

## ② Image Sensing & Acquisition.

\* Images are created when light or other energy (like X-rays or infrared) interacts with objects by reflecting off or passing through them.

\* If the energy reflects, we see an image like a mirror reflection. If it passes through, like X-rays through a body, it helps create an internal image.

\* Some systems, like electron microscopes or gamma imaging (SPECT), use special converters to turn this energy into visible images.

\* There are three main types of sensors used to convert light or other energy into digital images.

1. Single imaging sensor

— Captures one image at a time

2. Line sensor

— Captures images line by line, useful for scanning.

3. Array Sensor —

— Captures the entire image at once, like a camera sensor.

### Sensor Process

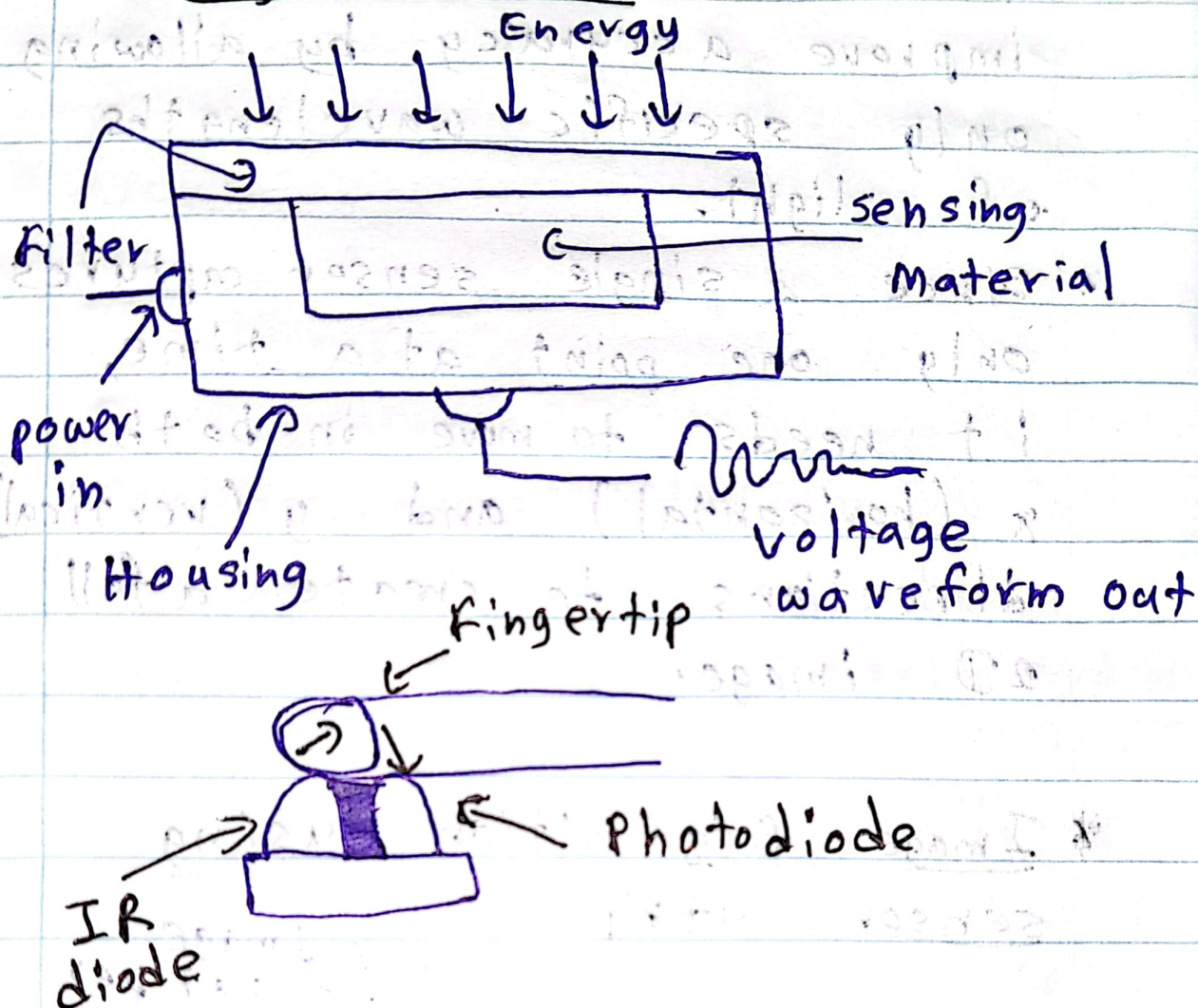
\* The sensor converts incoming energy into voltage using electrical power and special materials that react to the energy type.

\* This voltage signal is then digitized to create a digital image.

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## \* Image acquisition using a single sensor

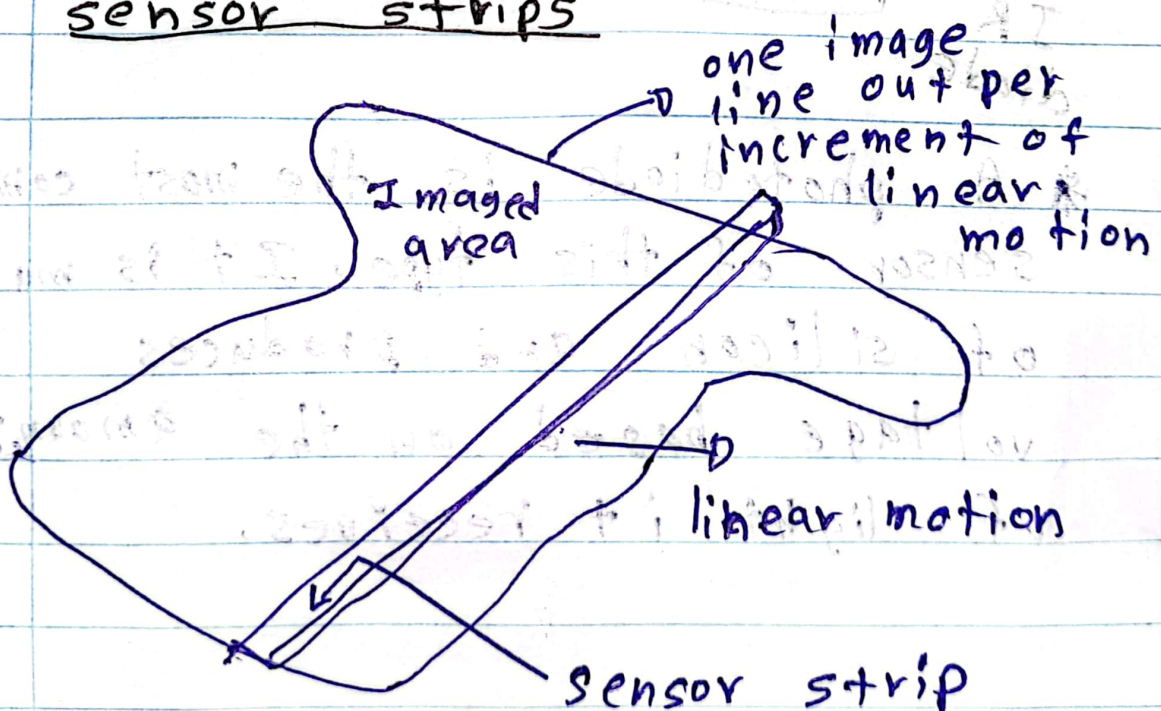


\* A photodiode is the most common sensor of this type. It is made of silicon and produces voltage based on the amount of light it receives.

\* A filter can be placed in front of the sensor to improve accuracy, by allowing only specific wavelengths of light.

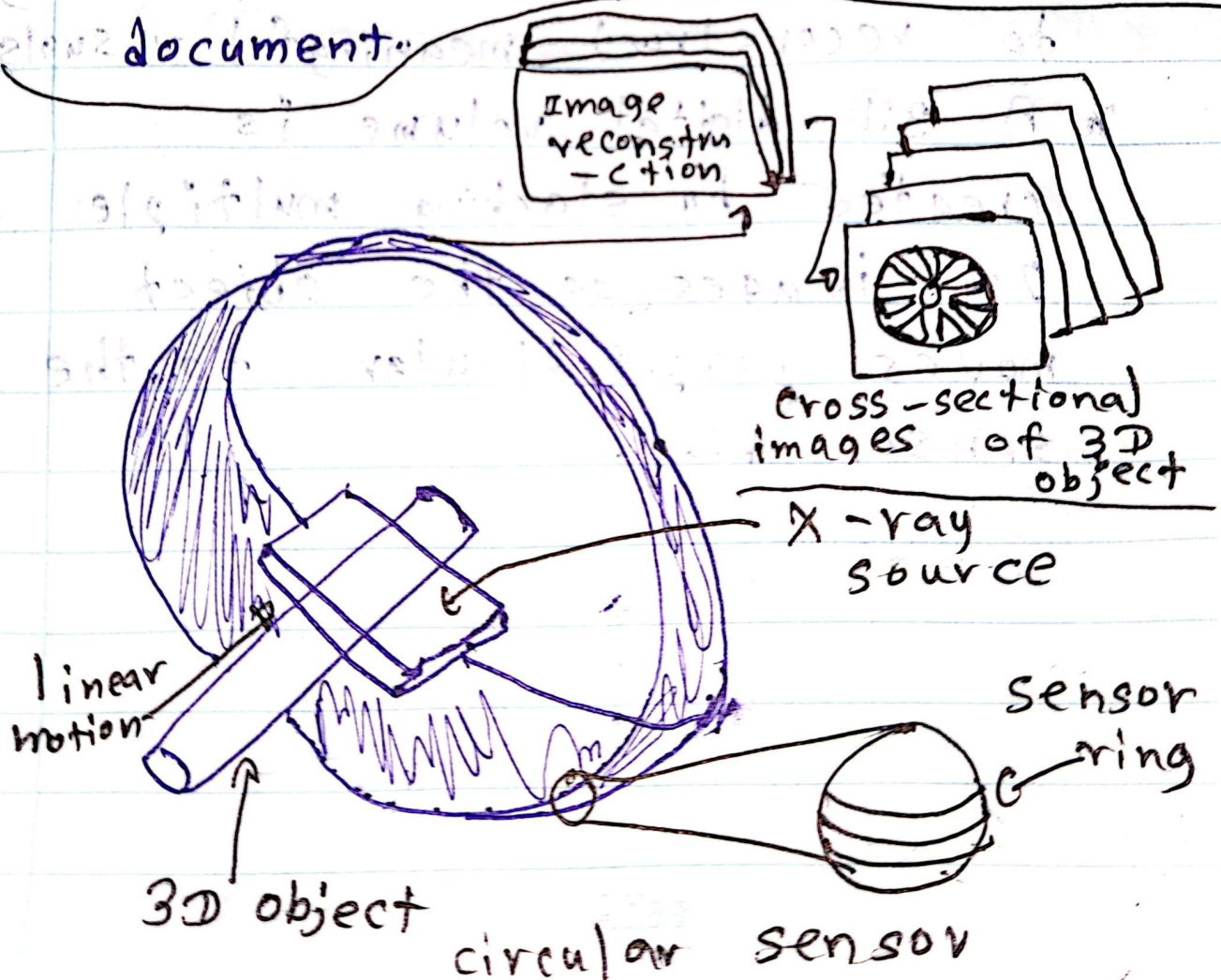
\* Since a single sensor captures only one point at a time, it needs to move in both  $x$  (horizontal) and  $y$  (vertical) directions to create a full 2D image.

### \* Image Acquisition using sensor strips





- \* A sensor strip captures images in one direction (like a single row of pixels)
- \* To create a full image, the object, or sensor must move in the perpendicular direction
- \* This method is commonly used in flatbed scanners, where the scanning head moves to capture the entire document.



## \* Sensor Strips in a Ring Configuration

\* Used in medical and industrial imaging to capture cross-sectional (slice-by-slice)

Images of 3D objects.

\* Examples: CAT (CT scans), MRI, and PET scans use this method.

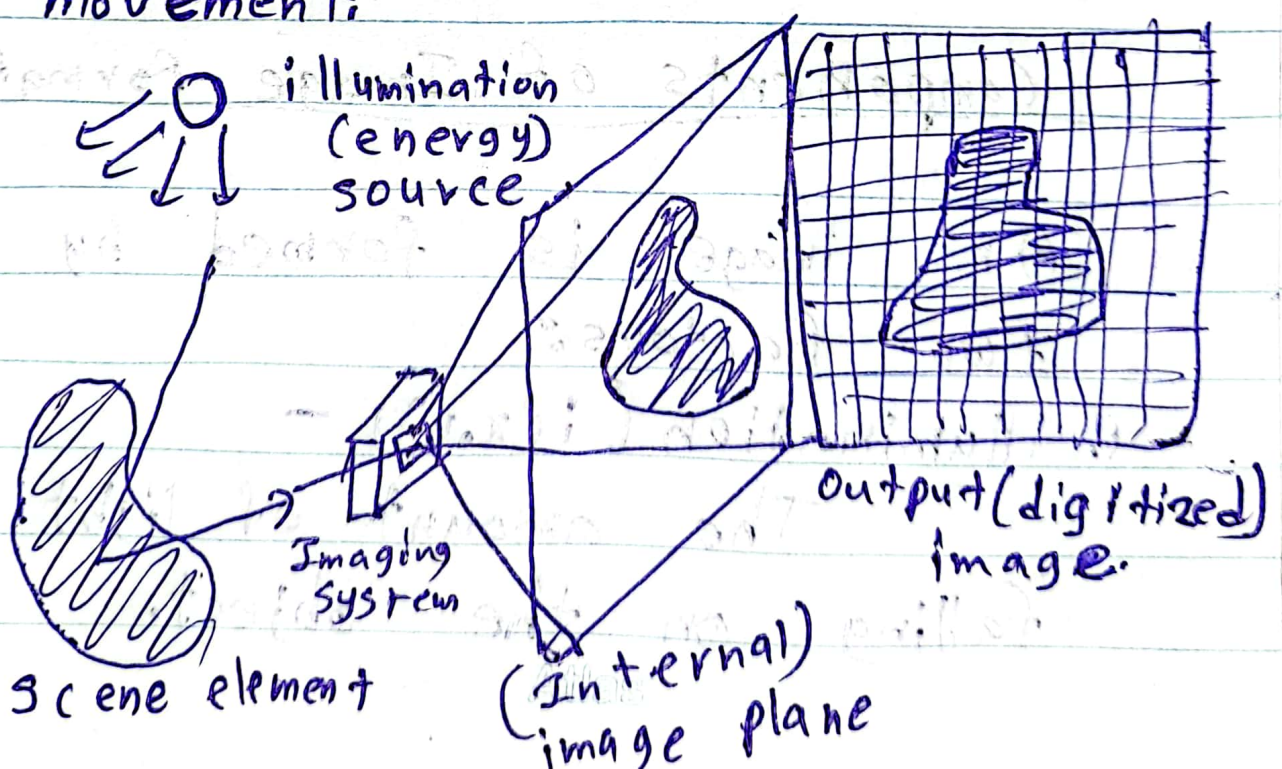
\* Unlike regular scanning, these images require complex processing to reconstruct meaningful visuals

\* A 3D digital volume is created by stacking multiple 2D images as the object moves perpendicular to the sensor ring.



## \* Image Acquisition using Sensor Arrays.

- \* Many electromagnetic and ultrasonic sensors are arranged in arrays for imaging.
- \* This method is commonly used in digital cameras
- \* Each sensor in the array captures total light energy falling on it, converting it into a digital image.
- \* key advantage: A 2D sensor array captures a complete image instantly without needing movement.



## Image Formation Model

- \* An image is represented as 2D function:  $f(x, y)$ , where  $x$  and  $y$  are coordinates and  $f(x, y)$  gives the brightness at that point.
- \* The brightness value depends on the energy source, such as light or electromagnetic waves.
- \* Since light has positive energy, the function must be non-zero and finite ( $0 < f(x, y) < \infty$ ).

## Components of Image Formation

An image is formed by two factors:

1. illumination ( $i(x, y)$ ) -

The amount of light falling on the object.



## 2. Reflectance ( $r(x, y)$ ) ~

The amount of light reflected from the object.

These combine as:

$$f(x, y) = i(x, y) \times r(x, y)$$

- \* illumination ( $i(x, y)$ ) is always positive ( $0 < i(x, y) < \infty$ )
- \* Reflectance ( $r(x, y)$ ) is between 0 (total absorption, black) and 1 (total reflection, white)

## Gray Levels and Grayscale

- \* The brightness at any point is called its gray level ( $I$ ), which lies within a range  $[L_{min}, L_{max}]$ , called the gray scale.
- \* In practice, this range is mapped to  $[0, L-1]$ , where:

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• 0 = black

• 1 = white

• Intermediate values  
= shades of gray.

$$(r(x) \times x + (b(x) \times (1 - x))) = (u(x))$$

Example:  $(u(x))$  is not null  
( $0 < (u(x)) < 1$ )  
if  $(r(x) \times x + (b(x) \times (1 - x)))$  is not null  
( $0 < (u(x)) < 1$ )

Example:  $(u(x))$  is not null

The value of  $(u(x))$  is not null  
if  $(r(x) \times x + (b(x) \times (1 - x)))$  is not null

Example:  $(u(x))$  is not null

Example:  $(u(x))$  is not null

Example:  $(u(x))$  is not null

Example:  $(u(x))$  is not null

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