Homework 5

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a. Dilation

Description: For each pixel, it checks a local neighborhood defined by the kernel and assigns the maximum pixel value found in that neighborhood to the current pixel position.



```
1. def dilation(img, kernel):
        kernel size = len(kernel)
       dilation_img = np.zeros_like(img)
3.
       for i in range(img size0):
5.
            for j in range(img size1):
                max_value = 0
7.
                for ki in range(kernel size):
                    for kj in range(kernel size):
                         ni, nj = i + ki - kernel_size // 2, j + kj - kernel_siz
10.
   e // 2
                        if 0 \le ni \le mg size 0 \le nj \le mg size 1:
11.
                             if kernel[ki][kj] == 1:
12.
                                 pixel value = img[ni][nj]
13.
                                 if pixel value > max value:
14.
                                     max_value = pixel_value
15.
                dilation img[i, j] = max value
16.
17.
        return dilation img.astype(np.uint8)
18.
```

b. Erosion

Description: For each pixel, it searches for the minimum pixel value within the neighborhood specified by the kernel, assigning that minimum value to the current position.



```
    def erosion(img, kernel):

        kernel size = len(kernel)
       erosion_img = np.zeros_like(img)
3.
       for i in range(img_size0):
5.
            for j in range(img size1):
                min value = 255
7.
                for ki in range(kernel size):
8.
                    for kj in range(kernel size):
9.
                         ni, nj = i + ki - kernel_size // 2, j + kj - kernel_siz
10.
   e // 2
                         if 0 \le ni \le mg size 0 \le nj \le mg size 1:
11.
                             if kernel[ki][kj] == 1:
12.
                                 pixel value = img[ni][nj]
13.
                                 if pixel value < min value:
14.
                                     min value = pixel value
15.
                erosion_img[i, j] = min_value
16.
17.
        return erosion img.astype(np.uint8)
18.
```

c. Opening

Description: First use erosion, then use dilation.



- 1. def opening(img, kernel):
- return (dilation(erosion(img, kernel), kernel))

d. Closing

Description: First use dilation, then use erosion.



- def closing(img, kernel):
- return (erosion(dilation(img, kernel), kernel))