Sources used in this book:
[1] [2] [3] [4] [5] [6] [7]

References

[1] B. Siciliano and O. Khatib, editors. *Springer Handbook of Robotics*. Springer, Berlin, Heidelberg, 2008.

[2] Richard P Paul. *Robot manipulators: mathematics, programming, and control: the computer control of robot manipulators*. the MIT Press, 1981.

[3] Haruhiko Asada and Jean-Jacques E Slotine. *Robot analysis and control*. J. Wiley New York, NY, 1986.

[4] Yoshihiko Nakamura. *Advanced robotics: redundancy and optimization*. Addison-Wesley Longman Publishing Co., Inc., 1990.

[5] Tsuneo Yoshikawa. *Foundations of robotics: analysis and control*. The MIT Press, 1990.

[6] J. Craig. *Introduction to Robotics: Mechanics and Control*. Addison Wesley, 1986.

[7] Reza N Jazar. *Theory of applied robotics: kinematics, dynamics, and control*. Springerverlag Us, 2007.