

Lab 24, network, part 1

By ADMIN | Published: FEBRUARY 9, 2014

This lab will be short; we will add all network modules needed for network layout and make a roadmap how to make the Raspberry Pi ethernet driver.

First have a look at other ports and inferno and find what is needed to compile with network support.

1. dev section needs:

```
1 + ip ip ipv6 ipaux iproute arp netlog ptclbsum iprouter plan9
  nullmedium pktmedium netaux
2 + ether netif netaux
```

2. add ip section

```
1 +ip
2 + il
3 + tcp
4 + udp
5 + ipifc
6 + icmp
7 + icmp6
```

3. mod section needs:

```
1 + crypt
2 + ipints
```

Then we will add etherusb.c from 9pi project (according to 9pi: it takes over the job of copying packets between the usb pipe and the kernel ether i/o queues, to save the extra overhead of doing it in user mode in the usb/ether driver.) Later we may not need it, but for now take it just to have complete compilation.

Then link section:

```
1 link
2 usbdwc
3 + etherusb
4 + ethermedium
5 + loopbackmedium
```

In archpi.c we will add ethernet initialization:

```
01 #include "dat.h"
02 #include "fns.h"
03
04 #include "../port/netif.h"
05 #include "etherif.h"
06 +
07 static void
08 linkproc(void)
09 {
10 ...
11 void
12 validaddr(void*, ulong, int) {}
13
14 +int
```

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```

15 +archether(unsigned ctrlrno, Ether *ether)
16 +{
17 +    switch(ctrlrno) {
18 +    case 0:
19 +        ether->type = "usb";
20 +        ether->ctrlrno = ctrlrno;
21 +        ether->irq = -1;
22 +        ether->nopt = 0;
23 +        ether->mbps = 100;
24 +        return 1;
25 +    }
26 +    return -1;
27 +}
28 +
29 +/*
30 + * stub for ../omap/devether.c
31 + */
32 +int
33 +isaconfig(char *class, int ctrlrno, ISAConf *isa)
34 +{
35 +    USED(ctrlrno);
36 +    USED(isa);
37 +    return strcmp(class, "ether") == 0;
38 +}

```

That’s enough for now. We can compile everything, we will have appropriate modules, but no ethernet driver yet.

As next actions I see two ways of implementing/porting it.

1. Raspberry Pi Usb driver for Plan9 written in C to be ported to Limbo
2. Raspberry Pi Usb driver for Plan9 written in C just used as some fileserver which is initialized from Usb Limbo layout (which /dev/usb files to use to read/write, etc)

CHANGES:

[Revision on code.google.com](#)

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