

**BIRLA INSTITUTE OF TECHNOLOGY AND SCIENCE, PILANI**

**INSTRUCTION DIVISION**

**SECOND SEMESTER 2015-2016**

**Course Handout (Part II)**

Date: 13/01/2016

In addition to part-I (General Handout for all courses appended to the time table) this portion gives further specific details regarding the course.

**Course No.** : CHE F342  
**Course Title** : Process Dynamics and Control  
**Instructor-in-charge** : HARE KRISHNA MOHANTA  
**Instructor (Tut/Prac)** : Pradipta Chattopadhyay, Srinivas Appari

**Course Description:**

Dynamic modeling and simulation of momentum, energy, mass transfer and reacting systems; analysis of the dynamic behaviour of lumped and distributed parameter systems; analysis and design of simple feedback and advanced control systems; design of control systems with multiple input and multiple output; introduction to computer control.

**Scope and Objective of the course:**

This course deals with the design of the control systems for chemical processes, not as a mathematical problem, but as an engineering task with all its attractive challenges and practical shortcomings using the fundamental concepts of process dynamics as the basis. The course aims to help the student in the selection of the best among the several alternative control configurations usually possible for a given processing unit or a complete plant. Finally the course will familiarize the student with a plethora of analytical tools and design methodologies to be understood before attempting the process control problems.

**Text Book:**

Seborg, D. E., Edgar, T. F. and Mellichamp, D.A., "Process Dynamics and Control", 3<sup>rd</sup> Ed., John Wiley and Sons, 2011.

**Reference Books:**

1. Coughanowr, D.R., Process Systems Analysis and Control, 2<sup>nd</sup> Ed., McGraw-Hill, 1991.
2. George Stephanopoulos, Chemical Process Control: An Introduction to Theory and Practice, Prentice Hall, 1984.

**Course Plan:**

| Lecture No. | Learning Objectives                        | Topics to be covered  | Ref. to T.B Chap. |
|-------------|--|---|-------------------|
| 1-2         | Introduction to process control            | Need of process control, process control strategies, process control activities   | 1                 |
| 3-5         | Theoretical models of chemical process     | Modeling principles, dynamic models, degrees of freedom analysis, solution of dynamic models  | 2                 |
| 6           | Laplace Transforms                         | Solution of differential equation   | App. A            |
| 7-9         | Transfer functions models                  | Development and properties of transfer functions, linearization of non-linear models, state-space and transfer function matrix models, use of MATLAB. | 3                 |
| 10-12       | Dynamic Behavior of First and second order | Response of first and second order processes, use of MATLAB.  | 4                 |

|                   |   |   |    |
|-------------------|---|---|----|
|                   | Processes   |   |    |
| 13-16             | Dynamics response characteristics of more complicated processes | Poles and Zeros and their effects, Effect of time delays, Dynamic response of higher order systems, use of MATLAB.                            | 5  |
| 17-20             | Feedback controllers  | Concept & type of feedback control, block diagram representation, response of PID controller, use of MATLAB.                                  | 7  |
| 21                | Control system instrumentation                                  | Transducers, transmitters, final control elements   | 8  |
| Mid-Semester Test |   |   |    |
| 22-25             | Process Safety and Process Control                              | Layers of protection, Alarm management, Abnormal event detection, Risk assessment.  | 9  |
| 26-27             | Dynamic behavior and stability of closed loop system            | Closed loop representation, transfer functions, stability analysis, use of MATLAB.  | 10 |
| 28-29             | PID controller design and tuning                                | Performance criterion, Model based design, controller tuning relations, Use of Simulink in controller tuning.                                 | 11 |
| 30-32             | Frequency response analysis and control system design           | Bode, Nyquist, Gain and Phase margin, closed-loop frequency response and sensitivity functions, use of MATLAB.                                | 13 |
| 33-35             | Feed forward and ratio control                                  | Ratio control, feed forward controller design based on steady state and dynamics equation, feed forward-feed-back controller, Use of Simulink | 14 |
| 36-39             | Enhanced single-loop control strategies                         | Cascade control, time-delay compensation, Inferential control, Override control, Nonlinear and adaptive control                               | 15 |
| 40-42             | Digital sampling, filtering and control                         | Signal processing, data filtering, tuning of digital PID controllers  | 17 |

#### Evaluation Schedule:

| Component                        | Duration (Minutes) | Weightage   | Date & Time             | Remarks |
|----------------------------------|--------------------|-------------|-------------------------|---------|
| Mid-Semester Test                | 90                 | 95 (31.67%) | 16/3 9:00 - 10:30 AM    | CB+OB   |
| Tutorial Tests (best 7 out of 8) | 15-20              | 70 (23.33%) | During Tutorial Hour    | CB/OB   |
| Surprise Tests (3)               | During Class hour  | 15 (5%)     | Throughout the Semester | CB/OB   |
| Comprehensive Examination        | 180                | 120 (40%)   | 11/5 FN                 | CB+OB   |

**Chamber consultation hour:** To be announced in the class.

**Make-up Policy:** Make-up will be granted only for genuine cases.

**Notices:** All notices concerning this course will be displayed in the Chemical Engineering Notice Board and in the on-campus Learning Management System, <http://nalanda.bits-pilani.ac.in/>

Instructor-in-charge  
CHE F342