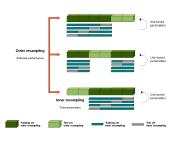
# **Introduction to Machine Learning**

# **Nested Resampling**



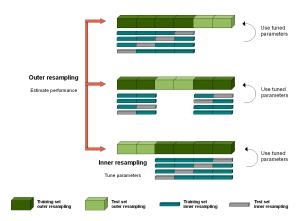
#### Learning goals

- Understand how the 3-way split of the data can be generalized to nested resampling
- Understand the goal of nested resampling
- Be able to explain how resampling allows to estimate the generalization error

Just like we can generalize hold-out splitting to resampling to get more reliable estimates of the predictive performance, we can generalize the training/validation/test approach to **nested resampling**.

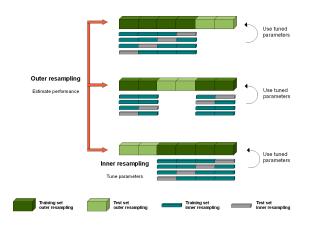
This results in two nested resampling loops, i.e., resampling strategies for both tuning and outer evaluation.

Assume we want to tune over a set of candidate HP configurations  $\lambda_i$ ;  $i=1,\ldots$  with 4-fold CV in the inner resampling and 3-fold CV in the outer loop. The outer loop is visualized as the light green and dark green parts.



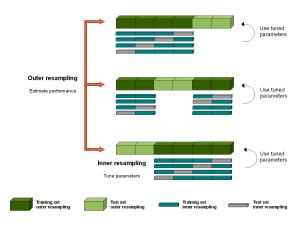
In each iteration of the outer loop we:

- Split off the light green testing data
- Run the tuner on the dark green part of the data, e.g., evaluate each  $\lambda_i$  through fourfold CV on the dark green part

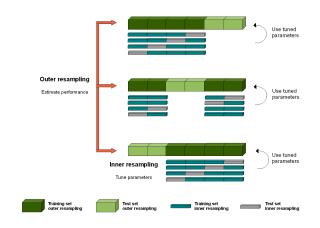


In each iteration of the outer loop we:

- Return the winning  $\lambda^*$  that performed best on the grey inner test sets
- Re-train the model on the full outer dark green train set
- Evaluate it on the outer light green test set



The error estimates on the outer samples (light green) are unbiased because this data was strictly excluded from the model-building process of the model that was tested on.



## **NESTED RESAMPLING - INSTRUCTIVE EXAMPLE**

Taking again a look at the motivating example and adding a nested resampling outer loop, we get the expected behavior:

