## Hyperopt

September 21, 2019

## 0.0.1 Multi variable functions

You can use ANY kind of non-standard multi-input single-output function which returns real values. In this example, we deal with a function of four variables and try to minimize it using the "hyperopt" python module. Note: for n-variable function you must pass a single parameter as n-sized list, and not n input parameters!

```
[2]: import numpy as np
    from hyperopt import fmin, tpe, hp, Trials
    from hyperopt import STATUS_OK
    def my fcn(x):
        return np.\sin(x[0]*(x[1]**2-x[2])/x[3])*np.\cos(x[0])
    x_mins_dict = fmin(
                      fn=my_fcn,
                      space=[hp.uniform('x_1', -100, 100), # search range for x[0]_{\sqcup}
     \rightarrow from -100 to 100
                              hp.uniform('x_2', -200, 100), # search range for x[1]_{\sqcup}
     → from -200 to 100
                              hp.uniform('x_3', 0, 50), # search range for x[2] from O_{\square}
     → to 50
                             hp.uniform('x_4', -100, -20) # search range for x[3]_{\sqcup}
     \rightarrow from -100 to -20
                            ],
                      algo=tpe.suggest,
                      max_evals=500 # stop searching after 500 iterations
```

```
100%|| 500/500 [00:30<00:00,
16.15it/s, best loss: -0.9929701556517146]
```

```
[3]: print(x_mins_dict) # the output of fmin is a dictionary x_mins = [e for e in x_mins_dict.values()] # converts dictionary to list print("my_fcn(x_mins) = " + str(my_fcn(x_mins))) # print function result at →x_mins
```

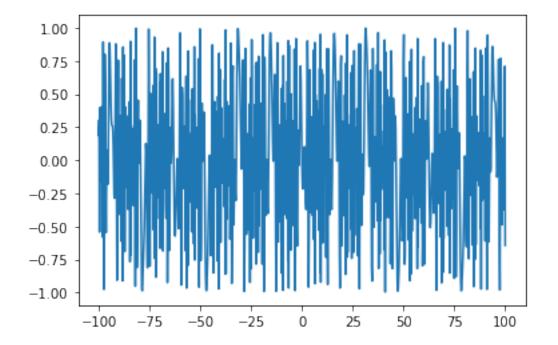
```
\{'x_1': -37.655734158571676, 'x_2': -114.7106365291187, 'x_3': 21.517362607413727, 'x_4': -61.18539419319436\}
my_fcn(x_mins) = -0.9929701556517146
```

Now, it would be nice to plot the function with the corresponing x\_mins, it can be a bit hard to find a way to visualize our data in a satisfying way. Therefore, the in the following section the same approach is repeated with a single variable version of the function, in order to nicely plot our results.

## 0.0.2 Single variable functions

Note: even if we use a discrete set of points to plot, the curve is linear spline interpolated. That's why the curve will look continuous.

[4]: [<matplotlib.lines.Line2D at 0x24ff24dba20>]



```
[5]: x_min_dict = fmin(fn=my_fcn_single, space=hp.uniform('x', -100, 100),
```

```
100%|| 500/500 [00:10<00:00,
48.83it/s, best loss: -0.9994964619398159]
{'x': -47.14529488207911}
```

```
[6]: x_min = x_min_dict['x']
y_min = my_fcn_single(x_min)

plt.plot(x,f(x))
plt.plot(x_min,y_min,color="red", markersize="12",marker='o')
```

[6]: [<matplotlib.lines.Line2D at 0x24ff2409400>]

