

# Introducing machine learning for high-performance scenario access and accurate EC control

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KSTAR Exp Briefing / Jan 7 202

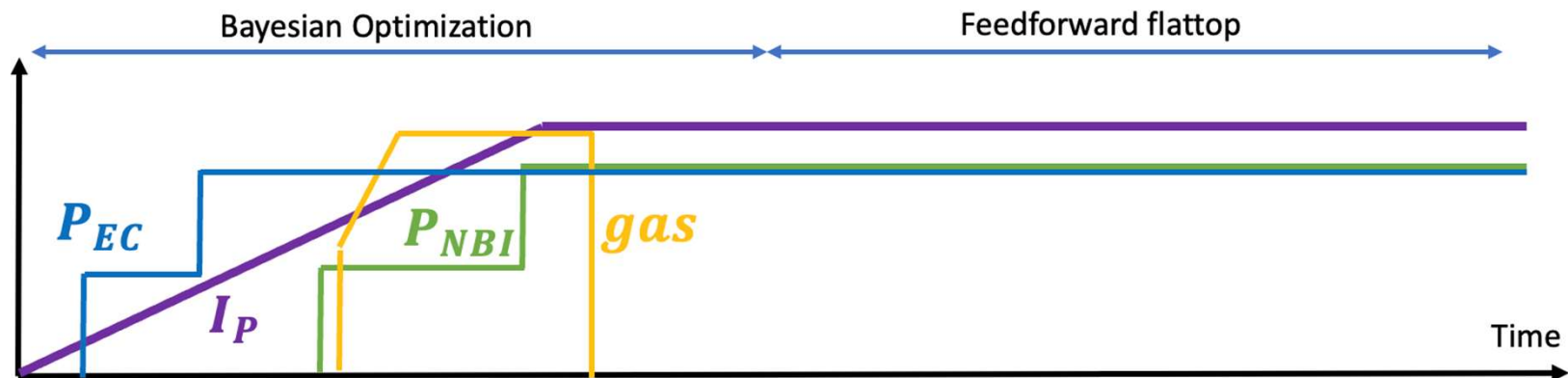


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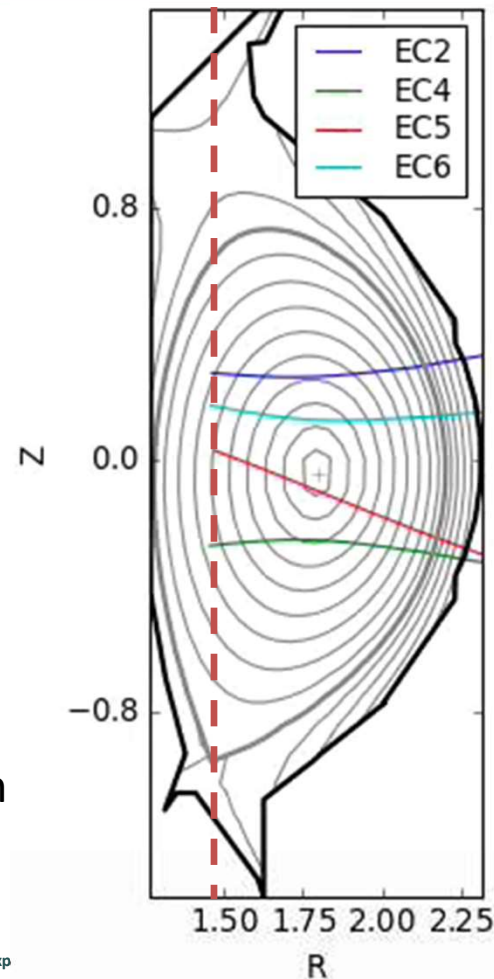
# Intershot Bayesian Optimization for developing high-performance KSTAR scenario

- Goal of maximize performance ( $\beta_N$ ) in the flattop of the shot
- Use historical KSTAR data to pretrain models, then update model based on results during experiment
- Adjust  $I_P$ ,  $P_{NBI}$ ,  $P_{EC}$ , gas feedforward waveforms between shots according to ML optimization
  - Do more exploration in early shots and focus in on high performance in later shots



# ML TORBEAM surrogate for feedback EC steering

- Accurate EC steering and control is desirable for variety of tasks:
  - NTM island suppression
  - ST control
  - Improved ELM suppression with edge ECCD
  - Impurity shielding effects
- Real-time TORBEAM code computationally expensive to run and can be inaccurate due to instability in rtEFITs
  - ML surrogate faster to run and more robust to numerical noise in real-time equilibria



## Torbeam-nn Inputs

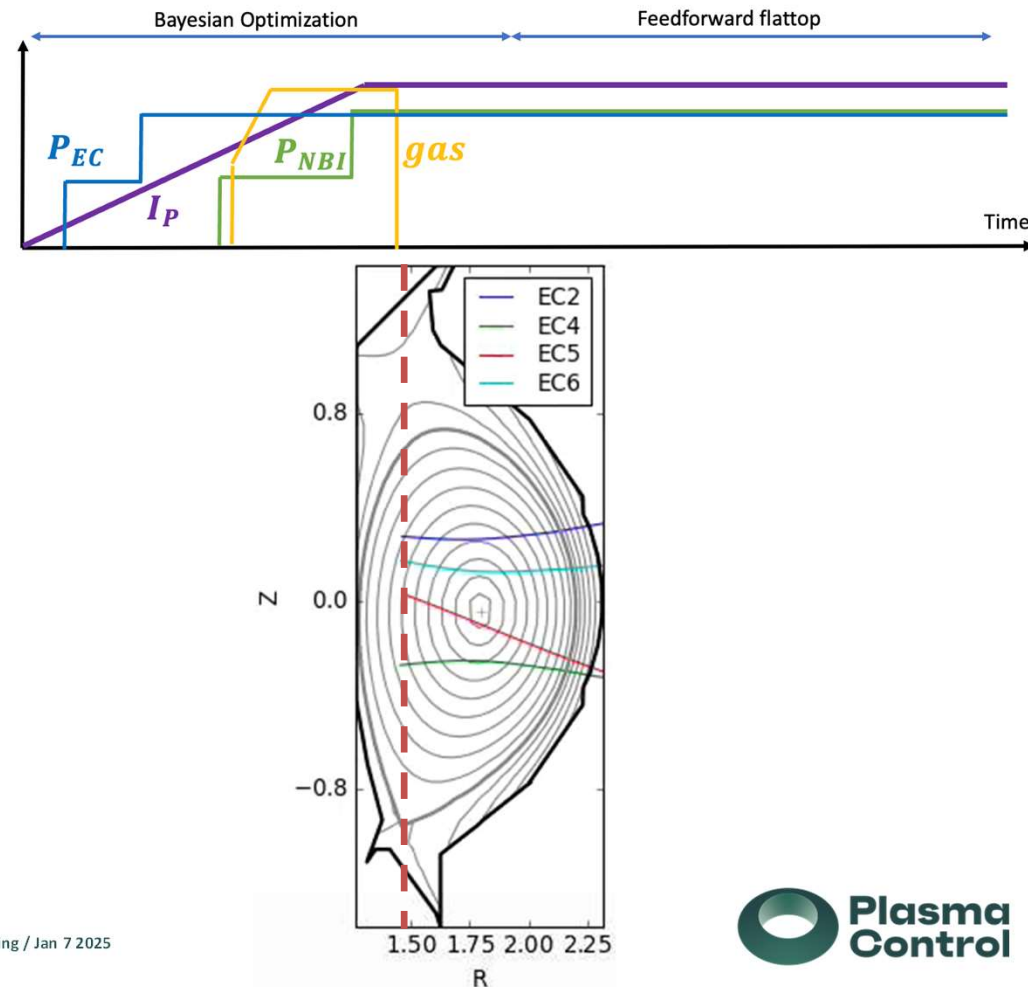
rtEFIT scalars

Real-time  $n_e$  profile - NERECON

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# Shot Plan (13-20 shots)

1. Stage 1: Restore H-mode reference (36497) (1-2 shots)
2. Stage 2: Bayesian optimization exploration (10-14 shots)
  - I. Start with larger exploration BO settings for BO of feedforward waveforms.
  - II. Commission feedback EC steering in flat-top.
    - I. Scan ECH Z positions to tune PID gains and assess accuracy of Torbeam-nn
3. Stage 3: Bayesian optimization high performance (2-4 shots)
  - I. Reduce exploration settings for BO to achieve high performance ramp-up scenario
  - II. If Torbeam-nn steering successful, add in scans over toroidal angles to validate tracking



# Hardware requirements and team

- $B_T$ : -1.9T
- $I_p$ : 0.5MA
- 5 NBI (all except NB2B)
- EC4 and EC5
  - Feedback mirror steering required
- Standard feedforward gas
  
- SL: Andy Rothstein
- CPO: Sanghee Lee
- ECH aimer: Minho Woo
- BO task coordinator: Minseok Kim
- PID tuning coordinator: Cheolsik Byun