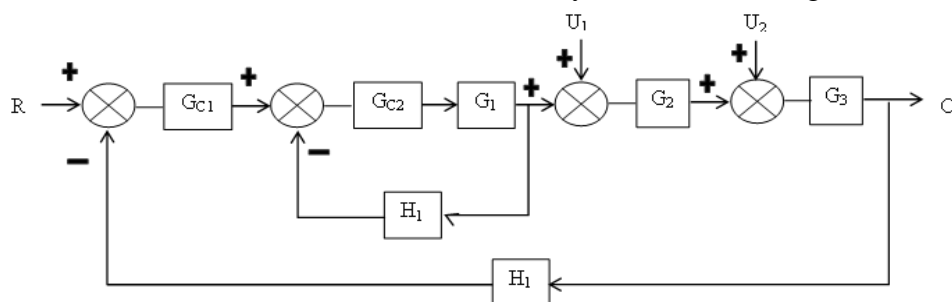


GUJARAT TECHNOLOGICAL UNIVERSITY**BE- SEMESTER-V (NEW) EXAMINATION – WINTER 2020****Subject Code:3150504****Date:29/01/2021****Subject Name:Instrumentation and Process Control****Time:10:30 AM TO 12:30 PM****Total Marks: 56****Instructions:**

1. Attempt any FOUR questions out of EIGHT questions.
2. Make suitable assumptions wherever necessary.
3. Figures to the right indicate full marks.

- | | Marks |
|---|--------------|
| Q.1 (a) Give the Theoretical value of time constant of the following first order systems: | 03 |
| 1. Mercury thermometer
2. Mixing process
3. Liquid level single tank system | |
| (b) Determine $f(t)$ for $f(s) = 1/[s^2(s + 1)]$ | 04 |
| (c) A square storage tank contains a liquid which is pumped by a centrifugal pump at a steady rate. Liquid enters the tank at a volumetric flow rate 200 Liter Per Hour and liquid level reaches steady-state value of 40 cm. if input flow rate is suddenly increased to 300 Liter Per Hour. Find the level response and Height of Liquid after 1 min.(Cross Section Area of tank is 15 centimeter x 15 centimeter) | 07 |
| Q.2 (a) Give the Laplace transform of the following | 03 |
| 1. $\cosh kt u(t)$
2. $\sin kt u(t)$
3. $t^n u(t)$ | |
| (b) Derive the Laplace transforms of Step and Sine forcing function. | 04 |
| (c) Prove that Response of Non-interacting tanks always result in an overdamped or critically damped second order system and never in an underdamped. | 07 |
| Q.3 (a) What is difference between Open-loop and Close-loop control system? | 03 |
| (b) Explain the following for underdamped response of second order system. | 04 |
| 1. Overshoot
2. Decay Ratio
3. Rise Time
4. Response Time | |
| (c) Determine the transfer function C/R for the system shown in Figure. | 07 |



- Q.4** (a) Discuss the special case application of proportional control in ON-OFF control system. **03**
- (b) What is Regulator-type problem in control system? Explain with example. **04**
- (c) The characteristic equation of control system is given as following. **07**
 $S^3 + 6s^2 + 11s + 6(1 + K_c) = 0$
Determine:
1. The Value of K_c for which the control system is stable.
2. The roots of the characteristic equation for the value of K_c for which the system is on the threshold of instability.
- Q.5** (a) Discuss the various components of a control system with example. **03**
- (b) Explain advantages and disadvantages of Distributed Control System. **04**
- (c) Discuss the rules for plotting Root-Locus Diagram for Negative Feedback control system. **07**
- Q.6** (a) What is difference between P and PID control? **03**
- (b) Explain the Routh theorems for stability test of control system. **04**
- (c) Explain the Ziegler-Nichols Controller rule for setting of parameter in P, PI, and PID feedback control system. **07**
- Q.7** (a) List various static characteristics of instruments and discuss any one in details **03**
- (b) What is difference in working between radiation pyrometer and optical pyrometer? **04**
- (c) List the various instruments used for measurement of vacuum. Explain construction and working of McLeod gage. **07**
- Q.8** (a) Explain SCADA system. **03**
- (b) List the various instrument used for measurement of humidity. Explain working of wet bulb and dry bulb thermometer used for measurement of relative humidity. **04**
- (c) Explain the construction, working and application of Magnetic float gauge. **07**

GUJARAT TECHNOLOGICAL UNIVERSITY**BE - SEMESTER-V (NEW) EXAMINATION – WINTER 2021****Subject Code:3150504****Date:17/12/2021****Subject Name:Instrumentation and Process Control****Time:02:30 PM TO 05:00 PM****Total Marks: 70****Instructions:**

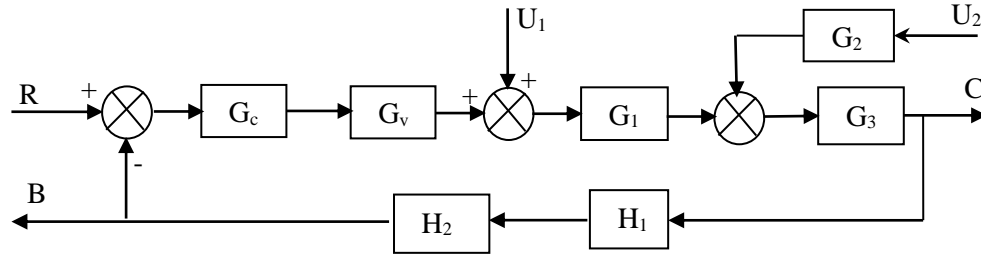
1. Attempt all questions.
2. Make suitable assumptions wherever necessary.
3. Figures to the right indicate full marks.
4. Simple and non-programmable scientific calculators are allowed.

MARKS

- Q.1 (a)** Give resistance capacitance lag for following systems. **03**
 (1) Liquid filled thermometer
 (2) Liquid level in a tank
 (3) Mixing tank
- (b)** Give Laplace transform for following. **04**
 (1) $\cos kt$
 (2) $\sin h kt$
 (3) $t e^{-at}$
 (4) t^n
- (c)** Solve this differential equation using Laplace transform **07**

$$\frac{d^3x}{dt^3} + 3 \frac{d^2x}{dt^2} + 3 \frac{dx}{dt} + x = 1$$
 Given that $x(0) = x'(0) = x''(0) = 0$
- Q.2 (a)** Describe how damping coefficient is important for deciding nature of response of a second order system. **03**
- (b)** Define following terms for under damping second order system **04**
 (1) Overshoot
 (2) Decay Ratio
 (3) Rise time
 (4) Response time
- (c)** Derive the equation for overshoot. **07**
- OR**
- (c)** A thermometer having first order dynamics with the time constant of 1 min. is placed in a temperature bath of 100° C. After it reaches steady state, it is suddenly placed in the temperature bath of 110° C at $t=0$ and left there for 1 min. and then it is immediately returned to the bath of 100° C. (i) Identify the type of forcing function. (ii) Obtain response of thermometer reading as a function of time. **07**
- Q. 3 (a)** Draw the block diagram for closed loop negative feedback control system and identify each of the components. **03**
- (b)** Differentiate between Regulator control and Servo control with their area of applications. **04**
- (c)** Derive the equation of transfer function and prove that liquid filled thermometer is a first order system. **07**
- OR**
- Q. 3 (a)** What is off set? Why it cannot be eliminated when P-controller is used? **03**

- (b) For the close loop control system diagram shown below, write the transfer functions for (1) C/R (2) C/U₁ (3) B/U₁ (4) B/R 04



- (c) Explain proportional band for a proportional controller with this numerical example. Proportional controller is used to control temperature within the range of 60 to 100 °F. The controller is adjusted so that the output pressure goes from 3 psi to 15 psi, as measured temperature goes from 71°F to 75 °F with the set point held constant. Find the gain and the proportional band. 07
- Q.4** (a) Explain Seeback effect of thermocouple. 03
- (b) Giving example of stirred tank heater system, explain the terms (i) Controlled variable (ii) Load Variable (iii) Set point (iv) Manipulated variable 04
- (c) Explain principle, construction and working of an optical pyrometer for temperature measurement. 07
- OR**
- Q.4** (a) Explain basic concept of SCADA system and its area of application. 03
- (b) Differentiate between ‘air to open’ and ‘air to close’ type of pneumatic control valves. Give your suggestions about which type of valve will be more suitable following systems. 04
- (1) Control valve fitted with steam inlet to an evaporator unit,
(2) Control valve fitted with cooling water inlet line to a condenser unit.
- (c) For the given characteristic equation of control system determine the value of k or which the control system is marginally stable. 07

$$s^3 + 4s^2 + 5s + 2 + 2k = 0$$

- Q.5** (a) Classify the pressure measuring instruments. 03
- (b) List the various instrument used for measurement of humidity. Explain working of wet bulb and dry bulb thermometer used for measurement of relative humidity. 04
- (c) Explain Burdon pressure gauge for pressure measurement with neat sketch. 07

OR

- Q.5** (a) List various direct methods for level measurement. 03
- (b) Explain static characteristics of an instrument in brief. 04
- (c) Explain the construction, working and application of Magnetic float gauge. 07

Seat No.: _____

Enrolment No. _____

GUJARAT TECHNOLOGICAL UNIVERSITY

BE - SEMESTER-V (NEW) EXAMINATION – SUMMER 2021

Subject Code:3150504

Date:05/10/2021

Subject Name:Instrumentation and Process Control

Time:10:30 AM TO 01:00 PM

Total Marks:70

Instructions:

1. Attempt all questions.
2. Make suitable assumptions wherever necessary.
3. Figures to the right indicate full marks.
4. Simple and non-programmable scientific calculators are allowed.

- Q-1** (a) What is stability? State bode stability criterion. **03**
(b) Derive the transfer function of PID controller. **04**
(c) Solve the following differential equation by using Laplace: **07**

$$\frac{d^2x}{dt^2} + 2\frac{dx}{dt} + 2x = 2 \quad \text{where } x(0) = x'(0) = 0$$

- Q-2** (a) Give full names for PLC, DCS, and SCADA. **03**
(b) Differentiate feedback and feed forward control system. **04**
(c) Derive the transfer function for mixing process as first order system. Also derive the step response. **07**

OR

- (c) Transfer function for the system is: **07**

$$G(s) = \frac{K_c}{(s+1)(s/2+1)(s/3+1)}$$

Determine the values of K_c for which the system is stable.

- Q-3** (a) The transfer function for thermometer is **03**

$$G(s) = \frac{1}{0.1s + 1}$$

The frequency of the bath-temperature variation is given as $10/\pi$ cycles/min. Find the frequency response

- (b) Explain Unit pulse input function. Derive its Laplace transform. **04**
(c) Explain with schematic the working of control valve and also discuss the transfer function of control valve. **07**

OR

- Q-3** (a) State and prove initial value theorem. **03**
(b) Define: 1. Manipulated Variable 2. Time constant 3. Overshoot 4. Transfer function. **04**
(c) For two tanks in series (Interacting manner), Derive the transfer function relating height liquid in second tank and input flow at tank 1. **07**

- Q-4** (a) Discuss servo and regulator problem. **03**
(b) Discuss in brief the characteristics of second order underdamped system. **04**
(c) Write a short note on PI controller. **07**

OR

- Q-4** (a) Give the classification of various methods for level measurement. **03**
(b) Explain the transportation lag and its transfer function. **04**

- (c) State various liquid column meters for pressure measurement. Explain inclined tube manometer with neat sketch. **07**
- Q-5** (a) State the various pressure measurement instruments. **03**
(b) Discuss the classification of flow meters. **04**
(c) Explain construction, working and principle of Rotameter with sketch **07**
- OR**
- Q-5** (a) Explain the static characteristics of instruments. **03**
(b) Discuss any one pyrometer in brief. **04**
(c) Describe the principle, construction and working of thermocouple used for temperature measurement. **07**

GUJARAT TECHNOLOGICAL UNIVERSITY**BE - SEMESTER-V(NEW) EXAMINATION – SUMMER 2022****Subject Code:3150504****Date:07/06/2022****Subject Name:Instrumentation and Process Control****Time:02:30 PM TO 05:00 PM****Total Marks: 70****Instructions:**

1. Attempt all questions.
2. Make suitable assumptions wherever necessary.
3. Figures to the right indicate full marks.
4. Simple and non-programmable scientific calculators are allowed.

MARKS

- Q.1**
- | | | |
|-----|--|-----------|
| (a) | Define step and input function. | 03 |
| (b) | Find the Laplace transform of $f(t) = 1$ & $f(t) = t$ | 04 |
| (c) | Derive the transfer function of mercury thermometer. Determine the response equation of mercury thermometer for step function. | 07 |

- Q.2**
- | | | |
|-----|---|-----------|
| (a) | Solve $\frac{dx}{dt} + 3x = 0, x(0) = 2$ | 03 |
| (b) | Derive the transfer function for Interacting system. | 04 |
| (c) | Solve the following differential equation by Laplace transform: | 07 |

$$\frac{d^3x}{dt^3} + 2\frac{d^2x}{dt^2} - \frac{dx}{dt} - 2x = 4 + e^{2t}$$

$$x(0) = 1, x'(0) = 0, x'' = -1$$

OR

- (c) Find the inverse Laplace Transform of the function:
- $$\bar{x}(s) = \frac{4s + 5}{(s-1)^2(s+2)}$$
- 07**

- Q.3**
- | | | |
|-----|--|-----------|
| (a) | Define dead zone and dead time lag | 03 |
| (b) | Explain Servomechanism type problem and Regulator problem | 04 |
| (c) | Define second order system. Derive the transfer function of U-Tube Manometer | 07 |

OR

- Q.3**
- | | | |
|-----|---|-----------|
| (a) | Derive transfer function for transportation lag. | 03 |
| (b) | Define: overshoot, decay ratio, response time and period of oscillations. | 04 |
| (c) | Write a note on Bellows differential pressure element with neat sketch. | 07 |

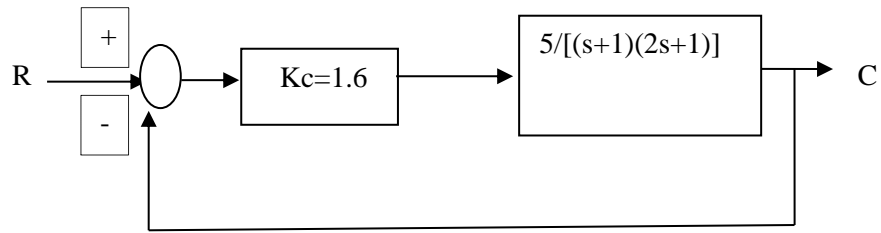
- Q.4**
- | | | |
|-----|--|-----------|
| (a) | Distinguish between Negative Feedback and Positive Feedback. | 03 |
| (b) | Describe the importance of root locus method in brief. | 04 |
| (c) | Discuss pressure spring thermometer with neat sketch. | 07 |

OR

- Q.4**
- | | | |
|-----|---|-----------|
| (a) | Highlight on hygrometer & hydrometer. | 03 |
| (b) | Differentiate between Open loop and closed loop control system. | 04 |
| (c) | Given the characteristic equation, determine the stability by the Routh criterion | 07 |
- $$s^4 + 3s^2 + 5s^2 + 4s + 2 = 0$$

- Q.5**
- | | | |
|-----|--|-----------|
| (a) | Describe PLC, DCS, and SCADA in brief. | 03 |
| (b) | Describe the bubbler system for liquid level measurement with neat sketch. | 04 |

- (c) The set point of the control system shown in figure below is given a step change of 0.1 unit. Determine: (a) The maximum value of C and (b) The offset. **07**



OR

- Q.5** (a) Write significance of gain margin and phase margin. **03**
 (b) What is offset? Explain P, PI and PID controller. **04**
 (c) Plot the bode diagram for the system whose overall transfer function is $1/(s+1)(s+5)$ **07**
