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## (a) Source codes:

```
Functions:
```

```
function rgb = hsi2rgb(hsi)
   %read hsi
   hsi = im2double(hsi);
   H = hsi(:, :, 1) * 2 * pi;
   S = hsi(:, :, 2);
   I = hsi(:, :, 3);
   R = zeros(size(hsi, 1), size(hsi, 2));
   G = zeros(size(hsi, 1), size(hsi, 2));
   B = zeros(size(hsi, 1), size(hsi, 2));
   % RG sector (0 <= H < 2*pi/3)
   idx = find( (0 \le H) & (H < 2*pi/3));
   B(idx) = I(idx) .* (1 - S(idx));
   R(idx) = I(idx) \cdot (1 + S(idx) \cdot cos(H(idx)) \cdot / \dots
   cos(pi/3 - H(idx)));
   G(idx) = 3*I(idx) - (R(idx) + B(idx));
   % BG sector (2*pi/3 <= H < 4*pi/3)
   idx = find((2*pi/3 \le H) \& (H < 4*pi/3));
   R(idx) = I(idx) .* (1 - S(idx));
   G(idx) = I(idx) .* (1 + S(idx) .* cos(H(idx) - 2*pi/3) ./ ...
   cos(pi - H(idx)));
   B(idx) = 3*I(idx) - (R(idx) + G(idx));
   % BR sector
   idx = find((4*pi/3 \le H) \& (H \le 2*pi));
   G(idx) = I(idx) \cdot (1 - S(idx));
   B(idx) = I(idx) .* (1 + S(idx) .* cos(H(idx) - 4*pi/3) ./ ...
   cos(5*pi/3 - H(idx)));
   R(idx) = 3*I(idx) - (G(idx) + B(idx));
   % output
   rgb = cat(3, R, G, B);
   rgb = max(min(rgb, 1), 0);
end
```

```
function hsi = rgb2hsi(rgb)
   %read image
   rgb = im2double(rgb);
   r = rgb(:, :, 1);
   g = rgb(:, :, 2);
   b = rgb(:, :, 3);
   % Implement the conversion equations.
   num = 0.5*((r - g) + (r - b));
   den = sqrt((r - g).^2 + (r - b).*(g - b));
   den(den == 0) = eps;
   theta = acos(num./(den));
   H = theta;
   H(b > g) = 2*pi - H(b > g);
   H = H/(2*pi);
   num = min(min(r, g), b);
   den = r + g + b;
   den(den == 0) = eps;
   S = 1 - 3.* \text{ num./den};
   H(S == 0) = 0;
   I = (r + g + b)/3;
   % Combine all three results into an hsi image.
   hsi = cat(3, H, S, I);
end
```

## Main Program

```
%% Clear the environment and the command line
clc;
close all;
clear;

%% read image
rose_img = imread('LovePeace rose.tif');
[m,n] = size(rose img);
```

```
%% Images of R, G, B
rose r = rose img(:,:,1);
rose g = rose img(:,:,2);
rose b = rose img(:,:,3);
%% Images of H,S,I
rose hsi = rgb2hsi(rose img);
rose h = uint8(255*mat2gray(abs(rose hsi(:,:,1))));
rose s = uint8(255*mat2gray(abs(rose hsi(:,:,2))));
rose i = uint8(255*mat2gray(abs(rose_hsi(:,:,3))));
%% RGB sharpening
laplacianKernel = [-1, -1, -1; -1, 8, -1; -1, -1, -1];
rose rgb lap = imfilter(double(rose img), laplacianKernel, "replicate");
rose rgb lap = uint8(255*mat2gray(abs(rose rgb lap)));
rose rgb sharpened = rose img + rose rgb lap;
%% HSI sharpening
laplacianKernel = [-1, -1, -1; -1, 8, -1; -1, -1, -1];
rose i lap = imfilter(double(rose i), laplacianKernel, "replicate");
rose i lap = uint8(255*mat2gray(abs(rose i lap)));
rose i sharpened = rose i + rose i lap;
rose hsi sharpened = cat(3, rose h, rose s, rose i);
rose hsi sharpened = hsi2rgb(rose hsi sharpened);
rose hsi sharpened = uint8(255*mat2gray(abs(rose hsi sharpened)));
%% Difference betewwn two image
rose diff = rose rgb sharpened - rose hsi sharpened + 255/2;
%% output
figure(1);
imshow(rose img,[]);
figure(2);
imshow(rose r,[]);
fig= qcf;
exportgraphics(fig, 'rose r.png', 'Resolution', 200);
figure(3);
imshow(rose g,[]);
fig= gcf;
exportgraphics(fig, 'rose g.png', 'Resolution', 200);
figure (4);
imshow(rose b,[]);
```

```
fig= gcf;
exportgraphics (fig, 'rose b.png', 'Resolution', 200);
figure(5);
imshow(rose h,[]);
fig= gcf;
exportgraphics(fig, 'rose h.png', 'Resolution', 200);
figure(6);
imshow(rose s,[]);
fig= gcf;
exportgraphics(fig, 'rose s.png', 'Resolution', 200);
figure(7);
imshow(rose i,[]);
fig= gcf;
exportgraphics(fig, 'rose i.png', 'Resolution', 200);
figure (9);
imshow(rose rgb sharpened,[]);
fig= gcf;
exportgraphics(fig, 'rose rgb sharpened.png', 'Resolution', 200);
figure(11);
imshow(rose i sharpened,[]);
fig= gcf;
exportgraphics(fig, 'rose i sharpened.png', 'Resolution', 200);
figure (12);
imshow(rose hsi sharpened,[]);
fig= gcf;
exportgraphics(fig, 'rose hsi sharpened.png', 'Resolution', 200);
figure(13);
imshow(rose diff,[]);
fig= gcf;
exportgraphics(fig, 'rose diff.png', 'Resolution', 200);
```







(c) Output images enhanced by RGB-sharpening and HSI-sharpening scheme:





(d) Difference image of two images obtained in (c):

