

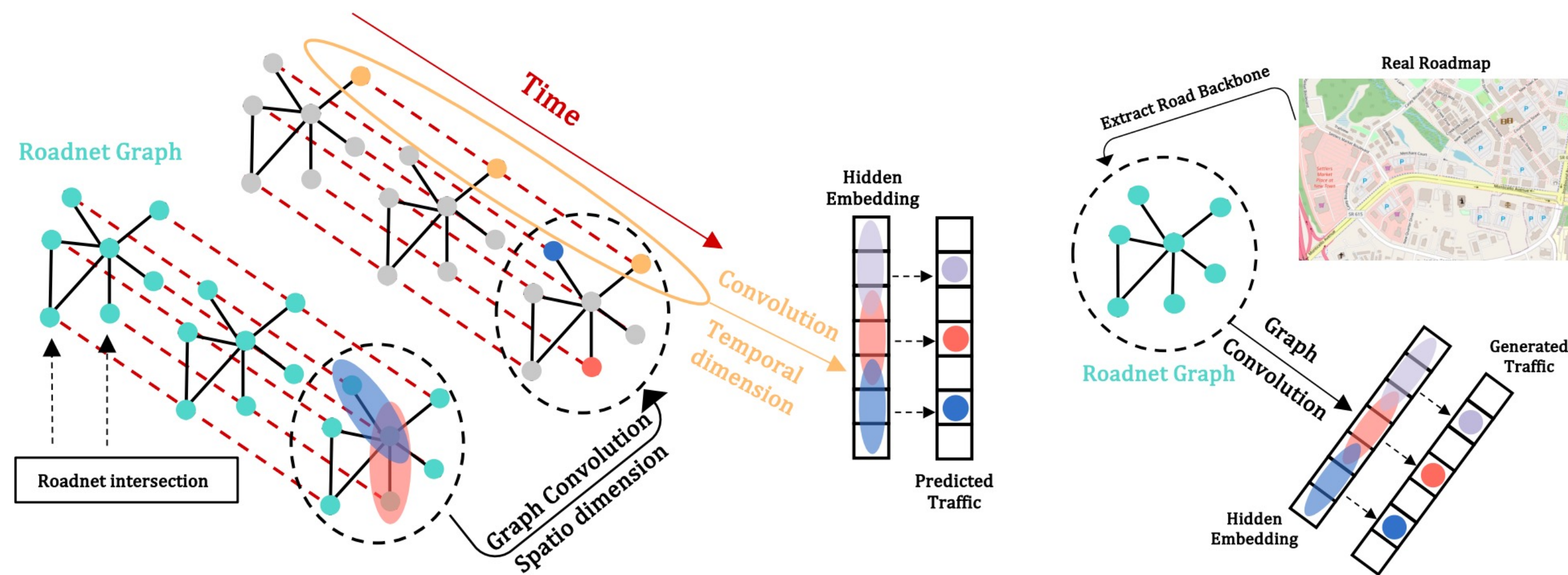
POI-based Traffic Generation via Supervised Contrastive Learning on Reconstructed Graph

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Motivation of Traffic Generation Problem

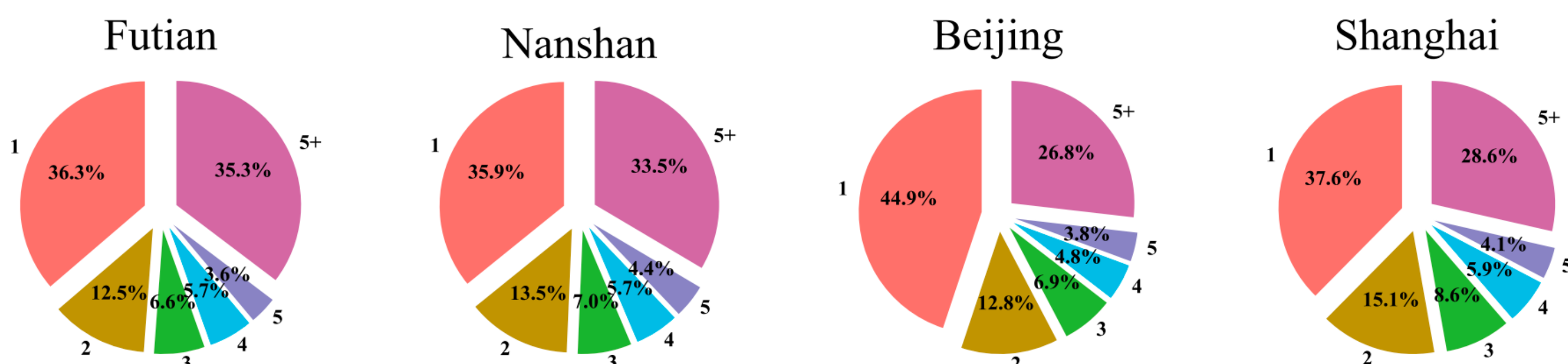
Conventional traffic prediction models are *contingent upon an expansive reservoir of historical traffic data* to enhance their predictive performance. However, *the acquisition of real-world traffic data*, particularly in smaller cities, is a big challenge.



Common frameworks of Traffic Prediction and Traffic Generation problems

Challenges

- Real-world road network graphs often *deviate from* the elemental principle that “*neighbor nodes exhibit similar features*”. Hop number of the shortest path between node pairs with nearest POI feature:



- Most previous models suffer from *the perceived inadequacy of end-to-end loss*.

Experiment Results

TG-SCR achieves the *best performance* on four real-world dataset.

Method	Futian			Nanshan		
	RMSE	MAE	MAPE	RMSE	MAE	MAPE
RF	64.28	52.83	35.13%	74.72	30.66	24.88%
XGBoost	76.13	62.01	36.37%	67.13	36.81	26.76%
SVR	262.91	157.56	64.06%	100.18	53.59	51.84%
GCN	173.57 ± 4.17	102.46 ± 2.61	49.76% ± 3.54%	92.57 ± 0.93	66.50 ± 0.43	25.38% ± 1.39%
GraphSAGE	102.64 ± 3.04	74.62 ± 2.56	42.94% ± 2.59%	90.18 ± 1.00	63.59 ± 0.46	24.73% ± 0.91%
GAT	92.47 ± 1.57	68.47 ± 0.47	39.83% ± 0.82%	71.48 ± 1.31	31.09 ± 0.55	21.41% ± 1.57%
GIN	79.33 ± 1.11	58.92 ± 0.54	40.97% ± 0.60%	65.25 ± 0.62	29.59 ± 0.28	21.08% ± 0.79%
DFG	82.39 ± 0.46	63.64 ± 0.37	38.61% ± 0.65%	72.46 ± 0.57	36.47 ± 0.30	23.35% ± 0.59%
DeepCrowd	92.46 ± 1.38	67.54 ± 0.70	38.45% ± 0.86%	74.36 ± 0.37	36.46 ± 0.23	23.72% ± 0.34%
TG-SCR	53.19 ± 0.40	41.03 ± 0.21	30.06% ± 0.69%	51.56 ± 0.42	27.43 ± 0.24	19.05% ± 0.29%

Method	Beijing			Shanghai		
	RMSE	MAE	MAPE	RMSE	MAE	MAPE
RF	9.03	4.56	17.62%	6.62	3.02	13.04%
XGBoost	14.52	7.33	29.24%	7.81	4.50	18.89%
SVR	19.12	10.16	36.34%	25.05	13.57	46.84%
GCN	20.46 ± 1.46	13.49 ± 0.84	56.20% ± 1.95%	18.34 ± 0.87	11.52 ± 0.33	42.71% ± 3.73%
GraphSAGE	22.56 ± 1.36	14.22 ± 0.83	53.37% ± 1.86%	14.36 ± 1.31	9.64 ± 0.83	41.69% ± 5.31%
GAT	18.92 ± 1.30	12.38 ± 0.56	33.27% ± 2.02%	9.44 ± 1.03	6.82 ± 0.95	28.59% ± 3.51%
GIN	10.29 ± 0.99	6.22 ± 0.40	24.68% ± 2.42%	6.57 ± 0.17	3.79 ± 0.06	21.06% ± 1.42%
DFG	3.48 ± 0.16	2.29 ± 0.06	9.55% ± 0.21%	2.39 ± 0.04	1.74 ± 0.02	9.54% ± 0.60%
DeepCrowd	10.29 ± 1.04	6.22 ± 0.46	24.86% ± 2.89%	6.57 ± 0.09	4.25 ± 0.03	16.63% ± 0.92%
TG-SCR	1.47 ± 0.07	1.10 ± 0.05	5.12% ± 0.14%	1.67 ± 0.03	1.26 ± 0.02	7.31% ± 0.83%

Method	Futian			Nanshan		
	RMSE	MAE	MAPE	RMSE	MAE	MAPE
TG-SCR	53.19 ± 0.40	41.03 ± 0.21	30.06% ± 0.69%	51.56 ± 0.42	27.43 ± 0.24	19.05% ± 0.29%
TG-SCR w/o GRM	55.67 ± 0.42	42.63 ± 0.21	31.28% ± 1.66%	52.72 ± 0.61	27.19 ± 0.23	19.28% ± 1.08%
TG-SCR w/o GRM & SCM	92.46 ± 1.38	67.54 ± 0.70	38.40% ± 0.86%	72.46 ± 0.57	36.47 ± 0.42	23.58% ± 8.36%



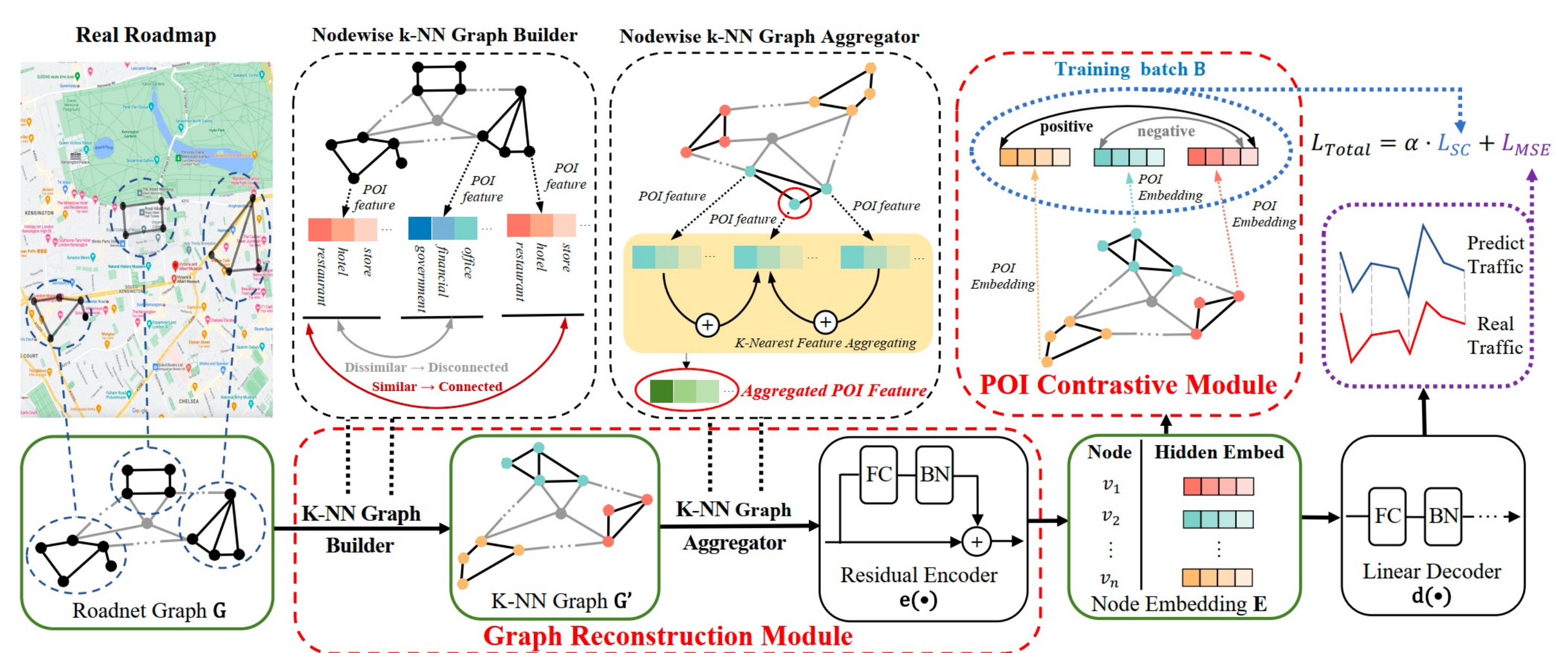
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Pipeline of Our Proposed Model: TG-SCR

- Graph Reconstruction Module.** This module includes a *k-NN Graph Builder* and a *k-NN Graph Aggregator* to reform the original roadnet graph and eliminate biases.
- POI Contrastive Module.** This module adds a *supervised contrastive loss* to help TG-SCR explicitly hold the former similarity relationships.



- Training algorithm of TG-SCR:**

Algorithm 1 Training procedure of TG-SCR

Input: Roadnet graph G with map-matched POI feature X , encoder $e(\cdot)$ and decoder $d(\cdot)$ parameterized with θ

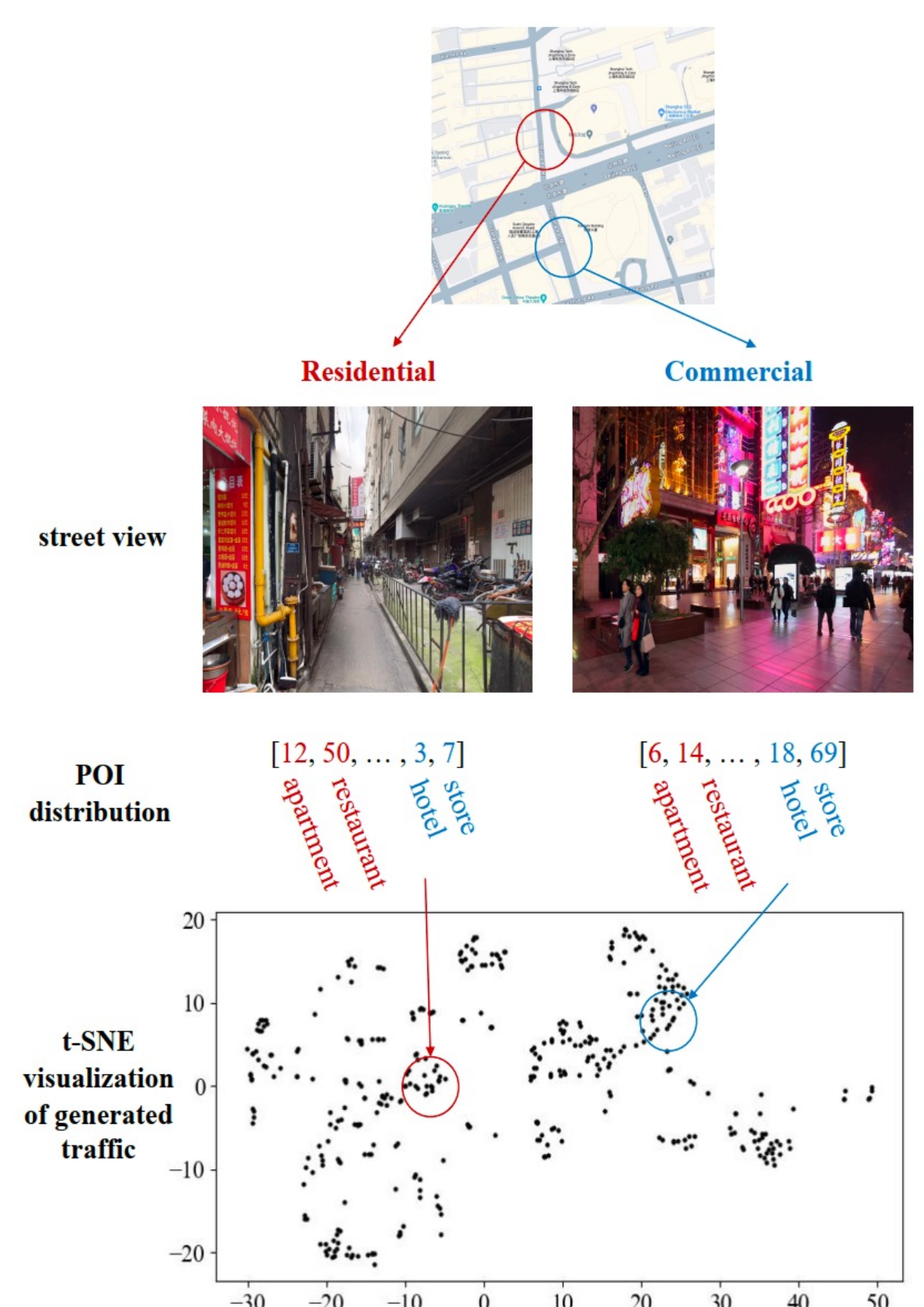
- Build k -NN graph G' from G based on Eq (3)
- Get Aggregated POI feature X' from X based on Eq (4)
- Compute POI embeddings: $E' = e(X')$
- repeat**
- Sample a training batch B including N nodes
- Define positive set \mathbb{P} and negative set \mathbb{N} based on Eq (5) and Eq (6)
- Compute L_{Total} based on Eq (9)
- Back Propagation
- Update θ based on Eq (7)
- until** $L_{Total} < \epsilon$

Output: Predicted traffic \hat{Y}

Real-World Case in Shanghai

- Despite close in graph, the generated traffic flows of nodes in these two locations *have a significant difference*.

- Through t-SNE visualization, TG-SCR keenly captures the POI distribution relationship.



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