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An IoT Based System for Remote Patient Monitoring

Alexandru Archip^{*}, Nicolae Botezatu^{*}, Elena Serban^{*}, Paul-Corneliu Herghelegiu^{*} and Andrei Zăla[†]

^{*}"Gheorghe Asachi" Technical University of Bălne

Faculty of Automatic Control and Computer Engineering

Email: {alexandru.archip,nbotezatu,eserban,perghhelegiu}@tuiasi.ro

[†]Moines,ti Emergency Hospital, Pitul, Romania

Email: andrezala@yahoo.com

Abstract—Following a surgical procedure patients are monitored in an ICU until physically stable, after which are discharged to a ward for further evaluation and recovery. Usually, ward evaluation does not imply continuous physiological parameters monitoring and therefore patient relapse is not uncommon. The present paper describes the steps taken to design and build a low-cost modular monitoring system prototype. This system aims to offer mobile support in order to facilitate faster and better medical interventions in emergency cases and has been developed using low-power dedicated sensor arrays for EKG, SpO2, temperature and movement. The interfaces for these sensors have been developed according to the REST model: a central control unit exposes a RESTful based Web interface that ensures a platform agnostic behaviour and provides a flexible mechanism to integrate new components.

Index Terms—Embedded Systems, Internet of Things, E-health, RESTful Web Services, Remote patient monitoring

I. INTRODUCTION

Active post-surgery patient monitoring plays an important role in clinical services. A viable solution for this task must be cost-effective, must solve the human resource availability problem and must have a positive impact on the patients' overall quality of life.

We devised a solution that includes modular sensors and is mostly built from off-the-shelf hardware modules. These sensor blocks are connected to a central unit. Communication between sensors and the control unit is performed using low-power radio interfaces, e.g. IEEE 802.15.4. Furthermore, this solution has been developed according to the IoT model: it embeds a software component running on the control unit that is responsible for data acquisition; such data is then made available in real-time to external devices in JSON format through a RESTful based Web Service. Except for minimal data conversion, storing and buffering in the software component does not perform any other data processing tasks. We adopted this approach because 1) data processing may vary depending on the physiological parameter in focus and 2) it may induce supplementary delays that could nullify the real-time behaviour of our prototype. Also, we have developed an application on mobile devices (i.e. tablets) that allows for real-time data visualisation by the design of a wearable patient monitoring device. The described prototype offers the following advantages:

First of all, it allows for physicians to monitor the patients filtering issues. Nowadays, telemedicine represents a very important research avenue. Significant effort has been deployed in assisting the patients in their everyday life through telehealth and telemedicine systems. An comprehensive review on the state-of-the-art in telemedicine systems and the communication technologies used has been presented by Custodero et al. [1]. Commonly, telehealth systems focus on detecting health related abnormalities. The related papers we analyzed describe similar systems at different levels of detail. Although the majority present whole systems, the authors usually focus on three main topics: (1) data acquisition and low level system design, (2) data transmission within the system and network related issues and (3) system integration in existing communication networks in the Internet-of-Things (IoT) paradigm. An early system that uses a cell phone application for remote monitoring uses a GPS, an accelerometer and a light sensor is described in [2]. The prototype in [3] allows physicians to remotely assess the patient's health in indoor and outdoor environments. Alongside sensors that acquire the data from the patient, their prototype also includes an analysis system for emergency cases. In [4], the authors propose a monitoring system based on Embedded Network Gateway Servers (ENGS) devices that send the acquired data via an embedded web server to a central server. The authors of [5] detail the specific challenges posed by the design of wearable patient monitoring devices. They address in detail power consumption, data acquisition and data filtering issues. In [6], a wireless sensor network for

monitoring physiological data in emergency combines a two-tier system architecture and a rate protocol to successfully address QoS requirements in large scale network. Both real-time and historical data analysis and management are the objectives of the framework presented in [7]. This framework intended to be lightweight and scalable, utilizes a resource-oriented architecture (ROA) based RESTful HTTP to connect wireless physiological sensors, wireless networks and a cloud computing platform.

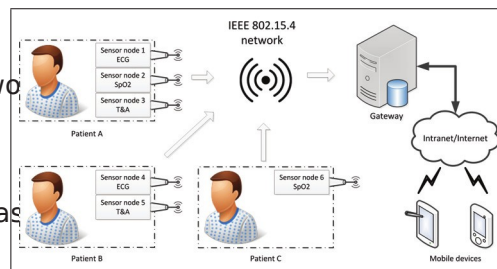


Fig. 1. Generic system architecture

Wanda a remote health monitoring system for failure patients is presented in [8]. The system consists of a smartphone-based data collection gateway, net-scale data storage and search system, and a backend analytics engine for diagnostic and prognostic purposes. The need and the benefits of electronic and IT services in the medical field are emphasised in [9]. The main purpose of the introduced framework is to provide better and more accurate data access for physicians and aid persons. A recent telemedicine monitoring system using ZigBee communications was developed by Tung et.al[10]. It offers medical data monitoring services, patient tracking and paging services.

A common problem that occurs when using different types of sensors is their interoperability as they might use different communication standards. A gateway that aims to solve this problem was presented in [11].

A follow-up on the home telemonitoring approaches, Chronic Obstructive Pulmonary Disease has been presented [12]. The authors stress out that remote monitoring is cheaper than the clinic one. Another conclusion of the study is that adjustments to the telemonitoring systems have to be done to fulfill all user requirements. These adjustments should mostly focus on the usability of the systems.

An IoT paradigm integrating health related systems that was developed to track the patients was described in [13]. The authors introduce VIRTUS, a new middleware software system that provides interconnectivity solutions between the sensors and the used mobile device.

To the best of our knowledge, there is no remote health monitoring system that provides support for real-time data acquisition and visual representation for multiple sensor types, while offering platform agnostic interfaces. The low-power profile and low cost of the modules used in our prototype are also key advantages of our solution.

III. SYSTEM DESIGN AND IMPLEMENTATION

The prototype system we developed implements acquisition and primary processing components for physiologic parameters. It also exposes interfaces for local and remote patient access. An overview of this prototype is presented in Fig. 1.

A patient monitor implements at least ECG, respiratory, SpO2, NIBP and temperature functionality. Usually a ward patient does not need all five parameters monitored, which leads to inefficient resources allocation (e.g. a patient scheduled for a minor surgical intervention might need only temperature monitoring to detect febrile states which can indicate a nosocomial or superinfection). As a result, the system was

designed with two other objectives in mind - flexibility and fair resource distribution.

These tasks are achieved by using two types of devices: sensor nodes and a Gateway. A sensor node monitors a single physiological signal and patients can be equipped with more than one node according to their needs (one ECG node and one SpO2 node). The Gateway gathers the data from the sensor nodes and makes it available through a minimal RESTful based Web interface to the medical staff. This interface ensures the compliance with the IoT model.

A. Sensor nodes

The sensor nodes are mobile, battery powered devices. They are equipped with an IEEE 802.15.4 radio module used to transfer the acquired data to the Gateway.

The core of the node is the Zolertia Z1 platform, a Berkeley Labs variant. It is based on a TI MSP430 16-bit microcontroller which runs at max. 16 MHz as is characterised by rich low-power capabilities.

As a proof of concept we have built a prototype system which includes the following node types:

- ECG node - based on Medlab EG04000, a four lead ECG module with 6 channels (I, II, aVR, aVL, aVF). The node is configured to use 3-6 channels at 50 samples per second with an amplitude of 0.03125 mV/LSB.
- SpO2 node - based on Medlab EG00352 module configured to output the waveform 50 samples per second. SpO2 values and perfusion index outputs are synchronized with the heart rate.
- Temperature and acceleration (T&A) node - a Maxim DS18B20 sensor is used for skin temperature measurement and is sampled every minute. An Analog Devices ADXL345 3-axis accelerometer is used to detect abnormal movements like seizures, excessive shivers or falls.

The application that runs on the nodes is based on the OpenWSN framework [14]. The framework enables the development of IoT solutions based on the 6LoWPAN, RPL and CoAP protocols.

Regardless of the node type, application has a generic structure (Fig. 2). This facilitates the rapid development of node types if specific module or sensor drivers are provided. The application uses a generic UART driver for the ECG and SpO2 nodes and for the temperature and acceleration

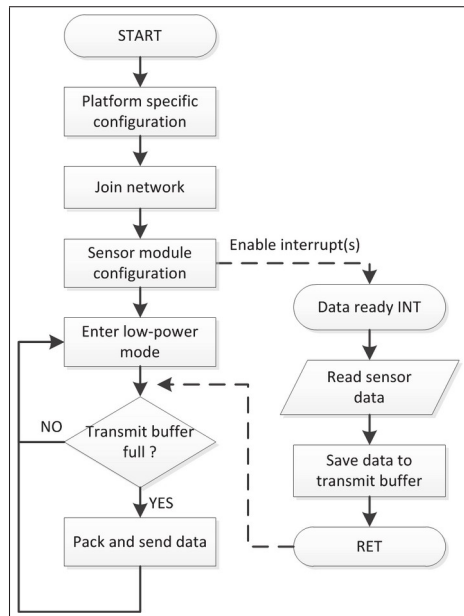


Fig. 2. Prototype system architecture at a glance

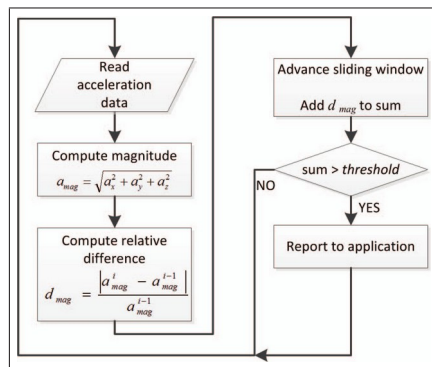


Fig. 3. Motion detection mechanism

it uses I2C (accelerometer) and 1-Wire (temperature sensor drivers).

After the node executes the start-up code, it tries to join the network created by the Gateway and upon success, it receives the configuration parameters for the sensing module(s). The configuration step for the sensing module also enables one or more interrupts that are used for data reception. The main loop of the application enables the MSP430's LPM0 low-power mode which keeps active only selected peripherals (e.g. UART, I2C) and their clock sources. This mode is left when an interrupt is generated and upon return from the interrupt the node checks the transmit buffer and if necessary sends the stored data. Data is temporarily stored until at least 100 bytes of data are available (the IEEE 802.15.4 packets have at most 128 bytes including headers).

No specific processing is done on the node data (i.e. the communication overhead induced by such an interpretation, except for the motion detection mechanism, is kept to be minimal). The raw acceleration data sampled at 50 Hz would have increased the overhead of the radio link while bringing no benefit to the system.

benefit to the system so we aimed to implement the monitoring and detection mechanism without increasing the energy footprint of the node.

The simple mechanism is based on a 5 second sliding window used in conjunction with the difference between acceleration samples: 1) compute the magnitude of the current acceleration sample; 2) determine the relative difference between the magnitudes of two consecutive samples; 3) add the difference to a running sum; if the value of the sum is larger than a certain threshold a message is added to the transmit buffer.

B. Gateway

The Gateway is the main element of the system and is based on a Raspberry Pi system. The SBC is paired with a Zolertia Z1 platform used for data reception and sensor network management tasks. The data received from the sensor network is unpacked, stored and served upon request.

Fig. 4 presents the interactions between the software modules of the Gateway. The Manager module represents the logic between the other modules. The Web Server module provides an interface for the client applications used for configuration and for accessing stored data (e.g. get monitoring status, get sensor type and status, get patient data history, login and user management). The DataSocket module is used for real-time data access. This module streams the data acquired from the sensors to the application. The File System module manages the access to the database. The database stores patient personal data, associated sensor nodes data history and sensor node (i.e. type, capabilities and settings) data. The Z1 platform accesses configuration information for the joining nodes and sends received data to the connected ones.

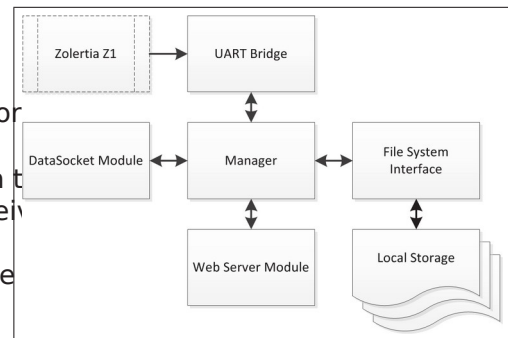


Fig. 4. Gateway software modules

C. The RESTful based Web Service

The RESTful based Web Service for our prototype has been designed with respect to the following considerations: 1) it must be lightweight such that it would offer quick response times; 2) it must supply for quick access to its underlying resources; 3) the embedded processing must not be maintained to a possible minimum such that the energy

consumption of the Gateway device is within acceptable limits – this is a mandatory requirement since the Gateway is a low power profile device; 4) it must ensure real-time full access to sensor data, in a platform agnostic manner.

In order to satisfy requirements 1) and 2) we have considered the lowest number of useful resources that are needed to implement the RESTful approach. Our system focuses on remote patient monitoring in hospital wards, following an ICU discharge. Therefore the virtual resources of the RESTful Web Service are the physician/nurse that would interpret the sensor data and the group of patients that must be kept under surveillance. At any given time, only one person from the medical staff may access a single Gateway device. This approach also complies with requirement 3), since it excludes the need for message routing and action isolation between multiple clients using the same system. Also, the RESTful Web Service simply delivers the data to interested parties without any supplemental processing. We considered several approaches to address requirement 4): WebSockets, push notifications and basic TCP client-server communications. We chose to use basic TCP client-server communications.

When a physician or nurse chooses to closely survey a patient, the application on their device would provide a TCP server socket. The connection properties of the socket are forwarded to the Gateway device which creates a virtual resource that embeds the corresponding TCP client endpoint. The data exchanged between the two devices (the Gateway and the monitoring device) are represented as standard ASCII characters.

The complete set of resources and the allowed HTTP methods for our RESTful Web Service are given in Table I. All messages exchanged are represented using the JSON format.

TABLE I
THE RESTFUL API OF OUR PROTOTYPE

Virtual resource URI	HTTP method	Brief description
/ping	GET	query status of gateway
/login	POST	user LOGIN
/login/<token>	GET	read/query user token
	DELETE	user LOGOUT
/sensors?token=<token>	GET	list available sensors
/patients?token=<token>	GET	list available patients
/patient/set/<patientid>	POST	sets active patient
/patient/history/<patientid>?token=<token>	GET	reads active patient's historic medical data
	PUT	creates a new virtual resource embedding the TCP client
/patient/start	DELETE	deletes the virtual resource embedding the TCP client

D. Communication Pattern

The communication pattern between the Gateway device and mobile device application (a tablet case) is exemplified in Fig 5.

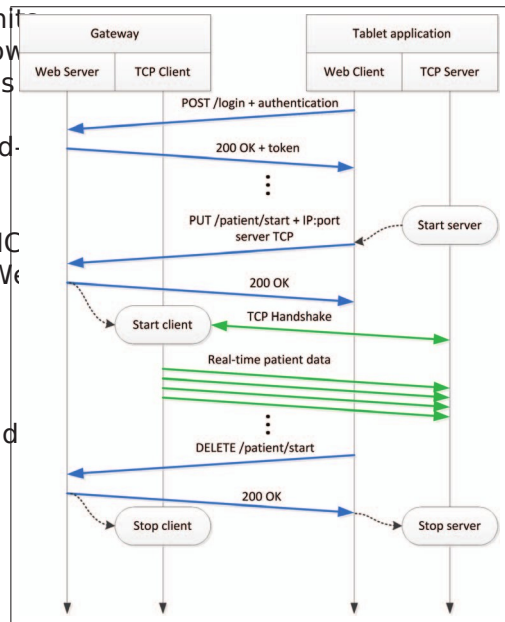


Fig 5. Sample communication flow for real-time acquisition

The client application on the mobile device performs a *POST* call to the RESTful API */login* resource in order to authenticate the physician/nurse that uses the system. Upon a successful login, the users are presented with a list of patients that are connected to the Gateway device. In the next step, the medical operator may select a particular patient to monitor. The application on the mobile device opens a TCP server socket endpoint and transmits the socket properties to the Gateway through a *PUT* call. The Gateway uses this data and connects to the remote server on the mobile device. Upon a successful connection, the Gateway application begins sending the corresponding sensor data to the mobile device. The application on the mobile device will receive the data from the Gateway and render it to the medical operator. Once the medical operator decides the patient no longer needs monitoring, he/she will issue a stop monitoring command which will be sent to the Gateway as a *DELETE* call and will close the corresponding TCP server socket. Gateway devices will also close its corresponding TCP client endpoint.

E. Mobile device application

The mobile device application was developed in Android Studio. The mobile device used for testing is a Sony xperia Z3 Compact tablet. Following the steps presented in the subsection III-D, the main purpose of this application is to render the sensor data it receives in real-time. In order to ensure this behaviour, we have considered the following: we have worked with a maximum number of 4 sensors (ECG, accelerometer, SpO2 and temperature sensors) of these 4 devices, the ECG sensor outputs the data on 3 distinct channels. To solve this challenge, the mobile application includes 4 distinct, high-priority threads, that are assigned as follows: 3 threads handle

the data from the 3 ECG channels and the last thread. The setup included two 2400 mAh NiMH rechargeable cells. The displayed data are read from the series configuration high-side current sensing circuit Gateway device as follows: 50 samples per second for ECG based on an Texas Instruments INA168 IC and a step-up DC-DC converter with a 3.3 V output. The step-up converter had to be used because of the ECG and SpO2 acquisition modules specifications that state an operating voltage of $3.3\text{ V} \pm 5\%$.

The ECG data is depicted by three separate graphs for each channel. The SpO2 data is displayed in a separate graphic. The other data types, like the temperature and pulse rate, are displayed as numerical values. Fig. 6 gives an example of the main view of the mobile device application. The accelerometer data is used to issue alerts whenever movements are detected (in order patients falls).

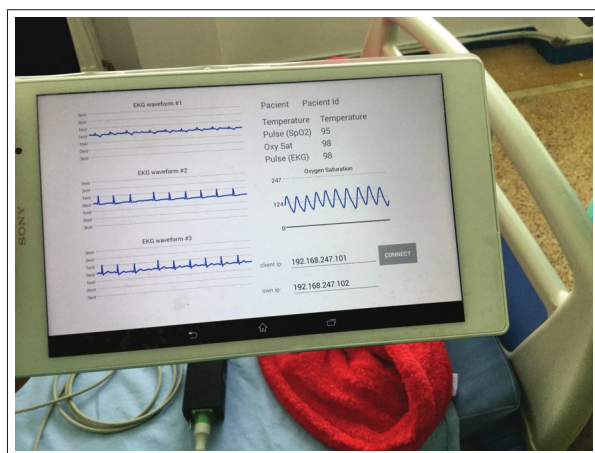


Fig. 6. Sample output on an Android based tablet

An image of the sensors and the Raspberry Pi board (the Gateway) we have used may be observed in Fig. 7.

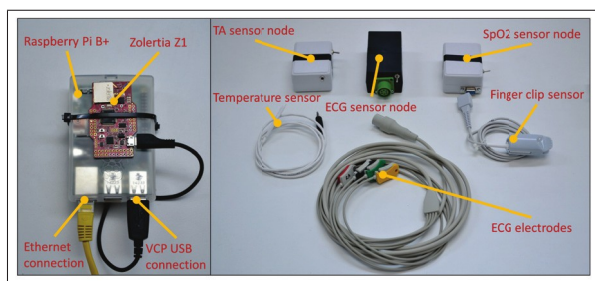


Fig. 7. Gateway (left) and Mobile sensors (right)

IV. TESTS AND RESULTS

We performed two types of tests: one to evaluate the power consumption of the sensors and the mobile Gateway and the second one to assess the accuracy of the acquired data and the real-time capabilities of the remote monitoring system.

A. Power consumption tests and results

One drawback of battery powered devices is the need to frequently recharge or change the batteries which results in system downtimes and increased operational costs. As a result, we set-up a testbench in order to determine the power profiles of the sensor nodes.

These tests included two 2400 mAh NiMH rechargeable cells. The displayed data are read from the series configuration high-side current sensing circuit Gateway device as follows: 50 samples per second for ECG based on an Texas Instruments INA168 IC and a step-up DC-DC converter with a 3.3 V output. The step-up converter had to be used because of the ECG and SpO2 acquisition modules specifications that state an operating voltage of $3.3\text{ V} \pm 5\%$. The results are presented in Table 5. Including the initialization phase, the power rating of each node type can be seen in Table 6. Each node type spends most of the time in a low-power (LP) state; on a regular basis the sensors are sampled (SMP); and data is transmitted when the buffers are full (TX). One such example is given in Fig. 8.

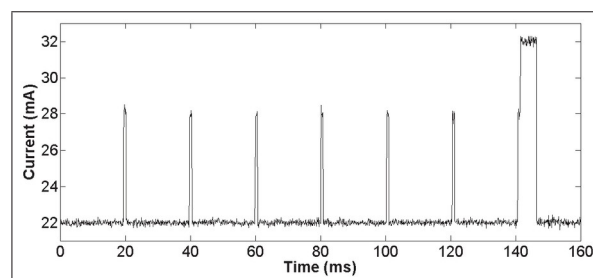


Fig. 8. Current trace for the ECG node. From left to right, the first six current spikes indicate sampling (SMP) periods of the system, whereas the spike that starts at 140 ms indicates a sampling period followed by the activation of the radio module and the transmission of data.

For both the ECG and SpO2 nodes the biggest current consumers are the acquisition modules (ECG - 22 mA, SpO2 max. 20 mA) and the radio ($< 17\text{ mA}$). Based on the sampling rate of the sensors and on the buffering of the radio, the duty cycle was kept at 1.2% for the ECG node and 0.5% for the SpO2 one. Based on these characteristics, in simulation the ECG node exceeded 4 days of operation and the SpO2 one exceeded 5 days. In our workbench the ECG node stopped operation after 85 hours, and the SpO2 one after 109 hours.

The lowest power consumption was achieved for the TA node due to the low current consumption of the two sensors and the low duty cycle of the radio module. The operating time of this node type was evaluated only in simulation and exceeded 1.3 years.

B. Feasibility tests and results

The prototype system has been briefly deployed and tested at the Moines,ti Emergency Hospital, Borsos, Romania. These tests included sampling data from various patients that have undergone through various surgical procedures and were discharged in hospital wards until full recovery. The purpose had been to evaluate the feasibility and the real-time data acquisition capabilities of our prototype.

During these second group of tests, patients have been equipped with the sensors. The Gateway devices have been deployed within the ward, the patients and configured to access the Wi-Fi network of the hospital. A physician had to sample the data using an Android based tablet and monitor each patient for 10 to 15 minutes. The system performed well, supplying the desired data with no errors to the physicians.

TABLE II
SENSOR NODES STATES AND AVERAGE POWER CONSUMPTION

State	Description	Power	Time slice
ECG node			
LP	Low Power:MCU - processing core and main clock, radio module: disabled, communication module (UART) module: enabled;	76 mW	95.8%
SMP	SampleMCU, ECG module enabled; radio module disabled	92 mW	3%
TX	Transmit data: MCU, ECG module and radio module enabled	106 mW	1.2%
SpO2 node			
LP	Low Power:MCU and radio module disabled;UART and SpO2 module enabled	59 mW	98%
SMP	SampleMCU and SpO2 module enabled; radio module disabled	79 mW	1.5%
TX	Transmit data: MCU, SpO2 module and radio module enabled	92 mW	0.5%
Temperature/acceleration node			
LP	Low Power: MCU, communication modules (I2C, 1Wire), temperature sensor and radio module disabled; accelerometer enabled	0.4 mW	96.9%
SMP	Acceleration sample: MCU, accelerometer enabled; temperature sensor and radio module disabled	26 mW	2.9%
SMPT	Temperature sample: MCU, accelerometer, temperature sensor enabled; radio module disabled	0.1 mW	<0.1%
TX	Transmit data: MCU, accelerometer and radio module enabled; temperature sensor disabled	69 mW	<0.1%

Moreover, we did not notice any considerable delays between data acquisition and data visualisation on the mobile device.

V. CONCLUSIONS AND FURTHER DEVELOPMENT

In this paper we present a prototype system for remote patient monitoring. The main purpose of this prototype is to fill the gap in monitoring a patient's vital signs between ICU (after having undergone surgical procedures or other emergency treatments) and the actual hospital discharge. While ward evaluation may not necessarily require continuous physiological parameters assessment, patient relapse is not uncommon. The system we described may prove to be extremely useful in preventing such relapses since it allows the medical personnel to timely and accurately evaluate the ward patients.

The system is comprised of low-power profile sensors that communicate wirelessly with a Gateway type device implemented using the Raspberry Board. The overall functionality of these devices made available through a RESTful based Web Service. Therefore, this present prototype may be easily integrated within more complex based medical applications simply by calling the RESTful API we have designed.

At present we are actively involved in developing an iOS based application that would be a replica of the Android app and extend the functionality to iPad devices. The next

steps involve improving the overall quality of the prototype and automatic sensor discovery.

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