

## APPENDIX TO EXERCISE 1 CONTROLLING AN LED ON THE ZEDBOARD

This is an extension of Exercise 1. In this second part, we will use the Zedboard to execute the driver code. The board has eight switches, which we will use for the eight inputs, and has eight LEDs that we can use as outputs.

The mapping of signals to hardware in the Zedboard is made through a constraint file. You can find a sample file in this link:

https://github.com/Digilent/Zedboard-old/blob/master/Resources/XDC/zedboard\_master.xdc

Also, remember to install the board drivers so that you can choose the Zedboard when creating a project. Follow the instructions here:

https://reference.digilentinc.com/reference/software/vivado/board-files

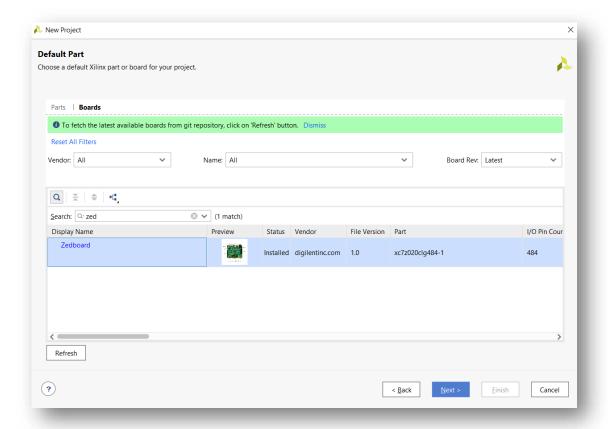
The rest of the document contains an example that shows how to get input from the eight switches in the Zedboard and control its LEDs using VHDL code. You can **use this example as a base to write your own code and implement Exercise 1** using switches as inputs.

For colors that are represented by RGB values different than 0 or 255, you will need to **use pulse width modulation** to emulate an intermediate value. To do that, create a new top module that maps the three outputs of your driver (which take values from 0 to 255) into a squared signal with the corresponding duty cycle.



In this example, we will show how to connect the 8 switches in the Zedboard to control the LEDs and also control some of the JA1 pin outputs.. Follow these steps:

✓ Create a new project, and choose Zedboard as the default Xilinx board





✓ Create a new source file, top.vhdl. Using the same names as in the constraint file, we will declare the inputs and outputs which will be automatically mapped to the hardware based on the constraint file:

```
21 | library IEEE;
22 use IEEE.STD LOGIC 1164.ALL;
23
24 🖯 entity top is
25 🖯
     Port (SW0 : in STD_LOGIC;
26
              SW1 : in STD LOGIC;
             SW2 : in STD LOGIC;
28
             SW3 : in STD_LOGIC;
29
              SW4 : in STD LOGIC;
30
              SW5 : in STD LOGIC;
31
             SW6 : in STD LOGIC;
32
             SW7 : in STD LOGIC;
33
34
              LDO : out STD LOGIC;
             LD1 : out STD_LOGIC;
35
             LD2 : out STD LOGIC;
36
37
             LD3 : out STD_LOGIC;
38
              LD4 : out STD LOGIC;
39
              LD5 : out STD LOGIC;
             LD6 : out STD_LOGIC;
4.0
41
             LD7 : out STD LOGIC;
42
43
              JA1 : out STD LOGIC;
44
              JA2 : out STD_LOGIC;
              JA3 : out STD LOGIC);
45 A
```

✓ Write a simple architecture

```
57 🖨 architecture Behavioral of top is
58
59 begin
60 LD0 <= SW0;
61
      LD1 <= SW0 AND SW1;
62
      LD2 <= SW1 AND SW2;
       LD3 <= SW2 AND SW3;
63
64
65
       LD7 <= SW7;
66
       LD6 <= SW6 OR SW5;
67
       LD5 <= SW5 OR SW6 OR SW7;
       LD4 <= SW4 OR SW5 OR SW6;
70
       JA1 <= SW0;
71
       JA2 <= SW1;
72
       JA3 <= SW2;
73
74 🖒 end Behavioral;
```

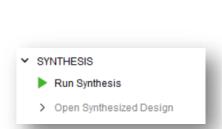


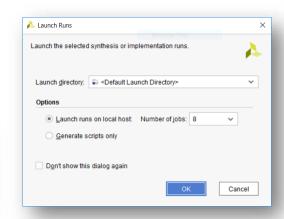
✓ Create a new constraint file. Paste the content from the sample you downloaded earlier and uncomment the lines mapping the eight switches, eight LEDs and the RGB LED 5.

✓ Run Synthesis. The higher the number of jobs, the faster *Vivado* will synthesize your design.

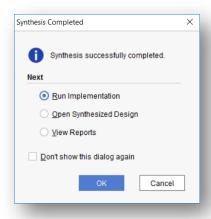




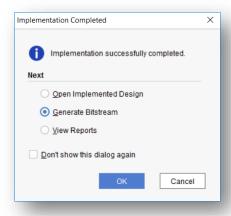




✓ Run implementation. Again, choose the highest number of jobs.



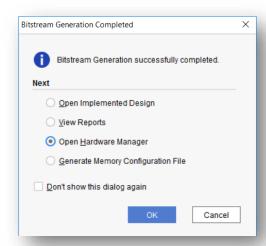
✓ Choose Generate Bitstream.



- ✓ Connect the Zedboard. First, make sure the switch is set to OFF. Then connect the power supply and the USB cable to the PROG port. Turn on the board.
- ✓ Open *Hardware Manager*.







✓ On the top of the window, choose **Open target**. Click in *Auto Connect*.



✓ Finally, click on *Program device*.



At this point, you should be able to control the LEDs with the switches and also the RGB LED if you connect it to the corresponding JA1 pins.