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Chinese version: 中文版



Hello, I am Zhaoyang Mu, a passionate researcher in robotics and scientific

Education

M.Sc. in Artificial Intelligence (0812J1), Dalian Maritime University (Aug 2023 - Present, expected Jun 2026)

Links

- Project Page (Sparse → Dense Transformer): https://pitohuieaiversion.github.io/Sparse_to_Dense_Transformer/
- Personal Website: http://www.zhaoyangmu.com
- GitHub: https://github.com/Pitohuie
- LinkedIn: www.linkedin.com/in/zhaoyang-mu-283497384

Introduction

Research Interests: Scientific computing + robotics.

Applying Transformer / Neural Operator models to CFD spatiotemporal fields, enabling zero-shot generalization across geometries and PDE acceleration.

Research on bionic sensing for underwater robots (TENG/artificial lateral line).

Skilled in Star-CCM+ / COMSOL / ANSYS for engineering simulations and SolidWorks / Shapr3D for mechanical design.

Contact

• Email:

<u>Mu</u>

mzymuzhaoyang@gmail

• Phone: +86 153 8213 020

• Google Scholar: Zhaoyaı

computing. Currently Research / Project Experience in Hangzhou.

DamFormer — Transformer for Dam-Break Generalization (2024-)

Built multi-geometry datasets and achieved cross-geometry zero-shot predictions. Published in Physics of Fluids.

Sparse → Dense Transformer — Spatiotemporal Super-Resolution Reconstruction (Ongoing)

Reconstruction of high-resolution CFD/environmental spatiotemporal fields from sparse sensors.

Bionic Undulating-Fin Propulsion Simulation (Westlake University) (Jun 2024 -Present)

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Advisor: Prof. **Minyi Xu**, School of Artificial Intelligence

B.Eng. in Materials
Science & Engineering
(Polymer), Dalian Maritime
University (Sep 2019 – Jun

2023)

GPA: **3.2/4.0 (82/100)**; Rank: **7/100**

Visiting Student / Research Assistant, i⁴-FSI Lab, School of Engineering, Westlake University (PI: Dixia Fan)

(Jun 2024 - Present)

Focus: Bionic undulating-fin propulsion simulation (Star-CCM+ + Java Macro, with cross-validation in ANSYS/COMSOL when needed)

Skills

Programming / ML: Python (PyTorch, NumPy, Pandas, Matplotlib), Java (Star-CCM+ Macro/Workflow); Transformer, Neural Operator

Simulation / Numerical: Star-CCM+ (CFD/FSI), COMSOL, ANSYS;

PDEBench

Mechanical / 3D Design:

SolidWorks, Shapr3D (3D/2D modeling, BOM, interference checking)

Hardware / Control:

STM32 NUCLEO-F439ZI, PWM/TACH feedback, TP-Link L3 managed switch, PowerShell flashing automation

Server / HPC: Linux, SLURM, PyTorch DDP/AMP, CUDA, NCCL, Weights & Biases

Research Tools: LaTeX, Overleaf, Git, data visualization CFD/FSI simulations in Star-CCM+; automated parameter sweeps with Java Macro.

Fan-Wall Wind Tunnel (21×21 / 10×10 Modular Array) (2023 - Present)

 $2.5~m \times 2.5~m$ modular array; STM32 multi-board PWM/TACH closed-loop system; VLAN/DHCP network management.

Ocean Observation Buoy — Lead Mechanical Designer (Westlake University) (2022)

Responsible for structure design, sealing, corrosion prevention, buoyancy and stability calculations, BOM drawings, and tank/sea trials.

Server / HPC Training & Deployment (2023 - Present)

PyTorch DDP/AMP, SLURM job arrays, Miniconda environment, CUDA setup, and W&B experiment logging.

Publications

Published in *Physics of Fluids*, *IEEE RA-L*, *Advanced Materials Technologies*, *Nano Energy*, *CAC*, and other journals/conferences (10+ papers in total).

Selected Publications:

Generalizing morphologies in dam break simulations using transformer model — Physics of Fluids **37**(1):016612, 2025

Rs-ModCubes: Self-reconfigurable, scalable, modular cubic robots for underwater operations — IEEE RA-L, 2025

Deep-Learning-Assisted Triboelectric Whisker Sensor Array... — Advanced Materials Technologies, 2025

Deep-learning-assisted triboelectric whisker... — Nano Energy 129:110011, 2024

Patents

CN119509546A | Dynamic Environmental Perception and Navigation Device & Method for Underwater Robots (Published: 2024-11-06)

Applicant: Westlake University

CN119239885A | *Underwater Robot Based on Vector Octa-Thruster Layout* (Published: 2024-11-06)

Applicant: Westlake University

CN119142488A | *Undulating-Fin Propulsion Based Underwater Robot* (Published: 2024-11-06)

Applicant: Westlake University

CN118182783A | Flexible-Fin Underwater Robot with Embedded Multi-Sensors and Operation Method (Published: 2024-04-23)

Applicant: Dalian Maritime University

CN118047007A | *Ship with Intelligent Dynamic Sensing System* (Published: 2024-03-14)

Applicant: Dalian Maritime University

CN308069533S (Design Patent) | Mobile Buoy Robot (Published: 2023-02-22)

Applicant: Westlake University

CN120217249A | Intelligent Monitoring System and Method for the Entire Water Network Process of Large Power Plants (Published: 2025-03-26)

Applicant: Huaneng (Guangdong) Energy Development Co., Ltd. Yutou Power Plant

CN120448721A | Power Plant Water Network Intelligent Monitoring Method Based on Dynamic Water Balance and ARIMA Model (Published: 2025-03-25)

Applicant: Huaneng (Guangdong) Energy Development Co., Ltd. Yutou Power Plant

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Languages

English (CET-4, CET-6)
Chinese (native)

Interests & Hobbies

Music Production / Arrangement

Music homepage:

Pitoyoung

Additional Information

<u>Full Resume Details (Notion Reference)</u>

Internships & Volunteering

Internship | Dalian Exploration Ocean Technology Co., Ltd. (2022–2023)

> Mechanical design and integration; ANSYS/COMSOL verification; participated in sea trials and project delivery.

Volunteer | Society of Engineers Annual Conference (Hangzhou) (2024)

Conference services and A/V support: registration, session organization, presentation switching, timing, and live streaming across multiple sessions.

Honors & Awards

8th China International "Internet+" College Students Innovation & Entrepreneurship Competition • Gold Award (Apr 2023)

Project: Kunpeng Technology — Leader in Underwater Hull Inspection Robots; Certificate No.: 202310033

2021 China Robot Conference (RoboCup China) · Underwater Robot "Aquatic Parade" · First Prize (Online, Apr 15–17, 2022)

Team: "Hada Mechanical Engineering Team One", Dalian Maritime University; Certificate No.: Y2109R025A0001

China College Student Mechanical Engineering Innovation & Creativity Competition \cdot "Mingshi Cup" Micro-Nano Sensing Technology and Intelligent Application Track \cdot First Prize (Jul 24, 2024)

Project: *DeepBlue Vision-Fusion Underwater Robot*; Advisor: Yiran Si; Institution: Dalian Maritime University; Certificate No.: MEICC05MNSI2024-CV1-006

Liaoning Province Mechanical Innovation Design Competition · Bronze Award (Apr 2024)

Project: *DeepBlue Sense* — *TENG-based Underwater Tactile Sensor*; Institution: Dalian Maritime University; Team Members: Junyue Zhou, Zhaoyang Mu, et al.; Advisors: Hao Wang, Minyi Xu, Peng Xu

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