EXPERIMENT NO. 2

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Semester /Section: Semester-V – AIML-V-B (AL-3)

Link to Code: NCU-Lab-Manual-And-End-Semester-Projects/NCU-CSL347-AAIES-Lab Manual at main ·

Piyush-Gambhir/NCU-Lab-Manual-And-End-Semester-Projects (github.com)

Date: 19.08.2023
Faculty Signature:

Grade:

Objective(s):

Understand what breadth first Search (BFS) and Depth first Search (DFS) is.

- Study about different uninformed searching approaches.
- Implement BFS and DFS for solving a real-world problem.

Outcome:

Students would be familiarized with BFS and DFS.

Students would be able to make a comparison between the two algorithms.

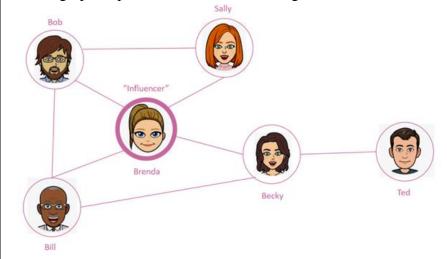
Problem Statement:

Implement Breadth-First Search (BFS) and Depth-First Search (DFS) algorithms in Python to analyze a simple social network. The program aims to explore social connections between users and offer insights into their relationships.

The program should be able to:

- Find groups of users who are directly or indirectly connected to the influencer "Brenda".
- Determine if there is a path between two users "Sally" and "Ted"

Use the graph as provided below for the assignment:



Background Study:

Breadth-First Search (BFS) and Depth-First Search (DFS) are graph traversal algorithms. BFS explores a graph level by level, visiting all neighboring nodes before moving deeper, utilizing a queue

data structure. On the other hand, DFS explores as deep as possible along each branch before backtracking, using a stack data structure. Both algorithms are fundamental in graph analysis and have various applications in tasks like path finding, cycle detection, and social network analysis.

Question Bank:

- 1. What do you understand by blind search algorithms?
 - Blind search algorithms are methods used in computer science to explore and traverse problem spaces without having any specific information about the structure or characteristics of the space. These algorithms rely solely on the information available during the search process and do not incorporate domain-specific knowledge.
- 2. What is Breadth-First Search and Depth-First Search?
 - Blind search algorithms are methods used in computer science to explore and traverse problem spaces without having any specific information about the structure or characteristics of the space. These algorithms rely solely on the information available during the search process and do not incorporate domain-specific knowledge.
- 3. What are the appropriate scenarios for using BFS and DFS algorithms?

 Breadth-First Search (BFS) is suitable for scenarios where finding the shortest path is important, like in navigation systems or puzzle-solving. It guarantees the shortest path but can require more memory due to the need to store the entire level's nodes.

Depth-First Search (DFS) is appropriate for scenarios where memory efficiency is crucial, such as solving mazes or searching through large trees. It doesn't guarantee the shortest path and can get stuck in infinite loops in some cases, but it's memory efficient as it explores one branch deeply before backtracking.

Student Work Area

Algorithm/Flowchart/Code/Sample Outputs

Pseudocode

END FUNCTION

```
BFS Pseudocode
FUNCTION path_using_bfs(graph, source_node, destination_node):
     Create a queue and ADD source_node to it.
     Create a set called visited and ADD source_node to it.
Create a dictionary called path and SET path[source_node] to None.
     WHILE queue is NOT empty:
current_node = REMOVE first element from queue.
          IF current_node is EQUAL to destination_node:
                {\tt RETURN} \  \, {\tt the} \  \, {\tt path} \  \, {\tt from} \  \, {\tt source\_node} \  \, {\tt to} \  \, {\tt destination\_node} \  \, {\tt using} \  \, {\tt the} \  \, {\tt path} \  \, {\tt dictionary}.
           FOR EACH neighbor in graph[current_node]:
                IF neighbor is NOT in visited:
ADD neighbor to visited.
                      SET path[neighbor] to current_node.
                      ADD neighbor to queue.
     END WHILE
     RETURN None.
END FUNCTION
 DFS Pseudocode
 FUNCTION path_using_dfs(graph, source_node, destination_node):
      Create a stack and PUSH source_node onto it.
Create a set called visited and ADD source_node to it.
      Create a dictionary called path and SET path[source_node] to None.
     WHILE stack is NOT empty:
    current_node = POP the top element from stack.
           IF current_node is EQUAL to destination_node:
                 RETURN the path from source_node to destination_node using the path dictionary.
           FOR EACH neighbor in graph[current_node]:

IF neighbor is NOT in visited:

ADD neighbor to visited.
                      SET path[neighbor] to current_node. PUSH neighbor onto stack.
           END FOR
      END WHILE
      RETURN None.
```

Code:

```
1 # importing required libraries
2 from collections import deque
[33] Python
```

Defining the Graph Using Adjacency List

Path Using BFS

Path Using DFS

Output:

```
1 # testing the code
2 print("BrS")
3 print(path_using_bfs(graph, "Brenda", "Ted"))
4 print("OFS")
5 print(path_using_dfs(graph, "Brenda", "Ted"))

W BFS
['Brenda', 'Becky', 'Ted']
DFS
['Brenda': None, 'Sally': 'Brenda', 'Becky': 'Brenda', 'Bill': 'Brenda', 'Ted': 'Becky'}
```