes

Calculates the checksum of a given bytes message. This is achieved by summing each byte in the message, inverting, and taking the last byte.

**Parameters**

**bytesIn** (*bytes*) – Bytes message containing POD packet data.

**Returns**

Two ASCII-encoded bytes containing the checksum for bytesIn.

**Return type**

bytes

**static ETX**() → bytes

Get end-of-transmission (ETX) character in bytes. ETX marks the end byte of a POD Packet.

**Returns**

Bytes for ETX(0x03).

**Return type**

bytes

**static IntToAsciiBytes**(*value: int, numChars: int*) → bytes

Converts an integer value into ASCII-encoded bytes.

First, it converts the integer value into a usable uppercase hexadecimal string. Then it converts the ASCII code for each character into bytes. Lastly, it ensures that the final message is the desired length.

Example: if value=2 and numBytes=4, the returned ASCII will show b'0002', which is '0x30 0x30 0x30 0x32' in bytes. Uses the 2's complement if the val is negative.

**Parameters**

- **value** (*int*) – Integer value to be converted into ASCII-encoded bytes.
- **numChars** (*int*) – Number characters to be the length of the ASCII-encoded message.

**Returns**

Bytes that are ASCII-encoded conversions of the value parameter.

**Return type**

bytes

**static PayloadToBytes**(*payload: int | bytes | tuple[int | bytes], argSizes: tuple[int]*) → bytes

Converts a payload into a bytes string.

**Parameters**

- **payload** (*int | bytes | tuple[int | bytes]*) – Integer, bytes, or tuple containing the payload.
- **argSizes** (*tuple[int]*) – Tuple of the argument sizes.

**Raises**

- **Exception** – Payload requires multiple arguments, use a tuple.
- **Exception** – Payload is the wrong size.

- **Exception** – Payload has an incorrect number of items.
- **Exception** – Payload has invalid values.
- **Exception** – Payload is an invalid type.

**Returns**

Bytes string of the payload.

**Return type**

bytes

**static STX()** → bytes

Get start-of-transmission (STX) character in bytes. STX marks the starting byte of a POD Packet.

**Returns**

Bytes for STX (0x02).

**Return type**

bytes

**static TwosComplement(val: int, nbits: int)** → int

Gets the 2's complement of the argument value.

**Parameters**

- **val** (*int*) – Value to be complemented.
- **nbits** (*int*) – Number of bits in the value.

**Returns**

Integer of the 2's complement for the val.

**Return type**

int

## 1.7 SerialCommunication module

**class SerialCommunication.COM\_io**(*port: str | int, baudrate: int = 9600*)

Bases: object

COM\_io handles serial communication (read/write) using COM ports.

**\_\_serialInst**

Instance-level serial COM port.

**Type**

Serial

**CloseSerialPort()** → None

Closes the instance serial port if it is open.

**static GetCOMportsList()** → list[str]

Finds all the available COM ports on the user's computer and appends them to an accessible list.

**Returns**

List containing the names of available COM ports.

**Return type**

list[str]



**GetPortName()** → str | None

Gets the name of the open port.

**Returns**

If the serial port is open, it will return a string of the port's name. If the port is closed, it will return None.

**Return type**

str|None

**IsSerialClosed()** → bool

Returns False if the serial instance port is open, True otherwise.

**Returns**

True if the COM port is closed, False otherwise.

**Return type**

bool

**IsSerialOpen()** → bool

Returns True if the serial instance port is open, false otherwise.

**Returns**

True if the COM port is open, False otherwise.

**Return type**

bool

**OpenSerialPort**(*port: str | int, baudrate: int = 9600*) → None

First, it closes the serial port if it is open. Then, it opens a serial port with a set baud rate.

**Parameters**

- **port** (*str | int*) – String of the serial port to be opened.
- **baudrate** (*int, optional*) – Integer baud rate of the opened serial port. Defaults to 9600.

**Raises**

**Exception** – Port does not exist.

**Read**(*numBytes: int*) → bytes | None

Reads a specified number of bytes from the open serial port.

**Parameters**

**numBytes** (*int*) – Integer number of bytes to read.

**Returns**

If the serial port is open, it will return a set number of read bytes. If it is closed, it will return None.

**Return type**

bytes|None

**ReadLine()** → bytes | None

Reads until a new line is read from the open serial port.

**Returns**

If the serial port is open, it will return a complete read line. If closed, it will return None.

**Return type**

bytes|None

**ReadUntil**(*eol: bytes*) → bytes | None

Reads until a set character from the open serial port.

**Parameters**

**eol** (*bytes*) – end-of-line character.

**Returns**

If the serial port is open, it will return a read line ending in eol. If closed, it will return None.

**Return type**

bytes|None

**SetBaudrate**(*baudrate: int*) → bool

**Write**(*message: bytes*) → None

Write a set message to the open serial port.

**Parameters**

**message** (*bytes*) – byte string containing the message to write.

## 1.8 Setup\_8206HR module

**class** Setup\_8206HR.**Setup\_8206HR**

Bases: [Setup\\_Interface](#)

Setup\_8206HR provides the setup functions for an 8206-HR POD device.

**\_PARAMKEYS**

Class-level list containing the device parameter dict keys.

**Type**

list[str]

**\_LOWPASSKEYS**

Class-level list containing the keys of the ‘Low-pass’ parameter dict value.

**Type**

list[str]

**\_PHYSICAL\_BOUND\_uV**

Class-level integer representing the max/-min physical value in uV. Used for EDF files.

**Type**

int

**\_NAME**

Class-level string containing the POD device name.

**Type**

str

**static** **GetDeviceName**() → str

Returns the name of the POD device.

**Returns**

String of `_NAME`.

**Return type**

str

**StopStream()** → None

Write a command to stop streaming data to all POD devices.

## 1.9 Setup\_8401HR module

**class** Setup\_8401HR.**Setup\_8401HR**

Bases: [Setup\\_Interface](#)

Setup\_8401HR provides the setup functions for an 8206-HR POD device.

REQUIRES FIRMWARE 1.0.2 OR HIGHER.

**\_PARAMKEYS**

class-level list containing the device parameter dict keys.

**Type**

list[str]

**\_CHANNELKEYS**

class-level list containing the keys of 'Preamplifier Gain','Second Stage Gain','High-pass','Low-pass','Bias','DC Mode' parameters.

**Type**

list[str]

**\_PHYSICAL\_BOUND\_uV**

class-level integer representing the max/-min physical value in uV. Used for EDF files.

**Type**

int

**\_NAME**

class-level string containing the POD device name.

**Type**

str

**static** **GetDeviceName()** → str

returns the name of the POD device.

**Returns**

String of \_NAME.

**Return type**

str

**StopStream()** → None

Write a command to stop streaming data to all POD devices.

## 1.10 Setup\_PodDevices module

**class** Setup\_PodDevices.**Setup\_PodDevices**(*saveFile: str | None = None, podParametersDict: dict[str, dict | None] | None = None*)

Bases: object

Setup\_PodDevices allows a user to set up and stream from any number of POD devices. The streamed data is saved to a file.

REQUIRES FIRMWARE 1.0.2 OR HIGHER.

### **\_Setup\_PodDevices**

Dictionary containing the Setup\_Interface subclasses for each POD device.

#### **Type**

dict[str, *Setup\_Interface*]

### **\_saveFileName**

String containing the path, filename, and file extension to a file to save streaming data to. The filename will be extended with “\_<DEVICE NAME>\_<DEVICE NUMBER>” for each device.

#### **Type**

str

### **\_options**

Dictionary listing the different options for the user to complete.

#### **Type**

dict[int, str]

**GetOptions()** → dict[int, str]

Gets the dictionary of setup options.

#### **Returns**

Dictionary listing the different options for the user to complete (\_options).

#### **Return type**

dict[int, str]

**GetPODparametersDict()** → dict[str, dict[int, dict]]

Sets up each POD device type. Used in initialization.

#### **Returns**

Dictionary of all POD devices initialization. The keys are the device name and the entries are the initialization dictionaries.

#### **Return type**

dict[str, dict[int, dict] ]

**GetSaveFileName()** → str

Gets the name of the class object’s save file.

#### **Returns**

String of the save file name and path (\_saveFileName).

#### **Return type**

str

**Run()** → None

Prints the options and asks the user what to do. Loops until ‘Quit’ is chosen.

**SetupPODparameters**(*podParametersDict*: *dict[str, dict | None]*) → None

Sets up each POD device type. Used in initialization.

**Parameters**

**podParametersDict** (*dict[str, dict | None]*) – Dictionary of all POD devices initialization. The keys are the device name and the entries are the initialization dictionaries.

**SetupSaveFile**(*saveFile*: *str | None = None*) → None

Gets the path/file name from the user and stores it. Used in initialization.

**Parameters**

**saveFile** (*str | None, optional*) – String of the save file, which includes the directory path, filename, and file extension. Defaults to None.

## 1.11 Setup\_PodInterface module

**class** Setup\_PodInterface.**Setup\_Interface**

Bases: object

Setup\_Interface provides the basic interface of required methods for subclasses to implement. SetupPodDevices.py is designed to handle any of these children.

**\_NAME**

Class-level string for the Device name. This should be overwritten by child subclasses.

**Type**

str

**\_PORTKEY**

Class-level string that is the parameter's dictionary key for the COM port.

**Type**

str

**\_podDevices**

Instance-level dictionary of pod device objects. MUST have keys as device number.

**Type**

dict[int,*POD\_Basics*]

**\_podParametersDict**

Instance-level dictionary of device information. MUST have keys as device number, and each value must have { '\_PORTKEY': str, ...other values... }.

**Type**

dict[int,dict]

**\_saveFileName**

Instance-level string filename: <path>/file.ext. The device name and number will be appended to the filename.

**Type**

str

**AreDeviceParamsValid**(*paramDict*: *None | dict[int, dict]*)

Checks if the parameters dictionary is valid.

**Parameters**

**paramDict** (*None* | *dict[int, dict]*) – Dictionary of parameters for all POD devices.

**Raises**

- **Exception** – Parameters must be contained in a dictionary.
- **Exception** – Device keys must be integer type.
- **Exception** – Device parameters must be dictionary type.
- **Exception** – Device parameters dictionary is empty.

**ConnectAllPODdevices()** → bool

Connects all setup POD devices.

**Returns**

True if all devices are successfully connected, false otherwise.

**Return type**

bool

**DisplayPODdeviceParameters()** → None

Display all the pod device parameters in a table.

**static GetDeviceName()** → str

returns the name of the POD device.

**Returns**

String of \_NAME.

**Return type**

str

**GetPODparametersDict()** → dict[int, dict]

Gets a dictionary whose keys are the device number and the value is the device parameters dict.

**Returns**

Dictionary of POD device parameters. The keys are the device number.

**Return type**

dict[int, dict]

**SetFileName(fileName: str)** → None

Sets the filename to save data to. Note that the device name and number will be appended to the end.

**Parameters**

**fileName** (*str*) – String file name.

**SetupPODparameters(podParametersDict: dict[int, dict] | None = None)** → None

Sets the parameters for the POD devices.

**Parameters**

**podParametersDict** (*dict[int, dict]* | *None, optional*) – dictionary of the device parameters for all devices. Defaults to None.

**StopStream()** → None

Write a command to stop streaming data to all POD devices.

**Stream()** → dict[int, threading.Thread]

Tests that all devices are connected then starts streaming data.

**Raises**

**Exception** – Test connection failed.

**Returns**

Dictionary with integer device number keys and Thread values.

**Return type**

dict[int,Thread]





## INDICES AND TABLES

- `genindex`
- `modindex`
- `search`



## PYTHON MODULE INDEX

### b

BasicPodProtocol, [1](#)

### g

GetUserInput, [5](#)

### p

PodCommands, [9](#)

PodDevice\_8206HR, [13](#)

PodDevice\_8401HR, [14](#)

PodPacketHandling, [17](#)

### s

SerialCommunication, [20](#)

Setup\_8206HR, [22](#)

Setup\_8401HR, [23](#)

Setup\_PodDevices, [24](#)

Setup\_PodInterface, [25](#)



## Symbols

- `_CHANNELKEYS` (Setup\_8401HR.Setup\_8401HR attribute), 23
- `_LOWPASSKEYS` (Setup\_8206HR.Setup\_8206HR attribute), 22
- `_NAME` (Setup\_8206HR.Setup\_8206HR attribute), 22
- `_NAME` (Setup\_8401HR.Setup\_8401HR attribute), 23
- `_NAME` (Setup\_PodInterface.Setup\_Interface attribute), 25
- `_PARAMKEYS` (Setup\_8206HR.Setup\_8206HR attribute), 22
- `_PARAMKEYS` (Setup\_8401HR.Setup\_8401HR attribute), 23
- `_PHYSICAL_BOUND_uV` (Setup\_8206HR.Setup\_8206HR attribute), 22
- `_PHYSICAL_BOUND_uV` (Setup\_8401HR.Setup\_8401HR attribute), 23
- `_PORTKEY` (Setup\_PodInterface.Setup\_Interface attribute), 25
- `_Setup_PodDevices` (Setup\_PodDevices.Setup\_PodDevices attribute), 24
- `__ARGUMENTS` (PodCommands.POD\_Commands attribute), 9
- `__B4BINARYLENGTH` (PodDevice\_8206HR.POD\_8206HR attribute), 13
- `__B4LENGTH` (PodDevice\_8206HR.POD\_8206HR attribute), 13
- `__B5BINARYLENGTH` (PodDevice\_8401HR.POD\_8401HR attribute), 14
- `__B5LENGTH` (PodDevice\_8401HR.POD\_8401HR attribute), 14
- `__BINARY` (PodCommands.POD\_Commands attribute), 9
- `__CHANNELMAPALL` (PodDevice\_8401HR.POD\_8401HR attribute), 14
- `__MINBINARYLENGTH` (BasicPodProtocol.POD\_Basics attribute), 1
- `__MINSTANDARDLENGTH` (BasicPodProtocol.POD\_Basics attribute), 1
- `__NAME` (PodCommands.POD\_Commands attribute), 9
- `__NOVALUE` (PodCommands.POD\_Commands attribute), 9
- `__RETURNS` (PodCommands.POD\_Commands attribute), 9
- `__U16` (PodCommands.POD\_Commands attribute), 10
- `__U8` (PodCommands.POD\_Commands attribute), 10
- `__commands` (PodCommands.POD\_Commands attribute), 10
- `__numPod` (BasicPodProtocol.POD\_Basics attribute), 1
- `__serialInst` (SerialCommunication.COM\_io attribute), 20
- `_commands` (BasicPodProtocol.POD\_Basics attribute), 1
- `_options` (Setup\_PodDevices.Setup\_PodDevices attribute), 24
- `_podDevices` (Setup\_PodInterface.Setup\_Interface attribute), 25
- `_podParametersDict` (Setup\_PodInterface.Setup\_Interface attribute), 25
- `_port` (BasicPodProtocol.POD\_Basics attribute), 1
- `_preampGain` (PodDevice\_8206HR.POD\_8206HR attribute), 13
- `_preampGain` (PodDevice\_8401HR.POD\_8401HR attribute), 14
- `_saveFileName` (Setup\_PodDevices.Setup\_PodDevices attribute), 24
- `_saveFileName` (Setup\_PodInterface.Setup\_Interface attribute), 25
- `_ssGain` (PodDevice\_8401HR.POD\_8401HR attribute), 14

## A

- `AddCommand()` (PodCommands.POD\_Commands method), 10
- `AreDeviceParamsValid()` (Setup\_PodInterface.Setup\_Interface method), 25
- `ArgumentHexChar()` (PodCommands.POD\_Commands method), 10
- `AsciiBytesToInt()` (PodPacketHandling.POD\_Packets static method), 17
- `ASCIIBytesToInt_Split()` (PodPacketHandling.POD\_Packets static method), 17
- `AskForFloat()` (GetUserInput.UserInput static method), 5

AskForFloatInList() (*GetUserInput.UserInput* static method), 5

AskForFloatInRange() (*GetUserInput.UserInput* static method), 5

AskForInput() (*GetUserInput.UserInput* static method), 6

AskForInt() (*GetUserInput.UserInput* static method), 6

AskForIntInList() (*GetUserInput.UserInput* static method), 6

AskForIntInRange() (*GetUserInput.UserInput* static method), 6

AskForStrInList() (*GetUserInput.UserInput* static method), 7

AskForType() (*GetUserInput.UserInput* static method), 7

AskForTypeInList() (*GetUserInput.UserInput* static method), 7

AskForTypeInRange() (*GetUserInput.UserInput* static method), 8

AskYN() (*GetUserInput.UserInput* static method), 8

## B

BasicPodProtocol module, 1

BinaryBytesToInt() (*PodPacketHandling.POD\_Packets* static method), 18

BinaryBytesToInt\_Split() (*PodPacketHandling.POD\_Packets* static method), 18

BuildPODpacket\_Standard() (*PodPacketHandling.POD\_Packets* static method), 18

## C

CalculateBiasDAC\_GetDACValue() (*PodDevice\_8401HR.POD\_8401HR* static method), 14

CalculateBiasDAC\_GetVout() (*PodDevice\_8401HR.POD\_8401HR* static method), 15

CastFloat() (*GetUserInput.UserInput* static method), 8

CastInt() (*GetUserInput.UserInput* static method), 8

CastStr() (*GetUserInput.UserInput* static method), 9

Checksum() (*PodPacketHandling.POD\_Packets* static method), 19

CloseSerialPort() (*SerialCommunication.COM\_io* method), 20

COM\_io (class in *SerialCommunication*), 20

CommandNumberFromName() (*PodCommands.POD\_Commands* method), 10

ConnectAllPODdevices() (*Setup\_PodInterface.Setup\_Interface* method), 26

## D

DisplayPODdeviceParameters() (*Setup\_PodInterface.Setup\_Interface* method), 26

DoesCommandExist() (*PodCommands.POD\_Commands* method), 11

## E

ETX() (*PodPacketHandling.POD\_Packets* static method), 19

## G

GetBasicCommands() (*PodCommands.POD\_Commands* static method), 11

GetChannelMapForPreampDevice() (*PodDevice\_8401HR.POD\_8401HR* static method), 15

GetCommands() (*PodCommands.POD\_Commands* method), 11

GetCOMportsList() (*SerialCommunication.COM\_io* static method), 20

GetDeviceCommands() (*BasicPodProtocol.POD\_Basics* method), 1

GetDeviceName() (*Setup\_8206HR.Setup\_8206HR* static method), 22

GetDeviceName() (*Setup\_8401HR.Setup\_8401HR* static method), 23

GetDeviceName() (*Setup\_PodInterface.Setup\_Interface* static method), 26

GetNumberOfPODDevices() (*BasicPodProtocol.POD\_Basics* static method), 2

GetOptions() (*Setup\_PodDevices.Setup\_PodDevices* method), 24

GetPODpacket() (*BasicPodProtocol.POD\_Basics* method), 2

GetPODparametersDict() (*Setup\_PodDevices.Setup\_PodDevices* method), 24

GetPODparametersDict() (*Setup\_PodInterface.Setup\_Interface* method), 26

GetPortName() (*SerialCommunication.COM\_io* method), 20

GetSaveFileName() (*Setup\_PodDevices.Setup\_PodDevices* method), 24

GetSSConfigBitmask\_int() (*PodDevice\_8401HR.POD\_8401HR* static method), 15

GetSupportedPreampDevices() (*PodDevice\_8401HR.POD\_8401HR* static method), 15

GetTTLbitmask\_Int() (*PodDevice\_8401HR.POD\_8401HR* static method),

15  
GetUserInput  
module, 5

## I

IntToAsciiBytes() (PodPacketHandling.POD\_Packets static method), 19  
IsCommandBinary() (PodCommands.POD\_Commands method), 11  
IsPreampDeviceSupported() (PodDevice\_8401HR.POD\_8401HR static method), 16  
IsSerialClosed() (SerialCommunication.COM\_io method), 21  
IsSerialOpen() (SerialCommunication.COM\_io method), 21

## M

module  
BasicPodProtocol, 1  
GetUserInput, 5  
PodCommands, 9  
PodDevice\_8206HR, 13  
PodDevice\_8401HR, 14  
PodPacketHandling, 17  
SerialCommunication, 20  
Setup\_8206HR, 22  
Setup\_8401HR, 23  
Setup\_PodDevices, 24  
Setup\_PodInterface, 25

## N

NoValue() (PodCommands.POD\_Commands static method), 11

## O

OpenSerialPort() (SerialCommunication.COM\_io method), 21

## P

PayloadToBytes() (PodPacketHandling.POD\_Packets static method), 19  
POD\_8206HR (class in PodDevice\_8206HR), 13  
POD\_8401HR (class in PodDevice\_8401HR), 14  
POD\_Basics (class in BasicPodProtocol), 1  
POD\_Commands (class in PodCommands), 9  
POD\_Packets (class in PodPacketHandling), 17  
PodCommands  
module, 9  
PodDevice\_8206HR  
module, 13  
PodDevice\_8401HR

module, 14  
PodPacketHandling  
module, 17

## R

Read() (SerialCommunication.COM\_io method), 21  
ReadLine() (SerialCommunication.COM\_io method), 21  
ReadPODpacket() (BasicPodProtocol.POD\_Basics method), 2  
ReadUntil() (SerialCommunication.COM\_io method), 21  
RemoveCommand() (PodCommands.POD\_Commands method), 12  
RestoreBasicCommands() (PodCommands.POD\_Commands method), 12  
ReturnHexChar() (PodCommands.POD\_Commands method), 12  
Run() (Setup\_PodDevices.Setup\_PodDevices method), 24

## S

SerialCommunication  
module, 20  
SetBaudrate() (SerialCommunication.COM\_io method), 22  
SetBaudrateOfDevice() (BasicPodProtocol.POD\_Basics method), 2  
SetFileName() (Setup\_PodInterface.Setup\_Interface method), 26  
Setup\_8206HR  
module, 22  
Setup\_8206HR (class in Setup\_8206HR), 22  
Setup\_8401HR  
module, 23  
Setup\_8401HR (class in Setup\_8401HR), 23  
Setup\_Interface (class in Setup\_PodInterface), 25  
Setup\_PodDevices  
module, 24  
Setup\_PodDevices (class in Setup\_PodDevices), 24  
Setup\_PodInterface  
module, 25  
SetupPODparameters() (Setup\_PodDevices.Setup\_PodDevices method), 24  
SetupPODparameters() (Setup\_PodInterface.Setup\_Interface method), 26  
SetupSaveFile() (Setup\_PodDevices.Setup\_PodDevices method), 25  
StopStream() (Setup\_8206HR.Setup\_8206HR method), 22  
StopStream() (Setup\_8401HR.Setup\_8401HR method), 23

StopStream() (*Setup\_PodInterface.Setup\_Interface method*), 26  
 Stream() (*Setup\_PodInterface.Setup\_Interface method*), 26  
 STX() (*PodPacketHandling.POD\_Packets static method*), 20

## T

TranslatePODpacket() (*BasicPodProtocol.POD\_Basics method*), 3  
 TranslatePODpacket() (*PodDevice\_8206HR.POD\_8206HR method*), 13  
 TranslatePODpacket() (*PodDevice\_8401HR.POD\_8401HR method*), 16  
 TranslatePODpacket\_Binary() (*BasicPodProtocol.POD\_Basics static method*), 3  
 TranslatePODpacket\_Binary() (*PodDevice\_8206HR.POD\_8206HR method*), 13  
 TranslatePODpacket\_Binary() (*PodDevice\_8401HR.POD\_8401HR method*), 16  
 TranslatePODpacket\_Standard() (*BasicPodProtocol.POD\_Basics method*), 3  
 TwosComplement() (*PodPacketHandling.POD\_Packets static method*), 20

## U

U16() (*PodCommands.POD\_Commands static method*), 12  
 U8() (*PodCommands.POD\_Commands static method*), 12  
 UnpackPODpacket() (*BasicPodProtocol.POD\_Basics method*), 3  
 UnpackPODpacket\_Binary() (*BasicPodProtocol.POD\_Basics static method*), 3  
 UnpackPODpacket\_Binary() (*PodDevice\_8206HR.POD\_8206HR static method*), 13  
 UnpackPODpacket\_Binary() (*PodDevice\_8401HR.POD\_8401HR static method*), 17  
 UnpackPODpacket\_Standard() (*BasicPodProtocol.POD\_Basics static method*), 4  
 UserInput (*class in GetUserInput*), 5

## W

Write() (*SerialCommunication.COM\_io method*), 22  
 WritePacket() (*BasicPodProtocol.POD\_Basics method*), 4  
 WriteRead() (*BasicPodProtocol.POD\_Basics method*), 4