

Intensity Transformation and Spatial Filtering - I

Intensity Transformation and Image noise.

* What is the spatial Domain?

'The spatial domain refers to the actual pixels of an image. Each pixel has an intensity (brightness) value and a specific location (x, y)

IMAGE is represented in pixel domain -

There are 3 common Domain -

1. spatial Domain

2. Frequency Domain

3. Energy Domain

* Mathematical Representation

$$G(x, y) = T[f(x, y)]$$

$f(x, y)$: Input image (original image)

T : A transformation (or filter) applied to modify pixel values.

$G(x, y)$: output image (processed image).

* Examples of spatial domain techniques include

1. Intensity Transformations

e.g. contrast stretching, log transformation

2. Smoothing filters

e.g. mean filter, Gaussian filter.

3. Edge Detection

e.g. Sobel, Prewitt, Canny.

* Generalization of spatial domain techniques

filter, thresholding, binarization, and so on.

* Edge detection (contours, skeletonization)

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* What is Image Enhancement? *

Image enhancement is the process of modifying an image to make it more useful for a specific application.

* Why Are Enhancement Techniques Problem-Oriented? *

Different applications need different enhancement.

- Medical imaging: Enhancing X-rays or MRI

- Radar scans to detect diseases.

- Satellite images

- Security cameras: Reducing noise for clear video footage.

* Intensity Transformation *

* What is Intensity Transformation? *

Intensity transformation modifies the brightness and contrast of an image by changing pixel values.

$$S = T(r)$$

Transformation function

New pixel value → original pixel value

Types of Gray Level Transformations.

1. Linear Transformation (Direct Adjustments)

→ contrast stretching

→ Negative Transformation: $S = L - 1 - V$

2. Logarithmic Transformation (Enhancing Dark Details)

3. Power-Law (Gamma) Transformation (Adjusting Brightness)

$$S = C r^{\gamma}$$

Linear Transformation

→ Identity Transformation.

- No change in pixel values.

$$\cdot g(x, y) = f(x, y)$$

- Output same as input

- Used, analyzed without alteration.

→ Image Negatives → This transformation inverts the pixel values

Log Transformation

• what is Log Transformation?

Log transformation enhances dark regions

while compressing bright regions.

It is useful when an image has many dark pixels with hidden details.

• Types of Log Transformation

1. Log Transformation (Enhancing Dark Details)

2. Inverse Log Transformation,

(Enhancing Bright Details)

$$\rightarrow S = c \log(1 + r) \quad r >= 0$$

r = input pixel intensity

s = Output pixel intensity

c = Scaling constant (adjusts intensity range)

• Why Use Log Transformations?

Medical Imaging - Enhancing X-ray scans.

Satellite Images -

Low-light photography -

• Power-Law (Gamma) Transformation

- What is Power - Law (Gamma) Transformation?
 - The power-law transformation (also called gamma correction) is used to adjust the contrast of an image.
 - It maps input pixel values to output values based on a power function.

$$S = C \cdot V^{\gamma}$$

S = Output pixel value

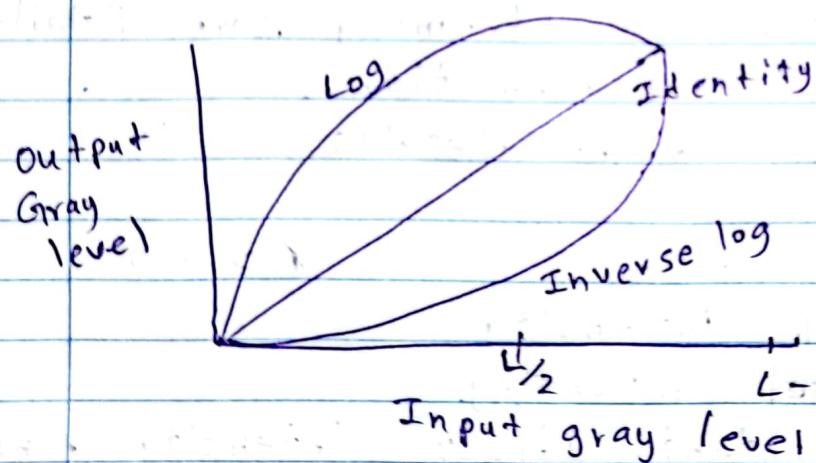
V = Input pixel value

C = Constant scaling factor

(Controls the overall brightness)

γ = Exponent that controls the nonlinear relationship between the input and output values.

• Intensity Transformation All in One



* Contrast Stretching.

- What is Contrast Stretching?

Contrast stretching is a technique used to increase the contrast in images, especially in low contrast images.

- Low contrast images can occur due to:

• poor illumination (insufficient light during capture)

- Limited dynamic range in the camera or sensor
- Incorrect lens settings (e.g. wrong aperture)

- Gray Level Slicing

purpose: Highlights specific intensity ranges in an image.

Histogram Processing.

A histogram in image processing is a graphical way to show how pixel intensities are distributed in an image.

• Understanding the Histogram

- In a grayscale image, each pixel has an intensity ranging from 0 (black) to 255 (white)
- A histogram counts how many pixels exist for each intensity level.
- It helps in analyzing the brightness, contrast, and exposure of an image.

Normalization of Histogram

- This is done by dividing each histogram value by the total number of CHAMARA pixels,

- why use Histogram Processing?

- Enhances contrast

- Equalizes brightness

- Improves image quality.

- Histogram Equalization

(PDF) probability distribution function:

$$p(r_k) = h(r_k) / N$$

(CDF) cumulative distribution function:

$$cdf(r_k) = \sum_{j=0}^k p(r_k)$$

$$s_k = ((L-1) \cdot cdf(r_k))$$

gray levels	0	1	2	3	4	5	6	7
No. of pixels	0	100	400	50	200	50	200	0

$$n = \sum n_k = 0 + 100 + 400 + 50 + 200 + 50 + 200 + 0 = 1000$$

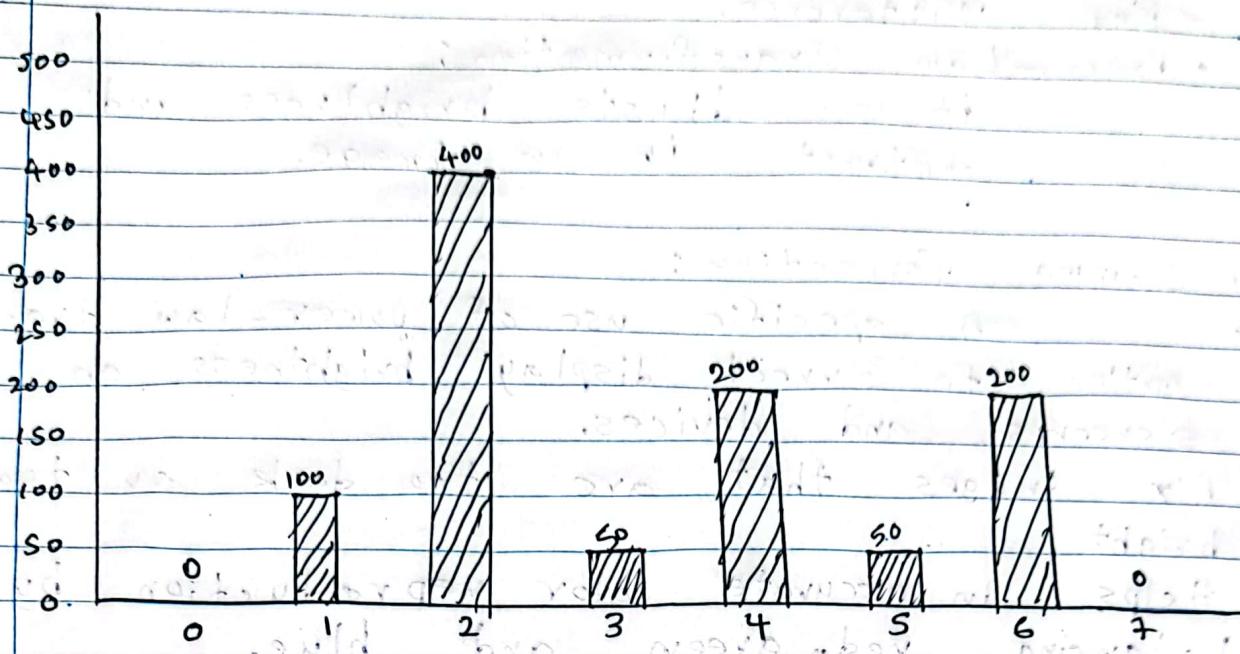
Gray level	0	1	2	3	4	5	6	7
n_k	0	100	400	50	200	50	200	0
$p_f = \frac{n_k}{n}$	0	0.1	0.4	0.05	0.2	0.05	0.2	0
$cdf(s_k)$	0	$0+0.1$ 0.1	$0.1+0.4$ 0.5	$0.5+0.05$ 0.55	$0.55+0.2$ 0.75	$0.75+0.05$ 0.80	$0.80+0.2$ 1.00	1
$(L-1) \times s_k$	0	7×0.1 0.7	7×0.5 3.5	7×0.55 3.85	7×0.75 5.25	7×0.80 5.6	7×1 7	7
Rounding	0	1	2	4	5	6	7	7

Old Gray levels	0	1	2	3	4	5	6	7
No. of pixel	0	100	400	50	200	50	200	0
New Gray Level	0	1	4	4	5	6	7	7

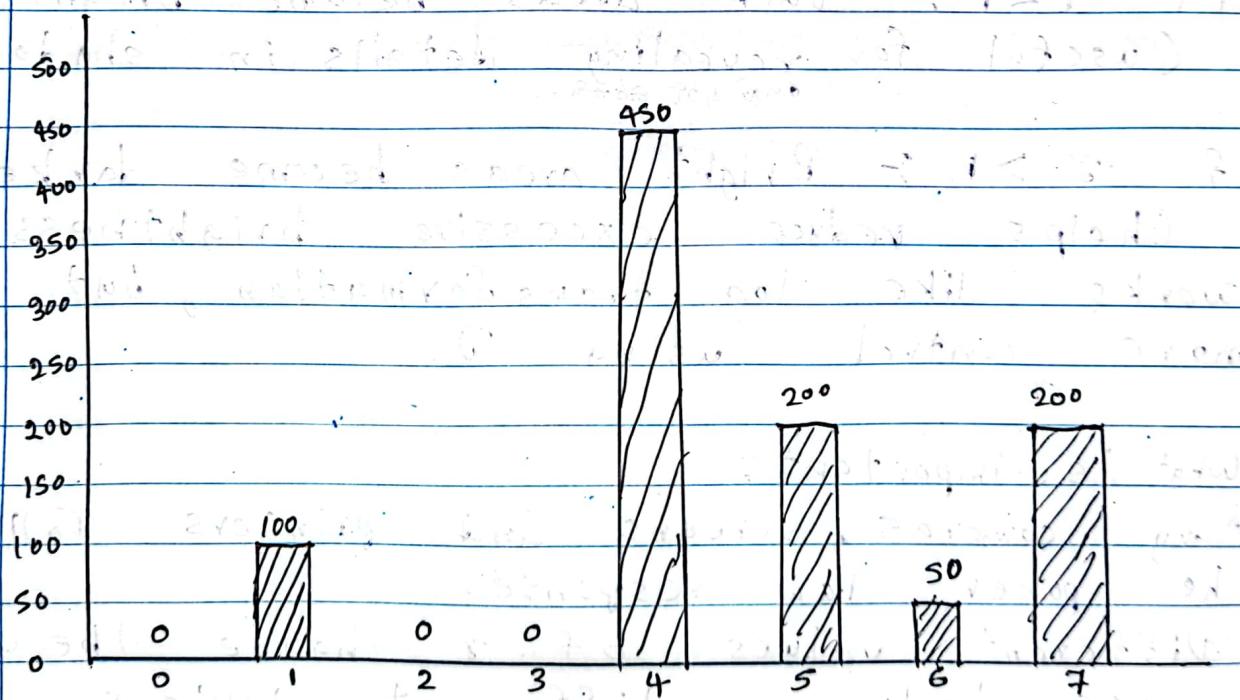
(4)

Date: / /
No:

original Histogram



PDI Equilized Histogram



* Power-Law (Gamma) Transformation No:.....

Key Difference:

- Power-Law Transformation:

it is adjusts brightness and contrast in an image.

- Gamma Correction:

A specific use of power-law transformation to correct display brightness on screens and devices.

- Fix images that are too dark or too bright
- Helps in accurate color reproduction by balancing red, green and blue.

→ How it works (Power-Law Transformation)

- * if $\gamma < 1$:- Dark areas become brighter
(useful for revealing details in shadows)
- * if $\gamma > 1$:- Bright areas become darker
(helps reduce excessive brightness)
- * Works like log transformation, but gives more control using γ

→ What is important?

- * Many cameras, screens and printers follow the power law response.
- * Different values of γ change the way images look on different devices.

Image Noise

- * Noise is a visual distortion in digital image.
- * It causes visual degradations in digital images:
- * Noise reduce image quality, making it look grainy, blurry, or speckled.
- * Even though noise is unavoidable, noise is always present, but if the main image data (signal) is strong enough, the noise become too small to notice.
- * SNR (Signal to Noise Ratio) compares the amount of useful image data (signal) to unwanted noise. A high SNR means clear image with little noise, while low SNR means noisier, degraded image.
- * In digital imaging, A Noisy image can be mathematically represented as,
$$g(x,y) = f(x,y) + n(x,y)$$

$f(x,y) \rightarrow$ original image pixel
 $n(x,y) \rightarrow$ noise in the image
 $g(x,y) \rightarrow$ final pixel value with noise

- * Source of Image Noise
 - Error occurs in image signal: noise happens when an image sent electronically from one place to another, data gets lost or mixed up.

ISO Factor ~~is~~ ~~not~~ ~~the~~
Guwa ~~min~~ ~~an~~ ~~is~~ ~~2nd~~
~~3rd~~ ~~did~~ ~~2nd~~ ~~is~~ ~~Bad~~
No:

- Exposure time :

If the camera's shutter open for a long time, static or unwanted signal maybe introduced, leading to noise.

- ISO Factor :

ISO setting on camera controls its sensitivity to light. Higher ISO setting can brighten images but also increase noise.

- Size of the sensor:

Smaller sensors have a reduced capacity to gather light, which can lead to increase noise.

- Pixel Density:

Higher pixel density means more pixel are packed into a small area, which can reduce light per pixel and increase noise.

- shadows :

In dark areas, camera has trouble capturing details, causing noise.

Types of Noise:

- * The distribution of noise is based on probability. So this described probability Density function (PDF).
- * PDF helps to understand the distribution of noise values.

* Noise types are,

1) Gaussian Noise -

- This is a common type of noise.

Gaussian noise happens in images because of things like electronic circuits and sensor issues in cameras, especially when there's poor lighting or high temperatures.

- It has a random distribution, meaning the noise values are normally distributed over time.

2) Rayleigh noise -

- Typically appears in images taken by devices that measure distance, like

3) Gamma (Erlang) noise and Exponential noise:

- This can be found in laser imaging.

4) Uniform Noise - This noise is rare in real world images.

5) Impulse Noise -

- Common type of noise found in digital images.

- Impulse noise doesn't affect every pixel in an image.

- Only some pixels are corrupted.

There are two main types:

1. Salt noise - This appears as white spots and has the highest brightness level.

2. Pepper noise - This appears as black spots and has the darkest brightness level.

Definition

noisy pixel

$\rightarrow 255$ - with probability $P/2$, pixel becomes white. This is

 $g(x,y) =$

small salt noise

 $\rightarrow 0$ - with probability $P/2$, pixel

becomes black - This is pepper noise.

clean pixel

$\rightarrow f(x,y)$ - with probability $1-P$,
The pixel remains unchanged.

In some applications, noisy pixels are not simply black or white, which makes the impulse noise removal problem more difficult.

Image Restoration

- * The main goal of restoration technique is to improve an image by reversing the damage.
- * Unlike image enhancement, which makes image look better for a specific purpose, restoration tries to get the image back to its original state.

Common ways to restore an image:

* Deblurring: \rightarrow soft manual

* Inverse filtering: \rightarrow hard

Periodic Noise: \rightarrow hard

* depends on spatial coordinates. \rightarrow can be reduced through

* reduced in frequency domain, filtering.

\rightarrow filter on image with low pass filter.

associated with periodic noise.

• \rightarrow $\text{scale} \approx 2^{1/2}$ \rightarrow low pass filter .

• \rightarrow $\text{filtering} \rightarrow \text{low pass filter}$.