



Simple Quick Dirty Collision Detection

For Beginners

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2D Collision Detection

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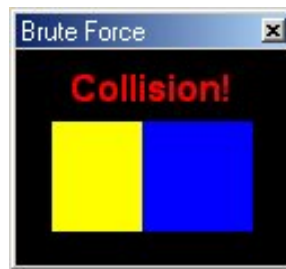
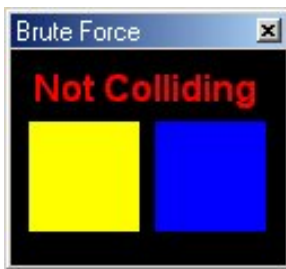
2D Collision Detection Methods

There are many types of 2D-collision detection that can be done. Such methods include brute force, bit array, bounding sphere, bounding box, axis sorting, tile based, sprite bounds, grid, and static. As you can see there are many different types of 2D-collision detection “styles,” but for the sake of this article we will deal with brute force and bounding sphere. Brute force, bit array, and tile based are usually the most common. Lets deal with brute force first. The Bounding Box and Axis Sorting is almost identical to the brute force.

Brute Force Collision Detection

In Visual Basic a brute force algorithm is as simple as the following. This algorithm is self-explanatory, it simply just checks the bounds of both Sprites.

Note: For simplicity, we will use picture box's.



Function:

```
Public Function Check_Collision_BF(Sprite1 As PictureBox, Sprite2 As PictureBox) As Boolean
```

```
    If Sprite1.Left > Sprite2.Left + Sprite2.Width Or _  
        Sprite1.Left + Sprite1.Width < Sprite2.Left Or _  
        Sprite1.Top > Sprite2.Top + Sprite2.Height Or _  
        Sprite1.Top + Sprite1.Height < Sprite2.Top Then
```

```
        Check_Collision_BF = False
```

```
    Else
```

```
        Check_Collision_BF = True
```

```
    End If
```

```
End Function
```

How to Use:

```
If Check_Collision_BF(pic2DColl(0), pic2DColl(1)) = True Then
```

```
    Label1.Caption = "Collision!"
```

```
Else
```

```
    Label1.Caption = "Not Colliding"
```

```
End If
```

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Bounding Sphere Collision Detection



My personal opinion (*if it accounts for anything*) is that bounding spheres is far more easily to compute than anything. Its so simple its child's play, but people hear "bounding volumes" or "bounding sphere" and read a text book and it says something like " $(X^2 + X^2) - (Y^2 + Y^2)$ " and freak out. It's nothing like that. There is actually two ways of doing this and I'll show you both. One way is to figure (Sprite1.Pos = Sprite2.Pos - Radius) or use the positions and two radii. Sounds complicated, but like I said, it is simple. Here is example one.

Function 1 – Position, Position, Radii:

Public Function SphereCollision_2D1(X1 **As Single**, Y1 **As Single**, X2 **As Single**, Y2 **As Single**, Radius **As Single**) **As Boolean**

```
If X1 > X2 - Radius And X1 < X2 + Radius And _  
    Y1 > Y2 - Radius And Y1 < Y2 + Radius Then  
    SphereCollision_2D1 = True  
Else  
    SphereCollision_2D1 = False  
End If
```

End Function

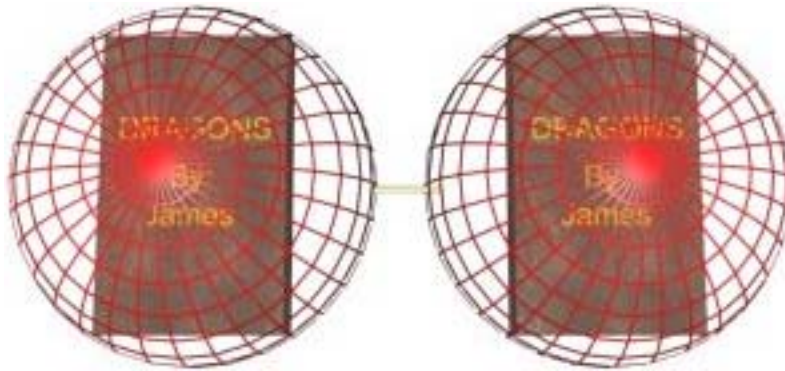
How to Use:

```
If SphereCollision_2D1 (pic2DColl(0).Left, pic2DColl(0).Top, pic2DColl(1).Left,  
pic2DColl(1).Top, 3) = True Then  
    Label1.Caption = "Collision!"  
Else  
    Label1.Caption = "Not Colliding"  
End If
```

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Function 2 – Position, Position, Radii, Radii:

Function 2 is pretty much does the same thing but it uses actual Distance to calculate the outcome. It takes the radius of both sprites then tests the distance between the “spheres”(radii).



```
Public Function SphereCollision_2D2(X1 As Single, Y1 As Single, X2 As Single, Y2 As Single,  
Radius1 As Single, Radius2 As Single) As Boolean
```

```
    Dim Dist As Single
```

```
    Dist = Radius1 + Radius2
```

```
    If ((Sqr(((X1 - X2) * (X1 - X2)) + _  
              ((Y1 - Y2) * (Y1 - Y2)))) < Dist) Then
```

```
        SphereCollision_2D2 = True
```

```
    Else
```

```
        SphereCollision_2D2 = False
```

```
    End If
```

```
End Function
```

How to Use:

```
    If SphereCollision_2D2 (pic2DColl(0).Left, pic2DColl(0).Top, pic2DColl(1).Left,  
pic2DColl(1).Top, 3, 3) = True Then
```

```
        Label1.Caption = "Collision!"
```

```
    Else
```

```
        Label1.Caption = "Not Colliding"
```

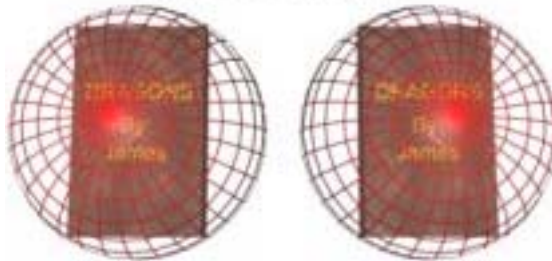
```
    End If
```

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Uses For – Position, Position, Radii, Radii

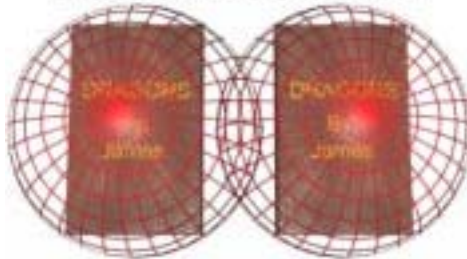
This method is good to detect collisions more accurately. Method one is decent but it can miss detections. If you want accuracy use method two with the following explanation.

No Collision



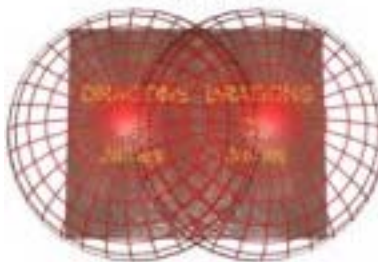
Here we can see clearly that there is no collision what so ever. Therefore, there is no need to check for collisions.

Possible Collision



Here the two bounding spheres are colliding, so we start checking for collisions between the books.

Collision



Here the two books are definitely colliding.

This method saves a lot of processing power because you're not checking for collisions at each frame, only the bounding spheres which do not take that much to compute. So you have two choices, the one described that checks collision with the books or you can simply check collisions with the spheres.

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So What About 3D Collision Detection?

3D-collision detection works the same as the two 2D bounding sphere examples I explained. All you need to do is add the (z) coordinates, not to hard.

Look at the 2D Demo and look at the comment. I added 3D Collision Detection to give you an example.

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**Thank you,
-James-**

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