

Files in this folder

“StructureMessages-UDP_4010[2018].pdf”. It explains how the messages’ format is; for LIDAR and dead-reckoning.

File **“Example_Read_UDP.m”**: Basic example, for reading UDP messages. You need to improve it.

In folder **“Simulator_and_data[2018]”**

“PossumSimulator09_UDP.exe” : Simulator, for playing data back. Just run it when needed.

“simu_Possum_ViaUDP.cfg”: configuration file for simulator. Plain text file, use Notepad or similar editor/viewer to access it. Usually, you do not need to modify it.

Subfolder **“DataToPlay”**: for datasets (no need to touch it), except we provide additional datasets.

Questions: ask the lecturer (j.guivant@unsw.edu.au)