MPTT Architecture (v40) Update

South China Pitter Liao 2022 March

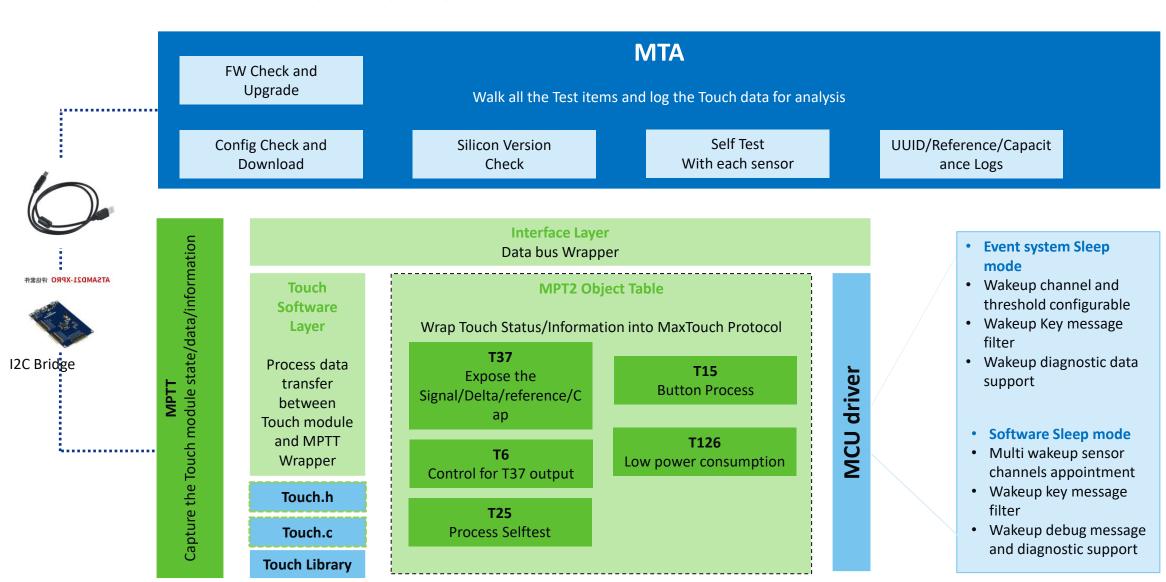


ECN

V40: First support 4x scanning mode



MPTT Architecture





MPTT Architecture

MPTT Interface

(Interface.c)

Hardware Abstract Layer

MPTT Hardware control (arch/avr/attiny/)

Bus management
Data
read/write/interrupt
(bus.c)

HW data interface wrapper (I2c.c)

I2C driver

HW management Reset manager (sysctrl.c)

Flash management config store (flash.c)

ADC management (pinconfig.c)

SYSCTRL driver Flash driver Timer driver GPIO management config gpio of sensor pins and offer pin fault detection

(pinconfig.c)

Touch library
management
Translate the touch lib
information to MPTT
format
(tsapi.c)

GPIO driver Pinmux driver ADC driver Touchlib

Touch Software Layer

MPTT software control (tsl.c)

ID Information
Hardware/Firmware ID
(mptt.c)

Object Tables
Address table /reporting IC
(mptt.c)

Message FIFO
Cache all messages of the registers
(mptt.c)

Registers
Function feature to process
parameters and report message
(objects/t5/t6/t15/...)

Debug Register
A buffer to store debugging data
(objects/t37.c)



Power consumption(4x)

ATTINY3217 XPRO + T10

Normal Buttons: 3.3V power supply, CPU 8Mhz, I2C interface, BOD 1Khz, WDG Enabled 4s, Oversampling 4, Prescale div 8, CSD=0

Low Power Button: Oversampling 16, Prescale div 4, CSD=0 (8 buttons, Mutual cap 4x, Freq Hop enabled, 1 buttons wakeup)

		Interval (ms)	Active (uA)		Idle						4 button	8buttons	BOD	BOD	BOD
				(uA)									sampled,	off	on
													ADC 8		
	Drift(s)		-		0.2	1	2	4	8	disabled	4	4	4	4	4
		1	3741					3746							
Software Sleep		4	3340					1620							
		10	1416					684							
		16	922					440							
		32	501					231							
		64	290					125			125	125			
		128	183					70							
		255	129					42							
		disabled	208					2.1							
		Interval	Active		Idle								BOD	BOD	BOD
		(ms)	(uA)		(uA)						1 button	4buttons	sampled,	off	on
													ADC 8		
	Drift(s)		-		0.2	1	2	4	8*	disabled	4	4	4	4	4
		1	3749					164		-					
Event		4	3395					92		-					
system Sleep		10	1419					-		-					
		16	924					27.7		-					
		32	503					18.5		-					
		64	290					13.5		-					
		128	183					11.5		-					
		255*	129					10.3		-					
		disabled	90					9		-					

~Times 5 from 1x

~Times 2 from 1x



5 minutes to create Project

- Clone project from Github:

```
git clone https://github.com/PitterL/mpt2.git git branch git checkout 3217-t10
```

- Files modified when transplanting to your own project:

```
qtouch\touch.h --- Define Qt library sensor configuration mpt2\board.c --- Define MPTT firmware sensor layout
```



Steps 1 (qtouch\touch.h)

- Sensor configuration

```
#define DEF_NUM_CHANNEL_GROUPS (2)
#define DEF_NUM_CHANNEL_NODES (DEF_NUM_CHANNEL_GROUPS << 2)</pre>
/* Defines mutual cap node parameter setting
* {X-line, Y-line, Charge Share Delay, NODE_RSEL_PRSC(series resistor, prescaler), NODE_G(Analog Gain , Digital Gain),
 * filter level}
#define GRP_0_4P_PARAMS
       { X(5), X(4), X(1), X(0) }, Y(2), 0, NODE_RSEL_PRSC(RSEL_VAL_0, PRSC_DIV_SEL_8),
            NODE_GAIN(GAIN_1, GAIN_1), FILTER_LEVEL_4
#define GRP_1_4P_PARAMS
        { X(5), X(4), X(1), X(0) }, Y(3), 0, NODE_RSEL_PRSC(RSEL_VAL_0, PRSC_DIV_SEL_8),
            NODE_GAIN(GAIN_1, GAIN_1), FILTER_LEVEL_4
/* Lumped as the auto scanning node */
#define GRP_Lump_4P_PARAMS
       { X(5) | X(4) | X(1) | X(0), X_NONE, X_NONE, X_NONE }, Y(2), 5, NODE_RSEL_PRSC(RSEL_VAL_0, PRSC_DIV_SEL_4),
            NODE_GAIN(GAIN_1, GAIN_1), FILTER_LEVEL_16
```



Steps 1 (qtouch\touch.h)

- Sensor selected

```
/* Normal channel nodes */
#define PTC_SEQ_NODE_CFG1 {
    GRP_0_4P_PARAMS, \
    GRP_1_4P_PARAMS, \
}

/* Auto scan channel use individual node */
#define PTC_SEQ_AUTO_SCAN_NODE_CFG1 { \
    GRP_Lump_4P_PARAMS \
}

/* key sensor to channel node */
#define TOUCH_KEY_SENSOR_MAPPING_4P { \
    0, 1, 2, 3, 4, 5, 6, 7 \
}

/* channel node to key sensor (fill `-1` for invalid node)*/
#define TOUCH_CHANNEL_NODE_MAPPIING_4P { \
    0, 1, 2, 3, \
    4, 5, 6, 7, \
}
```



Steps 1 (qtouch\touch.h)

- Keys Sensor configuration(Never mind, will be overridden in actual config)

```
/* All sensors */
    #define DEF_NUM_SENSORS (8)

/* Defines Key Sensor setting
    * {Sensor Threshold, Sensor Hysterisis, Sensor AKS}

    */
    #define KEY_0_PARAMS
    {
        20, HYST_25, NO_AKS_GROUP
    }

#define QTLIB_KEY_CONFIGS_SET { \
        KEY_0_PARAMS, KEY_0_PARAMS, KEY_0_PARAMS, \
        KEY_0_PARAMS, KEY_0_PARAMS, KEY_0_PARAMS, \
        KEY_0_PARAMS, KEY_0_PARAMS, KEY_0_PARAMS, \
        KEY_0_PARAMS, KEY_0_PARAMS, KEY_0_PARAMS, \
        Y
```



Step 2 (mpt2\board.c)

- Definition button groups:

```
qbutton config t buttons config[MXT TOUCH KEYARRAY T15 INST] = {
    #ifdef EVK_3217_T10
   { .node = { .origin = 0, .size = 4 } },
     \{ .node = \{ .origin = 4, .size = 4 \} \},
    #endif
// There are 3 groups default, you could set all channels to same group, or split it into several groups.
// It will finally be shown in `QTServer` T15 objects.
```

- Definition chip sensor channel group:

```
• qtouch_config_t tsl_qtouch_def = {
    #ifdef EVK_3217_T10
        .matrix_nodes = \{\{\text{.origin} = 0, \text{.size} = 4\}, \{\text{.origin} = 0, \text{.size} = 4\}\},
    #endif
// Sensor channels group as `X channels` * `Y channels` matrix format, it will show how many sensor matrix nodes in chip information.
// This is a virtual information, you just confirm xsize*ysize larger than qlib channels
Note:
origin: the start channel in qlib definition(touch.h)
size: how many sensor channels used in this group.
Please modify the Macro definition if you change ` EVK_3217_T10 ` to another name: project properties->Toolchains->Symbols
```



Compile and pack Firmware image

- Compiling with Microchip studio 7.0

https://www.microchip.com/en-us/development-tools-tools-and-software/microchip-studio-for-avr-and-sam-devices#tabs with `Debug` options, there will be hex image at `Debug\ATtiny3217-1Finger-Low_Power-4x-Project-MPT2.hex` (You could use the image now)

For version management and combined image generated:

 Firmware build version and fuse definition: qtouch\pack.h

```
The below definition is used for cupdi package tool.

Firmware version is a 32bit hexi value, which will be packed into eeprom segment.

Fuse content is a hexi byte array, NULL indicate ignored byte. THe information will be packed into fuse segment.

Warning: Support '//' comment mark, but not support '/ * * /' comment mark inside the definition

*/

/* Project code*/

#define PROJECT_CODE 0x5630343014 /*V040, v1.4*/

/* Fuse content */

// BOD level 2(2.6v Sampled 1Khz at Sleep, Enabled at Active), OSC 16Mhz, NVM protect after POR, EEPROM erased, WDT(4096ms)

#define FUSES_CONTENT {0x0A, 0x46, 0x7D, 0xFF, 0x00, 0xFF, 0x00, 0x00, 0xFF, 0xC5 } /* BYTE order */
```



Low Power Mode debugging(Evsys)

Set the macro in project build symbols:

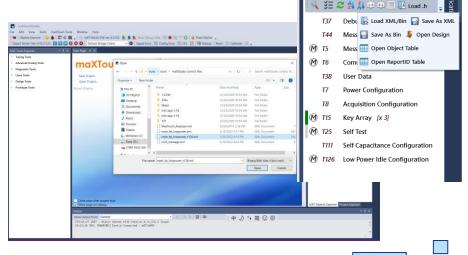
```
`OBJECT_T6`

`OBJECT_T37`

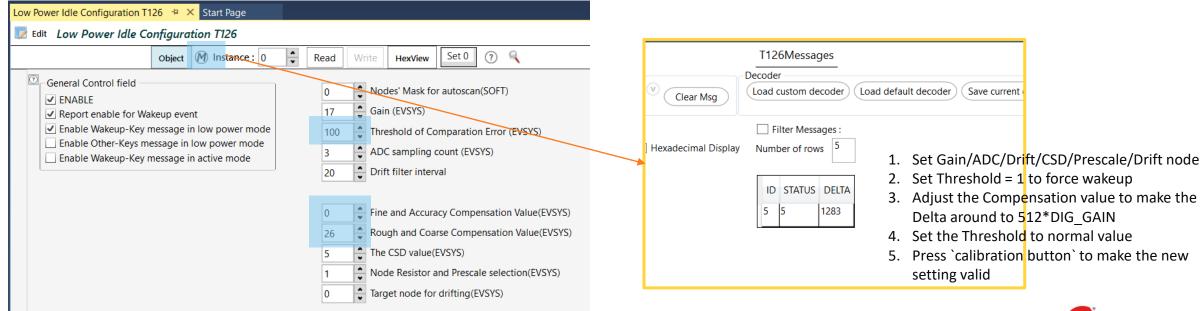
`OBJECT_T126`

`<del>OBJECT_T37_DEBUG_LOWPOWER_INFO</del>`

`<del>DEF_TOUCH_LOWPOWER_SOFT</del>` (set: software mode, clear: hardware mode)
```

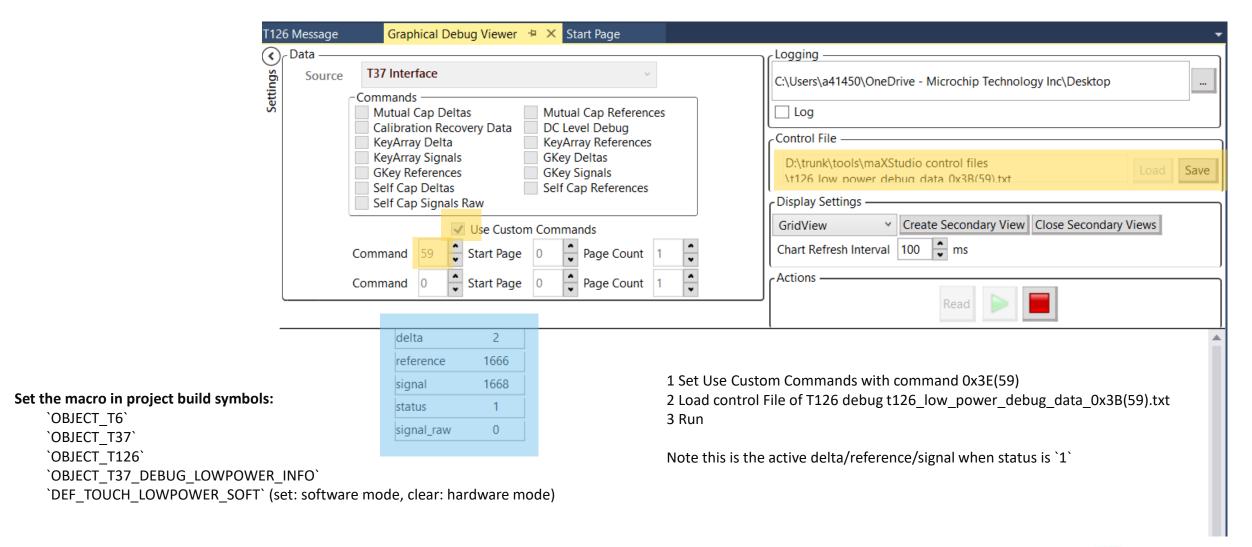


After the build, the T126 will be looked like(Please load the `mptt_4p_lowpower_t126_t15(3)` file of chip description script):





Low Power Mode debugging(Soft)





The MPTT (v40) Feature:

- 4x mode supported
 - Only finished the buttons support currently (will support slider/surface later)
- Individual auto scanning sensor supported with 1x low power mode
 - Assign the auto scanning sensor for 1x mode, and won't be scanned in active mode
 - Compensation/CSD/Prescale/Sampling count/Threshold assignable dynamically
 - Drift support



Thank you!

