

## 6. Root finding

## Summary of last lecture

- Taylor series
- Taylor polynomials + Lagrange remainder
- Solving equations as root finding
- Roots of polynomials: Fundamental Theorem of Algebra

## Goals for today

- Iterative algorithms
- Root-finding algorithms using iteration

## Root finding as a problem

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- Suppose we want to solve the problem  $y = \mathcal{F}(\mathcal{X})$
- Input  $\mathcal{X} = f$  – a function
- Problem  $\mathcal{F} =$  “calculate a root”
- Output  $y =$  position  $x^*$  of the root

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- Some algorithms can *refine* an approximation to give a *better* approximation



# Collaboration I

## Cosine-ing

- 1 Open the scientific calculator app on your computer (or online) and make sure it is in “radians” mode
- 2 Start with an initial value and keep hitting the “cosine” key.
- 3 What happens after you do this many times?
- 4 Write down a formula that describes the *process*.
- 5 What is the *end result* of the process? Can you write down a formula for it?
- 6 How could we generalise this?

## Visualising the cosine iteration

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$$x^* = \cos(x^*)$$

- So  $x^*$  *is a solution* of the transcendental equation

$$\cos(x) = x$$

- The iteration gives an approximation algorithm to calculate  $x^*$  as closely as we want!

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- How fast is the convergence?
  - I.e. how does  $|x_n - x^*|$  depend on  $n$ ?
- To solve  $h(x) = 0$ , how should we choose  $g$ ?

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- We say that  $x^*$  is a **fixed point** of  $g$
- Hence it solve  $f(x) := g(x) - x = 0$

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- $g$  is called a **contraction mapping**

- Since it contracts distances:  $|g(x) - g(y)| \leq k|x - y|$

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## Iterations as dynamical systems

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- By introducing a **fictitious** (discrete) time  $n$
- This is a common trick
  - e.g. Markov chains, elliptic PDEs



# Collaboration II

## Convergence

Suppose that  $x_0$  is *close* to  $x^*$ . How does the iteration  $x_{n+1} = g(x_n)$  behave?

- 1 Define the distance  $\delta_n := x_n - x^*$
- 2 Can you find the approximate dynamics of  $\delta$ ?
- 3 When will the dynamics converge to the fixed point?

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- We have

$$\begin{aligned}\delta_{n+1} &= x_{n+1} - x^* \\ &= g(x_n) - x^* \\ &= g(x^* + \delta_n) - x^* \\ &\simeq \delta_n g'(x^*)\end{aligned}$$

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- $\delta_n$  **decays** if  $|\alpha| < 1$  – **stable** fixed point
- $\delta_n$  **grows** if  $|\alpha| > 1$  – **unstable** fixed point

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- The fixed-point iteration *solves an equation*
  - It is an *approximation algorithm* for solving that equation!
  - What does the speed of convergence mean?
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- The speed of convergence tells us **how good the approximation algorithm is**
  - If we can find a different algorithm which *converges faster*, we will need to do *less work* to solve the problem

## Collaboration III

### Designing fixed-point iterations

Let's try to solve the equation  $x^2 - x + 1 = 0$  using fixed-point iteration.

- 1 Can you come up with a fixed-point iteration that does this?
- 2 Which root does it find?
- 3 Can you find the other one?

# Summary

- Iterations *may* converge
- If they converge, they converge to a **fixed point**
- Fixed points solve equations
  
- We can calculate a **convergence rate** to the fixed point
- This tells us **how good** the algorithm is