## (1 - 2) Introduction to C Data Structures & Abstract Data Types

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#### What is a Data Structure?

- A software construct describing the organization and storage of information
  - Designed to be accessed efficiently
  - Composite of related items
- An implementation of an abstract data type (ADTs) to be defined later
- Defined and applied for particular applications and/or tasks



## **Data Structures Exposed**

- You've already seen a few fixed-sized data structures
  - Arrays
  - Structures or structs in C



### Review of Basic C Data Structures (1)

- Recall an array is a collection of related data items
  - Accessed by the same variable name and an index
  - Data is of the same type
  - Items are contiguous in memory
  - Subscripts or indices must be integral and 0 or positive only
- Our visual representation of an array of chars, where first row is index and second is contents

index	0	 n-2	n-1
contents	'b'	 <b>'3'</b>	<b>'\0'</b>



## Review of Basic C Data Structures (2)

- Recall a structure or struct is a collection of related fields or variables under one name
  - Represent real world objects
  - Each field may be of a different data type
  - The fields are contiguous in memory
- Example struct describing a dog



## How Can We Expand on Our Data Structure Knowledge?

- In this course we will focus on dynamic data structures
  - These grow and shrink at runtime
- The major dynamic data structures include:
  - Lists
  - Stacks
  - Queues
  - Binary Trees
  - Binary Search Trees (BSTs)



## **Basic Applications of Dynamic Data Structures (1)**

- Lists are collections of data items lined up in a row
  - Insertions and deletions may be made anywhere
  - May represent movie & music collections, grocery store lists, & many more...
- Stacks are restricted lists
  - Insertions and deletions may be made at one end only
    - These are Last In, First Out (LIFO) structures
  - May be used with compilers & operating systems, & many more applications...



## Basic Applications of Dynamic Data Structures (2)

- Queues are also restricted lists
  - Insertions are made at the back of the queue and deletions are made from the front
    - These are First In, First Out (FIFO) structures
  - May represent waiting lines, etc.
- BSTs require linked data items
  - Efficient for searching and sorting of data
  - May represent directories on a file system, etc.
- This course will focus on these dynamic data structures and corresponding implementations in both C and C++



## What do these C Dynamic Structures have in Common?

- Of course dynamic growing and shrinking properties...
- Implemented with pointers
  - Recall a pointer is a variable that stores as its contents the address of another variable
    - Operators applied to pointers include
      - Pointer declaration i.e. char \*ptr
      - Dereference or indirection i.e. \*ptr
      - Address of i.e. &ptr
      - Assignment i.e. ptr1 = ptr2
      - Others?
- Require the use of structs
  - Actually self-referential structures for linked implementations



#### What is a Self-Referential Structure?

- A struct which contains a pointer field that represents an address of a struct of the same type
- Example

```
typedef struct node
{
    char data;
    // self-referential
    struct node *pNext;
} Node;
```



## Dynamic Memory Allocation / Deallocation in C (1)

- The growing and shrinking properties may be achieved through functions located in <stdlib.h> including:
  - malloc() for allocating/growing memory
  - free() for de-allocating/shrinking memory
  - realloc() for resizing memory
  - Also consider calloc()



## Dynamic Memory Allocation / Deallocation in C (2)

 Assume the following: Node \*pItem = NULL; How to use malloc() pItem = (Node \*) malloc (sizeof (Node)); // Recall malloc ( ) returns a void \*, // which should be typecasted How to use free() free (pItem); // Requires the pointer to the memory to be // de-allocated How to use realloc() pItem = realloc (pItem, sizeof (Node) \* 2); // Allocates space for two Nodes and // returns pointer to beginning of resized // memory



# How Do We Know Which Values and Operations are Supported?

- Each data structure has a corresponding model represented by the abstract data type (ADT)
  - The model defines the behavior of operations, but not how they should be implemented



## **Abstract Data Types**

- Abstract Data Types or ADTs according to National Institute of Standards and Technology (NIST)
  - Definition: A set of data values and associated operations that are precisely specified independent of any particular implementation.



#### **Data Structure**

- Data Structures according to NIST
  - Definition: An organization of information, usually in memory, for better <u>algorithm</u> <u>efficiency</u>, such as <u>queue</u>, <u>stack</u>, <u>linked list</u>, <u>heap</u>, <u>dictionary</u>, and <u>tree</u>, or conceptual unity, such as the name and address of a person. It may include redundant information, such as length of the <u>list</u> or number of <u>nodes</u> in a <u>subtree</u>.



#### **ADTs versus Data Structures**

- Many people think that ADTs and Data Structures are interchangeable in meaning
  - ADTs are logical descriptions or specifications of data and operations
    - To abstract is to leave out concrete details
  - Data structures are the actual representations of data and operations, i.e. implementation
- Semantic versus syntactic



## **Specification of ADT**

- Consists of at least 5 items
  - Types/Data
  - Functions/Methods/Operations
  - Axioms
  - Preconditions
  - Postconditions
  - Others?



## **Example Specification of List ADT (1)**

- Description: A list is a finite sequence of nodes, where each node may be only accessed sequentially, starting from the first node
- Types/Data
  - e is the element type
  - L is the list type



## **Example Specification of List ADT (2)**

- Functions/Methods/Operations
  - InitList (L): Procedure to initialize the list L to empty
  - DestroyList (L): Procedure to make an existing list L empty
  - ListIsEmpty (L) -> b: Boolean function to return TRUE if L is empty
  - ListIsFull (L) -> b: Boolean function to return TRUE if L is full
  - CurlsEmpty (L) -> b: Boolean function to return TRUE if the current position in L is empty



## **Example Specification of List ADT (3)**

- Functions/Methods/Operations Continued
  - ToFirst (L): Procedure to make the current node the first node in
     L; if the list is empty, the current position remains empty
  - AtFirst (L) -> b: Boolean function to return TRUE if the current node is the first node in the list or if the list and the current position are both empty
  - AtEnd (L) -> b: Boolean function to return TRUE if the current node is the last node in the list or if the list and the current position are both empty
  - Advance (L): Procedure to make the current position indicate the next node in L; if the current node is the last node the current position becomes empty



## **Example Specification of List ADT (4)**

- Functions/Methods/Operations Continued Again
  - Insert (L,e): Procedure to insert a node with information e before the current position or, in case L was empty, as the only node in L; the new node becomes the current node
  - InsertAfter (L,e): Procedure to insert a node with information e into L after the current node without changing the current position; in case L is empty, make a node containing e the only node in L and the current node
  - InsertFront (L,e): Procedure to insert a node with information e into L as the first node in the List; in case L is empty, make a node containing e the only node in L and the current node
  - InsertInOrder (L,e): Procedure to insert a node with information e into L as node in the List, order of the elements is preserved; in case L is empty, make a node containing e the only node in L and the current node



## **Example Specification of List ADT (5)**

- Functions/Methods/Operations Continued One Last Time
  - Delete (L): Procedure to delete the current node in L and to have the current position indicate the next node; if the current node is the last node the current position becomes empty
  - StoreInfo (L,e): Procedure to update the information portion of the current node to contain e; assume the current position is nonempty
  - RetrieveInfo (L) -> e: Function to return the information in the current node; assume the current position is nonempty



## **Example Specification of List ADT (6)**

- Axioms
  - Empty ()?
  - Not empty ()?
  - Others?
- Preconditions
  - Delete () requires that the list is not empty ()
- Postconditions
  - After Insert () is executed the list is not empty ()
- Others?



#### **Visual of List ADT**

- View diagrams on the board
  - Nodes?
  - List?



#### **Next Lecture...**

 Introduction to implementation of a dynamically linked list



#### References

- P.J. Deitel & H.M. Deitel, C++: How to Program (10th ed.), Pearson Education Inc, 2017
- J.R. Hanly & E.B. Koffman, Problem Solving and Program Design in C (7<sup>th</sup> Ed.), Addison-Wesley, 2013



### **Collaborators**

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