

I want to pursue a PhD and build robust visual odometries on mobile robots. I am interested in robotics, vision and learning, especially on low-specs machines. currently, I'm working with Professor Gregory Dudek, building single image depth estimation system. Previously, together with Professor Jianwei Lu and Laurent Itti, we built mobile robots with visual inertial SLAM system. I have two top-tier published conference papers and three pre-printed first author papers.

While working with Professor Gregory Dudek, our researches was  
as [1] einstein's famous paper goes, we are living in a fake world.

## References

- [1] Albert Einstein, Boris Podolsky, and Nathan Rosen. Can quantum-mechanical description of physical reality be considered complete? *Physical review*, 47(10):777, 1935.