Group Dynamics in Human-Robot Collaboration

Filipa Correia

Postdoctoral Researcher





Who is Filipa Correla?

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Researcher on Human-Robot Interaction

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Researcher on Human-Robot Interaction

Computer Science

Robotics

Psychology

How can we develop social behaviours for robots?

HowDo robots need resocial behaviours!?

How can we develop social behaviours for robotic collaborators?



Research

PhD (2017-2021)

How can we develop social behaviours for robotic teammates?

Robotic Collaborator

Robotic Teammate

What personalities do people prefer for a robotic teammate?

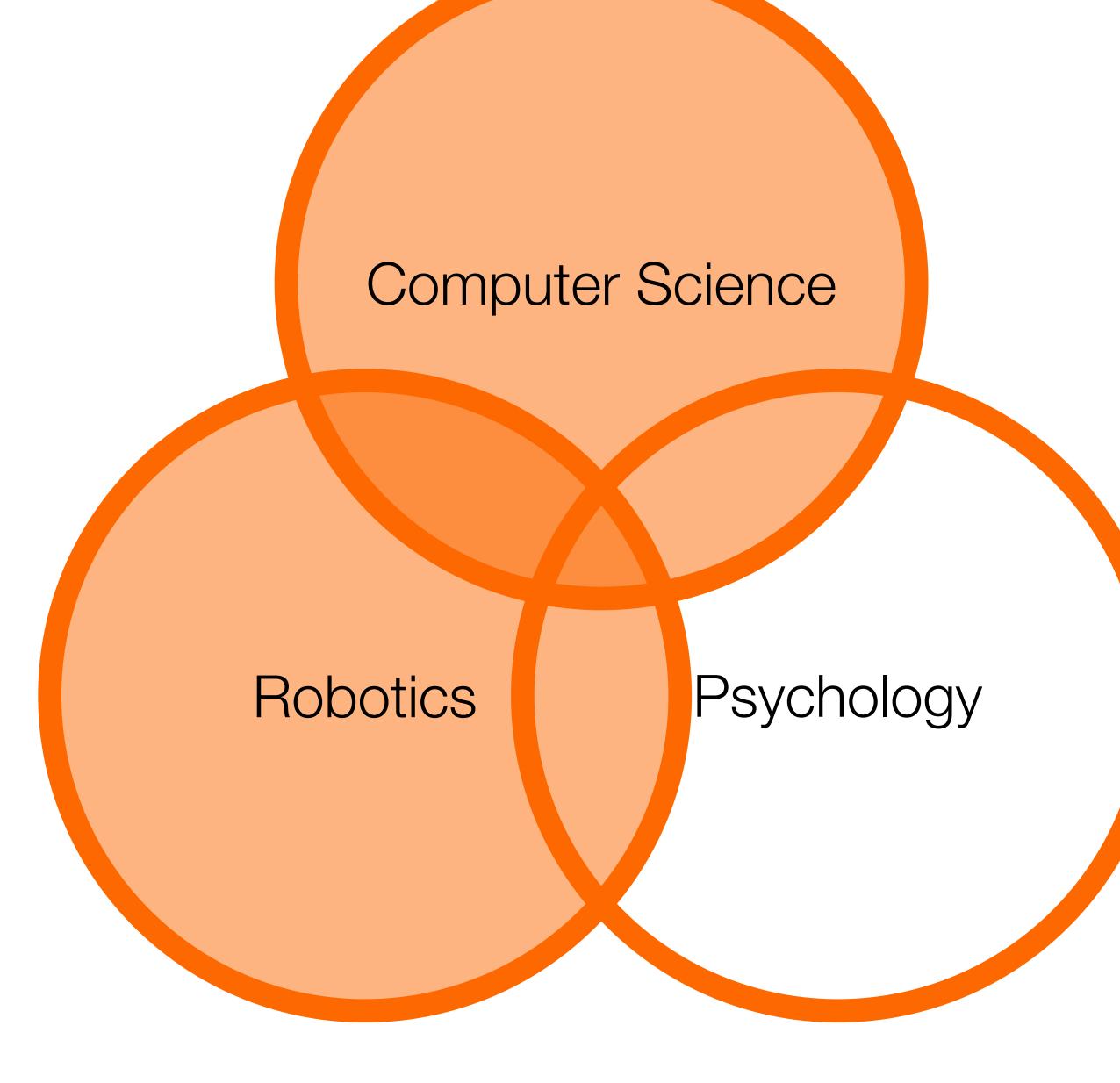
Do people mind if a robotic teammate has selfish actions?

Can a robotic teammate express group-based emotions?

Can the gaze cues of a robotic teammate impact the teamwork?

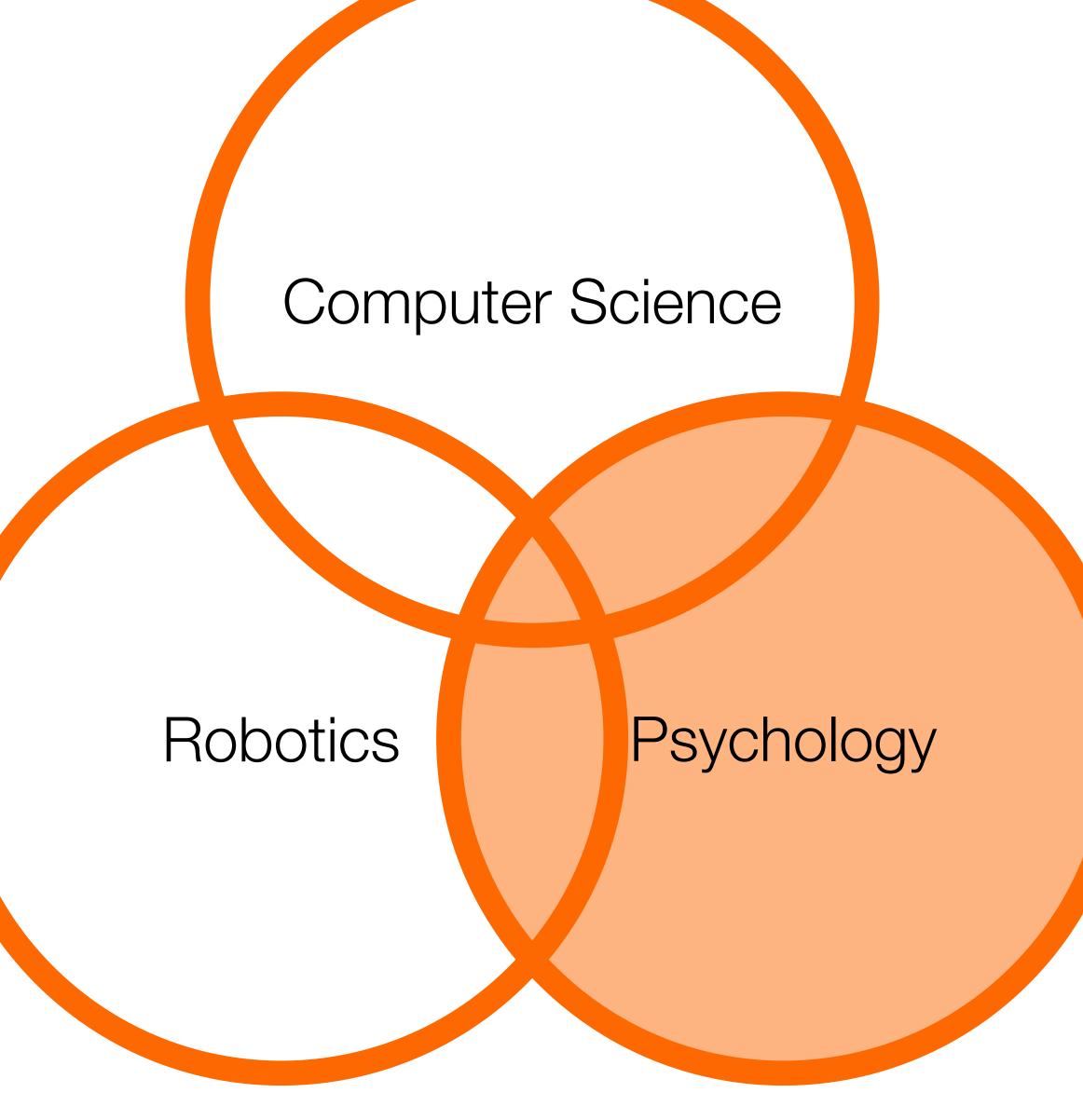
Contributions:

1. Development of autonomous social behaviour

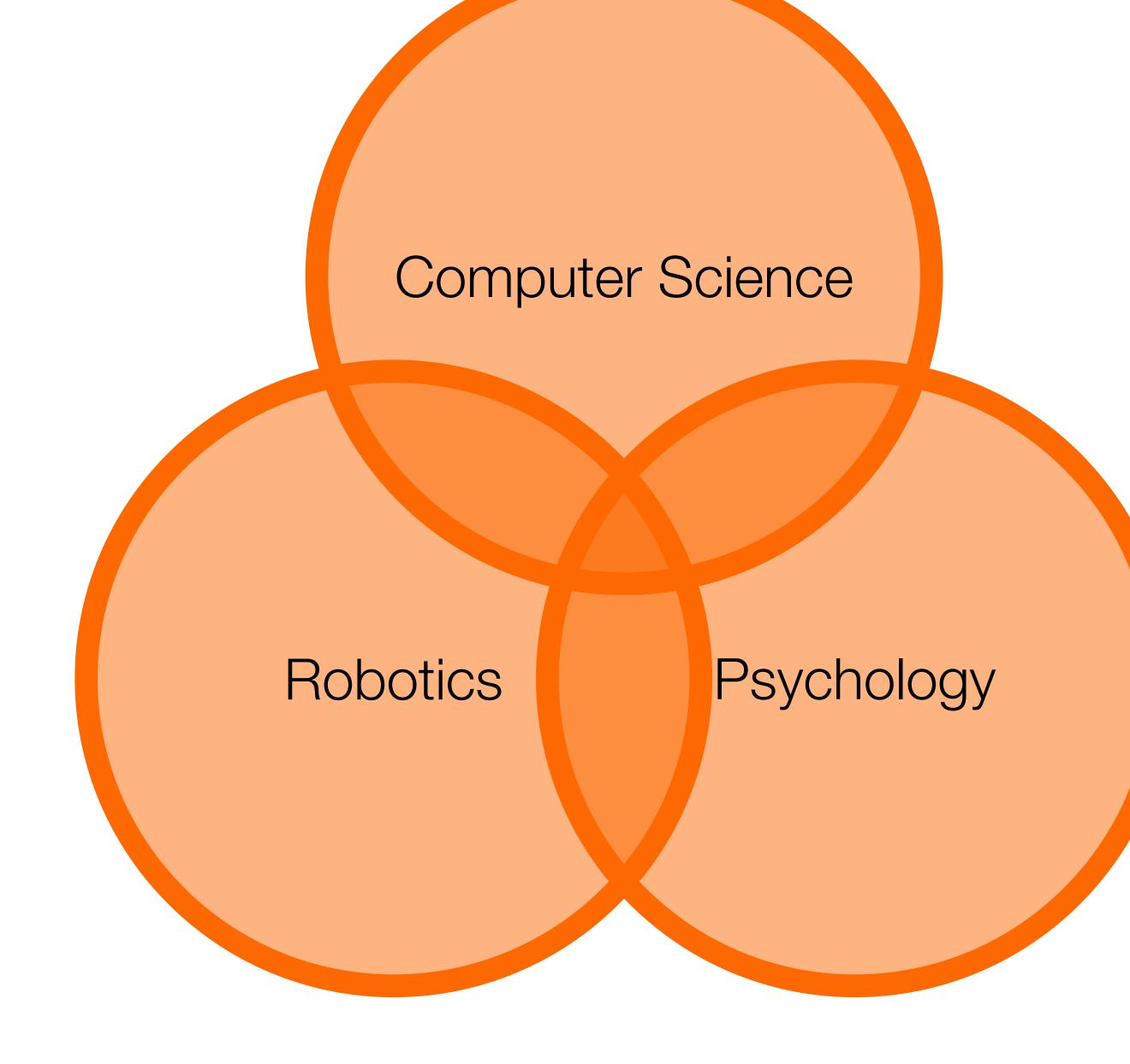


Contributions:

2. Evaluation of people's perceptions



Contributions:
3. Understanding human-robot teamwork



Research

Future Research

Group Dynamics in Human-Robot Collaboration

Future Research

Group Dynamics

Robots need:

To perceive social cues on human collaborators

To model the dynamical properties of the collaborative task

To have adaptive mechanisms to respond adequately

Group Dynamics

To perceive social cues on human collaborators

To model the dynamical properties of the collaborative task

To have adaptive mechanisms to respond adequately

- Gaze
- Attention
- Participation

Group Dynamics

To perceive social cues on human collaborators

To model the dynamical properties of the collaborative task

To have adaptive mechanisms to respond adequately

Real-time measures of collaboration (e.g. cohesion, satisfaction, fluency)

Group Dynamics

To perceive social cues on human collaborators

To model the dynamical properties of the collaborative task

To have adaptive mechanisms to respond adequately

Social Network Analysis (e.g. sociometry)

Research Mission

How can we develop social behaviours for robotic collaborators?

Future Research (short-medium term)

How can we develop social behaviours for robotic collaborators?

Group Dynamics in Human-Robot Collaboration!

design and

How can we develop social behaviours for robotic collaborators?

How can we design and develop social behaviours for robotic collaborators?

AnthropomorphismAgency

Can the behaviours of a non-humanoid robot be considered as anthropomorphic? Does that facilitate collaboration?

- Anthropomorphism

How humanlike should robots be in terms of shape and behaviours?

- Anthropomorphism

How should robots act in collaborative-control scenarios (i.e. semi-autonomous or mixed-agency)?



LARSYS Compatibility

LARSyS Compatibility

Human-Robot Collaboration

INTERACTION

LIFE

LARSyS Compatibility

Human-Robot Collaboration

INTERACTION

LIFE

AIR

OCEANS

URBAN

35

Potentia Funding

Potential Funding

2021

2022

2023

- Group Dynamics

FCT Scientific Employment Stimulus

FCT R&D Projects

- Anthropomorphism

Branco Weiss Fellowship

ERC

- Agency

Jacobs
Foundation
Fellowship

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Potential Colaborators

Robotics:

- Malte Jung, Cornel University USA
- Ginevra Castellano, Uppsala University Sweden
- Catharine Oertel, TU Delft The Netherlands
- Sarah Sebo, University of Chicago USA

Psychology:

- Astrid Rosenthal-von der Pütten, RWTH Aachen University Germany
- Marlena R. Fraune, New Mexico State University USA
- Patrícia Arriaga, ISCTE Portugal
- Pedro Marques-Quinteiro, ISPA Portugal

International Recognition

H-R Teamwork
H-R Group Interactions

- book chapters
- journal papers
- top-tier conferences
- invitation-only Dagstuhl workshop



Thank you!