

Live Coding Workshop - Useful material

Links to selected performances

Mike Hodnik (Minnesota, US) at the Spice Factory in Hamilton <https://www.youtube.com/watch?v=smQOiFt8e4Q>
(<https://www.youtube.com/watch?v=smQOiFt8e4Q>).

Algo/Afro (Sheffield, UK) https://www.youtube.com/watch?v=OenTVK_AW0Y (https://www.youtube.com/watch?v=OenTVK_AW0Y).

Livecodera Performances

Shelly Knotts <https://www.youtube.com/watch?v=fmTyaAJ5oDQ&list=PLMBIpiBV-wQKoXNk6RAJe5oKPkJCtmZks&index=13> (<https://www.youtube.com/watch?v=fmTyaAJ5oDQ&list=PLMBIpiBV-wQKoXNk6RAJe5oKPkJCtmZks&index=13>).

Flor De Fuego & Naoto Hieda https://www.youtube.com/watch?v=SIAO0Dk5_MI&list=PLMBIpiBV-wQKoXNk6RAJe5oKPkJCtmZks&index=8 (https://www.youtube.com/watch?v=SIAO0Dk5_MI&list=PLMBIpiBV-wQKoXNk6RAJe5oKPkJCtmZks&index=8).

Celeste Betancourt <https://www.youtube.com/watch?v=dRosJpKLw8I&list=PLMBIpiBV-wQKoXNk6RAJe5oKPkJCtmZks&index=4> (<https://www.youtube.com/watch?v=dRosJpKLw8I&list=PLMBIpiBV-wQKoXNk6RAJe5oKPkJCtmZks&index=4>).

Explore Euler Room!! <https://www.youtube.com/c/Eulerroom> (<https://www.youtube.com/c/Eulerroom>).

Links to communities online

Explore TopLap! <https://toplap.org/> (<https://toplap.org/>).

List of Nodes and communities <https://toplap.org/nodes/> (<https://toplap.org/nodes/>).

Discord Channels toplap: <https://discord.gg/RSMvvk8P> (<https://discord.gg/RSMvvk8P>), estuary:
<https://discord.gg/Q9tumbeP> (<https://discord.gg/Q9tumbeP>).

Environments

Sort of exhaustive list: <https://github.com/toplap/awesome-livecoding> (<https://github.com/toplap/awesome-livecoding>).

Selected environments: Hydra <https://hydra.ojack.xyz/> (<https://hydra.ojack.xyz/>),

SonicPi <https://sonic-pi.net/> (<https://sonic-pi.net/>),

SuperCollider <https://supercollider.github.io/> (<https://supercollider.github.io/>),

TidalCycles <http://tidalcycles.org/> (<http://tidalcycles.org/>),

Estuary langs: Punctual, cineCer0, miniTidal, locomotion, seis8vos, JSOlangs, etc... <https://estuary.mcmaster.ca>
(<https://estuary.mcmaster.ca>).